WÄRTSILÄ **Engines**

Marine Installation Manual

Wärtsilä X40 Issue December 2012

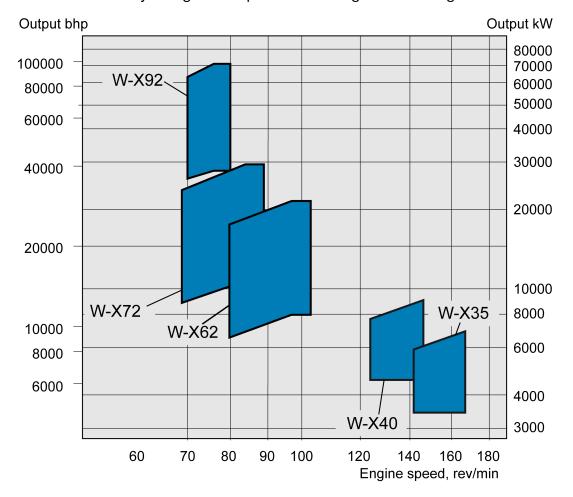


Preface

The **Wärtsilä RT-flex system** represents a major step forward in the technology of large diesel engines:

• Common rail injection - fully suitable for heavy fuel oil operation.

The Marine Installation Manual is for use by project and design personnel. Each chapter contains detailed information for design engineers and naval architects, enabling them to optimize plant items and machinery space, and to carry out installation design work.



This manual is only designed for persons dealing with this engine.

This manual provides the information required for the layout of marine propulsion plants. It is not to be considered as a specification. The build specification is subject to the laws of the legislative body of the country of registration and the rules of the classification society selected by the owners.

Its content is subject to the understanding that any data and information herein have been prepared with care and to the best of our knowledge. We do not, however, assume any liability with regard to unforeseen variations in accuracy thereof or for any consequences arising therefrom.

Attention is drawn to the following:

- All data are related to engines compliant with **IMO-2000 regulations Tier II**.
- The engine performance data (rating R1) refer to winGTD and netGTD.
- The engine performance data (BSFC, BSEF and tEaT) and other data can be obtained from the *winGTD and netGTD*. The winGTD can be downloaded from our Licensee Portal. The netGTD is accessible on internet using the following address:

http://www.wartsila.com/en/marine-solutions/products/netGTD

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List of updated text in this version

See section	on	Page
	Information in section "Preface" has been updated.	-ii
1.	Information in section "Engine Characteristics" has been updated.	11
1.1	Information in section "Primary engine data" has been updated.	12
1.2	Information in section "Tuning options" has been added.	13
1.2.1	Information in section "Delta Tuning" has been updated.	13
1.2.2	Information in section "Low-Load Tuning (LLT)" has been updated.	14
	Information in section "Tuning for de-rated engines:" has been updated.	15
	Information in section "Effect on engine dynamics:" has been updated.	16
	Information in section "Project specification for RT-flex engines:" has been updated.	16
1.3.1	Information in section "Design features:" has been added.	17
1.4	Information in section "The RT-flex system " has been updated.	19
1.4.1	Information in section "The major benefits of the RT-flex system are:" has been updated.	19
2.1	Information in section "Reference conditions" has been updated.	21
2.2	Information in section "Design conditions" has been updated.	21
2.3	Information in section "Ancillary system design parameters" has been updated.	22
2.4	Information in section "Engine performance data" has been updated.	22
2.5.1	Information in section "SAC parameters and turbocharger weights" has been updated.	23
	Information in section "SAC parameters and turbocharger weights" has been added.	23
2.5.2	Information in section "Air filtration" has been updated.	23
2.6	Information in section "Auxiliary blower" has been updated.	24
2.7	Information in section "Electrical power requirement" has been updated.	25
2.8	Information in section "Pressure and temperatures ranges" has been updated.	26
3.	Information in section "Engine Rating and Load Range" has been updated.	31
3.1	Information in section "Rating field" has been added.	31
3.1.1	Information in section "Influence of propeller revolutions on the power requirement" has been updated.	32
3.2.1	Information in section "Propeller curves" has been updated.	33
3.2.4	Information in section "Light running margin (LR)" has been updated.	35
	Information in section "Assuming, for example, the following:" has been updated.	35
	Information in section "This is the sum of the following factors:" has been updated.	36
3.2.5	Information in section "Engine margin (EM) or operational margin (OM)" has been updated.	36
3.2.6	Information in section "Load range limits" has been updated.	37
3.2.7	Information in section "Load range with main-engine driven generator" has been updated.	38
3.3	Information in section "Load range limit with controllable pitch propeller" has been updated.	39
3.4	Information in section "Requirements for control system with CPP" has been updated.	311
4.	Information in section "winGTD and netGTD" has been added.	41
5.	Information in section "Engine Dynamics" has been updated.	51
5.1	Information in section "External forces and moments" has been updated.	51

5.1.1	Information in section "External forces and moments" has been added.	52
5.1.4	Information in section "Power related unbalance (PRU)" has been updated.	54
5.2	Information in section "Lateral engine vibration (rocking)" has been updated.	55
5.3.1	Information in section "Engine stays" has been updated.	56
	Information in section "Hydraulic stays:" has been added.	56
	Information in section "Friction stays:" has been added.	57
5.3.2	Information in section "Electrically driven compensator" has been updated.	58
5.4	Information in section "Longitudinal engine vibration (pitching)" has been updated.	58
5.5.1	Information in section "Reduction of torsional vibration" has been updated.	58
5.6	Information in section "Axial vibration" has been updated.	510
5.6.1	Information in section "Reduction of axial vibration" has been updated.	510
5.7	Information in section "Hull vibration" has been updated.	511
5.8	Information in section "Summary of countermeasures for dynamic effects" has been updated.	511
5.8.1	Information in section "External mass moments" has been updated.	511
5.8.2	Information in section "Lateral and longitudinal rocking" has been updated.	511
5.8.3	Information in section "Torsional and axial vibrations" has been updated.	512
5.9	Information in section "System dynamics" has been updated.	512
5.10	Information in section "Order forms for vibration calculations and simulation" has been updated.	512
6.	Information in section "Auxiliary Power Generation" has been updated.	61
6.2	Information in section "Power take-off (PTO)" has been added.	62
6.2.1	Information in section "PTO power and speed" has been added.	62
7.	Information in section "Ancillary Systems" has been updated.	71
7.1	Information in section "Data for central freshwater cooling system (integrated HT)" has been updated.	72
7.1.1	Information in section "Data for central freshwater cooling system" has been updated.	72
8.	Information in section "Cooling Water System" has been updated.	81
8.1	Information in section "Central freshwater cooling system components" has been updated.	82
8.1.1	Information in section "Low-temperature circuit" has been updated.	82
8.1.2	Information in section "High-temperature circuit" has been updated.	83
8.2	Information in section "General recommendations for design" has been updated.	810
8.2.1	Information in section "Cooling water treatment" has been updated.	810
8.3	Information in section "Freshwater generator" has been updated.	811
8.3.1	Information in section "Alternative 'A'" has been updated.	812
	Information in section "Example" has been updated.	812
8.3.2	Information in section "Alternative 'B'" has been updated.	813
	Information in section "Example" has been updated.	814
8.4	Information in section "Pre-heating" has been updated.	815
9.	Information in section "Lubricating Oil Systems" has been updated.	91
9.2	Information in section "Main lubricating oil system" has been updated.	92
9.3.1	Information in section "Lubricating oil pump" has been updated.	93

9.3.2	Information in section "Lubricating oil cooler" has been updated.	93
9.3.3	Information in section "Lubricating oil full-flow filters" has been updated.	93
9.4	Information in section "Cylinder lubricating oil system" has been updated.	94
9.5.1	Information in section "Lubricating oil separator" has been updated.	94
9.6	Information in section "Lubricating oil requirements" has been updated.	95
	Information in section "Global brands of lubricating oils" has been updated.	96
	Information in section "Local brands of lubricating oils" has been added.	97
9.7	Information in section "Lubricating oil drain tank" has been updated.	98
9.7.1	Information in section "Arrangement of vertical lubricating oil drains" has been updated.	98
9.7.2	Information in section "Min. inclination angles at which the engine is to remain fully operational" has been updated.	99
9.7.3	Information in section "Dimensioning guide-lines and filling process" has been updated.	912
10.1	Information in section "Fuel oil requirements" has been updated.	101
10.1.1	Information in section "Viscosity (see figure)" has been updated.	102
10.1.2	Information in section "Carbon residue, asphaltenes sediment" has been updated.	103
10.1.3	Information in section "Sulphur" has been updated.	103
10.1.5	Information in section "Aluminium, silicon" has been updated.	103
10.1.6	Information in section "Water" has been updated.	103
10.1.8	Information in section "Pour point" has been updated.	104
10.2.2	Information in section "Service tanks" has been updated.	105
10.2.3	Information in section "Centrifugal separators" has been updated.	105
	Information in section "Separator without gravity disc:" has been updated.	105
	Information in section "Separator with gravity disc:" has been updated.	106
	Information in section "Separation efficiency" has been updated.	106
10.3.1	Information in section "Fuel oil feed pump" has been updated.	107
	Information in section "Example" has been updated.	107
10.3.2	Information in section "Pressure regulating valve" has been updated.	108
10.3.3	Information in section "Mixing unit" has been updated.	108
10.3.4	Information in section "High-pressure booster pump" has been updated.	108
10.3.5	Information in section "Fuel oil end heater" has been updated.	109
10.3.6	Information in section "Fuel oil filter" has been updated.	1011
	Information in section "Arrangement in the feed system (A)" has been updated.	1011
	Information in section "Back-flushing filter" has been updated.	1011
	Information in section "Duplex filter" has been updated.	1011
ļ	Information in section "Arrangement before engine inlet (B)" has been updated.	1012
	Information in section "Further specifications/properties of the filters:" has been updated.	1012
11.	Information in section "Starting and Control Air Systems" has been updated.	111
11.1	Information in section "Capacities of air compressor and receiver" has been updated.	112
11.1.1	Information in section "Air receiver and air compressor capacities" has been updated.	112
11.2.1	Information in section "Starting air compressors" has been updated.	113
11.2.2	Information in section "Starting air receivers" has been updated.	113
11.2.3	Information in section "Control air system supply" has been updated.	113

	Information in section "Control air capacities" has been updated.	113
12.	Information in section "Leakage Collection System" has been updated.	121
12.1	Information in section "Sludge oil trap" has been updated.	122
12.2	Information in section "Air vents" has been updated.	124
13.	Information in section "Exhaust Gas System" has been updated.	131
13.2	Information in section "Exhaust gas pipe diameters " has been updated.	131
14.	Information in section "Engine-room Ventilation" has been updated.	141
14.1	Information in section "Engine air inlet - Operating temperatures of 45 to 5°C" has been updated.	142
14.1.1	Information in section "Arctic conditions at operating temperatures of less than 5°C" has been updated.	143
15.	Information in section "Pipe Sizes and Flow Details" has been updated.	151
15.1	Information in section "Pipe velocities" has been updated.	151
17.	Information in section "Engine Automation" has been updated.	171
17.1.2	Information in section "Propulsion control system" has been updated.	173
	Information in section "Integrated solution" has been updated.	174
	Information in section "Alarm sensors and safety functions (part 1)" has been updated.	177
	Information in section "Alarm sensors and safety functions (part 2)" has been added.	1711
	Information in section "Classification societies" has been added.	1714
	Information in section "Request of classification societies" has been added.	1714
	Information in section "Functions and level" has been added.	1714
18.	Information in section "General Installation Aspects" has been updated.	181
18.1	Information in section "Engine Dimensions and masses" has been updated.	182
18.1.1	Information in section "Dimensions and masses of main components" has been updated.	183
18.1.2	Information in section "Thermal expansion at the turbocharger expansion joint" has been updated.	184
18.1.3	Information in section "Contents of fluid in the engine" has been updated.	185
18.1.4	Information in section "Crane requirements" has been updated.	185
18.1.5	Information in section "Piston and tie rod dismantling heights" has been added.	185
	Information in section "Piston dismantling heights" has been updated.	185
18.1.6	Information in section "Dismantling of scavenge air cooler" has been updated.	187
18.3	Information in section "Platform arrangements" has been updated.	1813
18.4	Information in section "Engine seating" has been updated.	1813
18.5.1	Information in section "Fitting of coupling bolts" has been updated.	1885
18.6.2	Information in section "Main shaft earthing system" has been updated.	1887
18.7	Information in section "Engine stays" has been added.	1890
18.8.1	Information in section "Extinguishing agents" has been updated.	18148
19.1.2	Information in section "Regulation regarding NOX emissions of diesel engines" has been updated.	191
19.1.3	Information in section "Measures for compliance with the IMO regulation" has been updated.	192
20.1	Information in section "Treatment against corrosion" has been updated.	201
20.4.1	Information in section "Installation and assembly of subassemblies" has been updated.	2073

20.4.2	Information in section "Installing a complete engine" has been updated.	2074
20.4.3	Information in section "Installing an engine from assembled subassemblies" has been updated.	2074
21.	Information in section "Engine and Shaft alignment" has been updated.	211
21.2	Information in section "Tools" has been updated.	2156
22.1	Information in section "Abbreviations" has been updated.	221

List of updated drawings in this version

Drawing number	Updates	Daga
	00000	Page
107.165.810 a Treaded Sleeve, Engine Stays, W5-8X40	new	18123
DAAD012368 - BoLT, To Engine Stays. Friction, W5-8X40	new	1895
DAAD020452 a Elastic BoLT, W6X40	revised from - to a	1821
107.165.811 - Piston Guide, Order Drwg., W5-8X40	new	18127
DAAD020880 - Engine Stays, Hydraulic Type, W5-8X40	new	18114
DAAD007603 a Denis Interface Specification, Denis-Unic / Content W5-8X40	r, revised from - to a	1715
107.165.812 - Pressure Gauge, Order Dr., W5-8X40	new	18128
107.380.159 b Round Nut, W5-8X40	revised from - to b	1898
107.165.813 b Prec. Seamless Pipe, Order Drwg., W5-8X40	new	18147
107.165.814 - Plug, Order Drwg., W5-8X40	new	18130
DAAD024352 - Engine Stays, Friction Type. Fuel Pumpe Side, W5-8X40	new	1892
107.165.815 - Support, W5-8X40	new	18124
107.425.523 c Engine Outline View, W6X40	revised from - to c	1810
107.245.419 c Expansion Tank, Central Cooling Water LT Circuit, W5-8X40	revised from b to c	840
107.425.524 a Engine Outline View, W7X40	new	1811
107.165.817 a Instruction For Pressure Test, 250 Bar, W5-8X40	new	18144
DAAD024355 - Engine Stays/ Friction Type, W5-8X40	new	1893
107.165.800 g Hydraulic Cylinder, To Engine Stays, W5-8X40	new	18115
107.165.818 b Testing and Filling Device, Order Drwg., W5-8X40	new	18143
107.165.801 f Cylinder, W5-8X40	new	18116
DAAD009317 b Engine Outline View, W5X40	revised from - to b	189
107.427.450 a Material and Test Specification, W5-8X40	revised from - to a	1822
107.165.802 a Piston, W5-8X40	new	18117
107.165.803 d Cover, W5-8X40	new	18118
DAAD020556 a Lubricating Oil System, W6X40	revised from - to a	917
DAAD013764 a Rubber Gasket, Vertical Oil Drain, W6X40	revised from - to a	921
107.165.804 b Valve Spindle, W5-8X40	new	18119
DAAD020382 a Fuel Oil System, Main Circuit, W5-8X40	revised from - to a	1017
107.431.447 a Jacking Screw, W6X40	revised from - to a	2158
DAAD024500 - Engine Stays, Friction Type. Exhaust Side, W5-8X40) new	1891
) new	18101

107.165.806 a Pointer, W5-8X40	new	18121
DAAD012458 a Clamping Part, Machined. To Engine Stays, W5-8X40	new	18100
DAAD023085 a Engine Outline View, W8X40	new	1812
107.165.808 a Connecting Piece (Sw41), W5-8X40	new	18120
DAAD006100 - Round Bar, W5-8X40	new	18145
107.165.809 - Bearer, W5-8X40	new	18122
107.385.952 c Heat Treatment Specification, Quench Temper Low Alloy Steel, W5-8X40	revised from a to c	1841
107.131.611 a Quality and Test Specification, BoLTs and Studs Sheet 1-, W5-8X40	revised from - to a	1863
107.246.429 e Assembly Instructions, To Engine Stays Friction, W5-8X40	new	18113
107.329.413 a Bladder Accumulator, Order Drawing, W5-8X40	new	18129
107.427.386 c Material and Test Specification, W5-8X40	revised from b to c	1834
DAAD013143 a Stay, Machined. To Engine Stays, W5-8X40	new	18103
DAAD012596 - Ring, To Engine Stays. Friction, W5-8X40	new	1899
107.385.944 b Testing Specification, Chemical Analysis Of Materials, W5-8X40	revised from a to b	1858
DAAD015249 b Pipe Connection Plan, W6X40	revised from a to b	163
DAAD013130 a Plate, Welded. To Engine Stays, W5-8X40	new	18105
107.165.820 b Hydraulic Lateral Device, For Main Engine, W5-8X40	new	18142
107.385.948 b Testing Specification, Evaluation Mechanical Properties, W5-8X40	revised from - to b	1849
107.245.489 - Ball Valve, Order Drawing, W5-8X40	new	18126
107.165.821 a Ring, W5-8X40	new	18125
DAAD012140 - Shim, To Engine Stays. Friction, W5-8X40	new	18102
107.165.822 - Male Union, Order Drwg., W5-8X40	new	18146
DAAD024360 - Disc Spring, To Engine Stays. Friction, W5-8X40	new	1897
DAAD012141 - Support, To Engine Stays. Friction, W5-8X40	new	1896
DAAD012142 - Support, To Engine Stays. Friction, W5-8X40	new	1894

Table of contents

1.	Engir	e Characteristics	1-1
	1.1 1.2	Primary engine data Tuning options	1-2 1-3
	1.3 1.4	Main features and parameters:	1-7 1-9
2.	Engir	ie Data	2-1
	2.1	Reference conditions	2-1
	2.2	Design conditions	2-1
	2.3	Ancillary system design parameters	2-2
	2.4	Engine performance data	2-2 2-2
	2.5 2.6	Turbocharger and scavenge air cooler Auxiliary blower	2-2 2-4
	2.7	Electrical power requirement	2-5
	2.8	Pressure and temperatures ranges	2-6
3.	Engir	e Rating and Load Range	3-1
	3.1	Rating field	3-1
	3.2	Load range	3-3
	3.3	Load range limit with controllable pitch propeller	3-9
	3.4	Requirements for control system with CPP	
4.	winG	TD and netGTD	4-1
5.	Engir	e Dynamics	5-1
	5.1	External forces and moments	5-1
	5.2	Lateral engine vibration (rocking)	5-5
	5.3 5.4	Reduction of lateral vibration Longitudinal engine vibration (pitching)	5-6 5-8
	5.5	Torsional vibration	5-8
	5.6	Axial vibration	
	5.7	Hull vibration	
	5.8 5.9	Summary of countermeasures for dynamic effects	5-11 5-12
	5.9 5.10	Order forms for vibration calculations and simulation	
6.		ary Power Generation	
0.	6.1	Waste heat recovery	
	6.2	Power take-off (PTO)	
7.		ary Systems	7-1
	7.1	Data for central freshwater cooling system (integrated HT)	7-2
8.		ng Water System	8-1
0.	8.1	Central freshwater cooling system components	8-2
	8.2	General recommendations for design	8-10
	8.3	Freshwater generator	8-11
	8.4	Pre-heating	8-15
	8.5	Drawings	8-15
9.	Lubri	cating Oil Systems	9-1
	9.1	Lubricating oil systems for turbochargers	9-2
	9.2 9.3	Main lubricating oil system Main lubricating oil system components	9-2 9-3
	9.3 9.4	Cylinder lubricating oil system	9-3 9-4
	9.5	Lubricating oil maintenance and treatment	9-4

	9.6	Lubricating oil requirements	
	9.7 9.8	Lubricating oil drain tank Drawings	
10.		Dil System	
	10.1	Fuel oil requirements	
	10.2	Fuel oil treatment	10-5
	10.3	Heavy fuel oil system components	
	10.4	Drawings	
11.		ng and Control Air Systems	
	11.1 11.2	Capacities of air compressor and receiver Starting and control air system specification	
	11.3		
	11.4	Drawings	11-3
12.	Leaka	age Collection System	12-1
	12.1		
		Air vents Drawings	
13		Jst Gas System	
10.	13.1		
		Exhaust gas pipe diameters	
14.	Engin	e-room Ventilation	
	· ·	Engine air inlet - Operating temperatures of 45 to 5°C	
15.	Pipe	Sizes and Flow Details	15-1
	15.1	Pipe velocities	15-1
	15.2	Piping symbols	15-3
16.		Connections	
	16.1	Drawings	16-1
17.	Engin	e Automation	
	17.1		
10	17.2	Drawings	
18.		ral Installation Aspects Engine Dimensions and masses	
	18.1 18.2	Outlines	
	18.3	Platform arrangements	
	18.4 18.5	Engine seating Engine coupling	
	18.6	Engine coupling	
	18.7	Engine stays	
	18.8	Fire protection	
19.	•	e Emissions	
		Exhaust gas emissions	
20.		e Dispatch and Installation	
	20.1 20.2	Treatment against corrosion	
	20.2 20.3	Engine dismantling Removing rust preventing oils	
	20.4		
21.	Engin	e and Shaft alignment	21-1
		Procedure	
	21.2	Tools	

22.	Appendix		
	22.1	Abbreviations	22-1
	22.2	SI dimensions for internal combustion engines	22-3
	22.3	Approximate conversion factors	22-5

List of tables

1.1	Primary engine data	1-2
1.2	Overall sizes of engine	1-8
2.1	Scavenge air cooler parameters	2-3
2.2	Turbocharger weights	2-3
2.3	Guidance for air filtration	2-3
2.4	Number of auxiliary blowers	2-4
2.5	Electrical power requirement	2-5
2.6	Pressure and temperature ranges	2-6
5.1	Mass moments and forces	5-2
5.2	Countermeasures for external mass moments	5-11
5.3	Countermeasures for lateral and longitudinal rocking	5-11
5.4	Countermeasures for torsional and axial vibration	5-12
6.1	PTO power and speed	6-2
7.1	Data for central freshwater cooling system	7-2
8.1	Low-temperature circuit	8-2
8.2	High-temperature circuit	8-3
9.1	Global brands of lubricating oils	9-6
9.2	Local brands of lubricating oils	9-7
9.3	Minimum inclination angles at which the engine is to remain fully operational (1)	9-9
9.4	Minimum inclination angles at which the engine is to remain fully operational (2)	9-9
9.5	Vertical lubricating oil drains to drain tank	9-10
11.1	Air receiver and air compressor capacities	11-2
15.1	Recommended fluid velocities and flow rates for pipework	15-1
17.1	Suppliers of remote control systems	17-3
17.2	Table of alarm sensors and safety functions (part 1)	17-7
17.3	Table of alarm sensors and safety functions (part 2)	17-11
17.4	Classification societies	17-14
17.5	Request of classification societies	17-14
17.6	Functions and level	17-14
18.1	Dimensions and masses of main components	18-3
18.2	Fluid quantities in the engine	18-5
18.3	Recommended total number of fire extinguishing bottles	18-148
22.1	Abbreviations	22-1
22.2	SI dimensions for internal combustion engines	22-3
22.3	Approximate conversion factors	22-5

List of figures

1.1	Cross section	1-1
1.2	Schematic functional principle of Low-Load Tuning	1-4
1.3	Delta Tuning and Low-load Tuning area	1-5
1.4	Typical BSFC curves to illustrate Standard Tuning, Delta Tuning and Low-Load Tuning	1-5
1.5	RT-flex key parts	1-9
2.1	Scavenge air cooler	2-2
2.2	Air filter size (example for 8-cyl. engine)	2-4
3.1	Rating field	3-1
3.2	Load range limits of an engine corresponding to a specific rating point Rx	3-4
3.3	Load diagram for a specific engine, showing the corresponding power and speed margins	3-5
3.4	Load range limits with load diagram of an engine corresponding to a specific rating point Rx	3-7
3.5	Load range diagram of an engine equipped with a main-engine driven generator	3-8
3.6	Load range diagram for CPP	3-10
5.1	External forces and moments	5-1
5.2	Locating electrically driven compensator	5-3
5.3	Power related unbalance (PRU)	5-4
5.4	External forces and moments	5-5
5.5	General arrangement of lateral stays (hydraulic)	5-6
5.6	General arrangement of lateral stays (friction)	5-7
5.7	Vibration damper (viscous type)	5-9
5.8	Vibration damper (Geislinger type)	5-9
5.9	Example of an axial damper (detuner)	5-10
6.1	Heat recovery, typical system layout	6-1
7.1	Central freshwater cooling system with integrated HT circuit	7-2
8.1	Central cooling water system, expansion tank	8-4
8.2	Central cooling water system, expansion tank (HT circuit)	8-6
8.3	Central cooling water system, expansion tank (LT circuit)	8-8
8.4	Freshwater generator installation, alternative 'A'	8-12
8.5	Freshwater generator installation, alternative 'B'	8-13
9.1	Pipe connections on the engine for the lubricating oil systems	9-1
9.2	Arrangement of vertical lubricating oil drains for the 6 cylinders	9-8
9.3	Minimum inclination angles at which the engine is to remain fully operational	9-10
9.4	Example of an accepted vertical drain connection	9-11
9.5	Filling process of lubricating oil tank	9-12
10.1	Typical viscosity / temperature diagram	10-2
10.2	Fuel oil system mixing unit	10-9
10.3	Filter arrangements	10-13

11.1	Starting and control air system	11-1
12.1	Sludge oil trap	12-2
12.2	Sludge oil trap	12-3
12.3	Arrangement of automatic water drain	12-4
13.1	Determination of exhaust pipe diameter	13-1
14.1	Direct suction of combustion air - main and auxiliary engine	14-1
14.2	Direct suction of combustion air - main and auxiliary engine	14-2
14.3	Scavenge air system for arctic conditions	14-3
14.4	Blow-off effect under arctic conditions	14-3
15.1	Piping symbols 1/3	15-3
15.2	Piping symbols 2/3	15-4
15.3	Piping symbols 3/3	15-5
17.1	EMA concept comprising DENIS, UNIC	17-1
17.2	Integrated/split solution	17-5
18.1	Engine dimensions	18-2
18.2	Thermal expansion, dim. X, Y, Z	18-4
18.3	Space requirements and dismantling heights for vertical piston lifting	18-6
18.4	Dismantling of SAC	18-7
18.5	Shaft earthing arrangement	8-88
18.6	Shaft earthing with condition monitoring facility	8-89
19.1	Speed dependent maximum average NO _x emissions by engines	19-1
19.2	Compliance with IMO regulations	19-2

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1. Engine Characteristics

The Wärtsilä X40 (W-X40) engine is a camshaftless low-speed, direct-reversible, two-stroke engine, fully electronically controlled, featuring common rail injection.

The W-X40 is designed for running on a wide range of fuels from marine diesel oil (MDO) to heavy fuel oils (HFO) of different qualities.

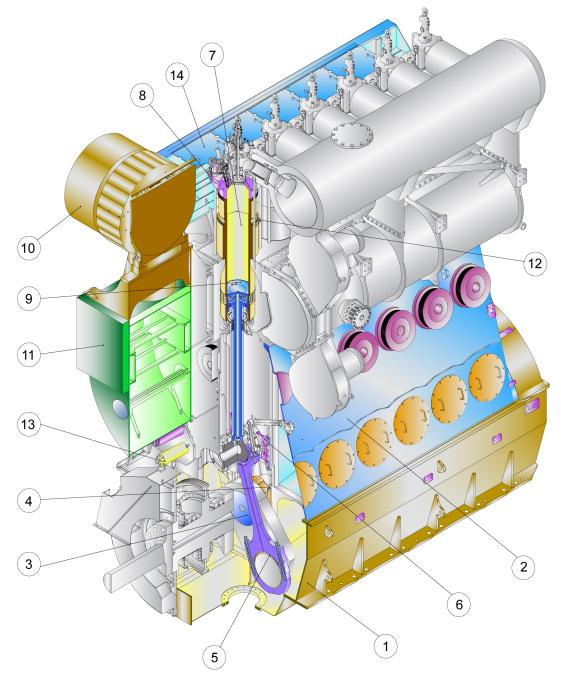


Figure 1.1: Cross section

1	Bedplate	6	Crosshead	11	Scavenging system
2	Column	7	Cylinder liner	12	Pulse Lubricating System
3	Crankshaft	8	Cylinder cover	13	Supply unit
4	Main bearing elastic studs	9	Piston	14	Rail unit (Common rail)
5	Bottom-end bearings	10	Turbocharging system		

1.1 Primary engine data

	Bore x stroke: 400 x 1,770 [mm]						
No. of cyl.	R1	R2	R3	R4			
· · ·	,	Power [kW]	· · · ·				
5	5,675	4,550	4,825	4,550			
6	6,810	5,460	5,790	5,460			
7	7,945	6,370	6,755	6,370			
8	9,080	7,280	7,720	7,280			
· · ·		Speed rpm					
All	146	146	124	124			
· · ·	Brake specific	fuel consumption (B	SFC) [g/kWh] Load 1009	%			
All 175		169	175	173			
· · ·		mep [bar]					
All	21.0	16.8	21.0	19.8			
Lubricati	ng oil consumption	(for fully run-in engine	es under normal opera	ting conditions)			
System oil	approximately 2.8 kg/cyl per day						
Cylinder oil	Guide feed rate 0.6 g/kWh						

Table 1.1: Primary engine data

NOTICE

¹⁾ The guide feed rate shown is for new engines equipped with Pulse Jet cylinder lubrication system. This allows important savings in engine operating costs. Engines with different lubricating systems might require a higher feed rate.

All brake specific fuel consumption (BSFC) data are quoted for fuel of lower calorific value 42.7 MJ/kg [10,200 kcal/kg]. All other reference conditions refer to ISO standard (ISO 3046-1). The figures for BSFC are given with a tolerance of +5%.

The values of power in kilowatt [kW] and fuel consumption in g/kWh are standard figures..

To determine the power and BSFC figures accurately in bhp and g/bhph respectively, the standard kW-based figures have to be converted by factor 1.36 (see also *winGTD and netGTD*).

1.2 Tuning options

With the introduction of the Wärtsilä RT-flex engines, a major step in the development of marine 2-stroke engines was taken. After the successful introduction of Delta Tuning, Wärtsilä Switzerland Ltd. is taking this development even further by introducing Low-Load Tuning (LLT).

1.2.1 Delta Tuning

Delta Tuning allows further reduction of the specific fuel oil consumption while still complying with all existing emission legislation. This is achieved by changing software parameters without modifying any engine parts. The Delta Tuning option needs to be specified at a very early stage of the project.

In realising Delta Tuning, the flexibility of the RT-flex system in terms of free selection of injection and exhaust valve control parameters, specifically variable injection timing (VIT) and variable exhaust closing (VEC), is used to reduce the brake specific fuel consumption (BSFC) in the part load range of less than 90% load.

Due to the trade-off between BSFC and NOx emissions, the associated increase in NOx emissions at part load must be compensated by a corresponding decrease in the full load NOx emissions. Hence, there is also a slight increase in full load BSFC to maintain compliance of the engine with the IMO NOx regulations.

The concept is based on tailoring the firing pressure and firing ratio for maximum efficiency in the range up to 90% load and then reducing them again towards full load. In this process, the same design-related limitations with respect to these two quantities are applied as in the specification of Standard Tuning.

NOTICE

The reliability of the engine is by no means impaired by the application of Delta Tuning, since all existing limitations to mechanical stresses and thermal load are observed.

1.2.2 Low-Load Tuning (LLT)

The complete flexibility in engine setting, which is an integral feature of the RT-flex common-rail system, enables fuel injection pressures and timing to be freely set at all loads. It is employed in special tuning regimes to optimize brake specific fuel consumption (BSFC) at individual engine loads.

This concept was first applied in Delta Tuning, which reduces BSFC for Wärtsilä RT-flex engines in the operating range of less than 90% engine load.

The concept has now been extended to Low-Load Tuning, which provides the lowest possible BSFC in the operating range of 40-70% engine load.

With Low-Load Tuning, RT-flex engines can be operated continuously and reliably at any load in the range of 30-100%.

The Low-Load Tuning concept is based on the combination of a specifically designed turbocharging system setup and appropriately adjusted engine parameters related to fuel injection and exhaust valve control.

The reduced part-load BSFC in Low-Load Tuning is achieved by optimizing the turbocharger match for part-load operation. This is done by increasing the combustion pressure at less than 75% load through an increased scavenge air pressure and a higher air flow (waste gate closed), and by blowing off part of the exhaust gas flow (waste gate open) at engine loads above 85%.

The higher scavenge air pressure at part-load results in lower thermal load and better combustion over the entire part-load range.

Low-Load Tuning requires the fitting of an exhaust gas waste gate (a pneumatically operated valve, see figure *1.2*) on the exhaust gas receiver before the turbocharger turbine. Exhaust gas blown off through the waste gate is by-passed to the main exhaust uptake. The waste gate is opened at engine loads above 85% to protect the turbocharger and the engine from overload.

A Wärtsilä RT-flex engine with Low-Load Tuning complies with the IMO Tier II regulations for NOx emissions.

The engine parameters controlling the fuel injection and exhaust valve operational characteristic have to be selected appropriately to allow realizing the full potential of the concept while ensuring compliance with the applicable NOx limit value. On the one hand, these parameters have to be specified in such a way that the transition between the bypass-closed and bypass-opened operating ranges can be realized as smooth as possible. On the other hand, a higher scavenge air pressure trendwise increases NOx emissions – hence, for achieving the same weightened average value over the test cycle, the parameters also need to be adjusted appropriately for compensating this increase.

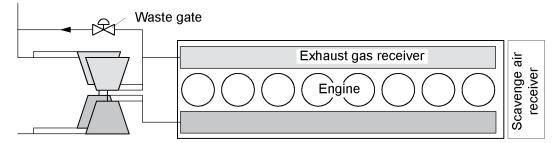


Figure 1.2: Schematic functional principle of Low-Load Tuning

1.2.3 Further aspects of engine tuning options

Tuning for de-rated engines:

For various reasons, the margin against the IMO NOx limit decreases for de-rated engines. Delta Tuning and Low-load Tuning thus holds the highest benefits for engines rated close to R1. Although with the de-rating the effect diminishes, Delta Tuning and Low-Load Tuning are applicable in the entire field (see figure *1.4*).

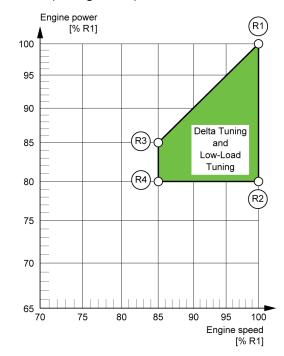


Figure 1.3: Delta Tuning and Low-load Tuning area

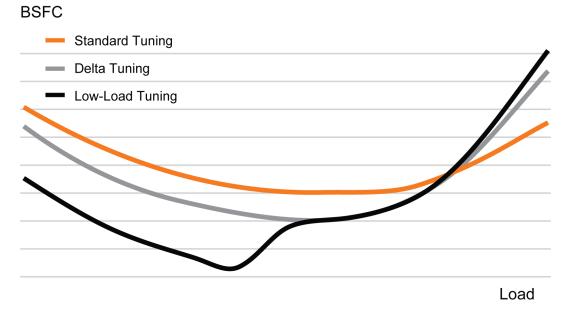


Figure 1.4: Typical BSFC curves to illustrate Standard Tuning, Delta Tuning and Low-Load Tuning

Effect on engine dynamics:

The application of Delta Tuning or Low-Load Tuning has an influence on the harmonic gas excitations and, as a consequence, the torsional and axial vibrations of the installation. Hence, the corresponding calculations have to be carried out with the correct data to be able to apply appropriate countermeasures, if necessary.

Project specification for RT-flex engines:

Although Delta Tuning is realised in such a way that it could almost be considered a pushbutton option, its selection as well as the selection of LLT also have an effect on other aspects of engine and system design.

Therefore the tuning option to be applied on RT-flex engines needs to be specified at a very early stage in the project:

- The calculations of the torsional and axial vibrations of the installation have to be performed using the correct data.
- The layout of the ancillary systems has to be based on the correct specifications.
- To prepare the software for the RT-flex system control, the parameters also have to be known in due time before commissioning of the engine.

Data for brake specific fuel consumption (BSFC) in section *Primary engine data* refer to Standard Tuning. Data for Delta Tuning and Low-Load Tuning can be obtained from the *winGTD and netGTD*.

1.3 Main features and parameters:

Bore 400 mm
Stroke 1,770 mm
Number of cylinders 5 to 8
<u>Main parameters (R1):</u>
Power (MCR) 1,135 kW/cyl
Speed (MCR) 146 rpm
Mean effect. press 21.0 bar
Mean piston speed 8.6 m/s

1.3.1 Design features:

- Welded bedplate with integrated thrust bearings and main bearings designed as large thin-shell white metal bearings
- Sturdy engine structure with stiff thin-wall box type columns and cast iron cylinder blocks attached to the bedplate by pre-tensioned vertical tie rods
- Welded bedplate with integrated thrust bearings and main bearings designed as large thin-shell white metal bearings
- Semi-built crankshaft
- Main bearing jack bolts for easier assembly and disassembly of white metal shell bearings
- Thin-shell white metal bottom-end bearings
- Crosshead with crosshead pin and single-piece large white-metal surface bearings lubricated by the engine lubricating system
- Rigid cast iron cylinder monoblock
- Special grey-cast iron cylinder liners, water cooled, and with load dependent cylinder lubrication
- Cylinder cover of high-grade material with a bolted exhaust valve cage containing a Nimonic 80A exhaust valve
- Piston with crown cooled by combined jetshaker oil cooling
- Constant-pressure turbocharging system comprising high-efficiency turbochargers and auxiliary blowers for low-load operation
- Latest piston running concept for excellent piston running and extended TBO up to 5 years
- Pulse Lubricating System for high-efficiency cylinder lubrication
- Supply unit: high-efficiency fuel pumps feeding the 1000 bar fuel manifold
- Rail unit (common rail): both common rail injection and exhaust valve actuation are controlled by quick acting solenoid valves
- Electronic engine control UNIC for monitoring and controlling the key engine functions

The W-X40 is available with 5 to 8 cylinders rated at 1,135 kW/cyl to provide a maximum output of 9,080 kW for the 8-cylinder engine (see section *1.1 Primary engine data*).

	Overall sizes of engines				
No. cyl.	Length [mm]	Piston dismantling height (crank center – crane hook) [mm]	Dry weight [t]		
5	5,107		109		
6	5,807		125		
7	6,507	7,700	140		
8	7,207		153		

Table 1.2: Overall sizes of engine

1.4 The RT-flex system

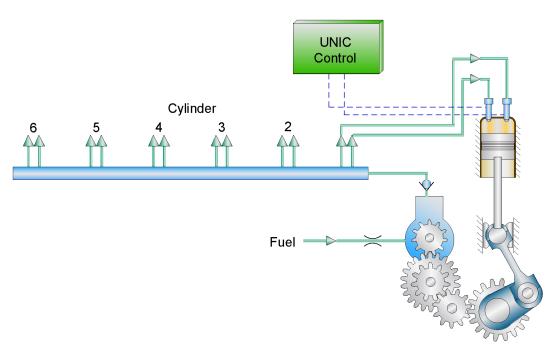


Figure 1.5: RT-flex key parts

All key engine functions such as fuel injection, exhaust valve drives, engine starting and cylinder lubrication are fully under electronic control. The timing of the fuel injection, its volumetric and various injection patterns are regulated and controlled by the UNIC control system.

1.4.1 The major benefits of the RT-flex system are:

- Adaptation to different operating modes
- Adaptation to different fuels
- Optimised part-load operation
- Optimised fuel consumption
- Precise speed regulation, in particular at very slow steaming
- · Smokeless mode for slow steaming
- Benefits in terms of operating costs, maintenance requirement and compliance with emissions regulations

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2. Engine Data

The engine can be operated in the ambient condition range between **reference conditions** and **design (tropical) conditions**.

2.1 Reference conditions

The engine performance data, like **BSFC**, **BSEF**, **tEaT** and others, are based on **reference conditions**. They are specified in ISO Standard 15550 (core standard) and for marine application in ISO Standard 3046 (satellite standard) as follows:

Air temperature before blower	25°C
Engine room ambient air temp	25°C
Coolant temp. before SAC	29°C for FW
Barometric pressure	1000 mbar
Relative air humidity	30%

2.2 Design conditions

The capacities of ancillaries are specified according to ISO Standard 3046-1 (clause 11.4) following the International Association of Classification Societies (IACS) and are defined as **design conditions**:

Air temperature before blower	45°C
Engine room ambient air temp	45°C
Coolant temp. before SAC	36°C for FW
Barometric pressure	1000 mbar
Relative air humidity	60%

2.3 Ancillary system design parameters

The layout of the ancillary systems of the engine is based on the rated performance (rating point Rx, CMCR). The given design parameters must be considered in the plant design to ensure a proper function of the engine and its ancillary systems.

Cylinder water outlet temp	85°C
Oil temperature before engine	45°C
Exhaust gas back pressure at rated power (Rx)	30 mbar

The engine power is independent of ambient conditions. The cylinder water outlet temperature and the oil temperature before engine are system-internally controlled and have to remain at the specified level.

2.4 Engine performance data

The calculation of the performance data **BSFC**, **BSEF** and **tEaT** for any engine power is done with the help of the *winGTD* and *netGTD*. Data for Delta Tuning and Low-Load Tuning are available on the *winGTD* and *netGTD*. If needed we offer a computerized information service to analyze the engine's heat balance and determine main system data for any rating point within the engine layout field.

2.5 Turbocharger and scavenge air cooler

The SAC and TC selection is given in *winGTD and netGTD*. Parameters and details of the scavenge air coolers are shown in section 2.5.1.

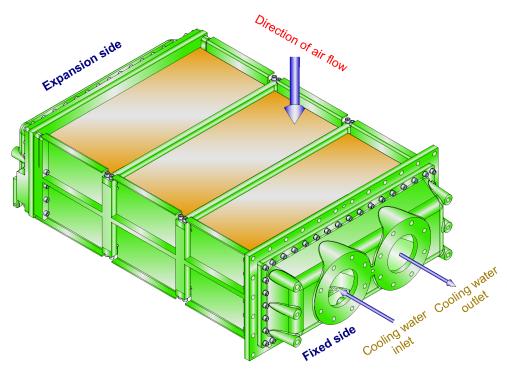


Figure 2.1: Scavenge air cooler

2.5.1 SAC parameters and turbocharger weights

SAC parameters and turbocharger weights

				Scaveng	e air cooler	parameter	S		
	Cooler	04.	Desig	n flow	Pressu (at desig		Water	Insert	
No. cyl.		Qty	Water [kg/s]	Air [kg/s]	Water [bar]	Air [Pa]	content [litres]	Dimension [mm]	Mass [kg]
			Fre	sh water co	oled / single	e-stage SA	C / separate	HT	
5	SAC283F	1	43.1	15.6	1.0	2,000	110	1420 x 1135 x 370	740
6	SAC283F	1	43.1	15.6	1.0	2,000	110	1420 x 1135 x 370	740
7	SAC285F	1	43.1	20.3	1.0	2,000	145	1820 x 1135 x 370	950
8	SAC285F	1	43.1	20.3	1.0	2,000	145	1820 x 1135 x 370	950

Table 2.1: Scavenge air cooler parameters

		AB	В	МНІ			
No. cyl.	Туре	Qty	Mass [kg]	Туре	Qty	Mass [kg]	
5	A165-L34	1	2,000	MET42MB	1	1,600	
6	A165-L35	1	2,000	MET53MB	1	4,100	
7	A170-L34	1	3,000	MET53MB	1	4,100	
8	A170-L35	1	3,000	MET53MB	1	4,100	

Table 2.2: Turbocharger weights

2.5.2 Air filtration

In the event that the air supply to the machinery spaces has a dust content exceeding 0.5 mg/m³, which can be the case for ships trading in coastal waters, desert areas or transporting dust creating cargoes, there is a risk of increased wear to the piston rings and cylinder liners. The normal air filters fitted to the turbochargers are intended mainly as silencers but not to protect the engine against dust.

The necessity for installing a dust filter and the choice of filter type depends mainly on the concentration and composition of the dust in the suction air. Where the suction air is expected to have a dust content of 0.5 mg/m³ or more, the engine must be protected by filtering this air before entering the engine, e.g. on coastal vessels or vessels frequenting ports having high atmospheric dust or sand content.

Wärtsilä Switzerland Ltd. advises to install a filtration unit for the air supplies to the diesel engines and general machinery spaces on vessels regularly transporting dust creating cargoes, such as iron ore and bauxite.

	Atmospheric dust concentration						
Normal	Normal shipboard requirement	Alternatives necessary in very special circumstances					
Most frequent particle sizes	Short period $< 5\%$ of running time, $< 0.5 \text{ mg/m}^3$	frequently to permanently $\geq 0.5 \text{ mg/m}^3$	permanently > 0.5 mg/m ³				
> 5 µm	Standard TC filter sufficient	Oil wetted or roller screen filter	Inertial separator and oil wetted filter				
< 5 µm	Standard TC filter sufficient	Oil wetted or panel filter	Inertial separator and oil wetted filter				
Valid for the vast majority of installations E.		These may apply in only very few, extreme cases. E.g.: ships carrying bauxite or similar dusty cargoes, or ships routinely trading along desert coasts.					

Table 2.3: Guidance for air filtration

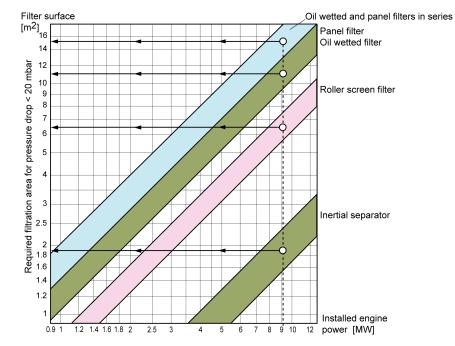


Figure 2.2: Air filter size (example for 8-cyl. engine)

2.6 Auxiliary blower

For manoeuvring and operating at low powers, electrically driven auxiliary blowers must be used to provide sufficient combustion air.

The following table shows the number of blowers required.

Number of cylinders	Number of required auxiliary air blowers
5	2
6	2
7	2
8	2

Table 2.4: Number of auxiliary blowers

2.7 Electrical power requirement

	No. cyl.	Supply voltage	Power requirement				
Auxiliary blowers *1)	5		2 x 20 kW (60 Hz)				
	6	440.14	2 x 20 kW (60 Hz)				
	7	440 V	2 x 26 kW (60 Hz)				
	8		2 x 26 kW (60 Hz)				
Turning gear	5		1.8				
	6	440.14	1.8				
	7	440 V	1.8				
	8		1.8				
Propulsion control system		24 VDC UPS	acc. to maker's specifications				
dditional monitoring devices (e.g. oil mist etector, etc.)		acc. to maker's specifications					

Table 2.5: Electrical power requirement

NOTICE

^{*1)} Minimal electric motor power (shaft) is indicated. The *actual* electric power requirement depends on the size, type and voltage/frequency of the installed electric motor. Direct starting or Star-Delta starting to be specified when ordering.

2.8 Pressure and temperatures ranges

The following table represents a summary of the required pressure and temperature ranges at continuous service rating (CSR). The gauge pressures are measured about (tbd) above the crankshaft centre line. The pump delivery head is obtained by adding the pressure losses in piping system, filters, coolers, valves, etc. and the vertical level pressure difference between pump suction and pressure gauge to the values in the table.

System	Location of measurement	Gauge pressure limit values [bar]		Temperature limit values [°C]		
		Min.	Max.	Min.	Max.	Diff.
Freshwater						
Cylinder cooling	Inlet	2.0	4.0	65	-	may 15
	Outlet each cyl.	-	-	80	90	max. 15
	Inlet cooler	2.0	4.0	25	36	*1)
SAC LT circuit (single-stage SAC)	Outlet cooler	-	-	-	80	')
Fuel oil						
Booster (injection pump)	Inlet	7.0 *2)	10.0 ^{*3)}	-	150	-
After pressure retaining valve	Return	3.0	5.0	-	-	-
Scavenge air						
Intake from engine room (pressure drop, max)	Air filter / silencer	max. 10 mbar		-	-	-
Intake from outside (pressure drop, max)	Ducting and filter	max. 20 mbar		-	-	-
	New SAC	max. 30 mbar		-	-	-
Cooling (pressure drop)	Fouled SAC	max. 50 mbar		-	-	-
Lubricating oil	1	1		1		
Servo oil	Servo oil pump inlet	3.8	4.8	-	-	-
NA - 1	Supply	3.8	4.8	40	50	
Main bearing oil	Outlet	-	-	-	-	-
	Inlet	3.8	4.8	40	50	max. 30
Piston cooling oil	Outlet	-	-	-	80	
Thrust bearing pads	Pads AHEAD	-	-	-	75	-
Torsional vibration damper (in case of steel spring	Supply	3.8	4.8	-	-	-
damper)	Inlet casing	1.0	-	-	-	-
	Supply	3.8	4.8	-	-	-
Integrated axial vibration damper (detuner)	Damp. chamber	1.7	-	-	-	-
TC bearing oil (on engine lub. oil system)	Inlet	1.0	2.5	-	-	-
ABB A100-L	Outlet	-	-	-	110	-
TC bearing oil (with separate lub. oil system)	Inlet	1.3	2.5		85	
ABB A100-L	Outlet	-	-		130	
TC bearing oil	Inlet	0.7	1.5	-	-	-
MHI MET MB	Outlet	-	-	-	85	-

System	Location of measurement	Gauge pressure limit values [bar]		Temperature limit values [°C]		
		Min.	Max.	Min.	Max.	Diff.
Air						
Starting air	Engine inlet	12	25/30	-	-	-
Control air	Engine inlet (engine internal)	6.0	7.5			
		norm	-	-	-	
Air spring air for exh. valve	Main distributor (engine internal)	6.0	7.5			
		normal 6.5		_	-	-
Exhaust gas						
Receiver	After each cylinder	-	-	-	515	Dev. <u>+</u> 50 *4)
	Before each TC	-	-	-	515	-
Manifold after turbocharger	Design maximum	30 mbar		-	-	-
	Fouled maximum	50 mbar			-	-

Table 2.6: Pressure and temperature ranges

NOTICE

^{*1)} The water flow has to be within the prescribed limits.

^{*2)} At 100% engine power.

^{*3)} In stand-by condition; during commissioning of the fuel oil system the fuel oil pressure is adjusted to 10 bar.

^{*4)} Maximum temperature deviation among the cylinders.

Servo oil pump inlet: the minimum pressure can be 0.8 bar lower than indicated due to the specified maximum allowable pressure difference over fine filter.

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3. Engine Rating and Load Range

Selecting a suitable main engine to meet the power demands of a given project involves proper tuning in respect of load range and influence of operating conditions which are likely to prevail throughout the entire life of the ship. This chapter explains the main principles in selecting a Wärtsilä 2-stroke marine diesel engine.

Every engine has a rating field within which the combination of power and speed (= rating) can be selected. Contrary to the 'rating field', the 'load range' is the admissible area of operation once the contract maximum continuous rating (CMCR) has been determined. To define the CMCR, various parameters need to be considered, such as propulsive power, propeller efficiency, operational flexibility, power and speed margins, possibility of a main-engine driven generator, and the ship's trading patterns. Selecting the most suitable engine is vital to achieving an efficient cost/benefit response to a specific transport requirement.

3.1 Rating field

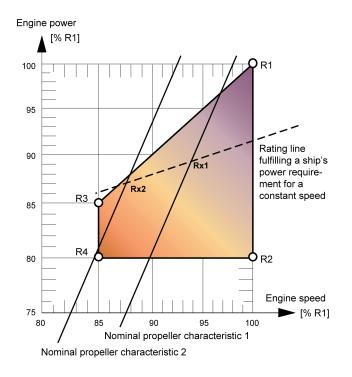


Figure 3.1: Rating field

The rating field shown in fig. 3.1 is the area of power and engine speed. In this area the contract maximum continuous rating of an engine can be positioned individually to give the wanted combination of propulsive power and rotational speed. Engines within this rating field will be tuned for maximum firing pressure and best efficiency. Experience over the last years has shown that engines are ordered with CMCR-points in the upper part of the rating field only.

The engine speed is given on the horizontal axis and the engine power on the vertical axis of the rating field. Both are expressed as a percentage [%] of the respective engine's nominal R1 parameters.

Percentage values are being used so that the same diagram can be applied to various engine models. The scales are logarithmic so that exponential curves, such as propeller characteristics (cubic power) and mean effective pressure (mep) curves (first power), are straight lines.

The rating field serves to determine the specific fuel oil consumption, exhaust gas flow and temperature, fuel injection parameters, turbocharger and scavenge air cooler specifications for a given engine.

Calculations for specific fuel consumption, exhaust gas flow and temperature after turbine are explained in further chapters.

- The rating points (R1, R2, R3 and R4) are the corner points of the engine rating field.
- The point R1 represents the nominal maximum continuous rating (MCR). It is the maximum power/speed combination which is available for a particular engine.
- The point R2 defines 100% speed and 80% power of R1.
- The point R3 defines 85% speed and 85% power of R1.
- The connection R1 R3 is the nominal 100% line of the constant mean effective pressure of R1.
- The point R4 defines 85% speed and 80% power of R1.
- The connection line R2-R4 is the line of 80% power between 85% and 100% speed of R1.
- Rating points Rx can be selected within the entire rating field to meet the requirements of each particular project. Such rating points require specific engine adaptations.

3.1.1 Influence of propeller revolutions on the power requirement

At constant ship speed and for a given propeller type, lower propeller revolutions combined with a larger propeller diameter increase the total propulsive efficiency. Less power is needed to propel the vessel at a given speed.

The relative change of required power in function of the propeller revolutions can be approximated by the following relation: $Px_2/Px_1 = (N_2/N_1)^{\alpha}$.

 $(Px_j = Propulsive power at propeller revolution N_j, N_j = Propeller speed corresponding with propulsive power Px_j)$

- 0.15 for tankers and general cargo ships up to 10,000 dwt
- 0.20 for tankers and bulk carriers from 10,000 dwt to 30,000 dwt
- $\alpha = 0.25$ for tankers and bulk carriers larger than 30,000 dwt

0.17 for reefers and container ships up to 3000 TEU

0.22 for container ships larger than 3000 TEU

This relation is used in the engine selection procedure to compare different engine alternatives and to select optimum propeller revolutions within the chosen engine rating field. Usually, the selected revolution depends on the maximum permissible propeller diameter.

The maximum propeller diameter is often determined by operational requirements such as:

- Design draught and ballast draught limitations
- Class recommendations concerning propeller/hull clearance (pressure impulse induced on the hull by the propeller)

The selection of a main engine in combination with the optimum propeller (efficiency) is an iterative procedure where also commercial considerations (engine and propeller prices) play a great role.

According to the above approximation, when a required power/speed combination is known - for example point Rx1 - a CMCR-line can be drawn which fulfils the ship's power requirement for a constant speed. The slope of this line depends on the ship's characteristics (coefficient α). Any other point on this line represents a new power/speed combination, for example Rx2, and requires a specific propeller adaptation.

3.2 Load range

The load range diagram shown in figure 3.2 defines the power/speed limits for the operation of the engine. Percentage values are given as explained in section 3.1; in practice absolute figures might be used for a specific installation project.

3.2.1 Propeller curves

To establish the proper location of propeller curves, it is necessary to know the ship's speed to power response. The propeller curve without sea margin (see 3.2.3) is, for a ship with a new and clean hull in calm water and weather, often referred to as 'trial condition'.

The curves can be determined by using full-scale trial results from similar ships, algorithms developed by maritime research institutes, or model tank results. Furthermore, it is necessary to define the maximum reasonable diameter of the propeller which can be fitted to the ship. With this information and by applying propeller series such as the 'Wageningen', 'SSPA' (Swedish Maritime Research Association), 'MAU' (Modified AU), etc., the power/speed relationships can be established and characteristics developed.

The relation between absorbed power and rotational speed for a fixed-pitch propeller can be approximated by the following cubic relation: $P_{i}(\mathbf{P}_{i} = (\mathbf{N}_{i}) \mathbf{N}_{i})$ (in which P_{i} = propeller power N = propeller apped)

 $P_2/P_1 = (N_2/N_1)^3$ (in which $P_i = propeller power, N_i = propeller speed)$

The propeller curve without sea margin is often called the 'light running curve'. The nominal characteristic is a cubic curve through the CMCR-point. (For additional information, refer to section *3.2.4*).

3.2.2 Sea trial power

The sea trial power must be specified. Figure 3.2 shows the sea trial power to be the power required for point B on the propeller curve. Often and alternatively, the power required for point A on the curve is referred to as 'sea trial power'.

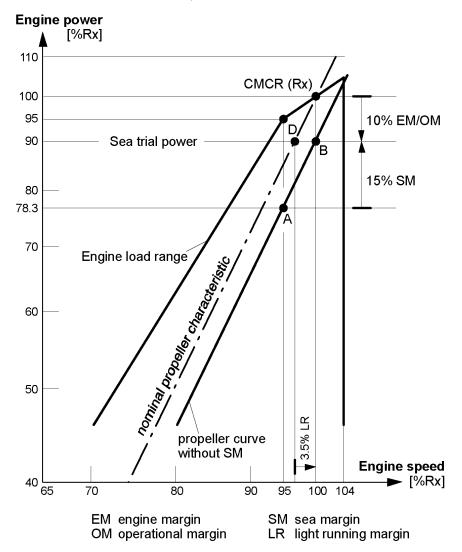


Figure 3.2: Load range limits of an engine corresponding to a specific rating point Rx

3.2.3 Sea margin (SM)

The increase in power to maintain a given ship's speed achieved in calm weather (point A in figure *3.2*) and under average service condition (point D) is defined as the 'sea margin'. This margin can vary depending on owner's and charterer's expectations, routes, season and schedules of the ship. The location of the reference point A and the magnitude of the sea margin are determined between the shipbuilder and the owner. They are part of the new building contract.

With the help of effective antifouling paints, dry-docking intervals have been prolonged to 4 or 5 years. Therefore, it is still realistic to provide an average sea margin of about 15% of the sea trial power (refer to Fig. *3.2*), unless, as mentioned above, the actual ship type and service route dictate otherwise.

3.2.4 Light running margin (LR)

The sea trial performance (curve 'a') in figure 3.3 should allow for a 4-7% light running of the propeller when compared to the nominal characteristic (the example in figure 3.3 shows a light running margin of 5%).

This margin provides a sufficient torque reserve whenever full power must be attained under unfavourable conditions.

Normally, the propeller is hydrodynamically optimised for a point 'B'. The trial speed found for 'A' is equal to the service speed at 'D' stipulated in the contract at 90% of CMCR.

The recommended light running margin originates from past experience. It varies with specific ship designs, speeds, dry-docking intervals, and trade routes.

NOTICE

It is the shipbuilder's responsibility to determine the light running margin large enough so that, at all service conditions, the load range limits on the left side of the nominal propeller characteristic line are not reached (see section 3.2.6 and Fig. 3.4).

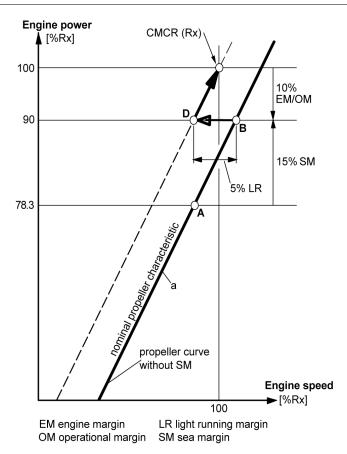


Figure 3.3: Load diagram for a specific engine, showing the corresponding power and speed margins

Assuming, for example, the following:

- Dry-docking intervals of the ship: 5 years
- Time between overhauls of the engine: 2 years or more
- Full service speed must be attainable, without surpassing the torque limit, under less favorable conditions and without exceeding 100% mep

Therefore the required 'light running margin' will be between 5 and 6%.

This is the sum of the following factors:

- **1.5-2%** influence of wind and weather with adverse effect on the intake water flow of the propeller. Difference between Beaufort 2, sea trial condition, and Beaufort 4-5, average service condition. For vessels with a pronounced wind sensitivity, i.e. containerships or car carriers, this value will be exceeded.
- 1.5-2% increase of ship's resistance and mean effective wake brought about by:
 - Rippling of hull (frame to frame)
 - Fouling of local, damaged areas, i.e. boot top and bottom of the hull
 - Formation of roughness under paint
 - Influence on wake formation due to small changes in trim and immersion of bulbous bow, particularly in ballast condition
- **1**% frictional losses due to increase in propeller blade roughness and consequent drop in efficiency, e.g. aluminium bronze propellers:
 - New: surface roughness = 12 micron
 - Aged: rough surface but no fouling = 40 micron
 - **1%** deterioration in engine efficiency such as:
 - Fouling of scavenge air coolers
 - Fouling of turbochargers
 - Condition of piston rings
 - Fuel injection system (condition and timing)
 - Increase of back pressure due to fouling of the exhaust gas boiler, etc.

3.2.5 Engine margin (EM) or operational margin (OM)

Most owners specify the contractual ship's loaded service speed at 85 to 90% of the contract maximum continuous rating. The remaining 10-15% power can then be used to catch up with delays in schedule or for the timing of dry-docking intervals. This margin is usually deducted from the CMCR. Therefore, the 100% power line is found by dividing the power at point D by 0.85-0.90. The graphic approach to find the level of CMCR is illustrated in figures *3.2* and *3.3*.

In the examples two current methods are shown. Figure *3.2* presents the method of fixing point B and CMCR at 100% speed, thus obtaining automatically a light running margin B-D of 3.5%. Figures *3.3* and *3.5* show the method of plotting the light running margin from point B to point D or D' (in our example 5%) and then along the nominal propeller characteristic to obtain the CMCR-point. In the examples, the engine power at point B was chosen to be at 90% and 85% respectively.

Continuous service rating (CSR=NOR=NCR)

Point A represents power and speed of a ship operating at contractual speed in calm seas with a new clean hull and propeller. On the other hand, the same ship at same speed under service condition with aged hull and average weather requires a power/speed combination according to point D, as shown in figure *3.4*. In that case D is the CSR-point.

Contract maximum continuous rating (CMCR = Rx)

By dividing, in our example, the CSR (point D) by 0.90, the 100% power level is obtained and an operational margin of 10% is provided (see Fig. *3.4*). The found point Rx, also designated as CMCR, can be selected freely within the rating field defined by the four corner points R1, R2, R3 and R4 (see the figure in section *3.1*).

3.2.6 Load range limits

Once an engine is optimised at CMCR (Rx), the working range of the engine is limited by the following border lines; refer to Fig. *3.4*:

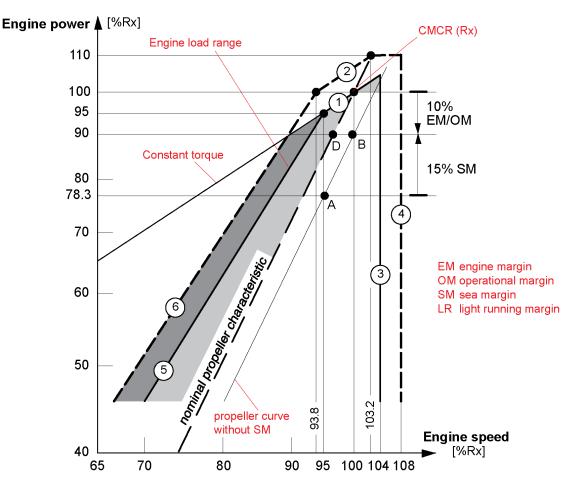


Figure 3.4: Load range limits with load diagram of an engine corresponding to a specific rating point Rx

- Line **1** is a constant mep or torque line through CMCR from 100% speed and power down to 95% power and speed.
- Line **2** is the overload limit. It is a constant mep line reaching from 100% power and 93.8% speed to 110% power and 103.2% speed. The latter one is the point of intersection between the nominal propeller characteristic and 110% power.
- Line 3 is the 104% speed limit where an engine can run continuously. For Rx with reduced speed $(N_{CMCR} \le 0.98 N_{MCR})$ this limit can be extended to 106%, however, the specified torsional vibration limits must not be exceeded.
- Line 4 is the overspeed limit. The overspeed range between 104 (106) and 108% speed is only permissible during sea trials if needed to demonstrate, in the presence of authorised representatives of the engine builder, the ship's speed at CMCR power with a light running propeller. However, the specified torsional vibration limits must not be exceeded.
- Line 5 represents the admissible torque limit and reaches from 95% power and speed to 45% power and 70% speed. This represents a curve defined by the equation: $P_2/P_1 = (N_2/N_1)^{2.45}$. When approaching line 5, the engine will increasingly suffer from lack of scavenge air and its consequences. The area formed by lines 1, 3 and 5 represents the range within which the engine should be operated. The area limited by the nominal propeller characteristic, 100% power and line 3 is recommended for continuous operation. The area between the nominal propeller characteristic and line 5 has to be reserved for acceleration, shallow water and normal operational flexibility.

Line 6

6 is defined by the equation: $P_2/P_1 = (N_2/N_1)^{2.45}$ through 100% power and 93.8% speed and is the maximum torgue limit in transient conditions.

The area above line **1** is the overload range. It is only allowed to operate engines in that range for a maximum duration of one hour during sea trials in the presence of authorized representatives of the engine builder.

The area between lines **5** and **6** and constant torque line (dark area of Fig. 3.4) should only be used for transient conditions, i.e. during fast acceleration. This range is called 'service range with operational time limit'.

3.2.7 Load range with main-engine driven generator

The load range with main-engine driven generator, whether it is a shaft generator (S/G) mounted on the intermediate shaft or driven through a power take-off gear (PTO), is shown by curve 'c' in figure 3.5. This curve is not parallel to the propeller characteristic without main-engine driven generator, due to the addition of a constant generator power over most of the engine load. In the example of figure 3.5, the main-engine driven generator is assumed to absorb 5% of the nominal engine power.

The CMCR-point is, of course, selected by taking into account the maximum power of the generator.

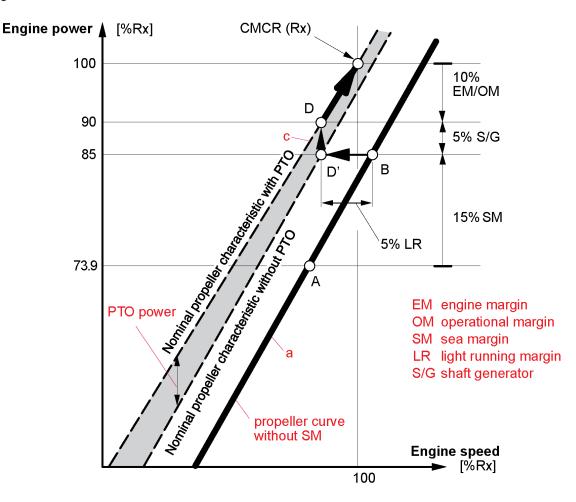


Figure 3.5: Load range diagram of an engine equipped with a main-engine driven generator

3.3 Load range limit with controllable pitch propeller

frequency.

For the controllable pitch propeller (CPP) load range limit consult winGTD and netGTD.

After starting, the engine is operated at an idle speed of up to 70% of the rated engine speed with zero pitch. From idle running the pitch is to be increased with constant engine speed up to at least point E, the intersection with line 6.

Line **5** is the upper load limit and corresponds to the admissible torque limit as defined in section *3.2.1* and shown in figure *3.2*. The area formed between **70%** speed and **100%** speed and between lines **5** and **6** rep

The area formed between 70% speed and 100% speed and between lines 5 and 6 represents the area within which the engine with CPP has to be operated.

- Line **6** is the lower load limit between 70% speed and 100% speed, with such a pitch position that at 100% speed a minimum power of 37% is reached, point F. It is defined by the following equation: $P_2/P_1 = (N_2/N_1)^3$ Along line **8** the power increase from 37% (point F) to 100% (CMCR) at 100% speed is the constant speed mode for shaft generator operation, covering electrical sea load with constant
- Line 7 represents a typical combinator curve for variable speed mode.

Manoeuvring at nominal speed with low or zero pitch is not allowed. Thus installations with main-engine driven generators must be equipped with a frequency converter when electric power is to be provided (e.g. to thrusters) at a constant frequency during manoeuvring. Alternatively, power from auxiliary engines may be used for this purpose.

For test purposes, the engine may be run at rated speed and low load during a one-time period of 15 minutes on the testbed (e.g. NOx measurements) and 30 minutes during dock trials (e.g. shaft generator adjustment) in the presence of authorized representatives of the engine builder. Further requests must be agreed by Wärtsilä Switzerland Ltd.

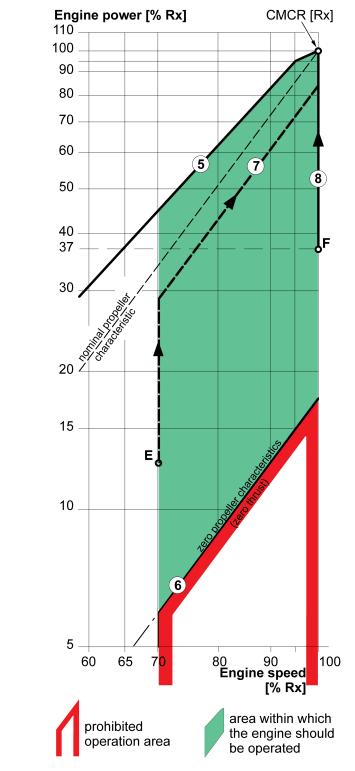


Figure 3.6: Load range diagram for CPP

3.4 Requirements for control system with CPP

Wärtsilä Switzerland Ltd. advises to include CPP control functions in an engine remote control system from an approved supplier. This ensures, amongst others, that the requirements of the engine builder are strictly followed.

The following operating modes shall be included in the control system:

Combinator mode 1

Combinator mode for operation without shaft generator. Any combinator curve including a suitable light running margin may be set within the permissible operating area, typically line **7**.

• Combinator mode 2

Optional mode used in connection with shaft generators. During manoeuvring, the combinator curve follows line **6**. At sea the engine is operated between point F and 100% power (line **8**) at constant speed.

For manual and emergency operation, separate set points for speed and pitch are usually provided. At any location allowing such operation, a warning plate must be placed with the following text:

Engine must not be operated continuously with a pitch lower than xx% at any engine speed above xx rpm.

- The values (xx) are to be defined according to the installation data.
- The rpm value normally corresponds to 70% of CMCR speed, and the pitch to approximately 60% of the pitch required for rated power.
- In addition, an alarm has to be provided in either the main-engine safety system or the vessel's alarm and monitoring system, in case the engine is operated for more than 3 minutes in the prohibited operation area. If the engine is operated for more than 5 minutes in the prohibited operation area, the engine speed must be reduced to idle speed (less than 70% speed).

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4. winGTD and netGTD

The purpose of these programs is to calculate the heat balance of a Wärtsilä two-stroke diesel engine for a given project. Various cooling circuits can be taken in account, temperatures and flow rates can be manipulated online for finding the most suitable cooling system.

This these programs provide the information required for the project work of marine propulsion plants. Its content is subject to the understanding that any data and information herein have been prepared with care and to the best of our knowledge. We do not, however, assume any liability with regard to unforeseen variations in accuracy thereof or for any consequences arising therefrom.

The winGTD is available as download from our Licensee Portal.

- 1 Open the Licensee Portal and go to:
 - 'Project Tools & Documents'
 - 'winGTD'
- 2 Click on the link and follow the instructions

The **netGTD** is accessible on internet using the following address:

http://www.wartsila.com/en/marine-solutions/products/netGTD



The data generated with this program are intended to provide the information required for the layout of marine propulsion plants. Their use is subject to the understanding that any data and information herein have been prepared with care and the best of our knowledge. We do not, however, assume any liability with regard to unforeseen variations in accuracy therof or for any consequences arising therefrom. This page intentionally left blank

5. Engine Dynamics

As a leading designer and licensor we are concerned that vibrations are minimised with our engine installations. The assessment and reduction of vibration is subject to continuing research. Therefore, we have developed extensive computer software, analytical procedures and measuring techniques to deal with this subject.

For successful design, the vibration behaviour needs to be calculated over the whole operating range of the engine and propulsion system. The following vibration types and their causes are to be considered:

- External mass forces and moments
- Lateral engine vibration
- Longitudinal engine vibration
- Torsional vibration of the shafting
- · Axial vibration of the shafting

5.1 External forces and moments

In the design of the engine, free mass forces are eliminated and unbalanced external moments of first, second and fourth order are minimized. However, 5 and 6-cylinder engines generate second order unbalanced vertical moments of a magnitude greater than those encountered with higher numbers of cylinders. Depending on the ship's design, the moments of fourth order have to be considered, too.

Under unfavourable conditions, depending on hull structure, type, distribution of cargo and location of the main engine, the unbalanced moments of first, second and fourth order may cause unacceptable vibrations throughout the ship and thus call for countermeasures. Figure 5.1 shows the external forces and moments acting on the engine. External forces and moments due to the reciprocating and rotating masses see section 5.1.1.

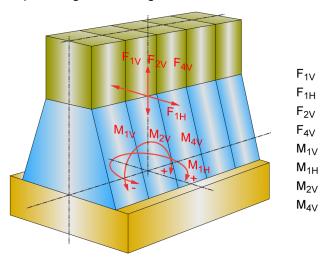


Figure 5.1: External forces and moments

resulting first order vertical force resulting first order horizontal force resulting second order vertical force resulting fourth order vertical force first order vertical mass moment first order horizontal mass moment second order vertical mass moment fourth order vertical mass moment

5.1.1 External forces and moments

				ces at R1 / Standa	_	
Cylinder number Engine Power [kW] / 146 rpm		5	6	7	8	
		5,675	6,810	7,945	9,080	
		F _{1V}	0	0	0	0
Free mass f	forces	F _{1H}	0	0	0	0
[±kN]		F _{2V}	0		0	
F _{4V}		F _{4V}	0	0	0	0
		M _{1V}	55	0	117	111
External ma ments		M _{1H}	48	0	55	96
[±kNm		M _{2V}	613	426	124	0
		M _{4V}	4	30	84	34
		1	0	0	0	0
		2	0	0	0	0
		3	0	0	0	0
		4	0	0	0	0
	Order	5	448	0	0	0
Lateral H- moments		6	0	325	0	0
M _{LH} [±kNm]		7	0	0	249	0
		8	0	0	0	185
		9	0	0	0	0
		10	38	0	0	0
		11	0	0	0	0
		12	0	12	0	0
		1	45	0	27	90
		2	24	16	5	0
		3	55	99	108	138
		4	15	115	327	133
		5	0	0	26	325
Lateral X- moments	Order	6	6	0	4	0
Moments M _{LX} [±kNm]	order	7	45	0	0	8
		8	30	21	2	0
		9	1	27	3	3
		10	0	7	19	0
		11	1	0	11	15
		12	2	0	0	2
Torque vari- ation	[±kľ	Nm]	457	327	251	186

Table 5.1: Mass moments and forces

NOTICE

^{*1)} No engine-fitted 2^{nd} order balancer available. If reduction on M_{2v} is needed, an external 2^{nd} order compensator has to be applied.

- The resulting lateral guide force can be calculated as follows: F_L = M_{LH} x 0.376 [kN].
- The values for other engine ratings and engine tunings are available on request.
- Crankshaft type: FCV1 / full crank pin.

5.1.2 Balancing free first order moments

Standard counterweights fitted to the ends of the crankshaft reduce the first order mass moments to acceptable limits. However, in special cases non-standard counterweights can be used to reduce either M_{1V} or M_{1H} .

5.1.3 Balancing free second order moments

The second order vertical moment (M_{2V}) is higher on 5-cylinder engines compared with 6-8-cylinder engines, the second order vertical moment being negligible for the 6-8-cylinder engines.

Since no engine-fitted second order balancer is available, Wärtsilä Switzerland Ltd. recommends for 5-cylinder engines to install an electrically driven compensator on the ship's structure (Fig. *5.2*) to reduce the effects of second order moments to acceptable values.

If no experience is available from a sister ship, it is advisable to establish at the design stage what kind the ship's vibration will be. Section *5.1.1* assists in determining the effect of installing the 5-cylinder engines. However, when the ship's vibration pattern is not known at an early stage, an external electrically driven compensator can be installed later, should disturbing vibrations occur; provision should be made for this countermeasure. Such a compensator is usually installed in the steering compartment, as shown in figure *5.2.* It is tuned to the engine operating speed and controlled accordingly.

Suppliers of electrically driven compensators

Gersten & Olufsen AS

Savsvinget 4 DK-2970 Hørsholm Denmark Tel. +45 45 76 36 00 Fax +45 45 76 17 79 www.gertsen-olufsen.dk

Fax +81 6 6397 3475

www.nishishiba.co.jp

Nishishiba Electric Co., Ltd

Shin Osaka lida Bldg. 5th Floor 1-5-33, Nishimiyahara, Yodogawa-ku Osaka 532-0004 Japan www.gertsen-olufsen.dk 2nd order compensator

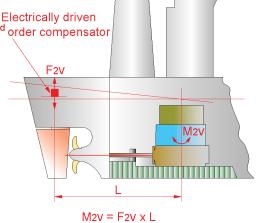


Figure 5.2: Locating electrically driven compensator

5.1.4 Power related unbalance (PRU)

The so-called Power Related Unbalance (PRU) values can be used to evaluate if there is a risk that free external mass moments of first and second order cause unacceptable hull vibrations.

The external mass moments M_1 and M_2 given in section 5.1 are related to R1 speed. For other engine speeds, the corresponding external mass moments are calculated with the following formula:

 $M_{Rx} = M_{R1} x (n_{Rx}/n_{R1})^2$

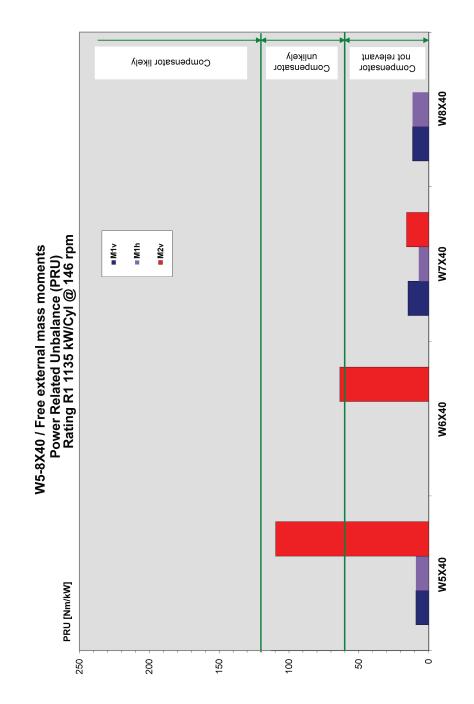


Figure 5.3: Power related unbalance (PRU)

5.2 Lateral engine vibration (rocking)

The lateral components of the forces acting on the crosshead induce lateral rocking, depending on the number of cylinders and firing order. These forces may be transmitted to the engine-room bottom structure. From there hull resonance or local vibrations in the engine room may be excited.

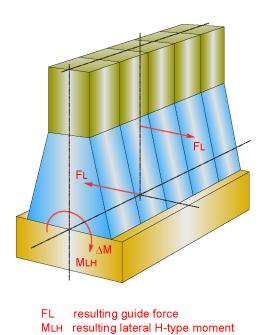
There are two different modes of lateral engine vibration, the so-called 'H-type' and 'X-type'; refer to Fig. *5.4*.

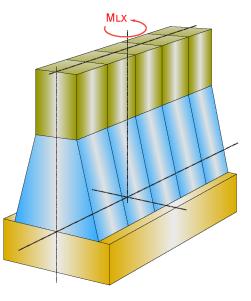
The 'H-type' lateral vibrations are characterized by a deformation where the driving and free end side of the engine top vibrate in phase as a result of the lateral guide force F_L and the lateral H-type moment. The torque variation (ΔM) is the reaction moment to M_{LH} .

The 'X-type' lateral vibrations are caused by the resulting lateral guide force moment M_{LX} . The driving- and free-end side of the engine top vibrate in counterphase.

The table in section 5.1 gives the values of resulting lateral guide forces and moments of the relevant orders.

The amplitudes of the vibrations transmitted to the hull depend on the design of the engine seating, frame stiffness and exhaust pipe connections. As the amplitude of the vibrations cannot be predicted with absolute accuracy, the support to the ship's structure and space for installation of lateral stays should be considered in the early design stages of the engine-room structure.





MLX resulting lateral H-type moment

Figure 5.4: External forces and moments

5.3 Reduction of lateral vibration

5.3.1 Engine stays

Fitting of lateral stays between the upper platform level and the hull reduces transmitted vibration and lateral rocking. Two stay types can be considered:

Hydraulic stays:

Hydraulic stays

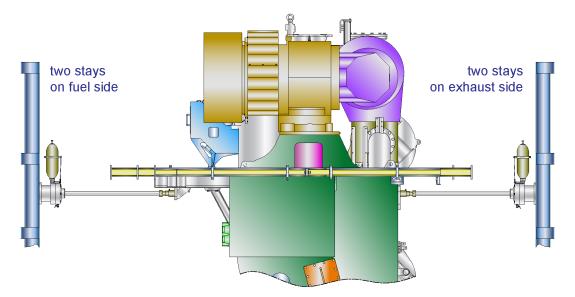
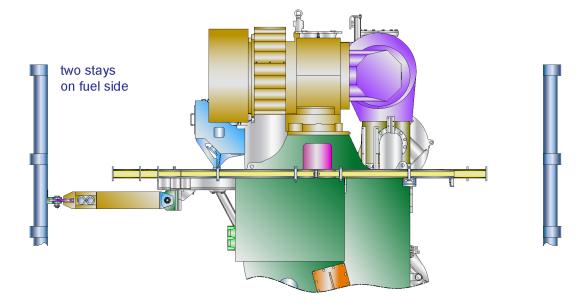


Figure 5.5: General arrangement of lateral stays (hydraulic)

Friction stays:

Friction stays



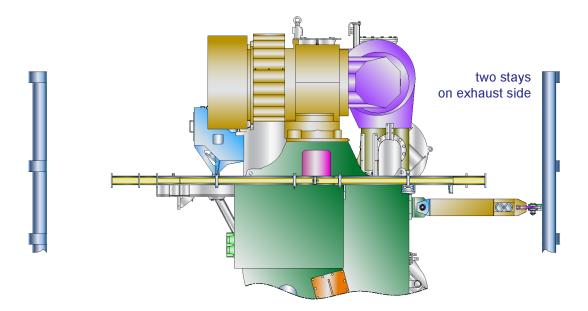


Figure 5.6: General arrangement of lateral stays (friction)

5.3.2 Electrically driven compensator

If for some reason it is not possible to fit lateral stays, an electrically driven compensator can be installed, which reduces the lateral engine vibrations and their effect on the ship's superstructure.

It has to be noted that only one harmonic excitation can be compensated at a time, and in case of an 'X-type' vibration mode, two compensators, one fitted at each end of the engine top, are necessary.

5.4 Longitudinal engine vibration (pitching)

In some cases with 5-cylinder engines, specially those coupled to very stiff intermediate and propeller shafts, the engine foundation can be excited at a frequency close to the full-load speed range resonance, leading to increased axial (longitudinal) vibration at the engine top and as a result of this to vibrations in the ship's superstructure (refer to section *5.6*). To prevent such vibration, the stiffness of the double-bottom structure should be as strong as possible.

5.5 Torsional vibration

Torsional vibrations are generated by gas and inertia forces as well as by the irregularity of the propeller torque. It does not cause hull vibration (except in very rare cases) and is not perceptible in service, but causes additional dynamic stresses in the shafting.

The shafting system comprising crankshaft, propulsion shafting, propeller, engine running gear, flexible couplings and power take-off (PTO), as any system capable of vibrating, has resonant frequencies.

If any source generates excitation at resonant frequencies, the torsional loads in the system reach maximum values. These torsional loads have to be limited, if possible by design, e.g. optimizing shaft diameters and flywheel inertia. If the resonance still remains dangerous, its frequency range (critical speed) has to be passed through rapidly (barred speed range), provided that the corresponding limits for this transient condition are not exceeded, otherwise other appropriate countermeasures have to be taken.

The amplitudes and frequencies of torsional vibration must be calculated at the design stage for every engine installation. The calculation normally requires approval by the relevant classification society and may require verification by measurement on board ship during sea trials. All data required for torsional vibration calculations should be made available to the engine supplier at an early design stage (see section *5.10*).

5.5.1 Reduction of torsional vibration

Excessive torsional vibration can be reduced, shifted or even avoided by installing a heavy flywheel at the driving end and/or a tuning wheel at the free end, or a torsional vibration damper at the free end of the crankshaft. Such dampers reduce the level of torsional stresses by absorbing part of the energy. Where low energy torsional vibrations have to be reduced, a viscous damper can be installed; refer to Fig. 5.7. In some cases the torsional vibration calculation shows that an additional oil-spray cooling for the viscous damper is needed. In such cases the layout has to be in accordance with the recommendations of the damper manufacturer and our design department.

For high energy vibrations, e.g. for higher additional torque levels that can occur with 5 and 6-cylinder engines, a spring damper with its higher damping effect may have to be considered; refer to Fig. *5.8*. This damper has to be supplied with oil from the engine's lubricating oil system. Depending on the torsional vibration energy to be absorbed, it can dissipate up to 30 kW energy (depends on number of cylinders).

The oil flow to the damper should be 5 to 8 m^3/h , but an accurate value will be given after the results of the torsional vibration calculation are known.

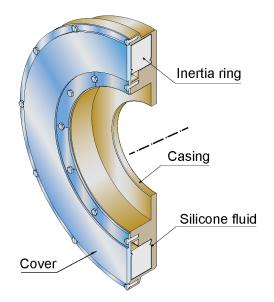


Figure 5.7: Vibration damper (viscous type)

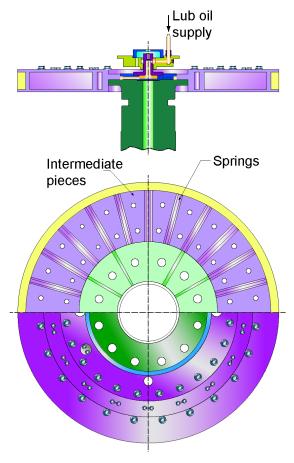


Figure 5.8: Vibration damper (Geislinger type)

5.6 Axial vibration

The shafting system, formed by the crankshaft and propulsion shafting, can vibrate in axial direction, the basic principle being the same as described in section 5.5. The system, made up of masses and elasticities, will feature several resonant frequencies. These will result in axial vibration causing excessive stresses in the crankshaft, if no countermeasures are taken. Strong axial vibration of the shafting can also lead to excessive axial (or longitudinal) vibration of the engine, particularly at its upper part.

The axial vibrations of installations mainly depend on the dynamical axial system of the crankshaft, the mass of the torsional damper, free-end gear (if any) and flywheel fitted to the crankshaft. Additionally, axial vibrations can be considerably influenced by torsional vibrations. This influence is called 'coupling effect of torsional vibrations'.

It is recommended to carry out axial vibration calculations at the same time as the torsional vibration calculation. To consider the coupling effect of the torsional vibrations on the axial vibrations, it is necessary to use a suitable coupled axial vibration calculation method.

5.6.1 Reduction of axial vibration

To limit the influence of axial excitations and reduce the level of vibration, the standard W-X40 engine is equipped with an integrated axial damper mounted at the free end of the crankshaft.

The axial damper reduces the axial vibrations in the crankshaft to acceptable values. No excessive axial vibrations should then occur, neither in the crankshaft, nor in the upper part of the engine.

The integrated axial damper does not affect the external dimensions of the engine. It is connected to the main lubricating oil circuit.

An integrated monitoring system continuously checks the correct operation of the axial damper.

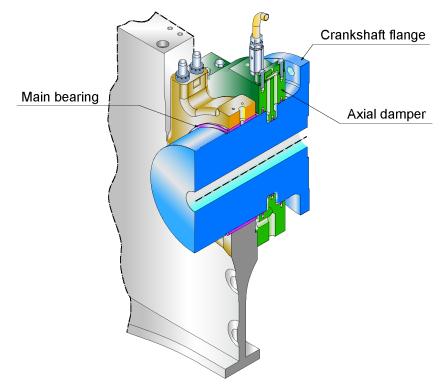


Figure 5.9: Example of an axial damper (detuner)

5.7 Hull vibration

The hull and accommodation area are susceptible to vibration caused by the propeller, machinery and sea conditions. Controlling hull vibration is achieved by a number of different means and may require fitting mass moment compensators, lateral stays, torsional damper and axial damper. Avoiding disturbing hull vibration requires a close cooperation between the propeller manufacturer, naval architect, shipyard and engine builder. To enable Wärtsilä Switzerland Ltd. to provide the most accurate information and advice on protecting the installation and vessel from the effects of plant vibration, complete the order forms as given in section *5.10* and send it to the address given.

5.8 Summary of countermeasures for dynamic effects

The following table indicates where special attention is to be given to dynamic effects and the countermeasures required to reduce them. Where installations incorporate PTO arrangements, further investigation is required, and Wärtsilä Switzerland Ltd. should be contacted.

5.8.1 External mass moments

No. cyl.	2 nd order compensator			
5	alancing countermeasure is unlikely to be needed 1)			
6	alancing countermeasure is unlikely to be needed 1)			
7	Balancing countermeasure is not relevant			
8	Balancing countermeasure is not relevant			
Table 5.2: Countermonourse for external mass memorie				

Table 5.2: Countermeasures for external mass moments

NOTICE

1) No engine-fitted 2^{nd} order balancer available. If reduction on M_{2v} is needed, an external 2^{nd} order compensator has to be applied.

5.8.2 Lateral and longitudinal rocking

No. cyl.	Lateral stays	Longitudinal stays
5	A	В
6	В	С
7	В	С
8	А	С

Table 5.3: Countermeasures for lateral and longitudinal rocking

NOTICE

A: The countermeasure indicated is needed.

B: The countermeasure indicated may be needed and provision for the corresponding countermeasure is recommended.

C: The countermeasure indicated is not needed.

5.8.3 Torsional and axial vibrations

No. cyl.	Torsional vibrations	Axial vibrations
5 to 8	Detailed calculations have to be carried out for every in- stallation, countermeasures to be selected accordingly (shaft diameters, critical or barred speed range, flywheel, tuning wheel, TV damper).	the axial vibration in the crankshaft. However, the effect

Table 5.4: Countermeasures for torsional and axial vibration

5.9 System dynamics

A modern propulsion plant may include a main-engine driven generator. This element is connected by clutches, gears, shafts and elastic couplings. Under transient conditions heavy perturbations, due to changing the operating point, loading or unloading generators, engaging or disengaging a clutch, cause instantaneous dynamic behaviour which weakens after a certain time (or is transient). Usually the transfer from one operating point to another is monitored by a control system to allow the plant to adapt safely and rapidly to the new operating point (engine speed control).

Simulation is an opportune method for analysing the dynamic behaviour of a system subject to heavy perturbations or transient conditions. Mathematical models of several system components such as clutches and couplings have been determined and programmed as library blocks to be used with a simulation program. This program allows to check, for example, if an elastic coupling will be overloaded during engine start, or to optimize a clutch coupling characteristic (engine speed before clutching, slipping time, etc.), or to adjust the speed control parameters.

This kind of study should be requested at an early stage of the project if some special specification regarding speed deviation and recovery time, or any special speed and load setting programs have to be fulfilled.

Wärtsilä Switzerland Ltd. would like to assist if you have any questions or problems relating to the dynamics of the engine. Please describe the situation and send or fax the completed relevant order form given in the next section 5.10. We will provide an answer as soon as possible.

5.10 Order forms for vibration calculations and simulation

For system dynamics and vibration analysis the following forms are available on the Licensee Portal. They can be filled in and submitted directly to Wärtsilä Switzerland Ltd.

Marine installation: Torsional Vibration Calculation	
Testbed installation: Torsional Vibration Calculation	PDF available on request
Marine installation: Coupled Axial Vibration Calculation	
Marine installation: Whirling/Bending Vibration Calculation	

If you have no access to the Licensee Portal, order these forms from Wärtsilä Switzerland Ltd. Send a PDF or fax a copy of the completed relevant forms to the following address:

Wärtsilä Switzerland Ltd. Dept. 10189 'Engine and System Dynamics' Zürcherstrasse 12 PO Box 414 CH-8401 Winterthur eMail: dynamics.ch@wartsila.com Fax: +41-52-262 07 25

6. Auxiliary Power Generation

This chapter covers a number of auxiliary power arrangements for consideration. However, if your requirements are not fulfilled, contact our representative or consult **Wärtsilä Switzerland Ltd.** directly. Our aim is to provide flexibility in power management, reduce overall fuel consumption and maintain uni-fuel operation.

The sea load demand for refrigeration compressors, engine and deck ancillaries, machinery space auxiliaries and hotel load can be met by using a main-engine-driven generator, a steamturbine driven generator using waste heat from the engine exhaust gas, or simply by applying auxiliary generator sets. The waste heat option is a practical proposition for high-powered engines employed on long voyages.

The electrical power required when loading and discharging cannot be met with a main-engine driven generator or with the waste heat recovery system, and for vessels employed on comparatively short voyages the waste heat system is not viable. Stand-by diesel generator sets **(Wärtsilä GenSets)** burning heavy fuel oil or marine diesel oil, available for use in port, when manoeuvring or at anchor, provide the required flexibility when the main-engine power cannot be used.

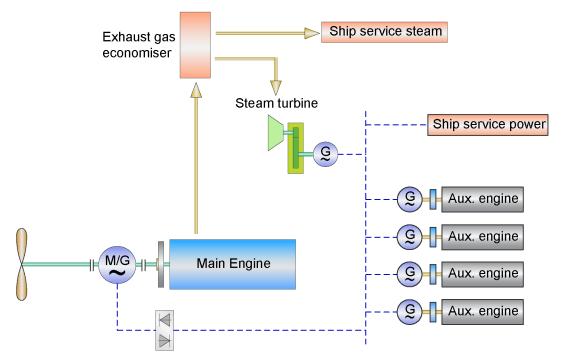


Figure 6.1: Heat recovery, typical system layout

Although initial installation costs for a heat recovery plant are relatively high, these are recovered by fuel savings if maximum use is made of the steam output, i.e. electrical power and domestics, space heating, heating of tank, fuel and water.

6.1 Waste heat recovery

Before any decision can be made on installing a waste heat recovery system (see Fig. 6.1) the steam and electrical power available from the exhaust gas is to be established.

For more information see chapter winGTD and netGTD.

6.2 Power take-off (PTO)

Main-engine driven generators are an advantageous option when consideration is given to the simplicity of operation and low maintenance costs. The generator is driven by a tunnel PTO gear with frequencey control provided by thyristor invertors or constant-speed gears. The tunnel gear is mounted on the intermediate propeller shaft. Positioning the PTO gear in that area of the ship depends upon the available space.

6.2.1 PTO power and speed

PTO tunnel gear with generator					
Generator speed (rpm)	1000, 1200, 1500, 1800				
Power (kWe)	700, 1200, 1800				

Table 6.1: PTO power and speed

Free end PTO is available on request.

An alternative is a shaft generator.

7. Ancillary Systems

Sizing engine ancillary systems, i.e. freshwater cooling, lubricating oil, fuel oil, etc., depends on the contract maximum engine power. If the expected system design is out of the scope of this manual, contact our representative or Wärtsilä Switzerland Ltd. directly.

The *winGTD* and *netGTD* enable all engine and system data at any Rx rating within the engine rating field to be obtained. However, for convenience or final confirmation when optimizing the plant, Wärtsilä Switzerland Ltd. provide a computerized calculation service.

All pipework systems and fittings are to conform to the requirements laid down by the legislative council of the vessel's country of registration and the classification society selected by the owners. They are to be designed and installed to accommodate the quantities, velocities, flow rates and contents identified in this manual, set to work in accordance with the build specification as approved by the classification society and protected at all times from ingress of foreign bodies. **All pipework systems are to be flushed and proved clean before commissioning.**

The data given in section 7.1 are applicable to the nominal maximum continuous rating R1 of the 5 to 8-cylinder engines and suitable for estimating the size of ancillary equipment.

These data refer to engines with the following conditions/features:

- At design (tropical) conditions
- Standard Tuning
- Central freshwater cooling system with single-stage scavenge air cooler (SAC) and integrated HT circuit
- ABB A100-L turbochargers
- Turbochargers lubricated from the engine's lubricating system

Furthermore the following data are obtainable from the *winGTD and netGTD* or on request from Wärtsilä Switzerland Ltd.:

- Data for engines fitted with MHI MET MB turbochargers
- Derating and part-load performance data
- Data for Delta Tuning
- Data for Low-Load Tuning

7.1 Data for central freshwater cooling system (integrated HT)

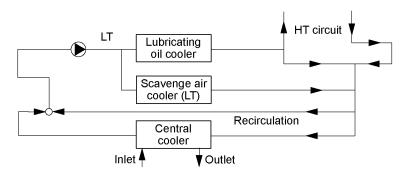


Figure 7.1: Central freshwater cooling system with integrated HT circuit

7.1.1 Data for central freshwater cooling system

Number of cylinders		5	5 6		8	
Speed R1 rpm		146				
Engine power R1	kW	5,675	6,810	7,945	9,080	
Turbochargers	-					
Type ABB	-	1 A165-L34	1 A165-L35	1 A170-L34	1 A170-L35	
Cylinder cooling (HT)				1	1	
Heat dissipation	kW	856	1,057	1,228	1,431	
Freshwater flow	m³/h	50	62	72	84	
Freshwater temp. engine in / out	°C	70 / 85	70 / 85	70 / 85	70 / 85	
Scavenge air cooler (LT)					1	
Heat dissipation kW		2,315	2,767	3,237	3,687	
Freshwater flow	m³/h	155	155	155	155	
Freshwater temp. cooler in / out °C		36 / 49 36 / 51		36 / 54	36 / 57	
Scavenge air mass flow t/h		41	50	58	66	
Lubricating oil cooler				1	1	
Heat dissipation	kW	520	617	725	823	
Oil flow *1)	m³/h	112	127	142	158	
Oil temp. cooler in / out	°C	54 / 45	55 / 45	55 / 45	56 / 45	
Water flow	m³/h	45	53	63	71	
Water temp. cooler in / out	°C	36 / 46	36 / 46	36 / 46	36 / 46	
Mean log temp. difference	°C	9	9	9	9	

Number of cylinders		5		6	6	7	,	8		
Central cooler	1			1				1		
Heat dissipation	kW	<w 3,691<="" td=""><td colspan="2">4,442</td><td colspan="2">5,190</td><td colspan="2">5,941</td></w>		4,442		5,190		5,941		
Freshwater flow	m³/h	20	0	208		218		226		
Freshwater temp. cooler in / out	°C	52 / 36		54 / 36		57 / 36		59 / 36		
Seawater flow	m³/h	18	0	21	7	25	3	29	290	
Seawater temp. cooler in / out	°C	32 /	50	32 /	50	32 / 50		32 /	50	
Mean log temp. difference	°C	3		4	Ļ	5	i	6		
Exhaust gas										
Heat dissipation *2)	kW	1,2	70	1,5	24	1,779		2,033		
Mass flow	t/h	41	.9	50.2		58.6		67.0		
Temp. after turbine	°C	27	7	27	'7	277		277		
Engine radiation										
Radiation	kW	61		7	0	79	9	87	7	
Starting air *3)										
Bottles (2 units), pressure	bar	30)	3	0	30	D	30)	
Bottles (2 units), capacity each	m ³	2.	0	2.	0	2.	5	2.	5	
Air compressors (2 units), capacity each	m³/h	60		60		75		75		
Pumps / delivery head *4)						1				
		m³/h	bar	m³/h	bar	m³/h	bar	m³/h	bar	
Lubricating oil		112	6.2	127	6.2	142	6.2	158	6.2	
High-temp. circuit		50	2.5	62	2.5	72	2.5	84	2.5	
Low-temp. circuit		200	2.0	208	2.0	218	2.0	226	2.0	
Fuel oil b	ooster	1.6	7.0	2.0	7.0	2.3	7.0	2.6	7.0	
Fuel o	il feed	1.4	4.0	1.7	4.0	2.0	4.0	2.3	4.0	
Sea	awater	180	2.2	217	2.2	253	2.2	290	2.2	

Table 7.1: Data for central freshwater cooling system

NOTICE

*1) Excluding heat and oil flow for damper and PTO gear.

*2) Available heat for boiler with gas outlet temperature 170°C and temperature drop of 5°C from turbine to boiler.

*3) For 12 starts and refilling time 1 hour, when $J_{rel} = 2.0$ (see section 11.2 Starting and control air system specification).

*4) Pressure difference across pump (final delivery head must be according to the actual piping layout).

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8. Cooling Water System

The cooling system runs on either one of the following standard layouts:

- 1 Central freshwater cooling system with single-stage scavenge air cooler and **integrated** HT circuit
- 2 Central freshwater cooling system with single-stage scavenge air cooler and **separate** HT circuit.

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

As freshwater is the standard cooling medium of the scavenge air cooler(s), this involves the use of a central freshwater cooling system.

The central freshwater cooling system comprises 'low-temperature' (LT) and 'high-temperature' (HT) circuits. Freshwater cooling systems reduce the amount of seawater pipework and its attendant problems and provide for improved cooling control. Optimizing central freshwater cooling results in lower overall running costs compared to the conventional seawater cooling system.

8.1 Central freshwater cooling system components

The high-temperature circuit may also be completely separated from the low-temperature circuit. In this case the high-temperature circuit has its own cooler with freshwater from the low-temperature circuit as cooling medium. The necessary data for this arrangement can be obtained from the *winGTD and netGTD*.

8.1.1 Low-temperature circuit

Seawater strainer

Simplex or duplex to be fitted at each sea chest and arranged to enable manual cleaning without interrupting the flow. The strainer perforations are to be sized (no more than 6 mm) to prevent passage of large particles and debris damaging the pumps and impairing heat transfer across the coolers.

Seawater strainer				
Pump type:	centrifugal			
Pump capacity:	refer to table 7.1 Data for central freshwater cooling system (integrated HT); the given seawater flow capacity covers the need of the engine only and is to be within a tolerance of 0 to $+10\%$			
Delivery head:	is determined by the layout of the system and is to ensure that the inlet pressure to the scavenge air coolers is within the range of the summarized data in section 2.8 Pressure and temperatures ranges			
Central cooler				
Cooler type:	plate or tubular			
Cooling medium:	seawater			
Cooled medium:	freshwater			
Heat dissipation:	refer to table 7.1			
Margin for fouling:	10-15% to be added			
Freshwater flow:	refer to table 7.1			
Seawater flow:	refer to table 7.1			
Temperatures:	refer to table 7.1			
Temperature control				
The central freshwater control of the ce	ooling system is to be capable of maintaining the inlet temperature to the scavenge air cooler between			
Freshwater pumps for	LT circuit			
Pump type:	centrifugal			
Pump capacity:	refer to table 7.1 Data for central freshwater cooling system (integrated HT); the given capacity of freshwater flow covers the need of the engine only and is to be within a tolerance of 0 to $+10\%$			
Delivery head:	the final delivery head is determined by the layout of the system and is to ensure that the inlet			

pressure to the scavenge air coolers is within the range of the summarized data

Table 8.1: Low-temperature circuit

8.1.2 High-temperature circuit

HT cooling water pump					
centrifugal, with a steep headcurve is to be given preference. As a guide, the minimum advisable curve steepness can be defined as follows:					
 For a pressure increase from 100% to 107%, the pump capacity should not decreby more than 10%. 					
refer to section 7.1 The flow capacity is to be within a tolerance of -10 to +20%.					
determined by system layout					
95°C					
-					

Pump delivery head (pp)

The required delivery head can be calculated as follows:

- \geq system pressure losses ($\Sigma\Delta p$)
- \geq required pressure at engine inlet (p₀)
- + pressure drop between pump inlet and engine inlet (d_p)
- constant (h / 10.2)
- $p_{p} \ge \Sigma \Delta p \ge p_{0}$ h / 10.2 + d_{p} [bar].

The system pressure losses ($\Sigma\Delta p$) are the pressure drop across the system components and pipework and the pressure drop across the engine. The pump delivery head (p_p) depends on the height of the expansion tank, the pressure drop between pump outlet and engine inlet (d_p), and the required pressure at engine inlet (p_0). The constant is given as the difference in height between the expansion tank and the engine inlet (h) divided by 10.2.

Expansion tank

The expansion tank is to be fitted at least 3.5m above the highest engine air vent flange to ensure that the required static head is applied to the cylinder cooling water system. It is to be connected by a balance pipe, to replenish system losses, using the shortest route to the cylinder cooling water pump suction, making sure that pipe runs are as straight as possible without sharp bends. The cylinder cooling water system air vents are to be routed through the bottom of the expansion tank with the open end below the minimum water level.

Automatic temp. control valve

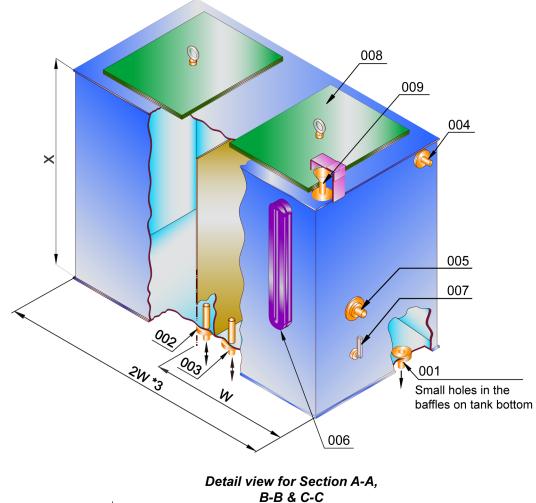
Electrically or electro-pneumatically actuated three-way type (butterfly valves are not adequate) having a linear characteristic

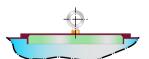
Design pressure:	5 bar			
Test pressure: refer to the specification laid down by the classification society				
Press. drop across valve: max. 0.5 bar				
Controller:	proportional plus integral (PI); also known as proportional plus reset for steady state error of max. $\pm 2^{\circ}C$ and transient condition error of max. $\pm 4^{\circ}C$			
Temp. sensor:	according to the control valve manufacturer's specification, fitted in the engine outlet pipe			

Table 8.2: High-temperature circuit

The illustrations below do not necessarily represent the actual configuration or the stage of development, nor the type of your engine.

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.





Detail view for Section X-X

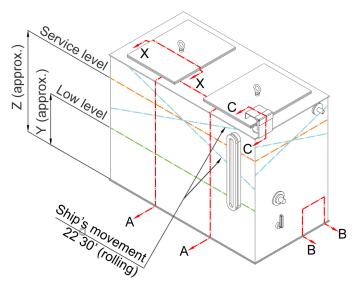


Figure 8.1: Central cooling water system, expansion tank

001	Drain	006	Level indicator *1)
002	Balance pipe from HT circuit	007	Thermometer
003	Balance pipe from LT circuit	008	Inspection cover *2)
004	Overflow / air vent	009	Filling pipe / inlet chemical treatment *2)
005	Low level alarm		

NOTICE

*1) Level indicator can be omitted if an alternative is fitted.

*2) Other designs (like hinged covers, etc.) are possible.

*3) Depending on actual ancillary plants. LT tank capacity to be increased accordingly.

Total capacity *3)	w	x	Y	z
(m³)				
1.0	800	800	330	640
1.5	800	1,200	500	960
2.0	800	1,600	670	1,280
2.5	1,000	1,250	530	1,000
3.0	1,000	1,500	630	1,200
3.5	1,000	1,750	730	1,400
4.0	1,000	2,000	830	1,600

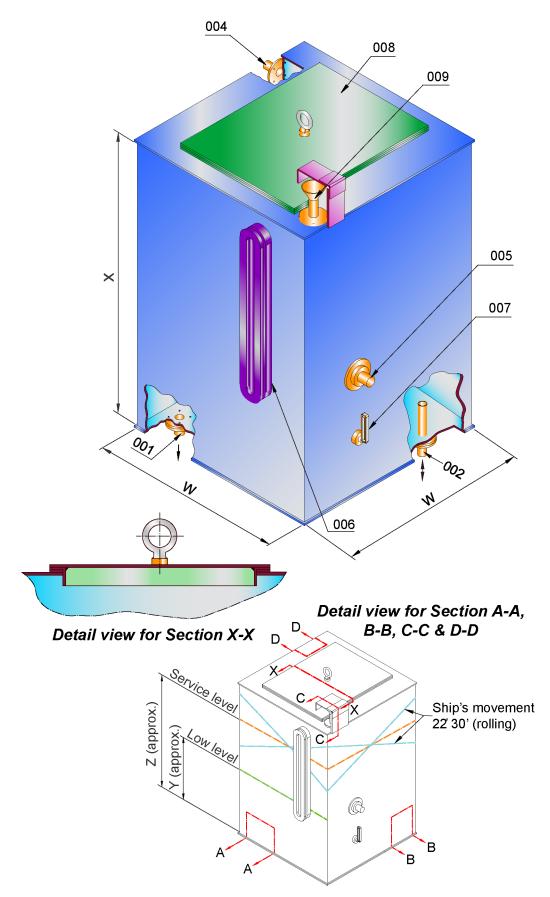


Figure 8.2: Central cooling water system, expansion tank (HT circuit)

001	Drain from HT circuit	006	Level indicator *1)
002	Balance pipe from circuit		Thermometer
		008	Inspection cover *2)
004	Overflow / air vent	009	Filling pipe / inlet chemical treatment *2)
005	Low level alarm		

NOTICE

*1) Level indicator can be omitted if an alternative is fitted.

*2) Other designs (like hinged covers, etc.) are possible.

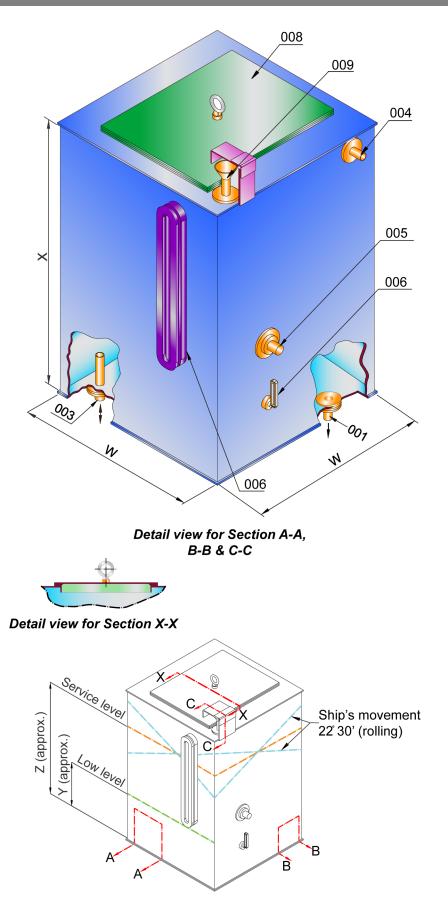


Figure 8.3: Central cooling water system, expansion tank (LT circuit)

001	Drain from LT circuit	006	Level indicator *1)
		007	Thermometer
003	Balance pipe from circuit	008	Inspection cover *2)
004	Overflow / air vent	009	Filling pipe / inlet chemical treatment *2)
005	Low level alarm		

NOTICE

*1) Level indicator can be omitted if an alternative is fitted.

*2) Other designs (like hinged covers, etc.) are possible.

8.2 General recommendations for design

The number of valves in the system is to be kept to a minimum to reduce the risk of incorrect setting.

Valves are to be locked in the set position and labelled to eliminate incorrect handling.

The possibility of manual interference with the cooling water flow in the different branches of the cylinder cooling water system is to be avoided by installing and setting throttling discs at the commissioning stage, but not by adjusting the valves.

Under normal operation of the cylinder cooling water system the pump delivery head and the total flow rate are to remain constant even when the freshwater generator is started up or shut down.

The cylinder cooling water system is to be totally separated from steam systems. Under no circumstances must there be any possibility of steam entering the cylinder cooling water system, e.g. via a freshwater generator.

The installation of equipment affecting the controlled temperature of the cylinder cooling water is to be examined carefully before being added. Uncontrolled increases or decreases in cylinder cooling water temperature may lead to thermal shock of the engine components and scuffing of the pistons. Thermal shock is to be avoided, and the temperature gradient of the cooling water when starting and shutting down additional equipment is not to exceed two degrees per minute at the engine inlet.

The design pressure and temperature of all the component parts such as pipes, valves, expansion tank, fittings, etc. are to meet the requirements of the classification society.

8.2.1 Cooling water treatment

Correct treatment of the cooling freshwater is essential for safe engine operation. Only totally demineralized water or condensate must be used. In the event of an emergency, tap water may be used for a limited period, but afterwards the entire cylinder cooling water system is to be drained off, flushed, and recharged with demineralized water.

Recommended parameters for raw water:

min. pH 6.5 max. dH 10°dH (corresponds to 180 mg/l CaCO₃) *1) max. chloride 80 mg/l max. sulphates 150 mg/l

NOTICE

*1) In case of higher values the water is to be softened.

In addition, the water used must be treated with a suitable corrosion inhibitor to prevent corrosive attack, sludge formation and scale deposits. (For details refer to the chemical supply companies.) Monitoring the level of the corrosion inhibitor and water softness is essential to prevent down-times due to component failures resulting from corrosion or impaired heat transfer. No internally galvanized steel pipes should be used in connection with treated freshwater, since most corrosion inhibitors have a nitrite base. Nitrites attack the zinc lining of galvanized piping and create sludge.

8.3 Freshwater generator

A freshwater generator, using heat from the cylinder cooling system to distil seawater, can be used to meet the demand for washing and potable water. The capacity of the freshwater generator is limited by the amount of heat available, which in turn is dependent on the service power rating of the engine. It is crucial at the design stage to ensure that there are sufficient safeguards to protect the main engine from thermal shock when the freshwater generator is started. To reduce such risk, the use of valves, e.g. butterfly valves at the freshwater generator inlet and in the bypass line which are linked and actuated with a large reduction ratio, will be of advantage. The following installations are given as examples and we recommend that the freshwater generator valves (7 and 8) be operated by progressive servomotors and a warning sign be displayed on the freshwater generator to remind engine room personnel of the possibility of thermal shocking if automatic start-up is overridden.

Avoid thermal shock to your main engine. The freshwater generator inlet and outlet valves to be opened and closed slowly and progressively.

The bypass with valve (8) must have the same pressure drop as the freshwater generator. The valve must be open when the freshwater generator is not in operation and closed when the freshwater generator is operating. To avoid any wrong manipulation we recommend to interlock valves 7 and 8.

Figures 8.4 and 8.5 provide two systems designed to use up to 50% of available heat (alternative 'A') and up to 85% of available heat (alternative 'B').

8.3.1 Alternative 'A'

Freshwater generators, with an evaporator heat requirement not in excess of 50% of the heat available to be dissipated from the cylinder cooling water at full load (CMCR) and only for use at engine loads above 50%, can be connected in series as shown in figure 8.4. The throttling disc (6) serves to correct the water flow rate if the pressure drop in the cooling circuit is less than that in the freshwater generator circuit. It is to be adjusted so that the cylinder cooling water pressure at the engine inlet is maintained within the pressure range of the summarized data in table 2.8 Pressure and temperatures ranges when the freshwater generator is started up and shut down.

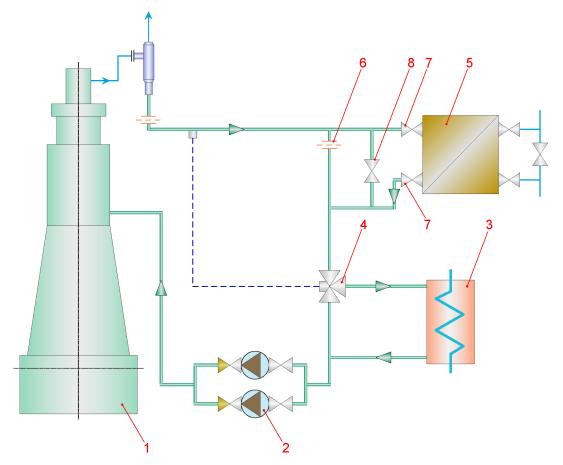


Figure 8.4: Freshwater generator installation, alternative 'A'

1	Main engine	5	Freshwater generator
2	Cylinder cooling water pump	6	Throttling disc
3	Cylinder cooling water cooler	7	Freshwater valves
4	Automatic temperature control valve	8	Freshwater generator by-pass valve

Example

8-cyl. engine - R1 specification with 9,080 kW at 146 rpm

The available heat (from section 7.1.1 Data for central freshwater cooling system) is 1,431 kW. Alternative 'A' uses up to 50% of the available heat, hence 715 kW of heat is available. Substitute this value in the equation:

- FW produced in t/day = constant x available heat
- FW produced in t/day = 32 x 10⁻³ x 715
- FW produced in t/day = 23

8.3.2 Alternative 'B'

A freshwater generator, with an evaporator heat requirement not in excess of 85% of the heat available to be dissipated from the cylinder cooling water at full load (CMCR), can be connected in series as shown in figure 8.5. This arrangement requires the provision of an additional automatic temperature control valve (4A), connected in cascade control with the cylinder cooling water cooler temperature control valve (4B), and controlled by the step controller (9) sensing the outlet cylinder cooling water temperature from the engine. If the cylinder cooling water outlet temperature is falling below the set point, valve (4A) reduces the flow of cylinder cooling water to the freshwater generator for compensation. A part of the cylinder cooling water is then routed directly to the cooling water pumps (2) until the normal temperature is attained. This means that the freshwater generator can be kept in continuous operation, although the generated freshwater volume decreases due to the reduced flow of hot water to the evaporator.

When the freshwater generator cannot dissipate all the heat in the cylinder cooling water, valve (4A) is fully opened across connections 1 and 2, and a valve travel limit switch changes the regulation of cylinder cooling water temperature over to temperature control valve (4B). This in turn passes water to the cylinder cooling water cooler (3) to maintain the cylinder water outlet at the required temperature. If in this condition the cylinder cooling water temperature falls below the set point and the cooler (3) is fully by-passed, valve (4B) is fully opened across connections 2 and 1, and a valve travel limit switch transfers the regulation of cylinder cooling water temperature back to temperature control valve (4A). As an alternative to the single-step controller (9), two controllers can be installed, one for each valve, making sure that there is a 3°C difference in the set point between (4A) and (4B) to avoid both controllers acting at the same time.

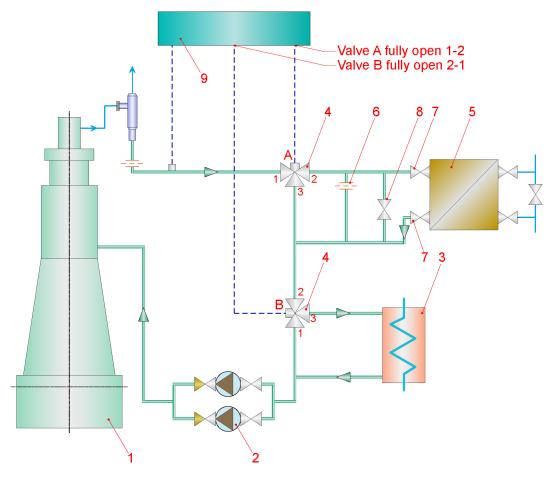


Figure 8.5: Freshwater generator installation, alternative 'B'

1	Main engine	6	Throttling disc
2	Cylinder cooling water pump	7	Cylinder water valve
3	Cylinder cooling water cooler	8	Freshwater generator by-pass valve
4	Automatic temperature control valve	9	Controller
5	Freshwater generator		

The quantity of freshwater produced by a single-effect vacuum (flash) evaporator can be estimated for guidance purposes as follows:

FW produced in t/day = 32 x 10⁻³ x Q_{FW}

where Q_{FW} is the heat in kW available from the cylinder cooling water, estimated from the derating table 7.1 Data for central freshwater cooling system (integrated HT)

Example

8-cyl. engine - R1 specification with 9,080 kW at 146 rpm fitted with central cooling system and single-stage scavenge air cooler

The available heat (from table 7.1 Data for central freshwater cooling system (integrated HT)) is 1,431 kW. Alternative 'B' uses up to 85% of the available heat, hence 1,216 kW of heat is available. Substitute this value in the equation:

- FW produced in t/day = constant x available heat
- FW produced in t/day = 32 x 10⁻³ x 1,216
- FW produced in t/day = 39

NOTICE

The indicated values for evaporator heat requirement and load in alternatives 'A' and 'B' (i.e. 50% and 85% respectively) are only applicable if there are **no additional heat consumers** installed (e.g. feed water pre-heater for waste heat recovery, etc.).

8.4 Pre-heating

To prevent corrosive liner wear when not in service or during short stays in port, it is important that the main engine is kept warm. Warming-through can be provided by a dedicated heater, using boiler raised steam or hot water from the diesel auxiliaries, or by direct circulation from the diesel auxiliaries.

If the main cylinder water pump is to be used to circulate water through the engine during warming-up, the heater is to be arranged parallel with the cylinder water system, and on/off control is to be provided by a dedicated temperature sensor at the cylinder water outlet of the engine. The flow through the heater is set by throttling discs, but not by valves, to assure flow through the heater.

If the requirement is for a separate pre-heating pump, a small unit of 10% of the main pump capacity and an additional non-return valve between the cylinder cooling water pump and the heater are to be installed. In addition, the pumps are to be electrically interlocked to prevent two pumps running at the same time.

Before starting and operating the engine, a temperature of 60°C at the cylinder cooling water outlet of the main engine is recommended. If the engine has to be started below the recommended temperature, engine power is not to exceed 80% of CMCR until the water temperature has reached 60°C.

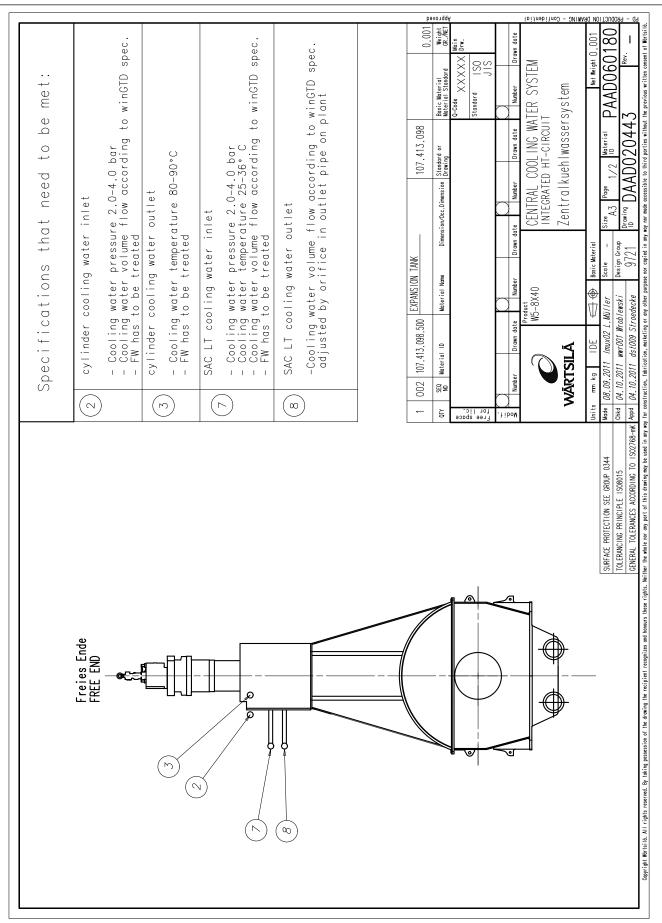
To estimate the heater power capacity required to achieve the target temperature of 60°C, the engine ambient temperature and the heating-up time are the key parameters.

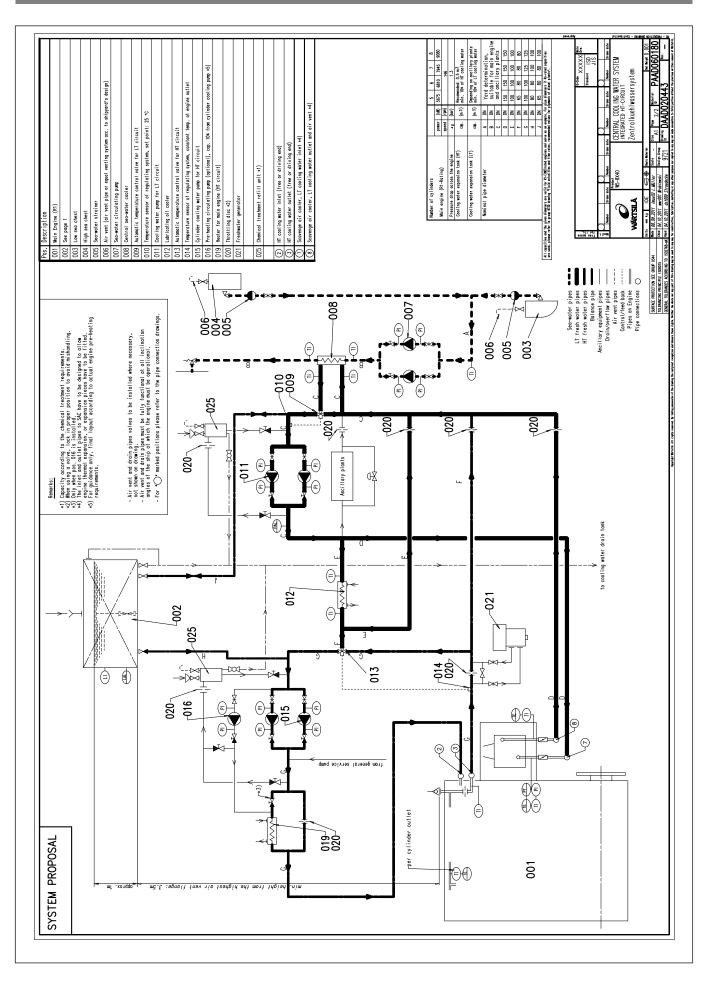
If the requirement for warming-up is from the cooling water systems of the diesel auxiliaries, it is essential that the amount of heat available at normal load is sufficient to warm the main engine. If the main and auxiliary engines have a cooling water system which can be cross-connected, it has to be ensured that any pressure drop across the main engine, when the cross-connection is made, does not affect the cooling water pressure required by the auxiliaries. If the cooling water systems are separate, then a dedicated heat exchanger is required to transfer the heat to the main cylinder water system.

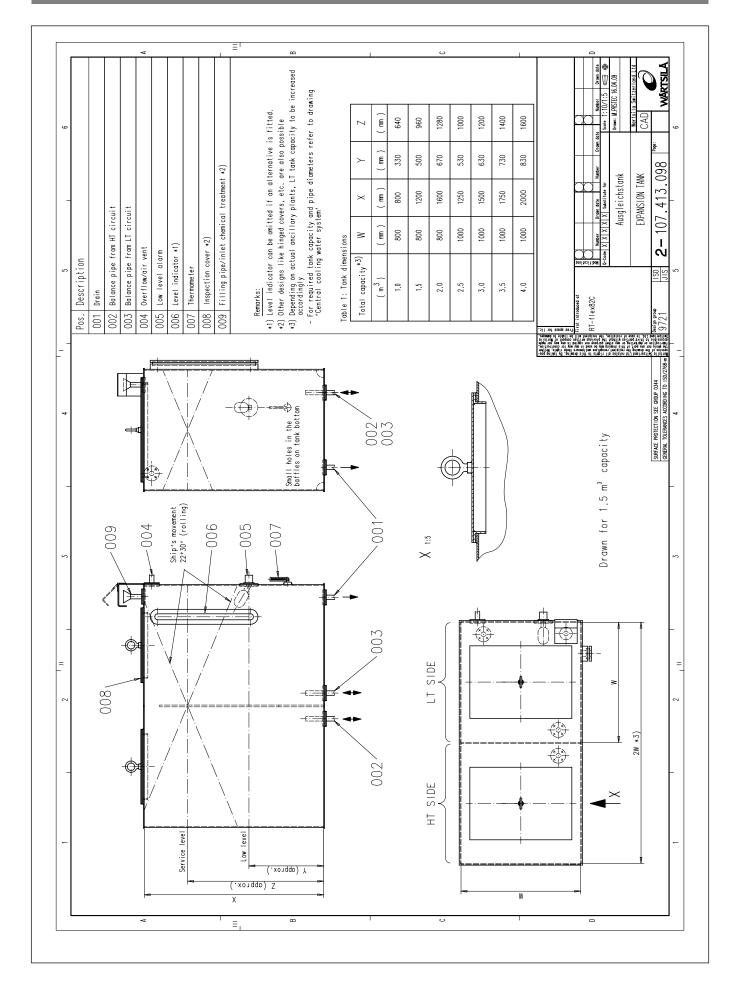
8.5 Drawings

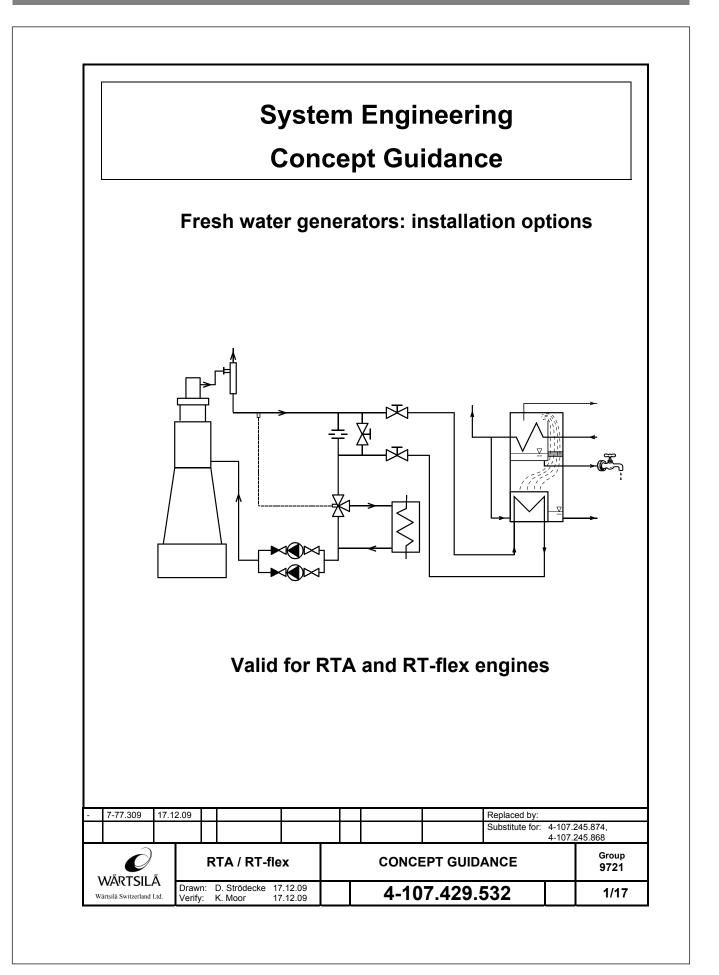
DAAD020444 -	Cooling Water Systems, Installation Drawings, W5-8X40	88-16
DAAD020443 -	Central Cooling Water System, Integrated HT-Circuit, W5-8X40	88-18
107.413.098 -	Expansion Tank, W5-8X40	88-19
107.429.532 -	Concept Guidance, W5-8X40	8836
DAAD020442 -	Central Cooling Water System, Separated HT-Circuit, W5-8X40	8838
107.413.097 -	Expansion Tank, Central Cooling Water HT Circuit, W5-8X40	8839
107.245.419 c	Expansion Tank, Central Cooling Water LT Circuit, W5-8X40	8840

Central cooling water system with single-stage	SAC
PAAD060175 Central cooling water system with single-stage and separated HT-circuit	
PAAD060174 Central cooling water system with single-stage and integrated HT-circuit	SAC
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2 2. 2.	[m ³ /day] fresh water production. Installation alternative 'A'
	[m ³ /day] fresh water production. Installation alternative 'A'
2.2) Optimized installation (single stage EM/C): up to should $2.7 \times 10^{-3} \times CMCD$
	[m ³ /day] fresh water production. Installation alternative 'B'
2.3	Installation, utilising main and auxiliary engine heat dissipation (single stage FWG): 3.7x10 ⁻³ x CMCR (ME) + 5.3x10 ⁻³ x base load (AE) [m ³ /day] fresh water production
2.4	Installation with booster heater (single-stage FWG): maximum possible fresh water production depending on the additional booster heater capacity
3	Multi-effect and multi-stage FWG: a multiple of the single-stage FWG
	installations
3.	1 Multi-effect evaporation FWG installations:
3.:	2 Multi-stage flash FWG: a multiple of the single-stage FWG installations
4	Heat-independent installations
5	Abbreviations

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Introduction

Production of fresh water on board of sea going vessels is a well-established requirement. However, nowadays a trend to install fresh water generators (FWG) with larger capacities can be seen. Most fresh water generators work according to the operating principle of distillation by utilising part of the engine waste heat. For very high water production, heatindependent fresh water generators are also employed, as described in section 4 on page 15.

This Concept Guidance assists in designing the installation which fits best to the fresh water demand while ensuring safe main engine operation. A simple formula in the following section titles allows calculating directly the possible fresh water production corresponding to the installed engine power in kilowatt [kW]. However, this simple formula is only applicable as a first estimation. The final possible water production depends on different factors, mainly on the available waste heat of the engines concerned and the heat demand of the chosen FWG type.

The available heat from the high temperature (HT) cooling water circuit depends on the main engine load¹ and the ambient conditions. At lower engine load and in colder ambient conditions the available heat decreases. The fresh water generator's heat requirement also depends on the ambient conditions, mainly on sea-water (SW) temperature: in colder ambient conditions the heat requirement increases. Therefore the FWG design has also to be determined in accordance with the vessel's operational profile.

In case of any doubt, please do not hesitate to contact Wärtsilä Switzerland.

If other high-temperature cooling water heat consumers are to be installed, the total heat requirement of all heat consumers has to be considered.

¹ And auxiliary engine load for installations as described in sections 2.3 (p. 9) and 2.4 (p. 10).

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The system drawings in this Concept Guidance show only installations with separated HT cooling water circuits, i.e. the HT and the LT cooling water circuits are separated by the HT cooling water cooler (HTC). However, this Guidance is also valid for installations with an integrated HT cooling water circuit. In integrated HT cooling water systems, LT cooling water is mixed to the HT circuit to maintain the required temperature at the engine inlet.

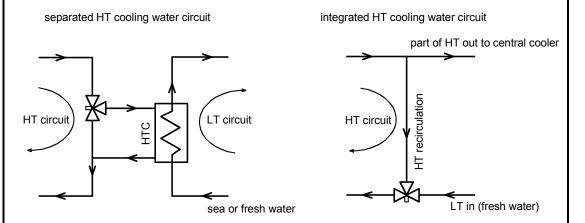


Fig. 1: The two principal types of cooling water systems

1 Safe engine operation

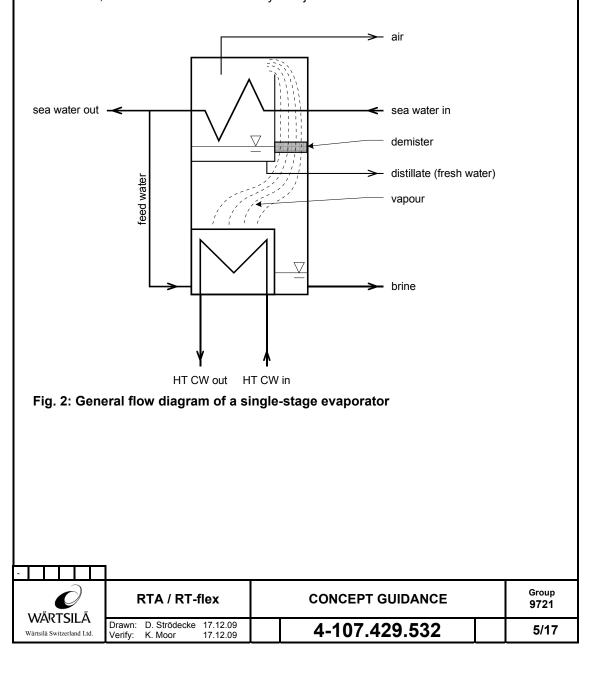
To avoid any negative impact of FWG operation on the engine, a few basic principles have to be observed:

- Avoid thermal shock to the engine. The fresh water generator inlet and outlet butterfly valves for the HT water are to be opened and closed slowly and progressively. They should be actuated manually with a large reduction ratio or preferably by a progressive servomotor with timer control. If the valves are manually operated, a conspicuous warning notice has to be positioned next to them. Please keep in mind that 50% to 100% of the cooling function may be taken over by the FWG, depending on the FWG design and the main engine load.
- Keep the water flow to the main engine always constant. Therefore do not install any stop valve in the main water flow to control the water flow.

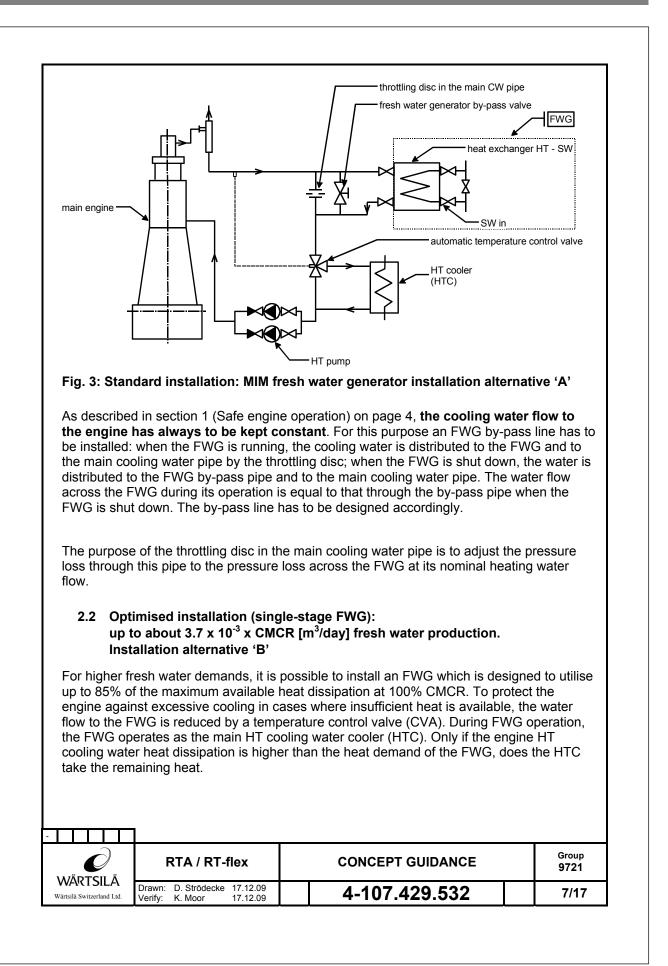
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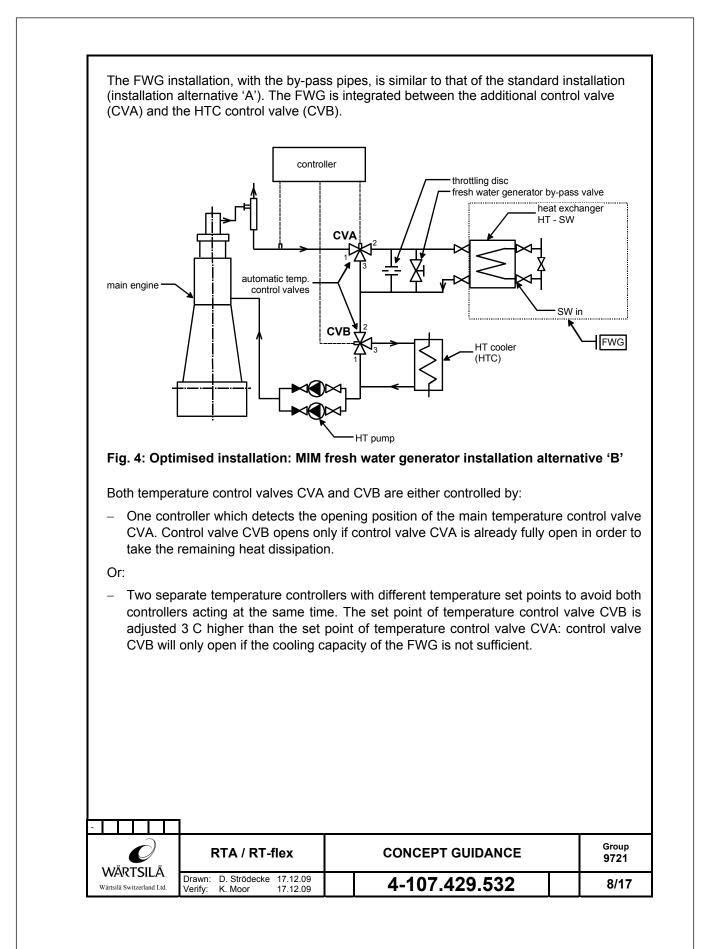
2 Single-stage fresh water generator

On board cargo vessels the fresh water is usually produced by evaporating sea water under vacuum conditions. The most common installation is a single-stage FWG. Different designs are possible, basically divided between those with tube or plate heat exchangers. However, the working principles are the same. Sea water is pre-heated by condensing the vapour in the FWG and heated by HT cooling water. About one third of the sea water evaporates. The vapour flows through the so-called demister which separates water droplets from the vapour. In the sea-water cooled condenser the vapour condensates as so-called distillate. The distillate is pumped to the storage tank. The non-evaporated two thirds of the sea water are removed as brine and pumped overboard. To obtain the vacuum in the FWG, the air has to be removed by an ejector.



up to	dard installation (single about 2.2 x 10 ⁻³ x CMC Illation alternative 'A'	e-stage FWG): R [m³/day] fresh water production.	
The FWG wo water flow an	orks as an additional coole id heat requirement. Ther	e fresh water generator directly into the H er, but without any control valve, i.e. at a refore the FWG can only be operated at e e HT cooling water to avoid cooling down	constant engine load
heat dissipati engines and heat is availa lower than 50	on at 100% CMCR for the up to 50% for the other R ble to cover the FWG nee 0% CMCR. However, in c e heat dissipation decrea	p to 40% of the maximum available HT co e RTA52U-B, RTA62U-B, RTA72U-B and TA and RT-flex engines. To ensure that s ed, the FWG must not be operated at eng old environments the FWG heat demand ises, i.e. the FWG has then to be operate	d RTĂ84C still sufficier gine loads increases,
The possible the following		epending on the available heat can be ca	lculated wit
FW pro	duced in m³/day = 32 x 10	0 ⁻³ x Q _{FW} .	
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2.3 Installation, utilising main and auxiliary engine heat dissipation (single stage FWG): 3.7x10⁻³ x CMCR (ME) + 5.3x10⁻³ x base load (AE) [m³/day] fresh water production A newly-developed system integrating the heat dissipation of the auxiliary engines into the HT system of the main engine is described below. The FWG capacity can be specified by taking into account the additional continuous heat available from the auxiliary engines at base load. HT fr. AE outlet heat exchanger circulation pump HT - SW 85°C/90° CVA 85°C/90°C HT fr. ME outlet HT to ME inlet SW in HT to AE inlet FWG CVB HT cooler (HTC) Fig. 5: Installation option utilising ME and AE cylinder cooling water waste heat A circulation pump ensures a constant water flow to the FWG, independent of main and auxiliary engines' load, but at different temperature levels. Depending on the opening position of temperature control valve CVA, part of the flow recirculates through the by-pass line between the FWG inlet and outlet. Control valve CVA maintains the cooling water temperature constant (85°C or 90°C²) at the main engine outlet. When the whole available heat cannot be dissipated by the FWG, the remaining heat is dissipated in the HT cooler. ² For RTA/RT-flex84T and RTA/RT-flex96C series only Group CONCEPT GUIDANCE RTA / RT-flex 9721 WÄRTSILÄ Drawn: D. Strödecke 17.12.09 4-107.429.532 9/17 Wärtsilä Switzerland Ltd Verify: K. Moor 17.12.09

Control valve CVB maintains the temperature of the cooled HT cooling water at 70°C. If the cooling water temperature after the control valve CVB falls below 70°C, the FWG circulation pump has to be stopped.

The 70°C warm cooling water can directly be used for pre-heating the stopped auxiliary engines respectively the stopped main engine.

Applying of an integrated HT cooling water circuit is also possible. The HT cooler has to be replaced by adding LT cooling water at the connection No. 2 of temperature control valve CVB.

Other advantages of this installation, besides the greater fresh water production potential, are:

- Pre-heating of the ME from the AE is possible when in port.
- Pre-heating of the AE from the running ME is possible.
- Only a small pre-heater for one AE is required (not shown in above schematic drawing).

For further information on this installation please contact Wärtsilä Switzerland.

2.4 Installation with booster heater (single-stage FWG): maximum possible fresh water production depending on the additional booster heater capacity

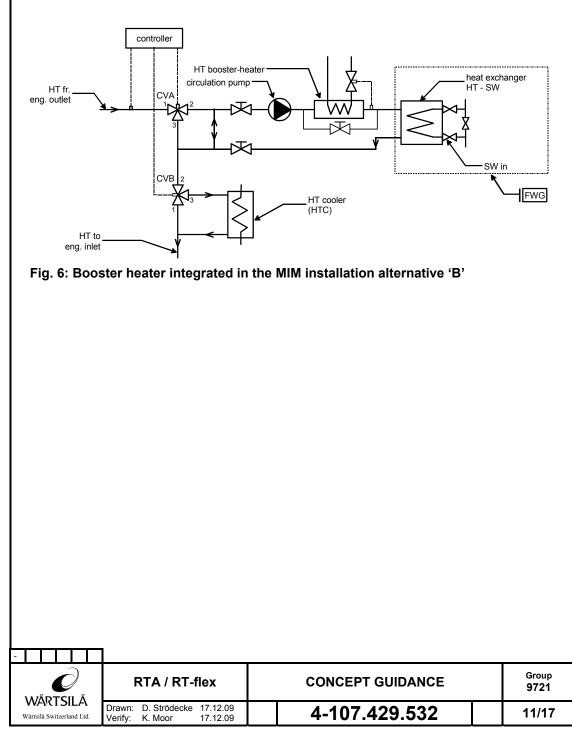
To increase the available heat for the FWG, also during lower part-load operation of the main engine and in colder ambient conditions, it is possible to install a booster heater. The heater may be operated with steam or thermal oil heated by the exhaust gas boiler, enabling another source of waste heat to be used for the fresh water production.

The booster heater can be integrated in the systems as described in section 2.2 on page 7 and section 2.3 on page 9.

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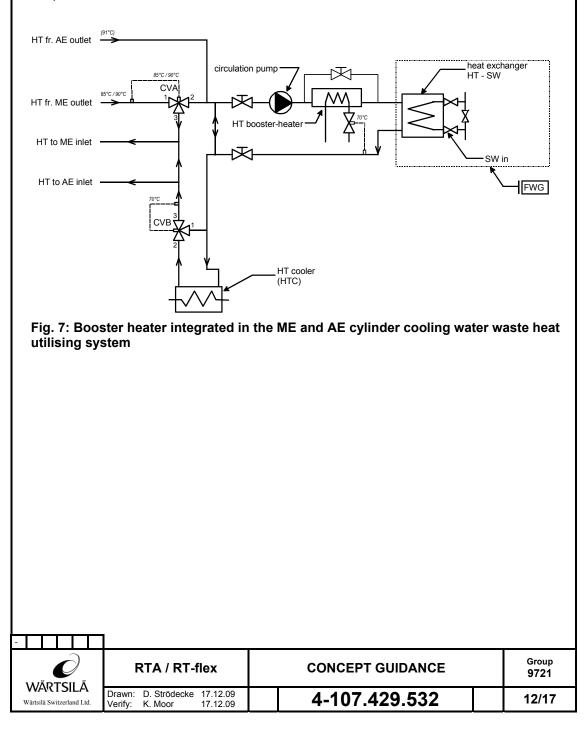
Booster heater integrated in the system of installation alternative 'B'

A circulation pump provides a constant water flow to the FWG according to the FWG demand. When the available waste heat from the main engine is not sufficient, control valve CVA provides less HT cooling water to the FWG. In this case the circulation pump recirculates part of the flow of the cooled water through the by-pass line between the FWG inlet and outlet. The booster heater ensures a constant FWG operating temperature.



Booster heater integrated in the system of section 2.3

In the system described in section 2.3 on page 9, a booster heater is integrated after the circulation pump. This ensures that the FWG is always operated at a constant temperature. For an optimum recovery of the HT cooling water heat it is recommended that the FWG outlet temperature be kept at about the same level as the outlet temperature after control valve CVB, i.e. 70°C. Therefore the booster heater should be controlled by the FWG outlet temperature.



3 Multi-effect and multi-stage FWG: a multiple of the single-stage FWG installations

To increase the possible water production with a given amount of (waste) heat, it is possible to install fresh water generators which utilise the available heat several times. The basic principal behind the higher water production of these FWG is a better reutilisation of the latent vapour condensation heat.

3.1 Multi-effect evaporation FWG installations:

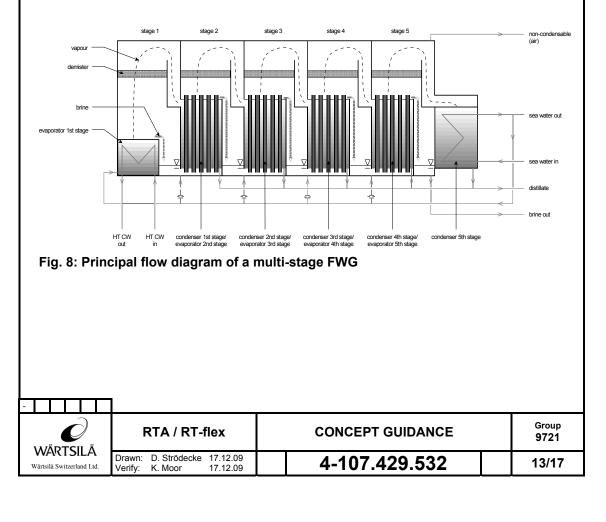
The single-stage FWG installations as described in section 2.1 to 2.4 can be replaced by a multi-effect evaporation FWG.

The multi-effect distillers (MED or MEP) utilise the latent vapour heat of the previous stage for evaporation in the following stage, i.e. the vapour condenser is cooled by heating up the sea water of the following stage.

Depending on the number of stages, it is possible to produce a multiple amount of fresh water compared to a single-stage FWG installation with the same heat input.

The figure below (Fig. 8) shows the working principle of a multi-effect evaporation FWG with five stages as an example.

For further information on this FWG type, please contact your FWG maker.



3.2 Multi-stage flash FWG: a multiple of the single-stage FWG installations

The multi-stage flash (MSF) FWG type also re-uses a significantly higher amount of the condensation heat compared to the single-stage FWG. The main difference compared to the multi-effect FWG is that the total heat transfer to the sea water takes place before the sea water enters the FWG. First the sea water is heated by the vapour condensation heat, beginning from the last stage up to the first one. Thus the sea water gets already 70-80% (depending on number of stages) of the total required heat. The remaining required heat is provided by the HT cooling water and/or by a booster heater. After the final heating-up, the sea water has got enough latent heat for the multi-evaporation stages, i.e. the sea water inlet temperature is on a higher level compared to the other FWG (nearly HT cooling water outlet temperature).

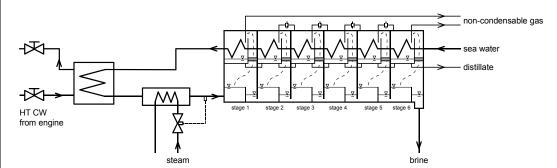
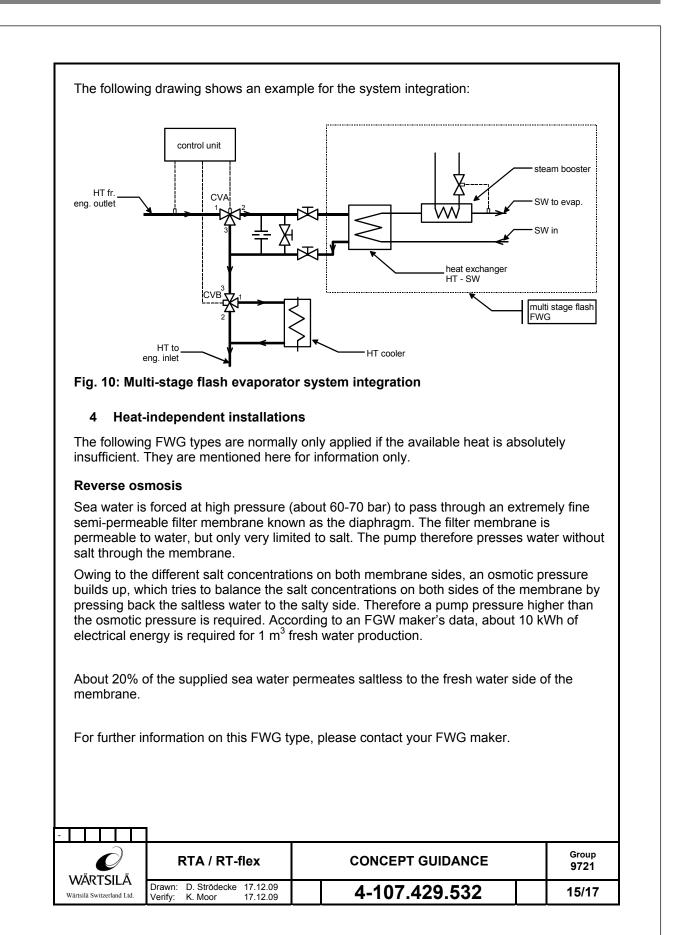


Fig. 9: Principal flow diagram of a multi-stage flash evaporator

The heated sea water enters the evaporation chambers from one stage to the next. The absolute pressure from the first stage to the last one is steadily decreased in a way that the sea water enters the chambers at a temperature level which is about 7°C higher than its boiling temperature. This leads to a spontaneous controlled evaporation of the superheated sea water. The sea water (brine) cools down due to the evaporation chill and flows to the next chamber with again a lower pressure inside. The process goes on until the sea water has passed the last chamber.

For further information on this FWG type, please contact your FWG maker.

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Vacuum vapour compression

The vacuum vapour compression (VVC) FWG consists of only one heat exchanger. The sea water on one side of the heat exchanger is heated by the heat of condensation of the mechanically compressed vapour, which is produced by partial evaporation of the sea water. This heat exchanger operation principle is comparable to the heat exchangers in the multi-effect FWG, except for its first stage.

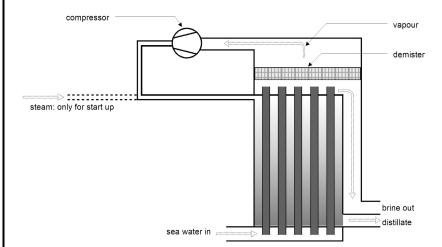


Fig. 11: Principal flow diagram of a vacuum vapour compression FWG.

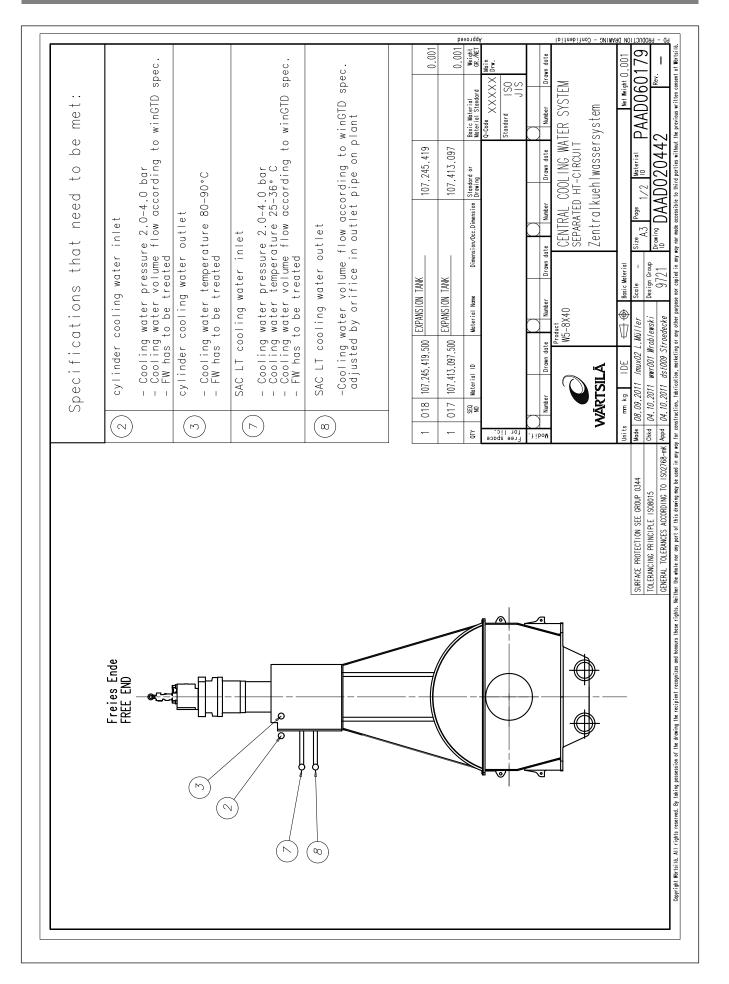
A mechanical compressor extracts the water vapour from the evaporation chamber, creating a vacuum which is required for sea water evaporation at a low temperature level. The compressed vapour flows from the compressor to the heat exchanger and condenses. According to an FGW maker's data, about 25 kWh of electrical energy is required for 1 m³ fresh water production.

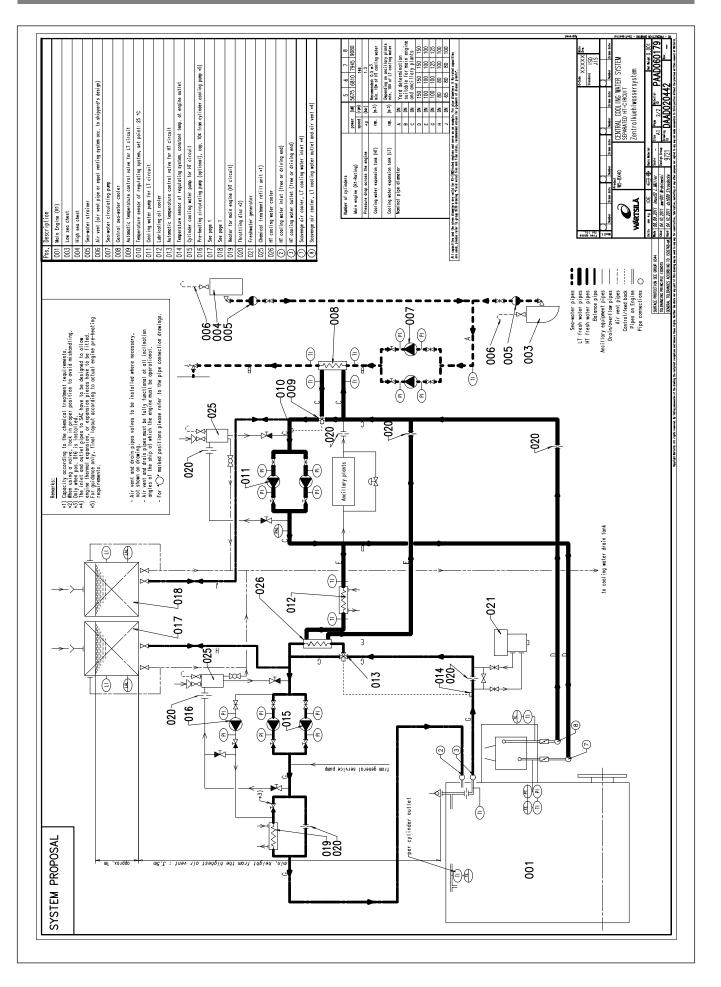
Another installation option is "thermo compression" instead of mechanical compression. Steam flows at high velocity through an ejector, creating the required vacuum for sea water evaporation, like the compressor in the mechanical installation, and draws through the created vapour. The steam-vapour mixture flows to the condenser side of the heat exchanger. The reduced steam velocity at this side increases the static pressure, and the steam condenses in the heat exchanger, heating the sea water in the evaporation chamber. The boiler feed water cannot be treated with the usual chemicals, owing to the mixing of vapour and steam.

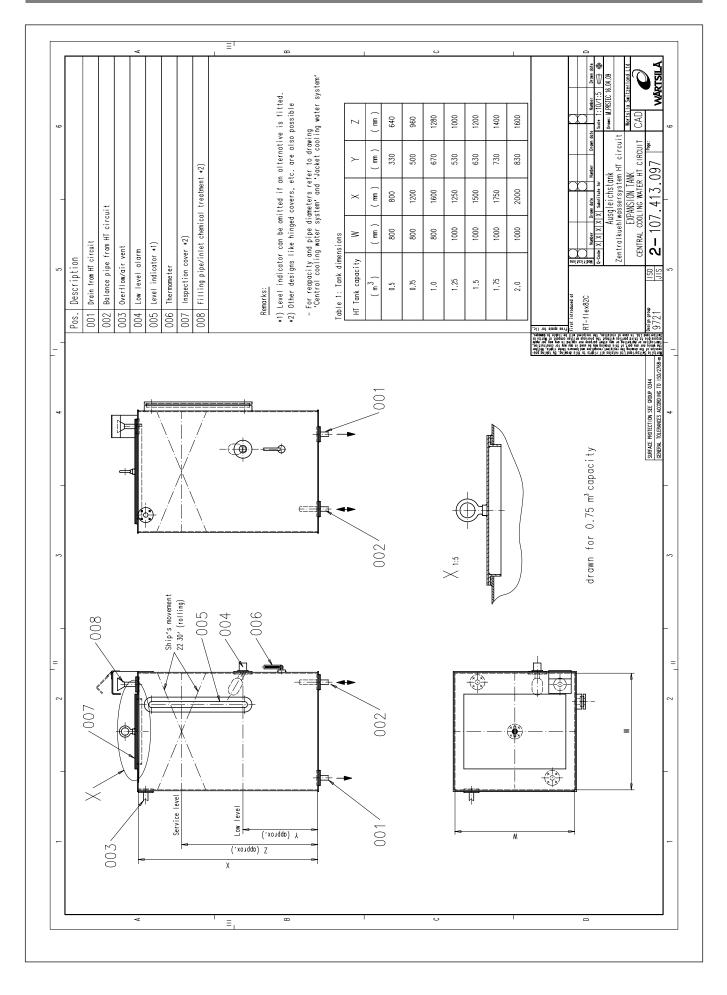
For further information on this FWG type, please contact your FWG maker.

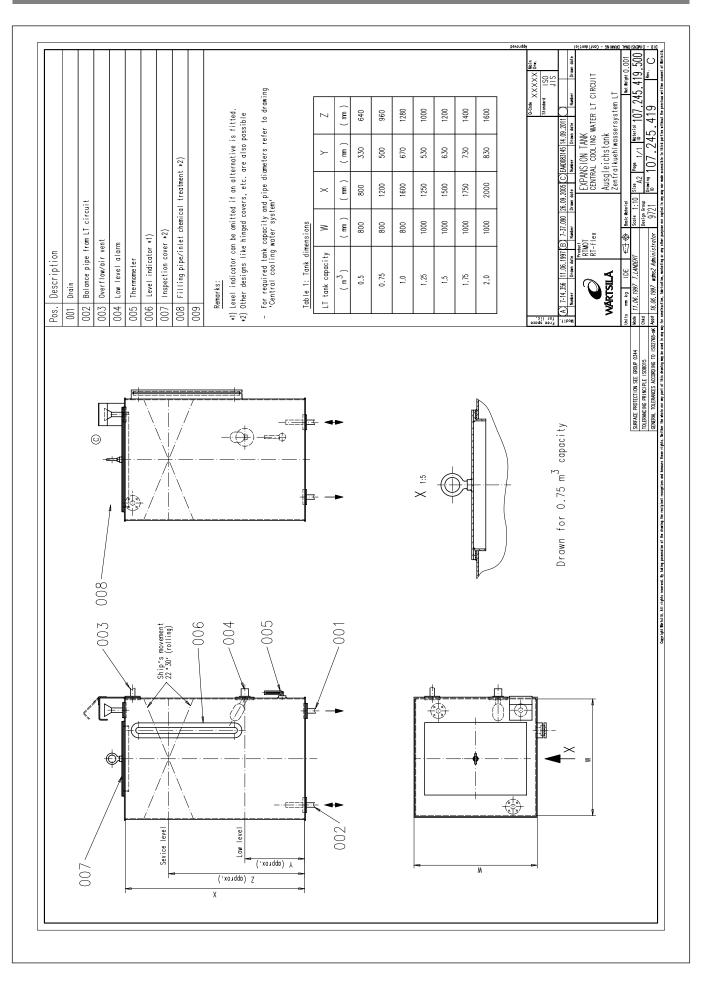
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5 Abbreviations					
AE	auxiliary engine				
CCW	cylinder cooling water				
CMCR	contracted maximum continuous rating				
CW	cooling water				
FW	fresh water				
FWG	fresh water generator				
	FWG types:				
	MEDmulti-effect distiller (tube type)MEPmulti-effect distiller (plate type)MSFmulti-stage flashROreverse osmosisVVCvacuum vapour compression				
ΗΤ	high temperature				
нтс	high temperature cooling water cooler				
LT	low temperature				
ME	main engine				
MIM	marine installation manual				
SW	sea water				
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9. Lubricating Oil Systems

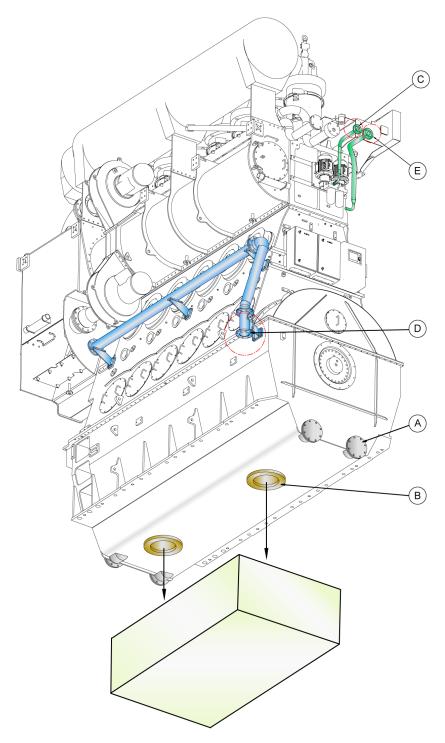


Figure 9.1: Pipe connections on the engine for the lubricating oil systems

A	Lubricating oil drain from bedplate horizontal (optional)	
	FOR TESTBED ONLY! Not connected.	
В	Lubricating oil drain from bedplate vertical	
	 Drain to lubricating oil drain tank: drain pipe positions to be clarified between shipyard and engine manufacturer 	
С	Cylinder lubricating oil outlet	
D	Lubricating oil inlet	
E	Cylinder lubricating oil inlet	

9.1 Lubricating oil systems for turbochargers

For lubricating oil of turbochargers equipped with separate lub. oil systems, the recommendations given by the supplier must be observed.

9.2 Main lubricating oil system

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

Lubrication of the main bearings, thrust bearings, bottom-end bearings, crosshead bearings, together with piston cooling, is carried out by the main lubricating oil system. The main bearing oil is also used to cool the piston crown as well as to lubricate and cool the torsional damper and the axial damper (detuner).

The consumption of system oil is given in chapter 1.1 Primary engine data.

9.3 Main lubricating oil system components

9.3.1 Lubricating oil pump

Positive displacement screw pumps with built-in overpressure relief valves, or centrifugal pumps (pump capacity see table 7.1 Data for central freshwater cooling system (integrated HT))

Positive displacement screw pump:	Refer to table 7.1. The given flow rate is to be within a tolerance of 0 to $+10\%$ plus back-flushing flow of automatic filter, if any.
Centrifugal pump:	Refer to table <i>7.1</i> . The given flow rate is to be within a tolerance of -10 to +10% plus back-flushing flow of automatic filter, if any.
Delivery head:	(See also table 7.1.) The final delivery head to be determined is subject to the actual piping layout.
Working temperature:	60°C
Oil type:	SAE30, 50 cSt at working temperature; maximum viscosity to be al- lowed for when sizing of pump motor is 400 cSt

9.3.2 Lubricating oil cooler

Oil flow: refer t	o table 7 <i>.1</i>
Type: plate	or tubular
Cooling medium: freshv	vater or seawater
Heat dissipation: refer t	o table 7.1
Margin for fouling: 10-15	% to be added
Oil viscosity at cooler inlet: 50 cS	t at 60°C
Oil temperature at inlet: appro	x. 60°C
Oil temperature at outlet: 45°C	
Working press. oil side: 6 bar	
Working press. water side: appro	x. 3 bar
Cooling water flow: refer t	o table 7.1
Cooling water temperature: freshv	vater 36°C

9.3.3 Lubricating oil full-flow filters

Туре*:	change-over duplex filter designed for in-service cleaning, with differ- ential pressure gauge and high differential pressure alarm contacts
Test pressure:	specified by classification society
Working pressure:	6 bar
Working viscosity:	95 cSt, at working temperature
Oil flow:	refer to table 7.1
Diff. pressure, clean filter:	max. 0.2 bar
Diff. pressure, dirty filter:	max. 0.6 bar
Diff. pressure, alarm:	max. 0.8 bar
Filter inserts bursting press.:	min. 8 bar (= differential pressure across the filter inserts)
Filter material:	stainless steel mesh
Mesh size:	sphere passing max. 0.034 mm

NOTICE

* Alternatively: Automatic back-flushing filter with differential pressure gauge and high differential pressure alarm contacts. Designed to clean itself automatically using reverse flow or compressed air techniques. The drain from the filter is to be sized and fitted to allow free flow into the residue oil tank. The output required by the main lubricating oil pump to 'back-flush' the filter without interrupting the flow is to be taken into account when estimating the pump capacity.

9.4 Cylinder lubricating oil system

Cylinder lubrication is carried out by a separate system, working on the once-through principle normally using a high-alkaline oil of SAE 50 grade. The cylinder lubricating oil is fed to the surface of the cylinder liner by a hydraulically actuated dosage pump through quills in the cylinder liner. The oil supply rate is adjustable and metered to suit the age and running condition of the piston rings and liners. The arrangement of service tank and storage tank can be changed by locating the storage tank in place of the service tank. If this arrangement is preferred, the storage tank is to be located at the same height as the service tank to provide the necessary head. Furthermore, it has to be of similar design, ensuring a sloping tank floor. For cylinder lubricating oil consumption refer to section *1.1 Primary engine data*.

9.5 Lubricating oil maintenance and treatment

It is essential that the engine lubricating oil is kept as clean as possible. Water and solid contaminants held in suspension are to be removed using centrifugal separators which operate in bypass to the engine lubricating system. Great care has to be taken of the separators and filters to ensure that they work correctly. The separators are to be set up as purifiers and completely isolated from the fuel oil treatment systems; there must be no possibility of cross-contamination.

9.5.1 Lubricating oil separator

Separator type:	self-cleaning purifier
Min. throughput capacity [I/h]:	0.140 x CMCR = [litres/hour], CMCR in kW For example 8-cyl. engine with CMCR at R1: 9,080 kW: 0.140 x 9,080 = 1,271 l/h.
Rated separator capacity:	The rated or nominal capacity of the separator is to be according to the recommendations of the separator manufacturer.
Separation temperature:	90-95°C; refer to manufacturer's instructions.

9.6 Lubricating oil requirements

The products listed in section 9.6.1 were selected in co-operation with the oil suppliers and in their respective product lines are considered as appropriate lubricants for the application indicated. Wärtsilä Switzerland Ltd. does not accept any liability for the quality of the supplied lubricating oil or its performance in actual service. In addition to the oils shown in the mentioned list, there are other brands which might be suitable for use in Wärtsilä two-stroke diesel engines. Information concerning such brands may be obtained on request from Wärtsilä Switzerland Ltd.

For normal operating conditions, a high-alkaline marine cylinder oil of SAE 50 viscosity grade with a minimum kinematic viscosity of 18.5 cSt at 100°C is recommended. The alkalinity of the oil is indicated by its Base Number (BN).

For the W-X40 engines designed with oil-cooled pistons, the crankcase oils typically used as system oil have the following properties (see also section *9.6.1*):

- Minimum BN of 5.0 mgKOH/g and detergent properties
- Load carrying performance in FZG gear machine test method A/8, 3/90 according to ISO 14635-1, failure load stage 11 as a minimum ¹⁾
- Good thermal stability
- Antifoam properties
- Good demulsifying performance

1) The FZG gear machines located at the FZG Institute, Munich/Germany shall be the reference test apparatus and will be used in the event of any uncertainty about test repeatability and reproducibility.

9.6.1 List of lubricating oils

Global brands of lubricating oils

Oil Supplier	System Oil	Cylinder Oil *a)	Cylinder Oil *b)
		Recommended for fuel with sulphur content > 1.5%	Recommended for fuel with sulphur content < 1.5%
ВР	Energol OE-HT 30	Energol CLO 50M	Energol CL-DX 405 Energol CL 505 *c)
Castrol	CDX 30	Cyltech 80 AW Cyltech 70	Cyltech 40 SX Cyltech 50 S *c)
Chevron (FAMM, Texaco, Caltex)	Veritas 800 Marine 30	Taro Special HT 70	Taro Special HT LS 40
ExxonMobil	Mobilgard 300 Exxmar XA	Mobilgard 570 Exxmar X 70 Mobilgard XN5744E *d)	Mobilgard L 540
T _4_1	Atlanta Marina D 2005	Talusia HR 70	Talusia LS 40
Total	Atlanta Marine D 3005	Talusia Ur	niversal *e)
Shell	Melina S30 Melina 30	Alexia 50	Alexia LS

Table 9.1: Global brands of lubricating oils

NOTICE

*a) With a sulphur content in the fuel between 1.5 and 2.0%, BN 40 can also be used.

*b) With a sulphur content in the fuel between 1.0 and 1.5%, BN 70 can be used only for a short period with low feed rate.

*c) This BN 50 cylinder lubricant can be used with up to 3.0% sulphur content in the fuel.

*d) This BN 60 cylinder oil is approved for a sulphur content in the fuel between 1.5 and 4.0%.

*e) This BN 57 cylinder lubricant can be used over the whole sulphur content range.

Local brands of lubricating oils

Oil Supplier	System Oil	Cylinder Oil *a)	Cylinder Oil *b)
		Recommended for fuel with sulphur content > 1.5%	Recommended for fuel with sulphur content < 1.5%
AGIP	Cladium 50	Punica 570	
Bardahl		Naval 50	
FL Selenia	MESYS 3006	MECO 5070	
LUKOIL	Navigo 6 SO	Navigo 70	MCL
SeaLub Alliance	GulfSea SuperBear 3008	GulfSea Cylcare DCA5070H	
юс	Servo Marine 0530	Servo Marine 7050	
JX Nippon Oil & Energy Corporation (NOC)	Marine S30	Marine C705	
Pertamina	Medripal 307	Medripal 570	
Petrobras	Marbrax CAD-308	Marbrax CID-57	Marbrax CID-54-AP Marbrax CID-55 *c)
PetroChina	KunLun DCC3008	KunLun DCA 5070H	
SK	Supermar AS	Supermar Cyl 70 plus	
*1 Limited to bore size of 62 cm		·	

Table 9.2: Local brands of lubricating oils

NOTICE

The application must be in compliance with the Wärtsilä general lubricating oil requirements and recommendations. The supplying oil company undertakes all responsibility for the performance of the oil in service to the exclusion of any liability of Wärtsilä Switzerland Ltd.

9.7 Lubricating oil drain tank

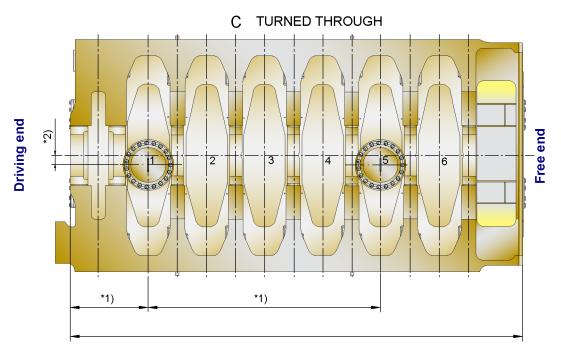
The engine is designed to operate with a dry sump; the oil returns from the bearings, flows to the bottom of the crankcase and through strainers into the lubricating oil drain tank. The drain connections from the crankcase to the drain tank are arranged vertically. There is to maintain adequate drainage under sea conditions resulting in pitching and rolling. Section 9.7.2 gives the minimum angles of inclination at which the engine is to remain fully operational.

The drain tank is to be located beneath the engine and equipped with the following:

- Depth sounding pipe
- · Pipe connections for lubricating oil purifiers
- · Heating coil adjacent to pump suction
- Air vents with flame protection

The classification societies require that all drain pipes from the crankcase to the drain tank are taken as low as possible below the free surface of the oil to prevent aeration and foaming; they have to remain below the oil surface at all times. Strict attention has to be paid to this specification. The amount of lubricating oil required for an initial charge of the drain tank is indicated in fig. 9.5. The total tank size is normally 5-10% greater than the amount of lubricating oil required for an initial filling (see fig. 9.5).

9.7.1 Arrangement of vertical lubricating oil drains





NOTICE

*1) Proposal to determine final position in accordance with shipyard.

*2) Alternatively the oil drains may also be arranged symmetrically on port/fuel pump side.

The illustration above does not necessarily represent the actual configuration or the stage of development, nor the type of your engine. For all relevant and prevailing information consult the drawings a the end of this chapter.

9.7.2 Min. inclination angles at which the engine is to remain fully operational

	Classification societies						
	American Bureau of Shipping	Bureau Veritas	China Classification Society	Croatian Register of Shipping	Det Norske Veritas 2005	Germanischer Lloyd	
	2007	2006	2002	-		2006	
Main and aux. engine							
Abbreviation	4/1/1/7.9	C/1/1/2.4			4/1/3/B 200	2/1.1/C.1	
Heel to each side	15°	15°	15°		15°	15°	
Rolling to each side	±22.5°	±22.5°	±22.5°		±22.5°	±22.5°	
Trim by the head *)	5°	5°	5°		5°	5°	
Trim by the stern *)	5°	5°	5°		5°	5°	
Pitching	±7.5°	±7.5°	±7.5°		±7.5°	±7.5°	
Emergency sets							
Abbreviation	4/1/1/7.9	C/1/1/2.4			4/1/3/B 200	2/1.1/C.1	
Heel to each side	22.5°	22.5°	22.5°		22.5°	22.5°	
Rolling to each side	±22.5°	±22.5°	±22.5°		±22.5°	±22.5°	
Trim	10°	10°	10°		10°	10°	
Pitching	±10°	±10°	±10°		±10°	±10°	
Electrical installation	1	1			1		
Abbreviation	4/1/1/7.9	C/1/1/2.4			4/8/3/B 100	2/1.1/C.1	
Heel to each side	22.5°	22.5°	15°		15°	22.5°	
Rolling to each side	±22.5°	±22.5°	±22.5°		±22.5°	±22.5°	
Trim	10°	10°	5°		5°	10°	
Pitching	±10°	±10°	±7.5°		±7.5°	±10°	

Table 9.3: Minimum inclination angles at which the engine is to remain fully operational (1)

	Classification societies						
	Korean Register of Shipping	Register of Register of Kaiji Rejestr	Registro Italiano Navale	Russian Maritime Register of Shipping			
	2007	2006	2005	2004	2007	2003	
Main and aux. engine				1			
Abbreviation		5/1/3.6	D/1.3	VI-1.6	C/1/1/2.4	VII-2.3	
Heel to each side	15°	15°	15°	15°	15°	15°	
Rolling to each side	±22.5°	±22.5°	±22.5°	±22.5°	±22.5°	±22.5°	
Trim by the head *)	5°	5°	5°	5°	5°	5°	
Trim by the stern *)	5°	5°	5°	5°	5°	5°	
Pitching	±7.5°	±7.5°	±7.5°	±7.5°	±7.5°	±7.5°	

	Classification societies						
	Korean Register of Shipping	of Register of	Nippon Kaiji Koykai	Polski Rejestr Statkow	Registro Italiano Navale	Russian Maritime Register of Shipping	
	2007	2006	2005	2004	2007	2003	
Emergency sets	·			·			
Abbreviation		5/1/3.6	D/1.3	VI-1.6	C/1/1/2.4	VII-2.3	
Heel to each side	22.5°	22.5°	22.5°	22.5°	22.5°	22.5°	
Rolling to each side	±22.5°	±22.5°	±22.5°	±22.5°	±22.5°	±22.5°	
Trim	10°	10°	10°	10°	10°	10°	
Pitching	±10°	±10°	±10°	±10°	±10°	±10°	
Electrical installation		· · · ·					
Abbreviation		6/2/1.9	H/1.1.7	VIII-2.1.2.2	C/2/2/1.6	XI-2.1.2.2	
Heel to each side		15°	15°	15°	15°	15°	
Rolling to each side		±22.5°	±22.5°	±22.5°	±22.5°	±22.5°	
Trim		5°	5°	5°	5°	5°	
Pitching		7.5°	±7.5°	±10°	±7.5°	±10°	

Table 9.4: Minimum inclination angles at which the engine is to remain fully operational (2)

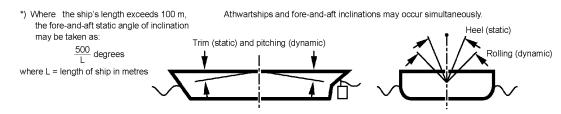


Figure 9.3: Minimum inclination angles at which the engine is to remain fully operational

Vertical lubricating oil drains to drain tank				
No Cyl. Necessary drains				
5	2			
6	2			
7	2			
8	2			
The arrangement of lubricating oil drains is to comply with the relevant classification society rules.				

Table 9.5: Vertical lubricating oil drains to drain tank

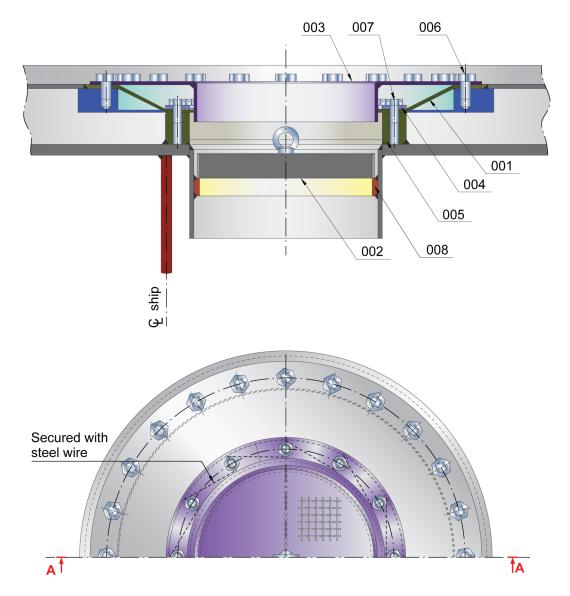
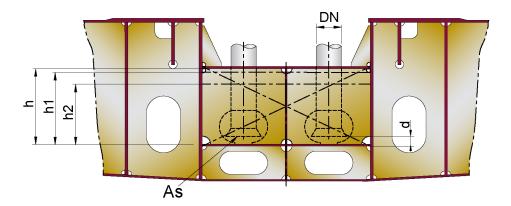


Figure 9.4: Example of an accepted vertical drain connection

001	Rubber gasket	005	Welding flange
002	Oil strainer	006	Hexagon head screw
003	Cover	007	Hexagon head screw
004	Ring	008	Support ring

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

9.7.3 Dimensioning guide-lines and filling process



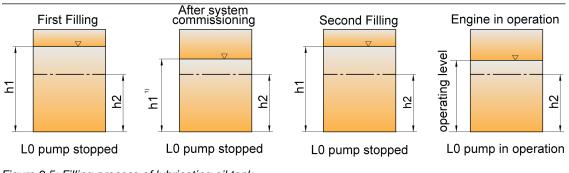


Figure 9.5: Filling process of lubricating oil tank

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

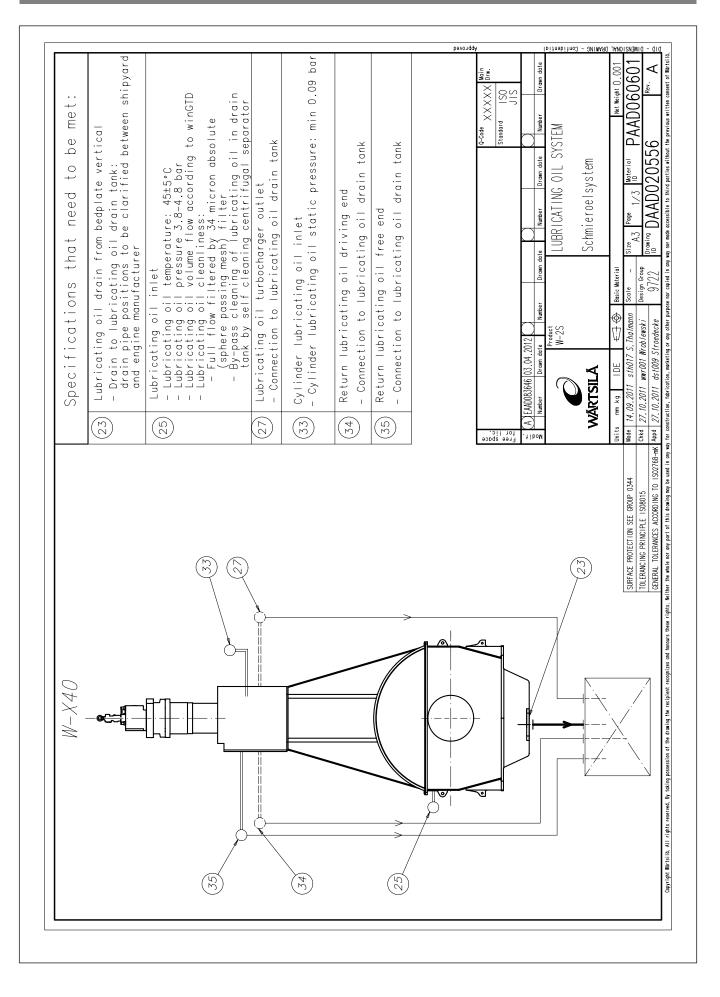
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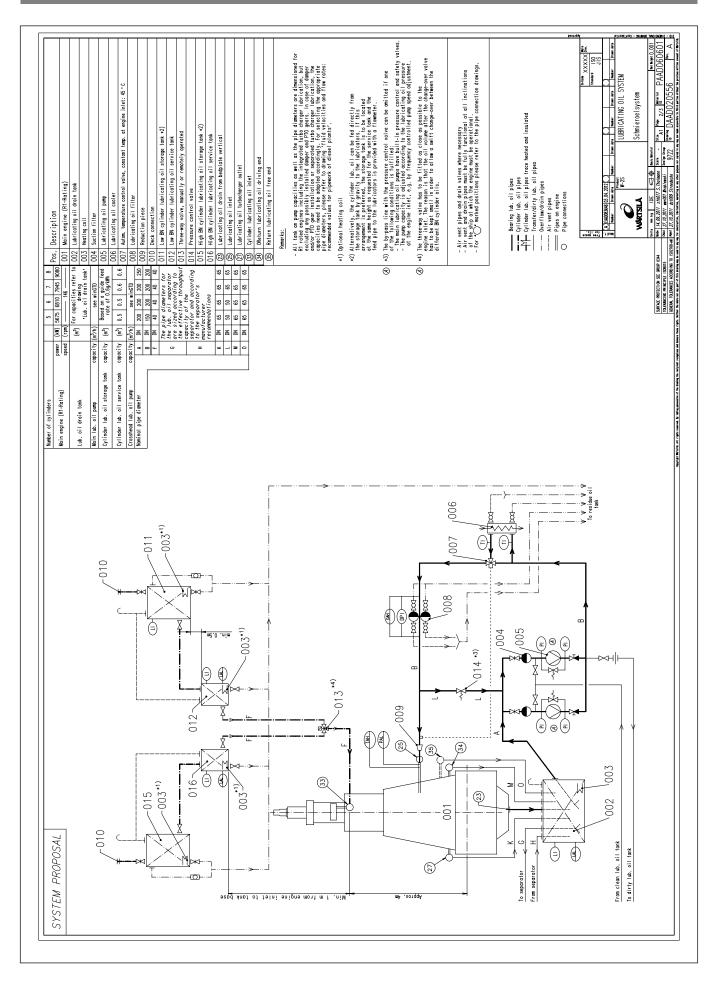
¹⁾ Level after filling of external system. Volume and level in the lub. oil drain tank depend on capacity of pipes, coolers, filters, etc. The oil volume in tank contains part of the oil quantity which drains back when the pumps are stopped.

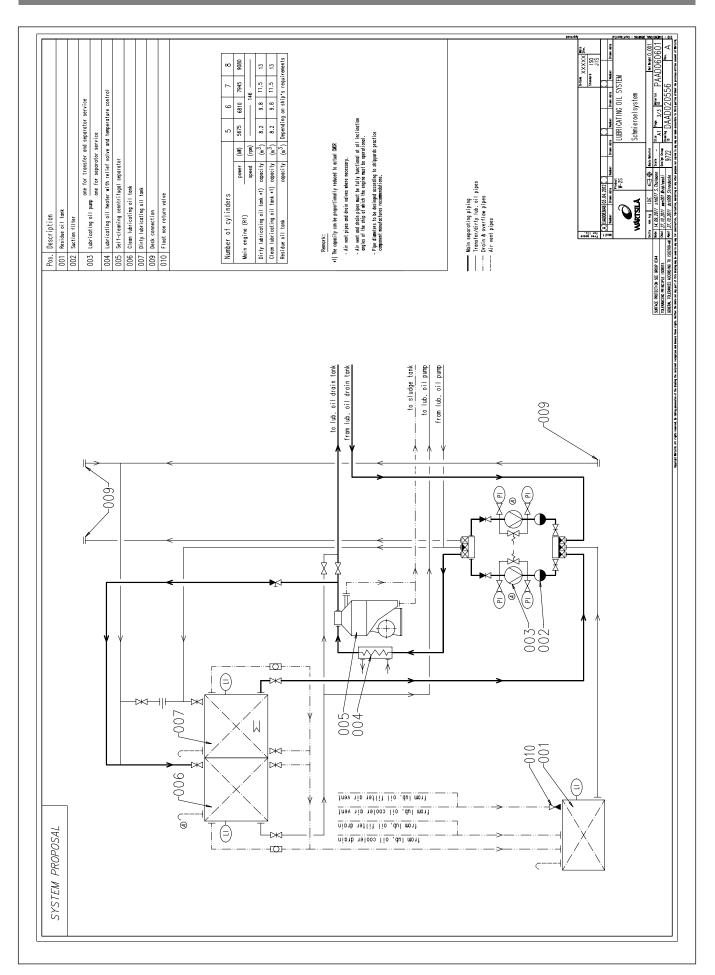
9.8 Drawings

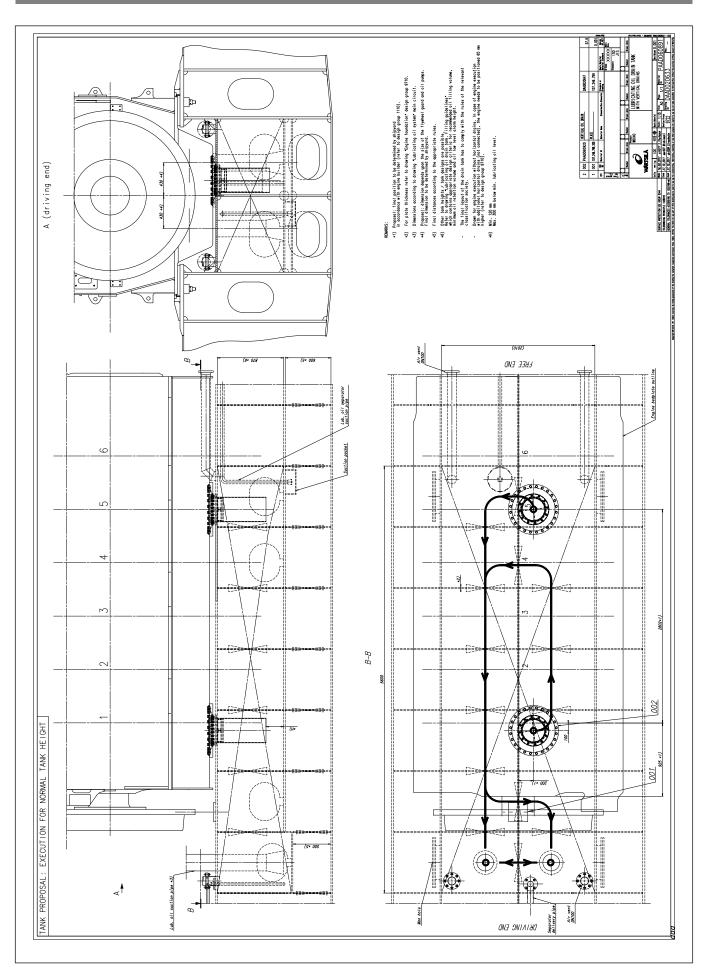
DAAD020638 -	Lubricating Oil System, With Vertical Drains, W6X40	9 9 14
DAAD020556 a	Lubricating Oil System, W6X40	
DAAD020633 -	Lubricating Oil Drain Tank, With Vertical Drains, W6X40	
107.246.799 e	Plate, To Hydraulic Jack, W6X40	
DAAD020647 -	Vertical Oil Drain, Assembly Drawing, W6X40	
DAAD013764 a	Rubber Gasket, Vertical Oil Drain, W6X40	
DAAD013848 -	Oil Strainer, Vertical Oil Drain, W6X40	
DAAD013964 -	Ring, Vertical Oil Drain, W6X40	
DAAD020639 -	Cover, Vertical Oil Drain, W6X40	
DAAD013657 -	Plate, Vertical Oil Drain, W6X40	
DAAD020573 -	Ring, Vertical Oil Drain, W6X40	
DAAD013763 -	Ring, Vertical Oil Drain, W6X40	
DAAD020574 -	Welding Flange, Vertical Oil Drain, W6X40	
DAAD013903 -	Support Ring, Vertical Oil Drain, W6X40	
107.341.455 a	Instruction For Flushing, Lubricating Oil System, W6X40	
DAAD020532 -	Lubricating Oil Drain Tank, Filling Guidelines, W6X40	

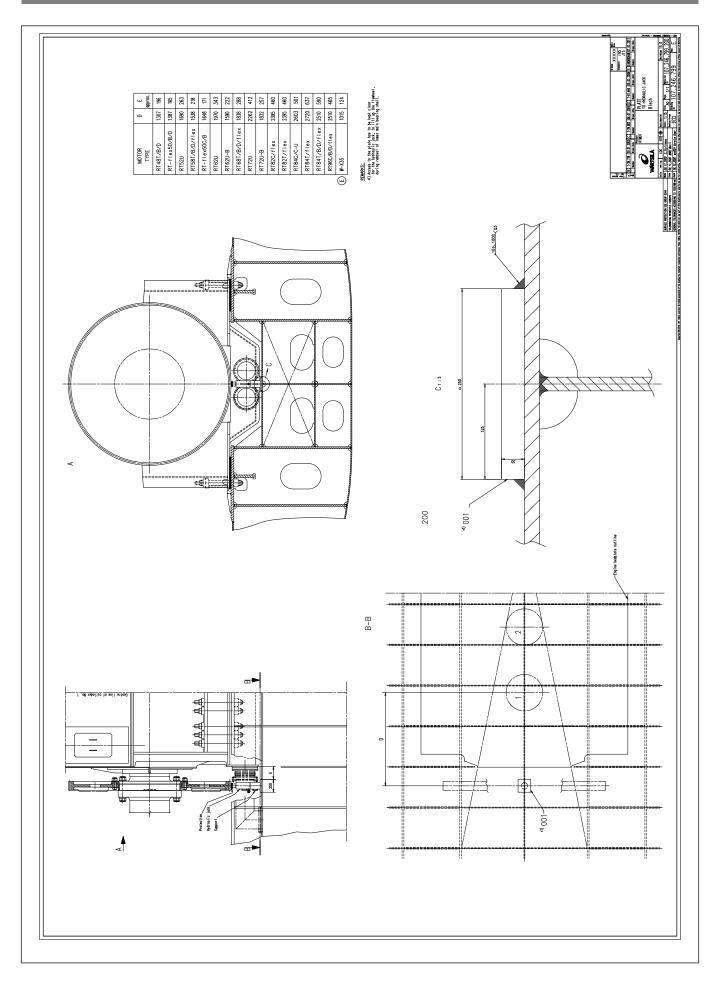
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for engine e ical drains	02 LUBRICATING OIL DRAIN TANK	500 INSTRUCTION FOR FLUSHING			Material Name		Drawn date Number	Product W6X40	÷ ۲		wr001 Wroblewski De st009 Stroedecke
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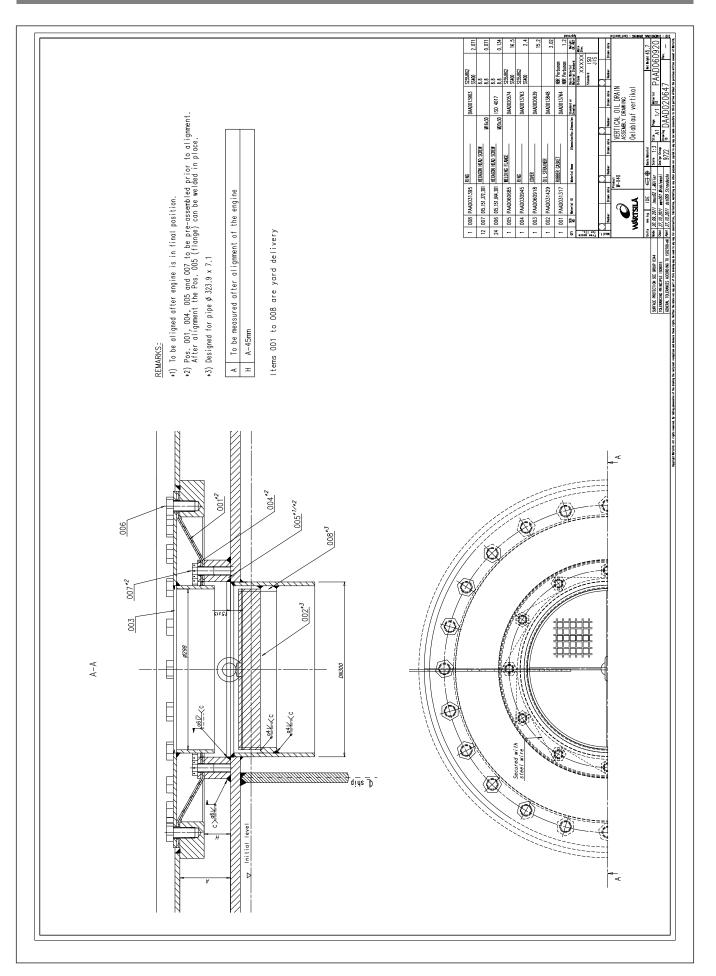


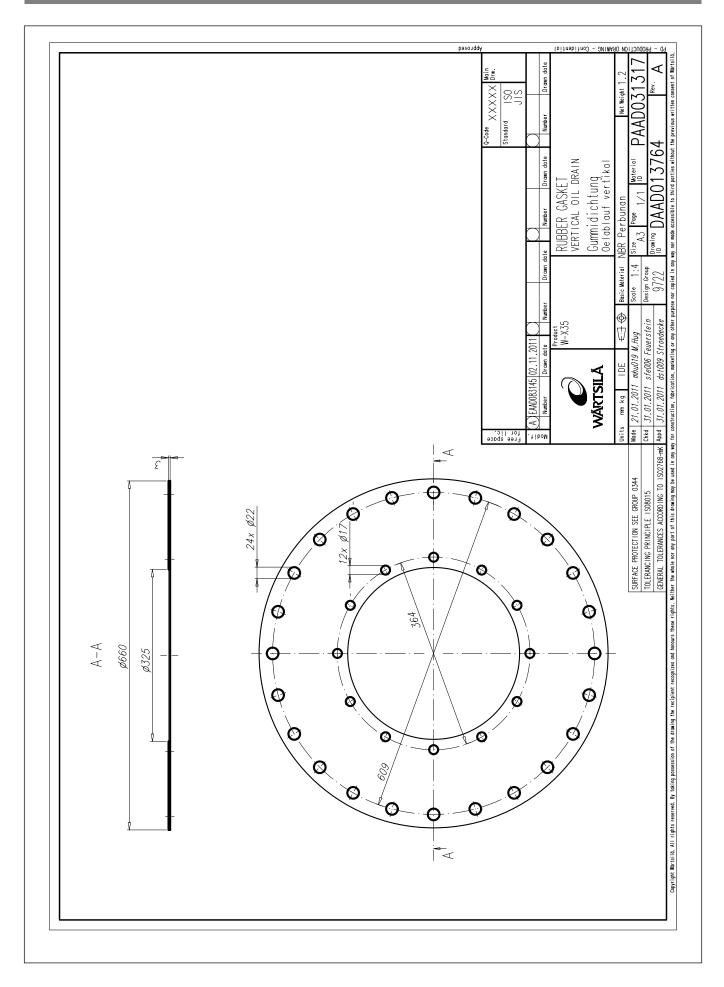


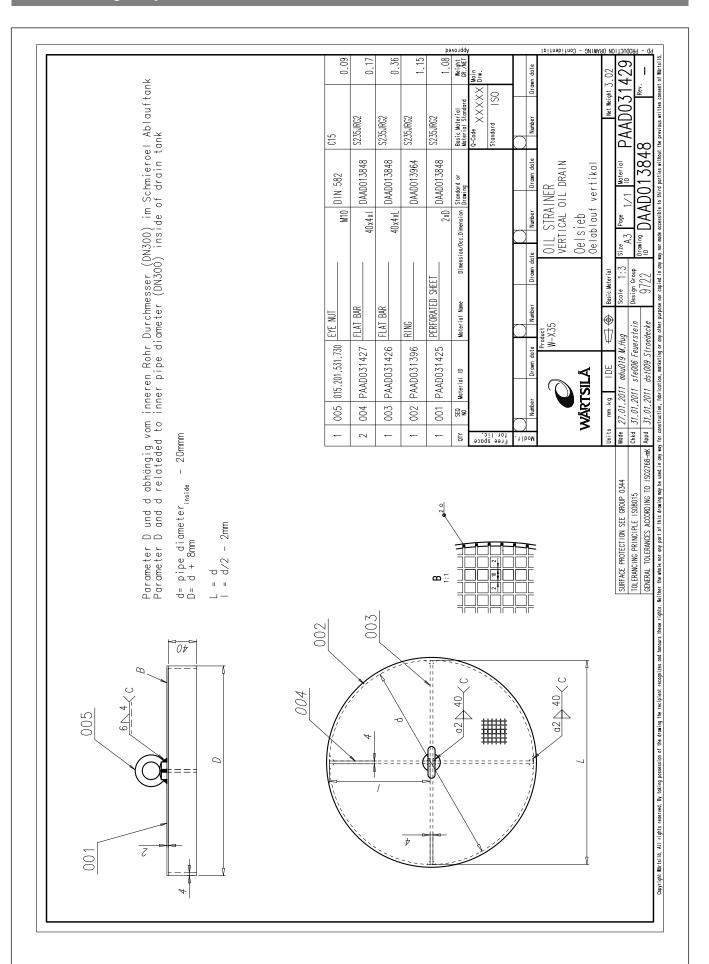


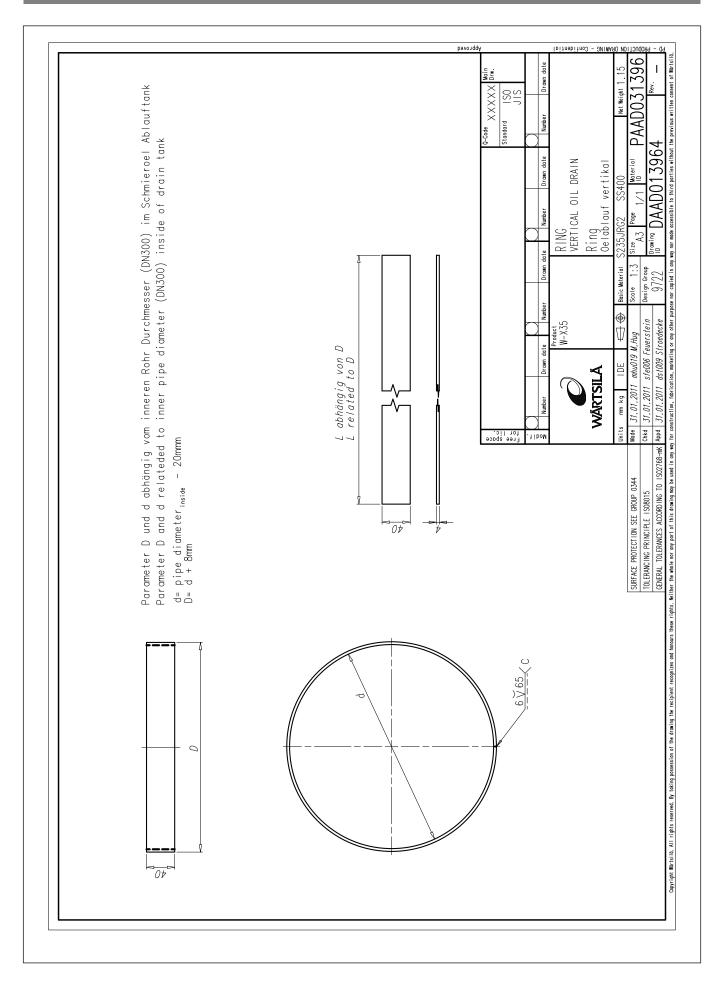




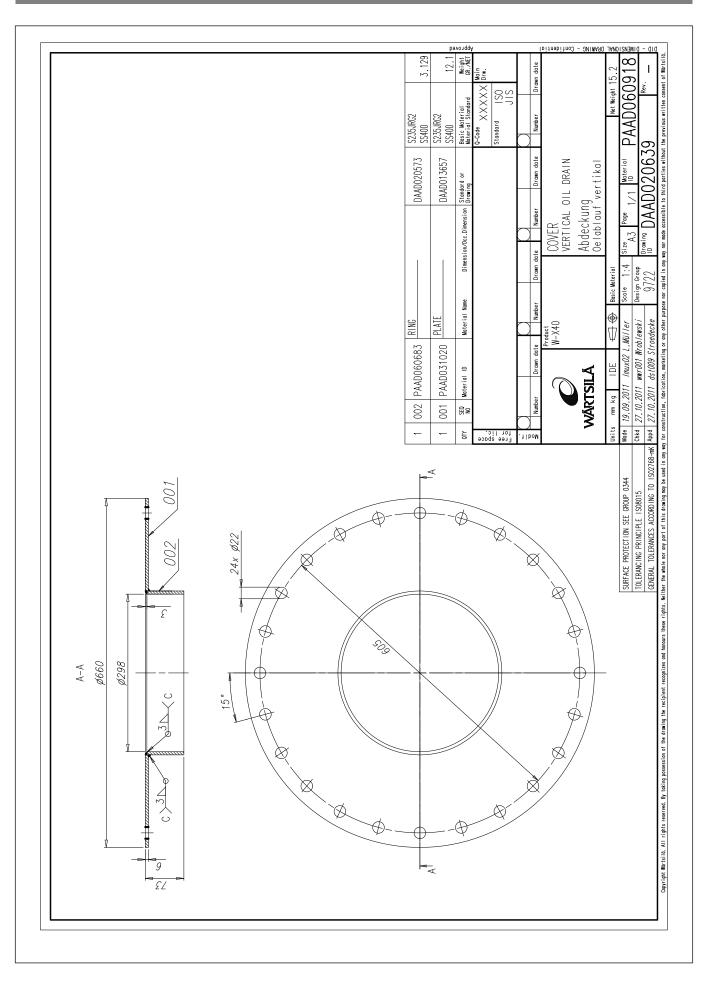




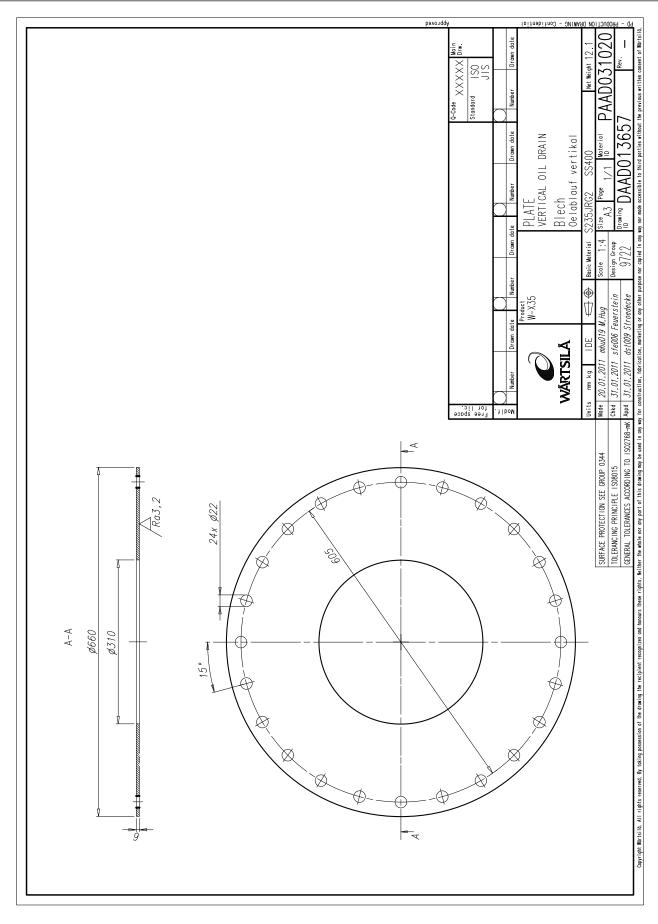


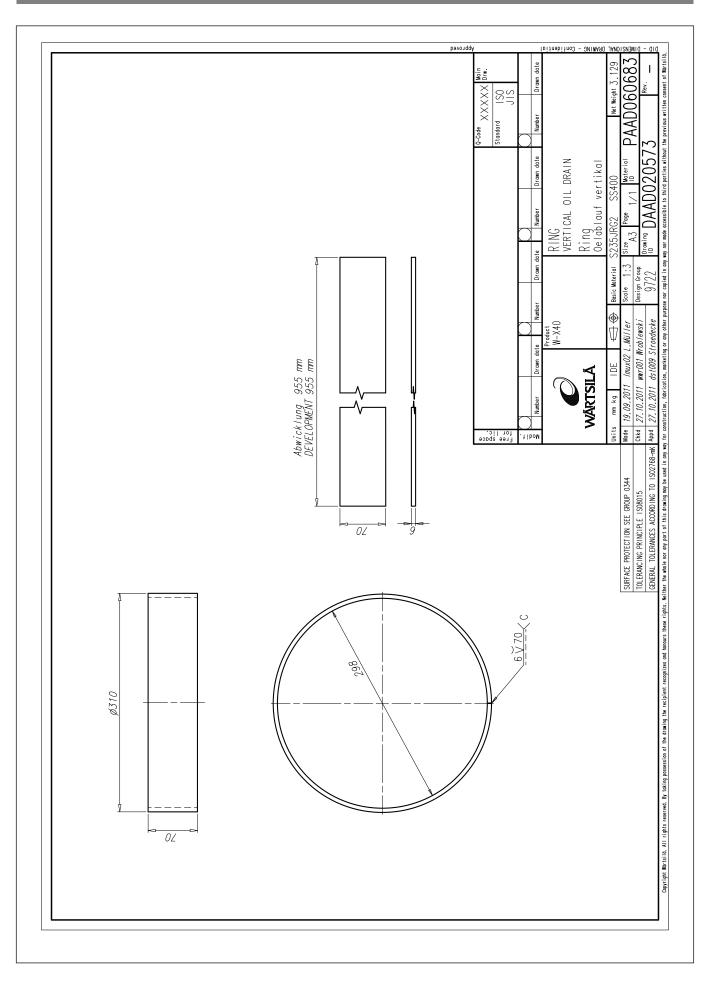


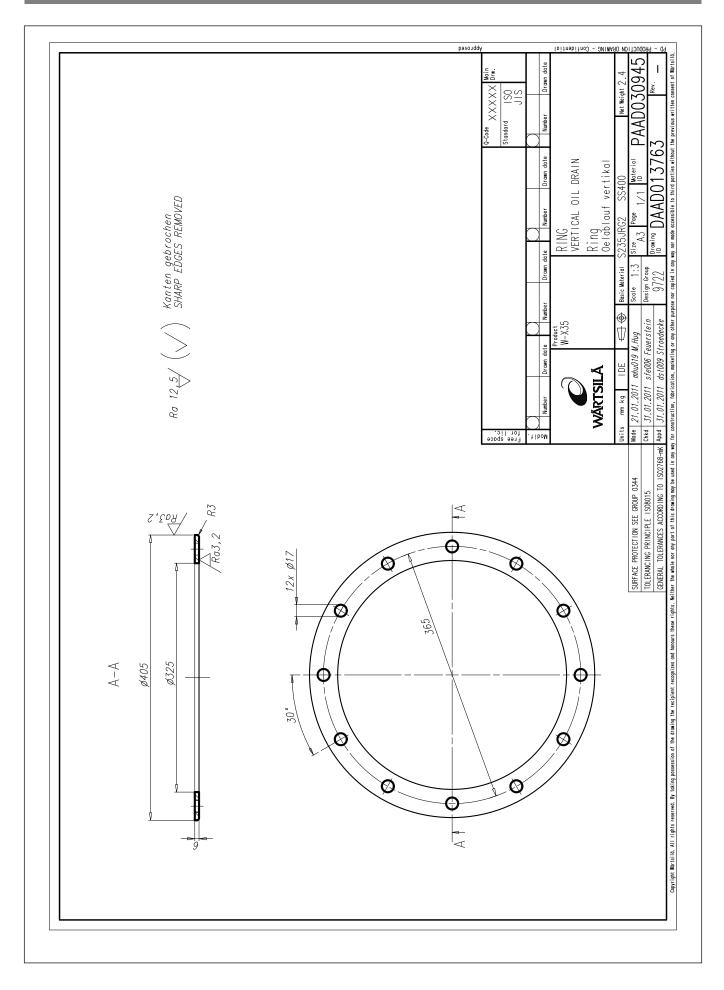


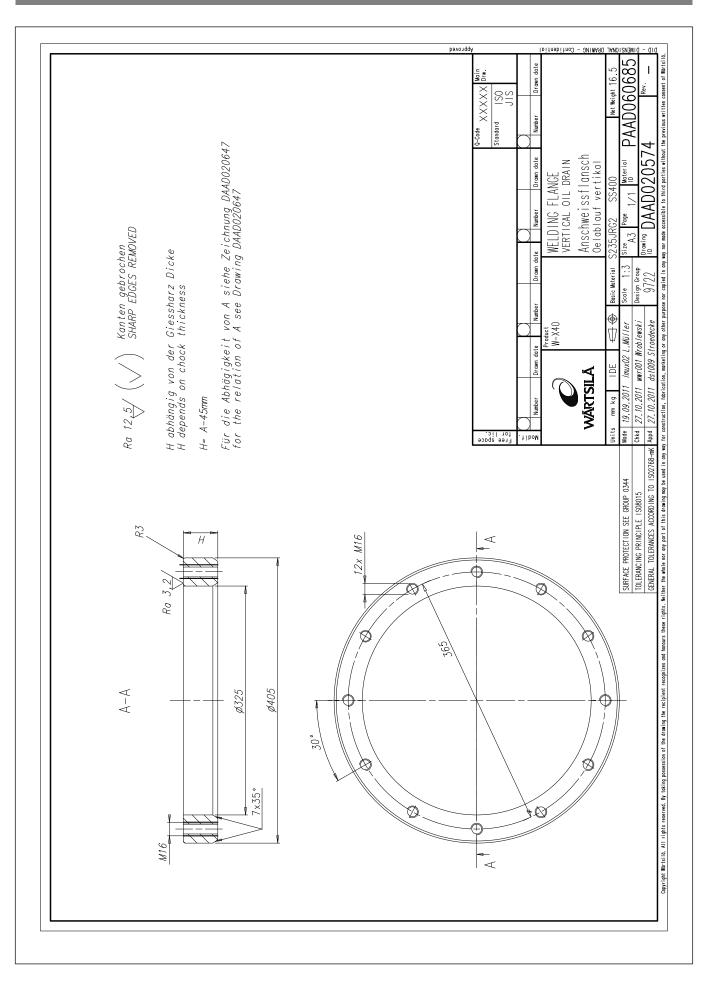


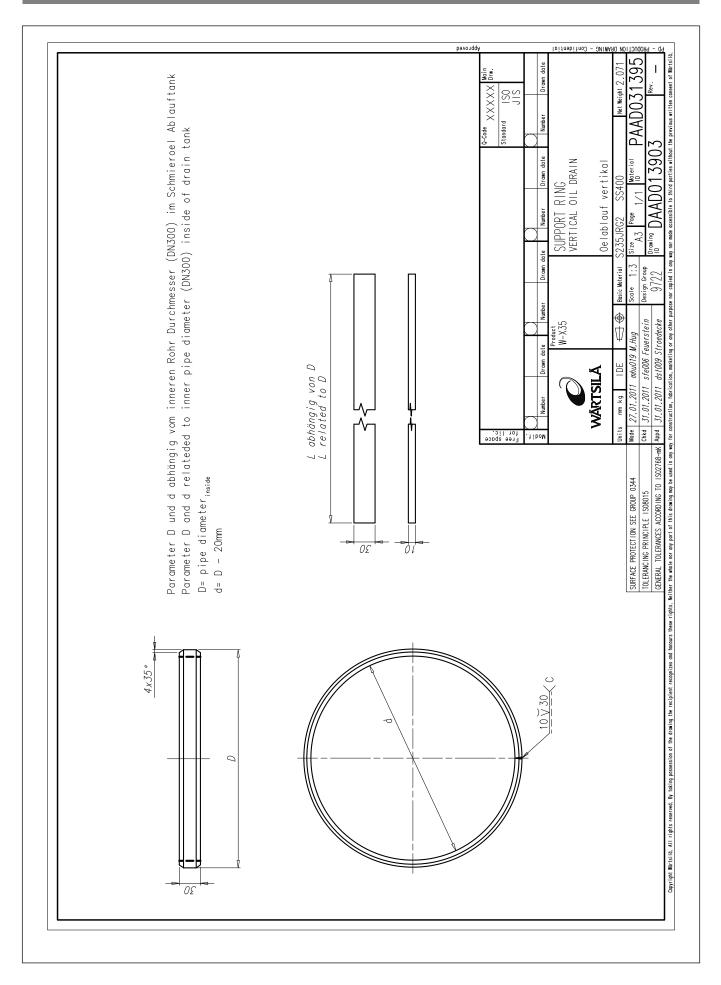












Flushing the lubricating oil system

1.1 Introduction

A correct manufacturing of the pipes avoids the presence of scales, slag and spelter. It is a fact that the expense for special welding methods, e.g. inert gas welding, is worthwhile when considering the costs of an extensive flushing procedure or the grinding and cleaning work if using normal electric arc welding or welding with electrodes. A thorough cleaning of the pipes before mounting is a must.

It is absolutely essential to ensure that the lubricating oil systems are clear of all foreign matter before circulating oil through to the engine. A systematic approach is to be adopted prior to commissioning when the engine, pipe work, filters, heat exchangers, pumps, valves and other components are flushed and are proved absolutely clear of any dirt by observation and physical inspection. The engine crankcase and lubricating oil drain tank are to be inspected and cleaned by hand to remove all residual build-debris; special attention is to be given to very small loose particles of welding matter such as spelter and slag.

The pipes of the entire lubricating oil system on the plant side are to be flushed separately.

1.2 Preparation before flushing

- 1. Led the lubricating oil connections immediately before the engine straight back into the lubricating oil drain tank by means of hoses or pipes see the figure.
- 2. Immediately before the engine, in the discharge pipes from the low-pressure and high-pressure lubricating oil pumps, install temporary filters with a mesh size (sphere passing) of max. 0.03 mm and equipped with magnetic elements. The surface loading of the temporary filters should be 1-2 l/cm²h. Alternatively, the plant lubricating oil filters can be used under the condition that the filter inserts are of mesh size of max. 0.03 mm and magnetic elements are used during flushing. After flushing, the filter inserts are to be replaced by the original ones and the filter housing is to be cleaned. In the final step of flushing, it is advisable to fit filter bag made of cotton or synthetic fabric of mesh size 0.040 to 0.050 mm to the end of the hoses or pipes, in order to facilitate checking the cleanliness of the system.
- 3. If the engine is supplied to the ship in sub-assemblies proceed as follows:
- Blank off each of the main bearing lubricating oil supply pipes at the main bearings in such a way that absolutely no oil can enter the bearing but oil can escape between pipe and blank piece.
- Blank off each of the crosshead lubrication linkage in that way, that absolutely no oil can enter the • bearing but oil can escape between linkage and blank piece.
- Blank off the oil supply of the axial damper in that way that absolutely no oil can enter the damper but oil can escape between pipe and blank piece.
- Disconnect respectively blank off all oil supply pipes to the supply unit, rail unit and the gear train.

1.3 Flushing external lubricating oil system

- 1. Fill the lubricating oil drain tank with sufficient oil to cover the pump suction and heat it up using tem-
- porary immersion heaters or the heating coil of the drain tank to approximately 40-60 °C. 2. Circulate the oil in the drain tank using the lubricating oil separators(s) and their pre-heater(s) to maintain the flushing temperature to improve oil cleanliness. Operate the separators(s) until all the flushing procedures are completed.
- 3. All system valves are to be fully open.
- 4. Good ventilation is to be provided to avoid condensation. At the exhaust side, the crankcase round covers are to be removed and on the fuel pump side the crankcase doors must be opened.
- 5. Flush the system by starting the low- and high- pressure lubricating oil pumps, the main and standby pumps are to be alternatively operated. Before starting the pumps, the oil cooler(s) might be bypassed at the beginning of the flushing procedure.

Circulate the oil through the pumps and hose connections back to the drain tank. Observe the suction and discharge pressures carefully. Do not let the pumps run hot. Observe the pressure drop through the filters, too.

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\.	<i>O</i> /ärtsilä		RTFL				INSTRUCTIONS FOR FLUSHING THE LUBRICATING OIL SYSTEM					Group 9722
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6. During the flushing procedure, the pipes are to be periodically tapped to help loosen any foreign matter that may be present. If available, vibrators are to be used. All pipes used during the engine operation must be flushed, including by-pass lines and the oil cooler(s). Drain the dirt of all equipment's (oil cooler(s), suction filters, etc.) where dirt can accumulate.

7. Inspect and clean the filters in the lubricating oil system periodically. Flushing is to be continued until filter bags remain clean and no residues can be found in the filters and; no metallic particles adhere to the magnetic filter inserts and no residues are detected in the bottom of the filter housing. When the system proves clean, remove any filter bags and connect the low- and high-pressure oil supply pipes to the engine.

1.4 Flushing within the engine

Only in the case of engines supplied to the ship in sub-assemblies.

1. Start up the low- and high- pressure lubricating oil pumps and flush through the engine for at least another 8 hours.

- 2. Inspect and clean the filter in the lubricating oil system periodically.
- 3. Flushing is to be continued until the filters are absolutely clean:

No metallic particles adhere to the magnetic inserts and no residues are detected in the bottom of the filter housing.

When the lubricating oil system proves clean, remove all blank pieces and temporary flushing filters. Any pipe-connecting piece, which was not flushed before, must be clean separately.

Drain the oil from the distribution pipe to the main bearings.

Inspect the inside of the pipes for eventual deposits. If clean, re-fit all oil pipes.

Make sure that all screwed connections are tight and secured.

Inspect the bottom of the crankcase and clean it if necessary.

1.5 Circulation of lubricating oil

- 1. Remove the inspection cover of the thrust bearing in main bearing girder #2.
- 2. Circulate the low- and high-pressure system for approximately two hours under normal operating pressure and temperature.
- 3. Observe the oil flow on all bearings, spray nozzles and any other engine component such as dampers for proper oil flow.
- 4. The turning gear is to be engaged to turn the engine from time to time. Carry out an inspection of the crankcase before refitting all the crankcase doors.
- 5. Check and clean the filters periodically.
- 6. To flush the by-pass line between the low- and high-pressure system on the engine, the regulating valve for adjusting the oil pressure to the main bearings must be throttled temporarily. During flushing the bypass, the high-pressure lubricating oil pump is to be stopped.

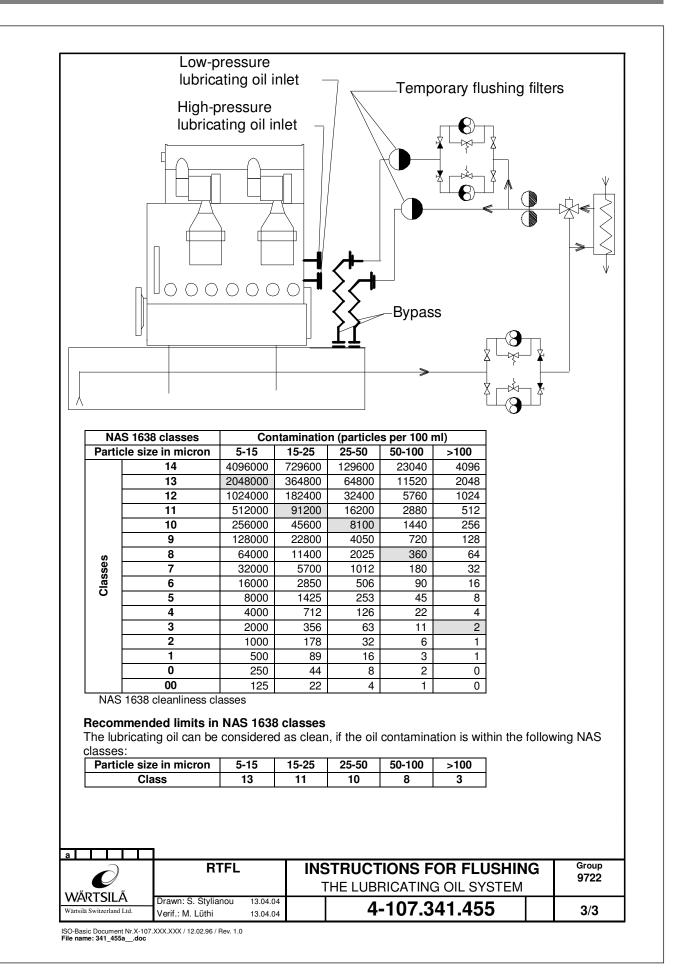
1.6 Cylinder oil supply system

It is absolutely essential to ensure that the cylinder oil system is clear of all foreign matter before connecting to the engine in order to safeguard the engine and assure proper operation. The storage and daily service tank are to be inspected and cleaned by hand to remove all residual build–debris, special attention is to be given to very small loose particles of welding matter such as spelter and slag.

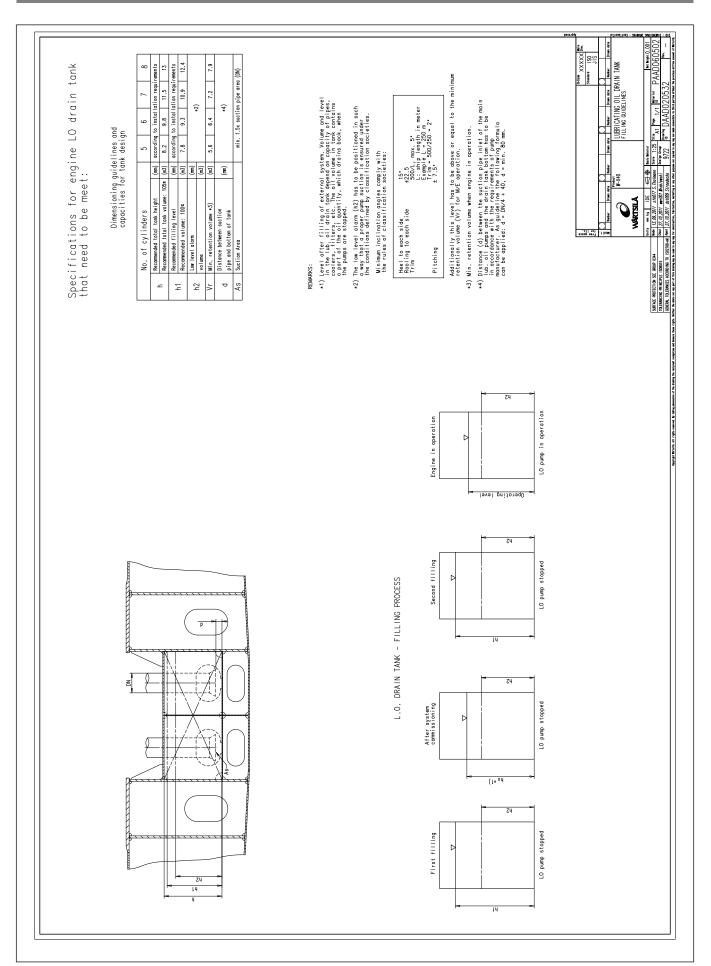
The complete piping, from the storage tank to the engine connection, has to be inspected and cleaned accordingly.

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	RTFL	INSTRUCTIONS FOR FLUSHING	Group 9722
		THE LUBRICATING OIL SYSTEM	9722
WÄRTSILÄ Wärtsilä Switzerland Ltd.	Drawn: S. Stylianou 13.04.04 Verif.: M. Lüthi 13.04.04	4-107.341.455	2/3

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Wärtsilä X40 Marine Installation Manual



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10. Fuel Oil System

A number of systems external to the engine are required to maintain heavy fuel oil and marine diesel oil in the quality required for efficient and reliable combustion.

10.1 Fuel oil requirements

In the folowing table the values in the column 'Bunker limit' indicate the minimum quality of heavy fuel as supplied to the installation. Good operating results have been achieved with all commercialised fuels within ISO 8217 limits. However, using fuel with lower density, ash and carbon residue content can have a positive influence on overhaul periods, by improving combustion, wear and exhaust gas composition.

The fuel oil as bunkered must be processed before it enters the engine. For the design of the fuel treatment plant, the relevant Wärtsilä recommendations have to be followed. The minimum centrifuge capacity is 1.2 x CMCR x BSFC / 1000 (litres/hour), which corresponds to 0.21 l/kW. The fuel oil treatment has to reduce catalyst fines and water to engine inlet limits.

ISO 8217 excludes adding foreign substances or chemical waste to the fuel, because of the hazards for the ship crew, machineries and environment. Testing for foreign substances like acids, solvents and monomers with titrimetric, infrared and chromatographic tests is not standard but recommended – because of the high likelihood of damage these substances can cause to fuel treatment, fuel pumps, fuel injection and piston running components.

Parameter	Unit	Bunker limit**	Test method *1)	Fuel quality (engine inlet)
Density at 15°C	kg/m ³	max. 1010 *2)	ISO 3675/12185	max. 1010
Kinematic viscosity at 50°C	mm²/s (cSt)	max. 700	ISO 3104	13-20
Carbon residue	m/m (%)	max. 22	ISO 10370	max. 22
Sulphur	m/m (%)	max. 4.5	ISO 8754/14596	max. 4.5
Ash	m/m (%)	max. 0.15	ISO 6245	max. 0.15
Vanadium	mg/kg (ppm)	max. 600	ISO 14597/IP501/470	max. 600
Sodium	mg/kg (ppm)	-	AAS	max. 30
Aluminium + Silicon	mg/kg (ppm)	max. 80	ISO 10478 / IP501 / 470	max. 15
Total sediment, potential	m/m (%)	max. 0.10	ISO 10307-2	max. 0.10
Water	v/v (%)	max. 0.5	ISO 3733	max. 0.2
Flash point	°C	min. 60	ISO 2719	min. 60
Pour point	۵°	max. 30	ISO 3016	max. 30

** ISO 8217:2005, class F, RMK700

*1) ISO standards can be obtained from the ISO Central Secretariat, Geneva, Switzerland (www.iso.ch).

*2) Limited to max. 991 kg/m3 (ISO-F-RMH700), if the fuel treatment plant (Alcap centrifuge) cannot remove water from high density fuel oil (excludes RMK grades).

- The fuel shall be free from used lubricating oil, a homogeneous blend with no added substance or chemical waste (ISO8217:2005-5-1).

10.1.1 Viscosity (see figure 10.1)

The recommended viscosity range at engine inlet is **13-20 cSt (mm2/s)**. The preheating temperature to reach 15 cSt is usually reported in bunker reports, but can also be estimated from the approximate viscosity/temperature chart in the engine instruction manual. Standard 380 cSt fuel (at 50°C) must be preheated to about 130°C.

The maximum viscosity of the bunkered fuel that can be used in an installation depends on the heating and fuel preparation facilities available. To achieve a good separation, the throughput and the temperature of the fuel going through the centrifuges must be adjusted in relation to the viscosity. Heating the fuel above 150°C to reach the recommended viscosity at engine inlet is not recommended, because the fuel may start to decompose and deposit.

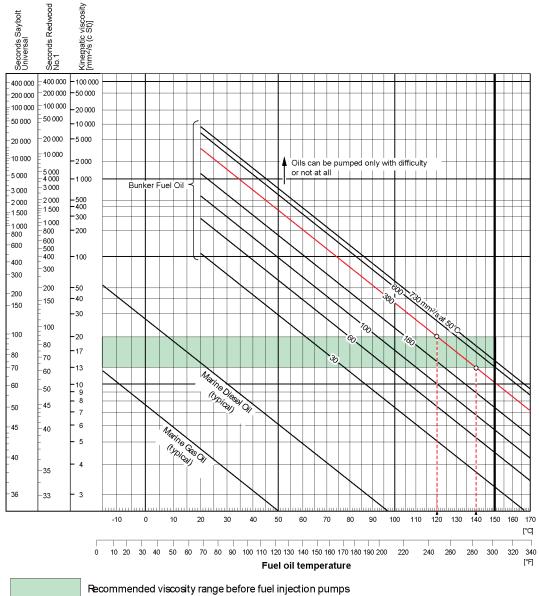




Figure 10.1: Typical viscosity / temperature diagram

Example:

To obtain the recommended viscosity before the fuel engine inlet, fuel oil of 380 mm²/s (cSt) at 50° C must be heated up to 120-140°C.

10.1.2 Carbon residue, asphaltenes sediment

The content of asphaltenes and related aromatic heavy fuel components is indicated by the carbon residue. These substances have high energy content, but high levels can impair the combustion quality of the fuel oil, promoting increased wear and fouling of engine components. An asphaltene content of up to 14% should be no problem.

The sediment potential is an indication for fuel stability. Asphaltenes must be kept solubilised to prevent problems of sludge formation in centrifugal separators and filters as well as on the tank bottom. Especially the addition of paraffinic distillates could cause the asphaltenes to settle out. To minimise compatibility risks, mixing bunkers from different suppliers and sources in storage tanks on board must be avoided. Onboard test kits are available to assess this risk.

10.1.3 Sulphur

The alkalinity of the cylinder lubricating oil, i.e. the base number (BN), should be selected with regard to the sulphur level of the fuel oil. When using a heavy fuel oil containing less than 1% sulphur, a low BN cylinder lubricant has to be used.

10.1.4 Ash and trace metals

Fuel oils with low contents of ash are preferable. Especially vanadium and sodium tend to promote mechanical wear, high-temperature corrosion and the formation of deposits in the turbocharger and on the exhaust valve. Sodium compounds depress the melting point of vanadium oxide and sulphate salts, especially when the vanadium to sodium ratio is 3:1. High sodium levels (as well as lithium and potassium) at engine inlet can cause fouling of turbocharger components. The effect of high-temperature corrosion and the formation of deposits can be counteracted by the application of ash modifiers.

10.1.5 Aluminium, silicon

Aluminium and silicon in the fuel oil are regarded as an indication of catalytic fines (cat fines), i.e. porcelain-like round particles used in petroleum refining. They cause high abrasive wear to piston rings and cylinder liners over a prolonged time period when embedded in the ring and liner surface. The most dangerous are cat fines with a diameter of 10-20 micron, which corresponds to common clearances and oil film thickness.

Cat fines tend to be attracted to water droplets and are very difficult to remove from the fuel oil, even more so when used lub. oil is present. Practical experience has shown that with proper treatment in the fuel oil separator, the aluminium and silicon content of 80 mg/kg can be reduced to 15 mg/kg, which is considered as just tolerable. For efficient separation, a fuel temperature as close as possible to 98°C is recommended. With more than 40 ppm cat fines in the bunkered fuel, reduced throughput in the separator is recommended.

Cat fines can accumulate in the sediment of the fuel tank from previous bunkers and be mixed into the fuel when the sediment is churned up in bad weather. For this reason all fuels should be assumed to contain cat fines, even if this is not apparent from the fuel oil analysis, making continuous and efficient centrifugation a paramount importance.

10.1.6 Water

The water content of the fuel oil must be reduced by centrifuging and by the use of proper draining arrangements on the settling and service tanks. A thorough removal of water is strongly recommended to ensure homogenous injection and to reduce the content of hydrophilic cat fines and sodium in the fuel oil. Sodium is not a natural oil component, but marine fuel oil is often contaminated with seawater containing sodium. A content of 1.0% seawater in the fuel oil corresponds to 100 ppm sodium.

10.1.7 Flash point

This is a legal requirement with regard to the fire hazards of petroleum based fuels.

10.1.8 Pour point

The operating temperature of the fuel has to be kept 5-10°C above the pour point to secure easy pumping.

10.1.9 Ignition quality

Contaminants, unstable fuels and incorrect injection (temperature, timing, nozzle wear) are the main reasons for incomplete or improper combustion. Some fuels cause more combustion problems by nature. These can possibly be detected by looking at the unnatural ratio between viscosity and density (CCAI) and by using combustion analyzing equipment like FIA tests.

10.2 Fuel oil treatment

10.2.1 Settling tanks

Gravitational settling of water and sediment from modern heavy fuel oils is an extremely slow process due to the small difference in densities. The settling process is a function of the fuel surface area of the tank to the viscosity, temperature and density difference. Heated large-surface area tanks enable better separation than heated small-surface area tanks.

10.2.2 Service tanks

Most of the service tank design features are similar to the settling tank, having a self-closing sludge cock, level monitoring device and remote closing discharge valves to the separator(s) and engine systems. The service tank is to be equipped with a drain valve arrangement at its lowest point, an overflow to the overflow tank, and recirculating pipework to the settling tank. The recirculation pipe reaches to the lower part of the service tank to guide water which may be present in the fuel after the separators (e.g. due to condensation or coil leakage) into the settling tank. A pipe to the separators should be provided to reclean the fuel in case of dirty water contamination. This line should be connected just above the drain valve at the service tank bottom.

The fuel is cleaned either from the settling tank to the service tank or recirculating the service tank. Ideally, when the main engine is operating at CMCR, the fuel oil separator(s) should be able to maintain a flow from the settling tank to the service tank with a continual overflow back to the settling tank. The sludge cock is to be operated at regular intervals to observe the presence of water, a significant indication for the condition of the separator(s) and heating coils.

Diesel oil service tanks are similar to heavy oil service tanks, with the possible exception of tank heating, although this may be incorporated for vessels constantly trading in cold climates.

10.2.3 Centrifugal separators

Separator type - self-clean- ing:	It is advisable to use fuel oil separators without gravity discs to meet the process requirements of the marine diesel oil and 730 cSt heavy fuel oils. These separators are self-adjusting and do not require gravity discs to be changed for different fuel densities. The manufacturers claim extended periods between overhaul and greatly improved reliability, enabling unattended onboard operation. The required minimum effective throughput capacity of the separators is determined as shown in the following example. The nominal separator capacity and the installation are to comply with the recommendations of the separator manufacturer.
Throughput capacity =	1.2 x CMCR x BSFC / 1000 [litres/hour]
Example:	8-cyl. engine with CMCR R1:
	• CMCR: 9,080 kW

- ,
- BSFC: 175 g/kWh

Throughput = $1.2 \times 9,080 \times 175$ (see table 1.1 Primary engine data) / 1000 = 1,907 litres/hour

The marine diesel oil (MDO) separator capacity can be estimated using the same formula.

Separator without gravity disc:

One of the main features of the self-adjusting separators is that only a single unit is required. This unit operates as a combined purifier/clarifier. However, as it is usual to install a standby separator as a back-up, it is of advantage to use the separator to improve the separation result. For the arrangement of the separators, parallel or in series, refer to the manufacturer's instructions.

Separator with gravity disc:

These types are running in series with the fuel being purified in one and clarified in the other; thus two separators are required. The clarifier improves the separation result and acts as a safety device in case the purifier is not properly adjusted. When processing heavy fuel oils it is indispensable to strictly adhere to the separator manufacturer's instructions. If using these separators it will be advantageous to install an extra separator for marine diesel oil, only to avoid the changing of gravity discs when changing over from HFO to MDO separation.

Separation efficiency

The separation efficiency is a measure of the separator's capability to remove specified test particles. The separation efficiency is defined as follows:

• $n = 100 \cdot (1 - C_{out}/C_{in})$

where :

n separation efficiency (%)

Cout number of test particles in cleaned test oil

C_{in} number of test particles in test oil before separator

The term Certified Flow Rate (CFR) has been introduced to express the performance of separators according to a common standard. CFR is defined as the flow rate in I/h 30 minutes after sludge discharge, at which the separation efficiency of the separator is 85%, when using defined test oils and test particles. CFR is defined for equivalent fuel oil viscosities of 380 cSt and 700 cSt at 50°C. More information can be found in the CEN (European Committee for Standardisation) document CWA 15375:2005 (E).

10.3 Heavy fuel oil system components

10.3.1 Fuel oil feed pump

Pump type:	 positive displacement screw pump with built-in overpressure relief valve
Pump capacity:	refer to table 7.1; the given capacity is to be within a tolerance of 0 to $+20\%$
Fuel type:	. marine diesel oil and heavy fuel oil, up to 730 cSt at 50°C
Working temperature:	ambient to 90°C
Delivery pressure:	The delivery pressure is to take into account the system pressure drop and prevent entrained water from flashing off into steam by ensuring that the pressure in the mixing unit is at least 1 bar above the water vapour pressure and no lower than 3 bar. The water vapour pressure is a result of the system temperature and pressure for a given fuel type. Heavier oils need more heat and higher temperatures to maintain them at the correct viscosity than lighter oils; refer to the following formula and example: Delivery gauge pressure = $p_v + 1 + \Delta p_1 + \Delta p_2$ [bar]
NOTICE	
p _v =	water vapour gauge pressure at the required system temperature [bar] (see viscosity/ temperature diagram fig. 10.1)
Δp ₁ =	maximum pressure losses between the feed pumps and the mixing unit [bar]
Δp ₂ =	maximum pressure change difference across the pressure regulating valve of the feed system between minimum and maximum flow; refer to <i>10.3.2</i>

Example

HFO of 730 cSt at 50°C

Required system temperature:	approx. 145°C
Water vapour gauge pressure at 145°C:	pv = 3.2 bar
Press. losses betw. feed pump and mixing unit:	Δp1 = 0.5 bar
Pressure change difference across the pressure	
regulating valve:	$\Delta p2 = 0.6 \text{ bar}$
Substituting these values in the formula:	delivery pressure = 3.2 + 1 + 0.5 + 0.6 = 5.3 bar

Electric motor

The electric motor driving the fuel oil feed pumps shall be sized large enough for the power absorbed by the pump at maximum pressure head (difference between inlet and outlet pressure), maximum fuel oil viscosity (600 cSt) and the required flow.

10.3.2 Pressure regulating valve

The pressure regulating valve maintains the inlet pressure to the booster system practically constant, irrespective of the actual amount of fuel consumed by the main engine and the auxiliaries. It should have a flat steady state characteristic across the fuel oil recirculation flow range.

Valve type:	Self- or pilot-operated which senses the upstream pressure to be maintained through an external line. It is to be pneumatically or direct hydraulically actuated with an additional manual control for emergency operation. When using a pneumatic type, use a combined spring type to close the valve in case of air supply failure.
Fuel oil viscosity:	100 cSt, at working temp. (HFO 730 cSt at 50°C)
Maximum capacity:	refer to feed pump capacity in table 7.1
Minimum capacity:	approx. 20% of that of the feed pump
Service pressure:	max. 10 bar
Pressure setting range:	2-6 bar
Inlet pressure change:	\leq 0.8 bar, between 20 and 100% flow (upstream pressure build-up over the valve capacity; between the minimum and maximum flow capacity)

Working temperature: ambient to 90°C

10.3.3 Mixing unit

Due to the small amount of fuel consumed, only a small mixing unit is required. It is recommended that the tank contains no more than approx. 100 litres. This is to avoid the changeover from HFO to MDO or vice versa taking too long.

The mixing unit equalizes the temperature between the hotter fuel oil returning from the engine and the cooler fuel oil from the service tank, particularly when changing over from heavy fuel oil to marine diesel oil and vice versa.

Туре:	cylindrical steel fabricated pressure vessel as shown in figure 10.2
Capacity:	see figure 10.2
Dimensions:	see figure 10.2
Service pressure:	10 bar
Test pressure:	according to the classification society
Working temperature:	ambient to 150°C

10.3.4 High-pressure booster pump

Pump type:	positive displacement screw pump with built-in overpressure relief valve
Pump capacity:	refer to table 7.1 Data for central freshwater cooling system (integrated HT); the given flow rate is to be within a tolerance of 0 to +20%
Inlet pressure	up to 6 bar
Delivery head:	see also table 7.1 Data for central freshwater cooling system (integrated HT); final delivery pressure according to the actual piping layout
Working temperature:	ambient to 150°C

Electric motor (booster pump)

Refer to the remarks for electric motor for the feed pumps.

10.3.5 Fuel oil end heater

Heater type:	steam, electric or thermal oil, tubular or plate type heat exchanger suitable for heavy oils up to 730 cSt at 50°C
Working pressure:	max. 12 bar, pulsating on fuel oil side
Working temperature:	ambient to 150°C, outlet temperature on fuel oil side
Heating capacity [kW]:	= 0.75 x 10 ⁻⁶ x CMCR x BSFC x (T ₁ - T ₂)
Consumption of saturated steam:	= 1.32 x 10 ⁻⁶ x CMCR x BSFC x ($T_1 - T_2$) (at 7 bar gauge pressure [kg/h]) where:

- BSFC is the brake specific fuel consumption at the contract maximum continuous rating (CMCR).
- T_1 is the temperature of the fuel oil at the viscosimeter.
 - T_2 is the temperature of the fuel oil from the service tank.

The viscosimeter monitors the fuel viscosity before the supply unit and transmits signals to the heater controls to maintain the viscosity by regulating the fuel temperature after the end heater.

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

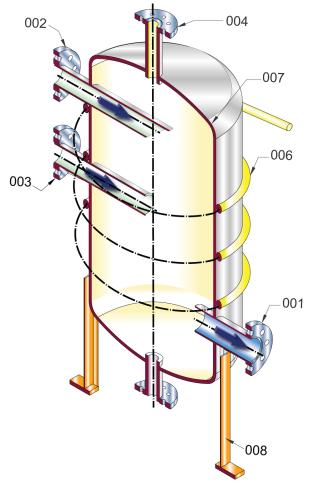


Figure 10.2: Fuel oil system mixing unit

001	Outlet	003	Inlet, from feed pump	005	Drain	007	Insulation
002	Inlet, return pipe	004	Vent	006	Heating coil	800	Mounting bracket *1)

NOTICE

Configuration and dimensioning of the mixing unit have to comply with the relevant classification society/rules.

*1) Mounting brackets for fixation on floor plate. The mixing unit must not, under any circumstances, be fitted unsupported.

10.3.6 Fuel oil filter

A mesh size of max. 10 micron (sphere passing mesh) is the absolute minimum requirement for the fuel oil filter. This specified filtration grade conforms to a high reliability and optimal cleaning efficiency of the centrifugal separators.

Wärtsilä Switzerland Ltd. highly recommends the following filter arrangement:

Arrangement in the feed system (A)

Figure *10.3*, A): If the requirement is for an automatic back-flushing filter, it is best to fit it on the low-temperature side in the discharge from the feed pumps. Locating the filter at this point reduces the risk of clogging due to asphaltene coagulation.

Back-flushing filter

Working viscosity:	100 cSt, for HFO of 730 cSt at 50°C
Flow rate:	Feed pump capacity, refer to table <i>7.1 Data for central freshwater cooling system (integrated HT)</i> . The given capacities cover the needs of the engine only. The feed pump capacity must be increased by the quantity needed for the back-flushing of the filter.
Service press. at filter inlet, after	
feed pumps:	10 bar
Test pressure:	specified by classification society
Permitted differential press. at 100 cSt:	• clean filter: max. 0.2 bar
	• dirty filter: 0.6 bar
	alarm setting: max. 0.8 bar
Min. bursting press. of filter in-	
sert:	max. 8 bar differential across filter
Working temperature:	ambient to 90°C
Mesh size:	max. 10 micron, sphere passing mesh
Filter insert material:	stainless steel mesh (CrNiMo)

Duplex filter

- The installation of the automatic back-flushing filter on the low-temperature side does not replace the need for a duplex filter fitted immediately before the supply unit.
- The same technical data are applied as specified for the arrangement before the supply unit. The filter mesh size (sphere passing) in this case is max. 0.060 mm (60 μm).

NOTICE

For various reasons cat fines may be present in the fuel entering the engine. They often cause excessive piston ring and cylinder liner wear. It is obvious that other exposed parts, e.g. fuel pumps, fuel injection valves, piston rod and piston rod stuffing boxes, will also be damaged if the fuel oil shows a high content of cat fines.

As an alternative, the following arrangement is possible:

Arrangement before engine inlet (B)

Figure 10.3, B): High-temperature (booster circuit).

This filter is most important to protect the supply unit and is to be installed as close as possible to the inlet of the supply unit. The absolute minimum requirements are met by using either of the following filters: duplex filter or automatic back-flushing filter.

Filter type:

Change-over duplex (full flow)

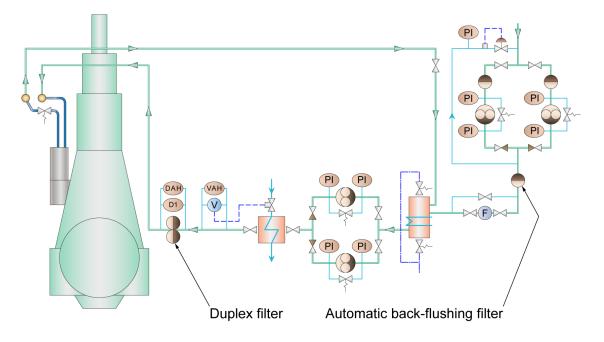
heatable, designed for in-service cleaning, fitted with differential pressure gauge and high differential pressure alarm contacts.

or

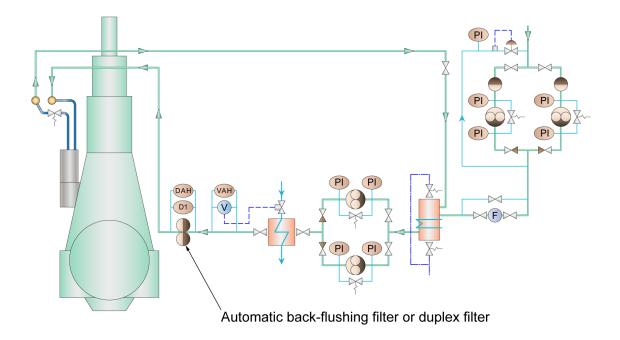
Automatic back-flushing filter

heated, with differential pressure gauge and differential pressure alarm contacts. Designed for automatic in-service cleaning, continuous or discontinuous back-flushing, using filtered fuel oil or compressed air techniques.

Further specifications/properties of the filters:



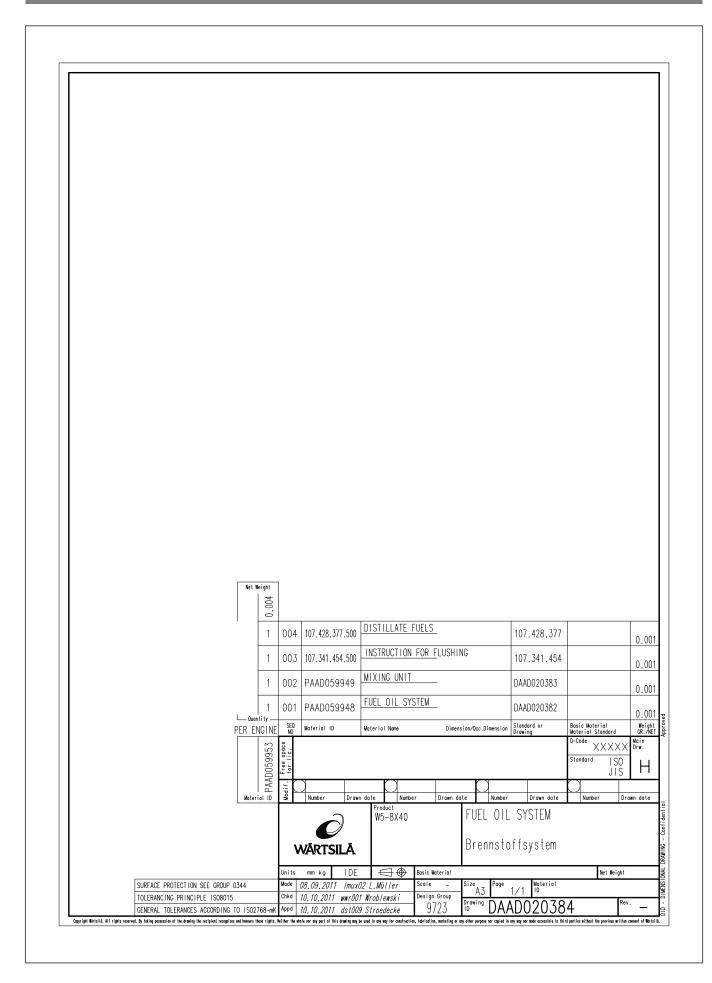
A) Back-flushing filter arrangement in the feed system



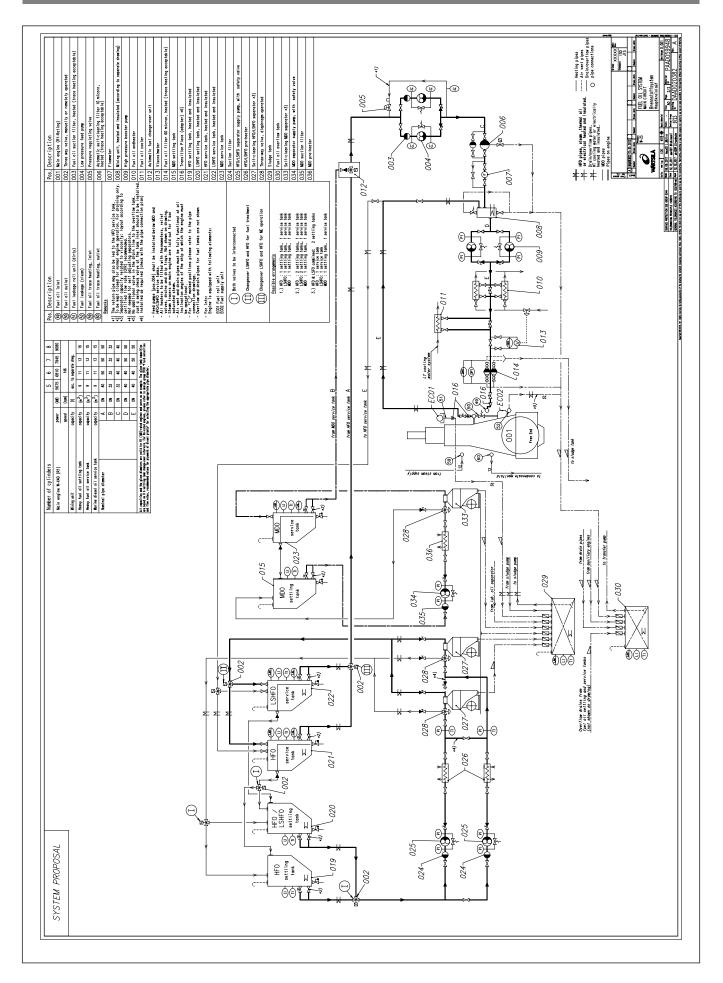
B) Back-flushing or duplex filter arrangement before engine inlet *Figure 10.3: Filter arrangements*

10.4 Drawings

DAAD020384 - Fuel Oil System, W5-8X40	. 101015
DAAD020382 a Fuel Oil System, Main Circuit, W5-8X40	. 101017
DAAD020383 - Mixing Unit, To Fuel Oil System, W5-8X40	
107.341.454 - Instruction For Flushing, The Fuel Oil System, W5-8X40	
107.428.377 - Distillate Fuels, Installation Aspects, W5-8X40	



Specifications that need to be met: (49) Fuel oil inlet - At least one fuel oil filter unit close to the engine inlet. - Fuel oil quality at engine inlet according to specification in Marine Installation Manual (MIM)	 Inlet pressure: stopped engine 10 bar running engine 7-10 bar - Viscosity MGO/MDO: 13-20 cSt Viscosity MGO/MDO: 2-20 cSt Max. temperature gradient during FO change-over: 2°C/min during FO change-over: 2°C/min ebsolute in the fuel oil system (sphere passing mesh) Volume flow: according to WinGTD 	 Fuel oil outlet Normal operation condition: Returning to mixing tank. Point operation condition: Returning to mixing tank. Fuel oil changeover while engine not in service: Returning to service tank. Fuel leakage rail unit (dirty) Free flow by gravity to sludge oil or appropriate tank, (not for revelse) pipe insulated and heated up (50-950°) 	 Fuel leakage pipe (clean) Free flow by gravity to fuel oil overflow tank, pipe insulated and heated up (50-95C°), no additional valve in drain, beside swing check valve at tank inlet. Fuel oil trace heating, inlet 	_	Q-Code XXXX Mein Standard ISO ISO Number Drawn date Drawn date	W-2S FUEL OIL SYSTEM WAIN CIRCUIT Brennstoffsystem Hauptkreislauf	Units mm kg IDE Image Discrete Mate Discrete Discrete <thdiscrete< th=""> Discrete Discret Discrete Discrete</thdiscrete<>
M-X40							SURFACE PROTECTION SEE (80UP 0344 SURFACE PROTECTION SEE (80UP 0344 TOLERANCINE PRINCIPLE 1508015 GENERAL TOLERANCES ACCORDING TO 1502768-mk



$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	 001 Outlet 000 Inité stimm ling	 004 Vent	005 Drain	006 Heating coil	007 Insulation	008 Mounting brackets *1)		Remorks:	 Configuration and dimensioning of the mixing unit have to comply with the relevant classification society/rules. 	*1) Mounting brackets for fixation on floor plate. The mixing unit must not be fitted unsupported under any circumstances.	*2) Shown on drawing.	hau.	Popro	Standard 16.		Number Drown date Number Drown date Number Drown date Number Drown date	RT-Engine MIXING UNIT		E	Scale 1:5 Size 3 Page 1/1 Material PAAD059949	10.10.2011 WWTOUT WTOD1EWSKI UESIGN OUP DIGWING DIGWING DIGWING OF ADD 020383 Rev
002 1																				V SEE GROUP 0344	IPLE ISOBUTS 3. ACCORDING TO ISO3
	004												002NG	(ND)	C	-	Capacity: Design pressure:	*2) Service temperature:	50		IOLERANCING PRINCIPLE ISOBOTS UNA GENERAL TOLERANCES ACCORDING TO ISO7268-mr Appd

1 Flushing the fuel oil system

1.1 Introduction

A correct manufacturing of the pipes avoids the presence of scales, slag and spelter. It is a fact that the expense for special welding methods, e.g. inert gas welding, is worthwhile when considering the costs of an extensive flushing procedure or the grinding and cleaning work if using normal electric arc welding or welding with electrodes. A thorough cleaning of the pipes before mounting is a must.

It is absolutely essential to ensure that the fuel oil systems are clear of all foreign matter before circulating fuel oil through to the engine. A systematic approach is to be adopted prior to commissioning when the tanks, pipe work, filters, end heaters, pumps, valves and other components are flushed and proved clear by observation and physical inspection. All fuel oil tanks are to be inspected and cleaned by hand to remove all residuals build-debris; special attention is to be paid to very small loose particles of welding matter such as spelter and slag.

The pipes of the entire fuel oil system on the plant side are to be flushed separately.

1.2 Preparation before flushing

- 1. By-pass the fuel oil connections immediately before the supply unit by means of temporary hoses or pipes as shown in the figure.
- 2. Install in the by-pass line a temporary filter with a mesh size (sphere passing mesh) of max. 0.03 mm and equipped with magnetic elements.

Alternatively, the plant fuel oil duplex filter, if available, can be used under the condition that the filter inserts are of mesh size (sphere passing mesh) of max. 0.03 mm. After flushing the filter, inserts are to be replaced by the original ones and the filter housing to be cleaned.

1.3 Flushing procedure

- 1. Fill the daily tank with sufficient marine diesel oil (MDO).
- 2. Circulate the MDO in the daily tank using the separator(s) and pre-heater(s) to maintain the cleanliness and the MDO temperature at approximately 30 °C. Operate the separator(s) until the flushing procedure is completed.
- 3. Circulate the MDO through the whole fuel oil system back to the daily tank by running the feed and booster pump.

Both pumps (feed and booster pump) must be in operation to ensure a correct fuel oil circulation through the whole fuel oil system. As the capacity of the booster pump(s) is higher than the one of the feed pump(s), part of the fuel returns, via the mixing tank, directly to the booster pump. The fuel must circulate freely in the return pipe to the daily tank and from the feed pump to the mixing unit.

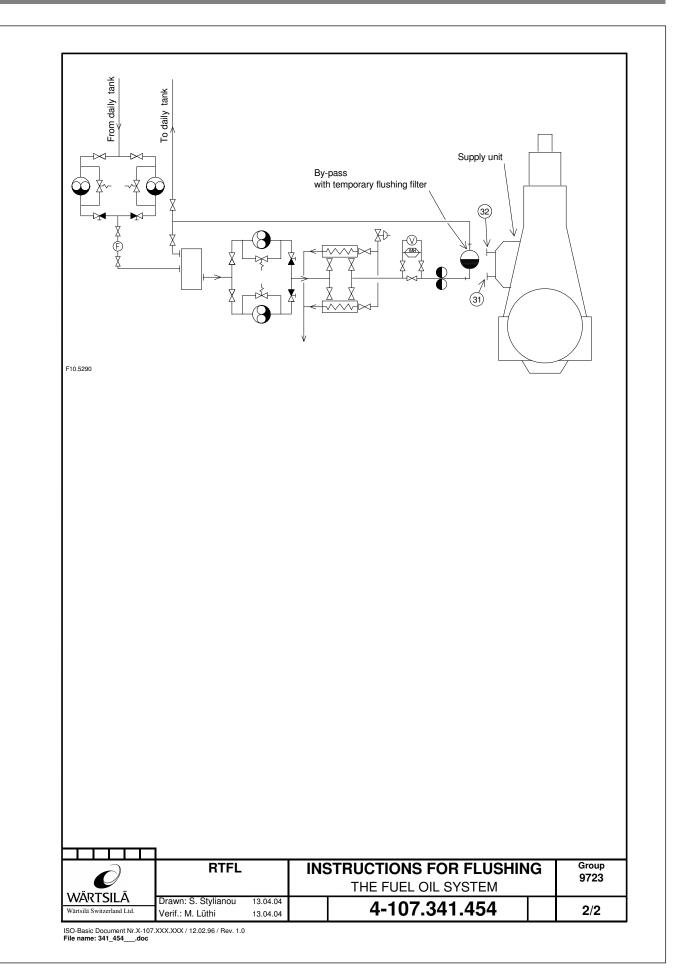
The main and stand-by pumps are to be alternatively operated. Observe the suction and discharge pressure carefully; do not let run the pumps hot. Observe the pressure drop through the filters too.

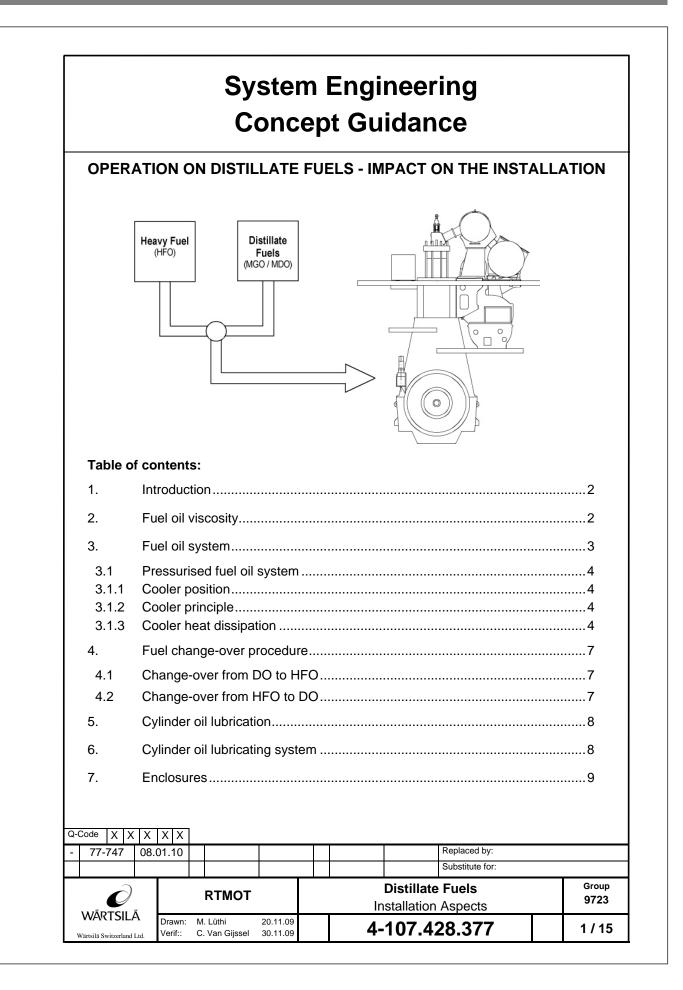
4. During the flushing procedure, the pipes are to be periodically tapped to help loosen any foreign matter that may be present. If available, vibrators are to be used. All pipes used during the engine operation must be flushed, including by-pass lines. Inspect and clean all filters in the fuel oil system periodically.

Drain the dirt of all equipments (mixing unit, end heater, etc.) where dirt can accumulate.

Flushing is to be continued until absolutely no residues can be found in the filters: No metallic particles adhere to the magnetic inserts and no residues are detected in the bottom of the filter housing. When the fuel oil system proves clean, the temporary flushing equipment can be removed and the engine connected to the fuel oil system.

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1. Introduction

Current and foreseen marine fuel legislation is limited to prescribing the maximum sulphur content of marine fuel oils or to reduce the sulphur in the exhaust gas with alternative methods equivalently.

The availability of fuels with various sulphur levels is not yet fully clear. However, as the demand for sulphur content in the fuel is reduced below 0.5%, the possibility of distillate fuel increases.

According to ISO 8217 standard, distillate fuels are categorised as DMX, DMA (also called MGO) and DMB (often called MDO). DMX is emergency fuel with a lower flashpoint, coming with additional storage precautions. Due to the low flash point, this fuel would not normally be used in marine diesel engines: DMA and DMB being the most common distillate fuels.

Wärtsilä Switzerland allows for its engines to be operated on all fuels supplied under the ISO 8217 standard.

This guide line is to mainly give information about the impact on the installation side, when using distillate fuels according to ISO 8217 standard. It is valid for RT-flex and RTA engines.

2. Fuel oil viscosity

The current recommendation for fuel viscosity at the fuel injector is 13 to 17cSt when operating on HFO. However, this viscosity level cannot be met with MDO and MGO unless the fuel is cooled down to very low temperatures.

Experience has however shown that viscosities for grades DMA and DMB distillate fuels have no adverse affect on the operation of the fuel system components: a nominal lower viscosity level of 2 cSt at the fuel pump is recommended.

To achieve this level a cooler may be required depending on the actual temperature of the distillate fuel delivered to the engine.

Table 1, page 9, shows the ISO 8217 standard. As example, the viscosity of the DMA grade as a function of the temperature is shown in figure 2, page 10.

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WÄRTSILÄ Wärtsilä Switzerland Ltd.	Drawn: M. Lüthi Verif:: C. Van Gijssel	20.11.09 30.11.09	4-107.428.377	2 / 15

3. Fuel oil system

A complete fuel oil system including the fuel oil treatment with a tank arrangement for various fuel oil qualities and the pressurised system is shown in figure 3, page 11. The tank arrangement shown in this enclosure is one possibility among several others. Further possible tank arrangements, as example:

1)	HFO LSHFO DO	1 settling tank 1 settling tank 1 settling tank	 + 1 service tank + 1 service tank + 1 service tank
2)	HFO LSHFO DO	2 settling tanks 2 settling tanks 1 settling tank	+ 1 service tank + 1 service tank + 1 service tank
3)	HFO & LSFO combined HFO LSHFO DO	2 settling tanks 1 service tank 1 service tank 1 settling tank	+ 1 service tank

Remark concerning the fuel oil pumps

The feed and booster pump capacities should be specified for the lower fuel oil viscosity, which normally corresponds to the MDO grade (7 - 11 cSt at 40°C). With lower fuel viscosities, the nominal pump capacities will decrease, therefore this has to be considered when determining the capacities of the feed and booster pumps. Furthermore, the lower lubricating capacity of distillate fuels with low viscosity compared to HFO may influence the lifetime of the feed and booster pumps, especially when operating long periods with these fuels. Therefore, the advice of the pump manufacturers should be sought regarding pump performance when operating with distillate fuels.

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WÄRTSILÄ Wärtsilä Switzerland Ltd.	Drawn: Verif::	M. Lüthi C. Van Gijssel	20.11.09 30.11.09	4-107.428.377	3 / 15

3.1 Pressurised fuel oil system

The main difference to the standard pressurised fuel oil system is the adding of a cooler, as shown in figure 4, page 13, to cool down the DO depending on the used viscosity grade.

3.1.1 Cooler position

The cooler-chiller unit should be located before the viscosimeter with the sensor to control the fuel temperature located close to the engine inlet.

Other locations, as for example in the fuel engine return line, are not recommended. The advantage of locating the cooler close to the engine inlet is to reduce as far as possible the reaction time of the fuel temperature control as it is done with fuel end heater, which is also located in the fuel delivery line to the engine.

3.1.2 Cooler principle

There are two possible cooling principles:

- Direct cooling: where the heat exchange directly occurs between the distillate fuel and the refrigerant (refrigerant fuel).
- The indirect-cooling: Where the refrigerant cools down fresh water (FW), which in turns cools down the distillate fuel (refrigerant – FW / FW – distillate fuel), as shown in figure 4.

The double heat exchanger arrangement is favoured basically in the event of fuel or refrigerant leakages; therefore direct cooling seems to be not accepted by the classification societies. However, shipyards should approach class for their advice / rules regarding direct cooling systems.

Seawater as coolant is, of course, not recommended at all.

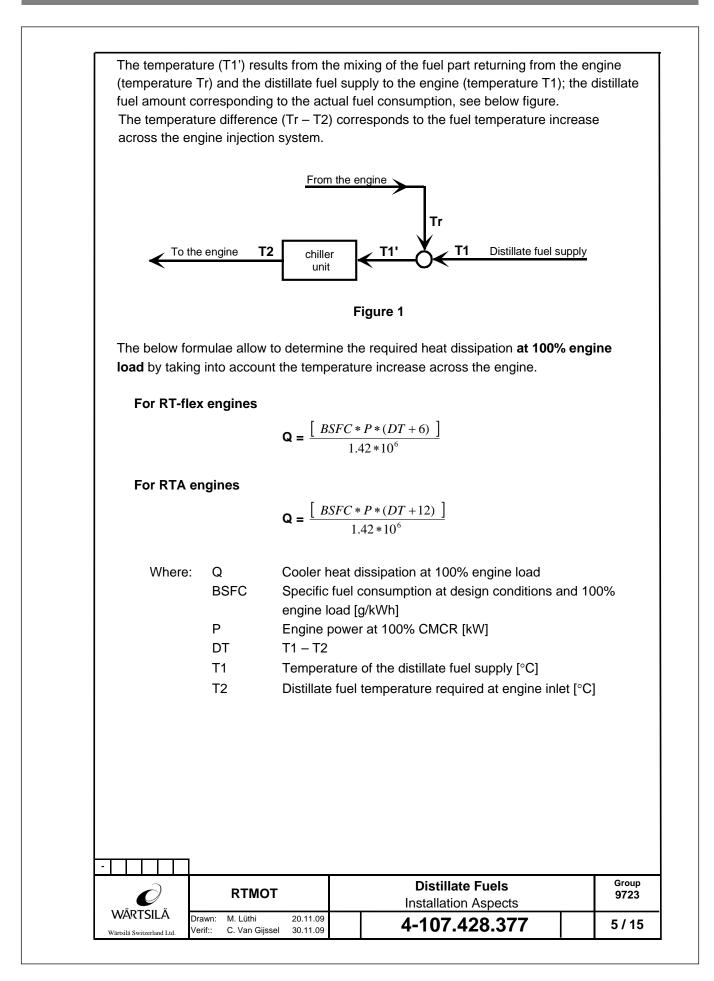
3.1.3 Cooler heat dissipation

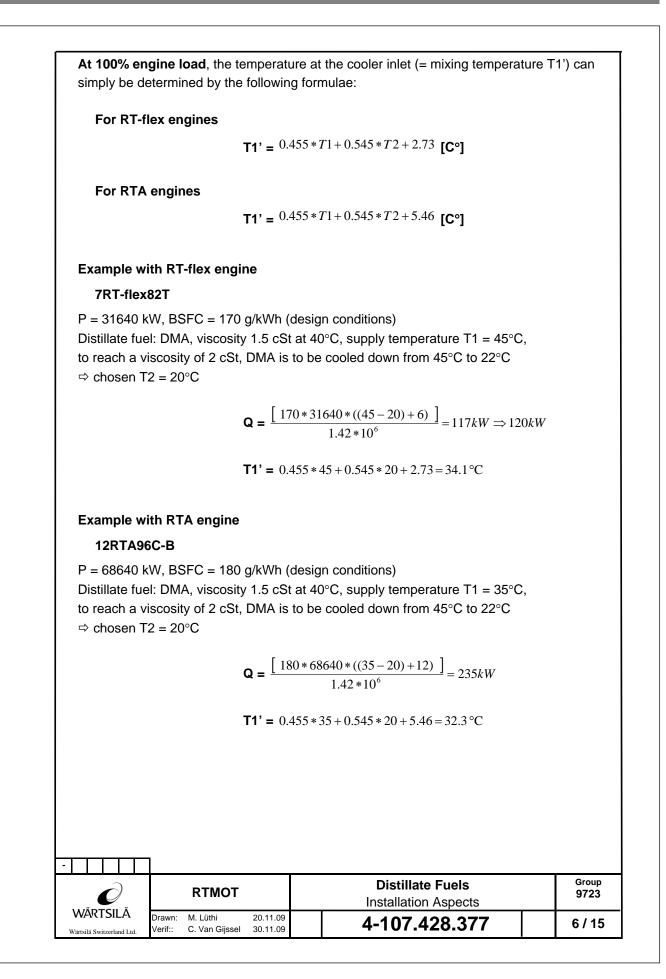
The cooler heat dissipation (Q) is determined by the following formula:

$$\mathbf{Q} = m * cp * DT[kW]$$

Where:	m cp	mass of the distillate fuel passing the cooler [kg/s] specific heat capacity of the distillate fuel [kJ/kg °C]
	ср	2.0 – 2.2 kJ/kg °C
	DT	T1' – T2
	T1'	temperature at the cooler inlet [°C]
	T2	temperature at the cooler outlet [°C]

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4. Fuel change-over procedure (Refer to figure 3) Changing over from diesel oil (DO) to heavy fuel oil (HFO) and vice versa

The change-over of the main engine operating mode HFO / DO or vice versa occurs through the three-way valve installed in the suction line from the HFO and DO tank (see figure 4, position 01).

When changing from one fuel to another however, thermal shock to the engine fuel injection system (injection pumps, piping, etc.) has to be prevented. Sudden temperature changes may lead to seizing of the fuel pump plungers; this may affect the manoeuvrability of the ship, or result in fuel pipe leakage with the risk of fire. Not only the temperature increase when changing over from DO to HFO is important, but also the temperature decrease when changing over from HFO to DO. The experience gained so far shows that the use of change-over valves (01) with time delay (e.g.: 10' duration from 100% on HFO to 100% DO), and acting therefore as mixing valves, has not been very successful. This is due to the fact that to mix both fuels properly, the HFO and DO pressures at the valve inlet must be equal, which, in practice, is hardly feasible.

A metering device gradually mixing DO and HFO to obtain the required temperature gradient could be foreseen. However, such a metering device will require additional components (pumps, mixing valve, etc.) to the existing fuel oil circuit and is considered as not necessary.

4.1 Change-over from DO to HFO

The fuel viscosity is controlled by the viscosimeter and the increase in the fuel temperature itself can be manually or automatically controlled. Depending on the viscosimeter type, a temperature ramp (gradient) can be set to automatically control the change in temperature. The maximum temperature gradient must not exceed 15 °C/min. The engine load must not exceed 75% of CMCR until the change-over procedure is finalised and the required HFO viscosity (13 to 17 cSt) is reached. The trace heating on the engine and installation side must be turned on at the same time when changing over. The change-over procedure itself is detailed in the relevant engine operating manual.

4.2 Change-over from HFO to DO

In this case, the temperature change cannot be influenced by the viscosimeter, but by the fuel volume available in the fuel system (as well as by the involved steel mass of the fuel system).

The mixing unit (04) serves to equalise the fuel oil temperature between the hot surplus heavy fuel oil returning from the engine and the heavy fuel oil from the service tank. It also provides an additional fuel volume, which limits the temperature gradients when changing over from HFO to DO or vice versa.

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A large capacity of the mixing unit will be of advantage in further reducing the temperature gradient. This will however increase the period for which both fuels are present together, and consequently the risk of compatibility problems may increase. The pipe diameters are normally dictated by the fluid velocity, however, the use of larger pipe diameters as required for the fuel oil pressurised circuit will be of advantage too, e.g. DN80 instead of DN65

A suggested measure to reduce the temperature difference between both fuels before changing over is to increase the DO temperature in the service tank. Such a measure should be considered with caution: the flash point of distillate fuels being rather low, e.g. 60°C for DMA grade. Further, this measure can be considered as a waste of energy: on one hand the DO is pre-heated and on the other hand is cooled down again to reach the required viscosity before entering the engine.

Figure 5, page 14, shows, as example, the progression trend of the fuel temperature as a function of the time for various engine loads by switching the change-over valves (01) from HFO to DO without any time delay. The highest temperature drop resulting in the highest temperature gradient takes place just after the change-over as it can be seen on this enclosure.

The engine load must be lower than 50% CMCR until the change-over procedure is finalised and until the required DO viscosity ($\geq 2 \text{ cSt}$) is reached. After a short period following the change-over from HFO to DO, the trace heating on the engine and installation side must be shut off. The change-over procedure itself is detailed in the relevant engine operating manual.

5. Cylinder oil lubrication

For operation on fuel with a sulphur content lower than 1.5%, the cylinder oil feed rate should be low and have 40BN. This is in order to prevent build-up of deposits, originating from un-neutralized hard calcium carbonate deposits.

Prior to changing over to distillate fuels the cylinder oil should be switched over to allow for the higher BN oil to be flushed through. The time for this to be achieved depends on the layout of the piping system, and in particular the volume. The use of low BN oil with a fuel with higher sulphur content during this relatively short change-over period will not have an adverse effect on the liner wear rates.

6. Cylinder oil lubricating system

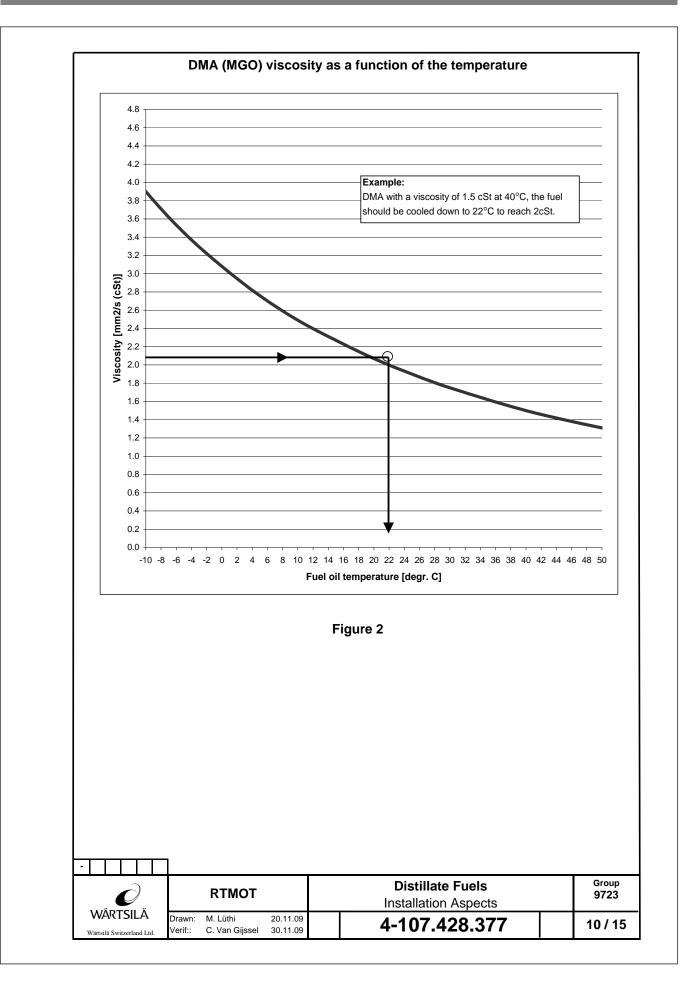
Figure 6, page 15, shows an arrangement of the cylinder lubricating system with two storage (01) and service tanks (02) for operation with high and low BN. The change-over from one oil quality to another occurs by means of the three-way valve (04), which is to be fitted as close as possible to the engine inlet, to avoid a too long time delay in the oil delivery due to the oil volumes contained in the supply pipes when changing over.

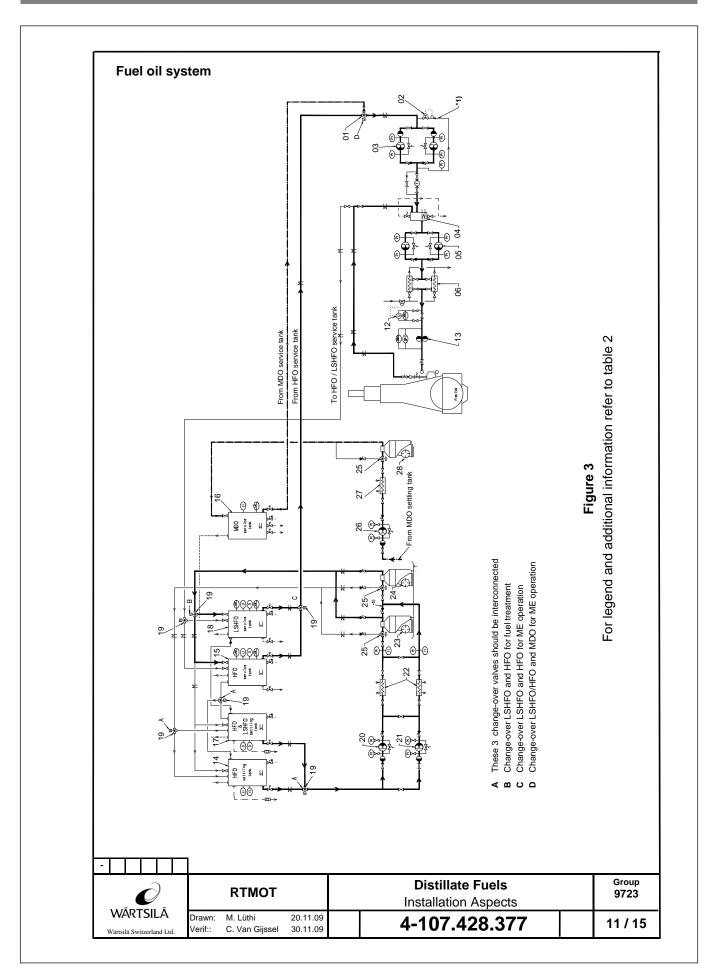
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7. Enclosures

ISO 8217 Fuel Standard - Marine Distillate Fuels

Parameter	Unit	Limit	DMX	DMA	DMB	DMC			
Density at 15 °C	kg/m³	Max	-	890	900	920			
Viscosity at 40 ° C	mm²/s	Max	5.5	6	11	14			
Viscosity at 40 °C	mm²/s	Min	1.4	1.5	-	-			
Micro Carbon Residue at 10% Residue	% m/m	Max	0.3	0.3	-	-			
Micro Carbon Residue	% m/m	Max	-	-	0.3	2.5			
Water	% V/V	Max	-	-	0.3	0.3			
Sulphur ^c	% (m/m)	Max	1	1.5	2	2			
Total Sediment Existent	% m/m	Max	-	-	0.1	0.1			
Ash	% m/m	Max	0.01	0.01	0.01	0.05			
Vanadium	mg/kg	Max	-	-	-	100			
Aluminium + Silicon	mg/kg	Max	-	-	-	25			
Flash point	°C	Min	43	60	60	60			
Pour point, Summer	°C	Max	-	0	6	6			
Pour point, Winter	°C	Max	-	-6	0	0			
Cloud point	°C	Max	-16	-	-	-			
Calculated Cetane Index		Min	45	40	35	-			
Appearance			Clear &	Bright	-	-			
Zinc ^d	mg/kg	Max	-		-	15			
Phosphorus ^d	mg/kg	Max	-		-	15			
Calcium ^d	mg/kg	Max	-		-	30			
d	Protocol con The Fuel sh A Fuel is co	designated by the International Maritime Organization, when its relevan Protocol comes into force. There may be local variations. The Fuel shall be free of ULO. A Fuel is considered to be free of ULO if one or more of the elements are below the limits. All three elements shall exceed the limits before							
		etroleum prod		rce : ISO 821 (class F) - Sp					
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Fuel oil system

- 01 Three-way valve, manually or remotely operated
- 02 Pressure regulating valve
- 03 Low pressure feed pump
- 04 Mixing unit, heated and insulated
- High pressure booster pump 05
- 06 Fuel end-heater

[...]

- 12 Viscosimeter
- 13 Fuel oil filter, heated
- 14 HFO settling tank, heated and insulated
- 15 HFO service tank, heated and insulated
- 16 MDO service tank
- 17 LSHFO settling tank, heated and insulated
- 18 LSHFO service tank, heated and insulated
- Three-way valve, manually or remotely operated 19
- HFO/LSHFO separator supply pump, with safety valve *2) 20
- 21 HFO/LSHFO separator supply pump, with safety valve *2)
- 22 HFO/LSHFO pre-heater
- 23 Self-cleaning HFO/LSHFO separator *3)
- 24 Self-cleaning HFO/LSHFO separator *3)
- 25 Three-way valve, diaphragm operated
- MDO separator supply pump, with safety valve *2) 26
- 27 MDO pre-heater
- 28 Self-cleaning MDO separator

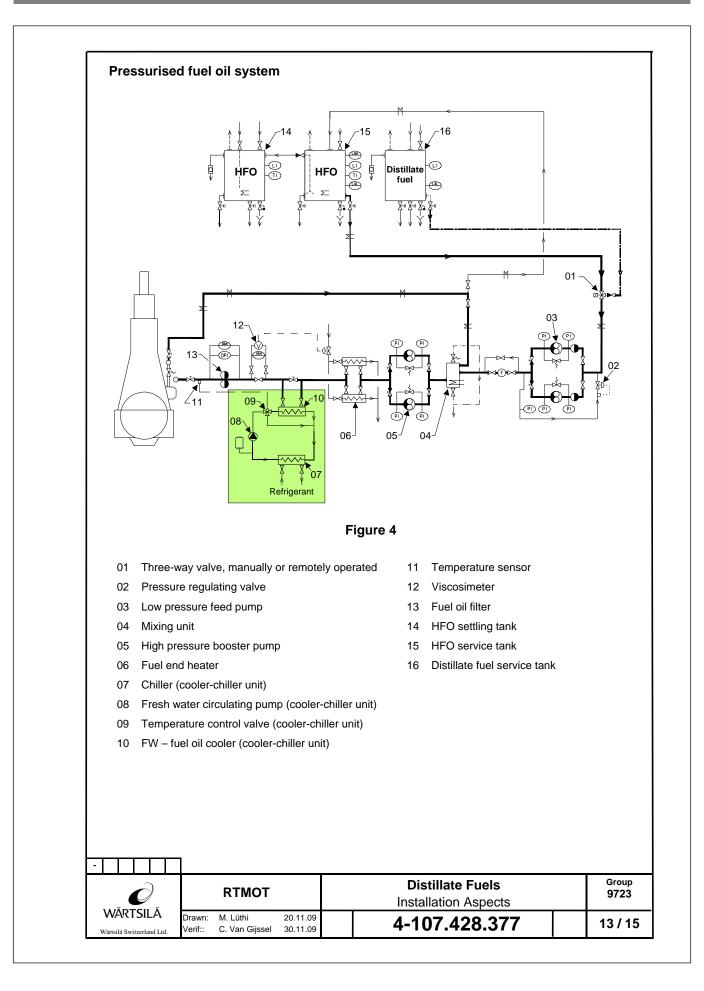
Table 2

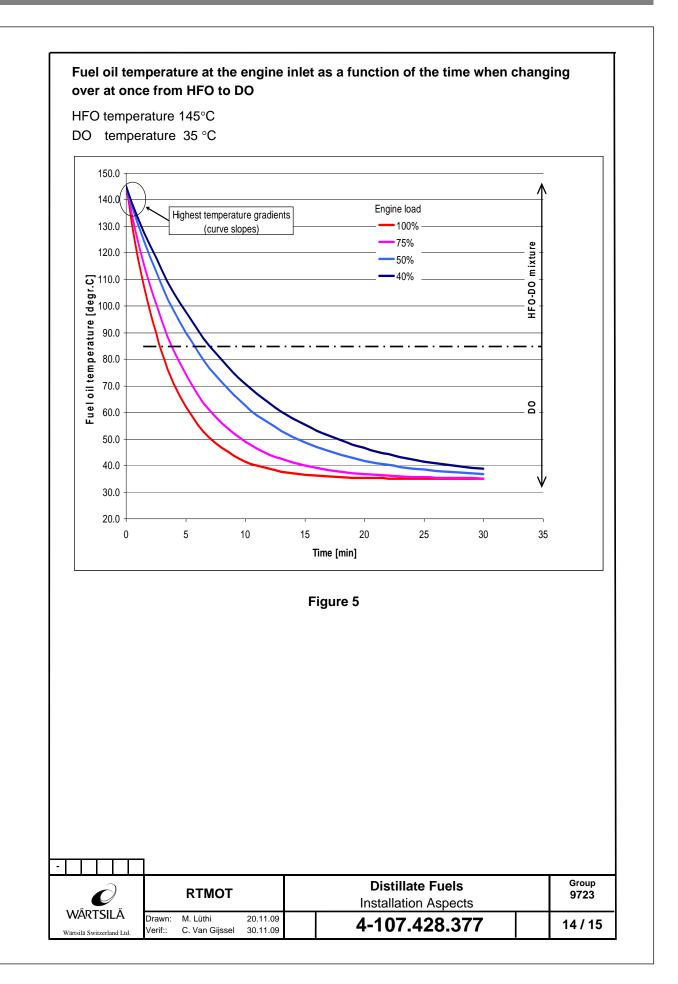
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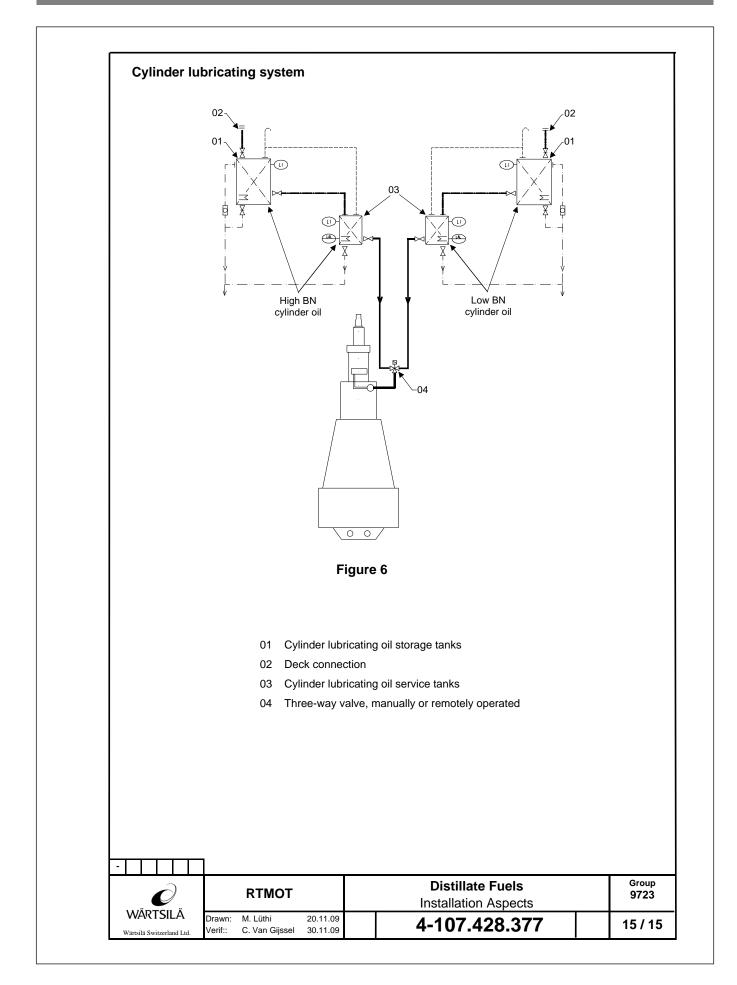
- *1) The return pipe may also be led to the HFO service tank.
- *2) Pump may be omitted, if integrated in separator.
- *3) Separator capacity related to viscosity in accordance with the instructions of the separator manufacturer.

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11. Starting and Control Air Systems

Compressed air is required for engine starting, engine control, exhaust valve air springs, washing plant for the scavenge air coolers, and general services. The starting and control air system shown in figure *11.1* comprises two air compressors, two air receivers, and systems of pipework and valves connected to the engine starting air manifold.

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

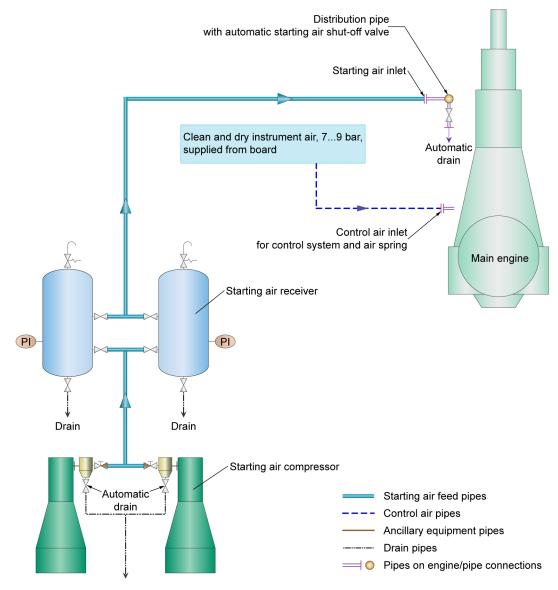


Figure 11.1: Starting and control air system

11.1 Capacities of air compressor and receiver

The capacity of the air compressor and receiver depends on the total inertia (J_{Tot}) of the propulsion system's rotating parts.

- Total inertia = engine inertia + shafting and propeller inertia => $(J_{Tot}) = (J_{Eng}) + (J_{S+P})$
- Propeller inertia includes the part of entrained water
- Engine inertia (J_{Eng}) see section 11.1.1
- Relative inertia $J_{Rel} = J_{Tot} / J_{Eng}$

The air receiver and compressor capacities of section *11.1.1* refer to a relative inertia ($J_{Rel} = 2.0$). For other values than 2.0, the air receiver and compressor capacities have to be calculated with the *winGTD and netGTD*. It provides data on the capacity of air compressor and receiver for relative inertia values (J_{Rel}).

Section 11.1.1 outlines the basic requirements for a system similar to figure 11.1 for maximum engine rating. The *winGTD* and *netGTD* enable to optimise the capacities of the compressors and air receivers for the contract maximum continuous rating (CMCR).

11.1.1 Air receiver and air compressor capacities

Starting air			
No. cyl.	Air receivers	Air compressors	
	Number of starts requested by the classification societies for reversible engines: 12 ^{*1)}		J _{Eng} *2)
	Max. air pressure: 30 bar	Free air delivery at: 30 bar	
	Number x volume ^{*3)} [m ³]	Number x capacity ^{*3)} [Nm ³ /h]	[kgm ²]
5	2 x 2.0	2 x 60	11,002
6	2 x 2.0	2 x 60	12,704
7	2 x 2.5	2 x 75	14,606
8	2 x 2.5	2 x 75	16,688

Table 11.1: Air receiver and air compressor capacities

NOTICE

^{*1)} 12 consecutive starts of the main engine, alternating between ahead and astern.

^{*2)} Data given for engines without damper and front disc on crankshaft, but smallest flywheel included.

^{*3)} Data for air pressure of 25 bar are available on winGTD and netGTD.

11.2 Starting and control air system specification

11.2.1 Starting air compressors

Generally: The discharge air temperature is not to exceed 90°C and the air supply to the compressors is to be as clean as possible without oil vapour. Capacity: refer to section *11.1.1* Delivery gauge pressure: 30 bar

11.2.2 Starting air receivers

Type: fabricated steel pressure vessels having domed ends and integrated pipe fittings for isolating valves, automatic drain valves, pressure reading instruments and pressure relief valves Capacity: refer to section *11.1.1*

Working gauge pressure: 30 bar

11.2.3 Control air system supply

The control air is supplied from the board instrument air supply system (see figure 11.1) providing air at 8 bar gauge pressure. The air quality should comply with the compressed air purity class:

2-4-2 according to ISO 8573-1 (2007-02-01)

Control air capacities

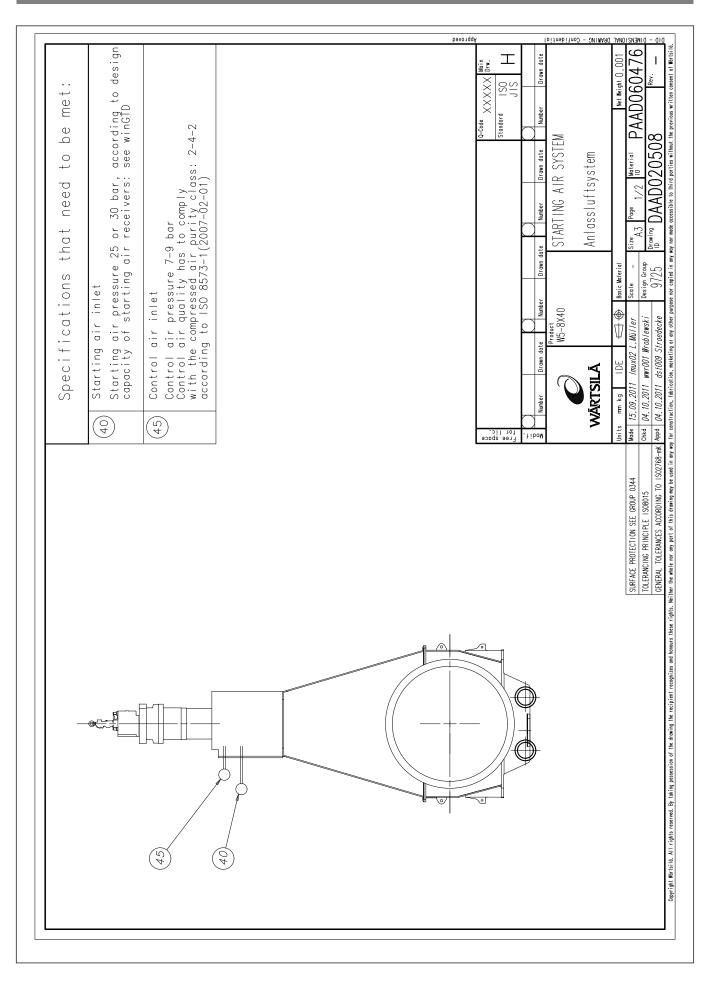
No. of	Capacity [Nm ³ /h]			
cyl.	Control system up to	Exhaust valve air spring	Total	
5	21.0	12.0	33.0	
6	21.0	14.4	35.4	
7	21.0	16.8	37.8	
8	21.0	19.2	40.2	

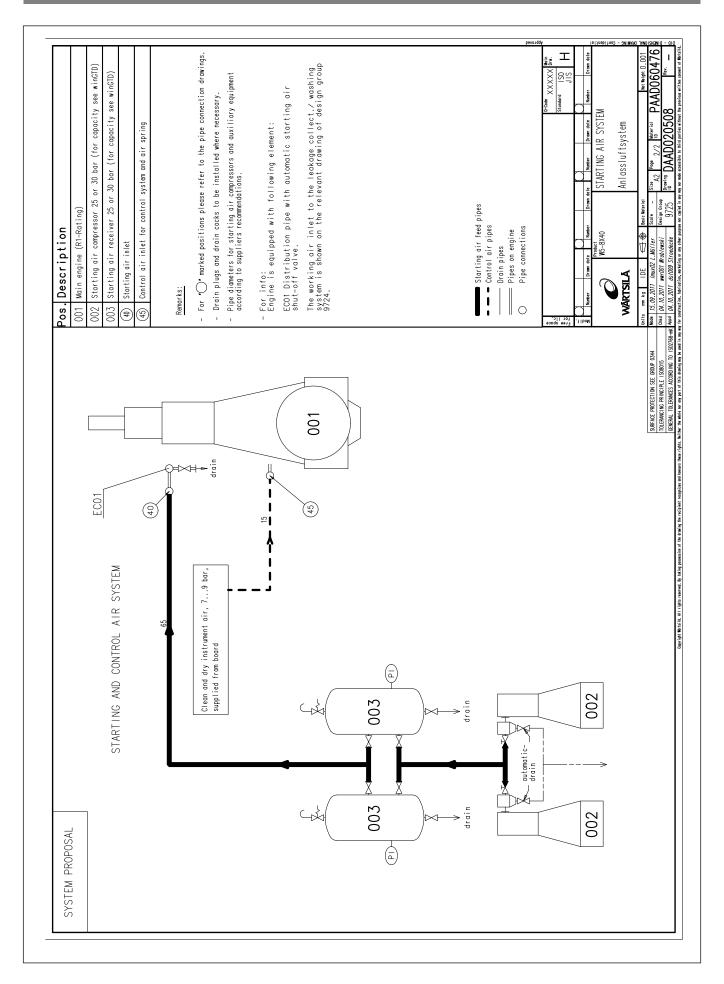
11.3 General service and working air

General service and working air for driving air powered tools and assisting in the cleaning of scavenge air coolers is also provided by the board instrument air supply system.

11.4 Drawings

11. Starting and Control Air Systems





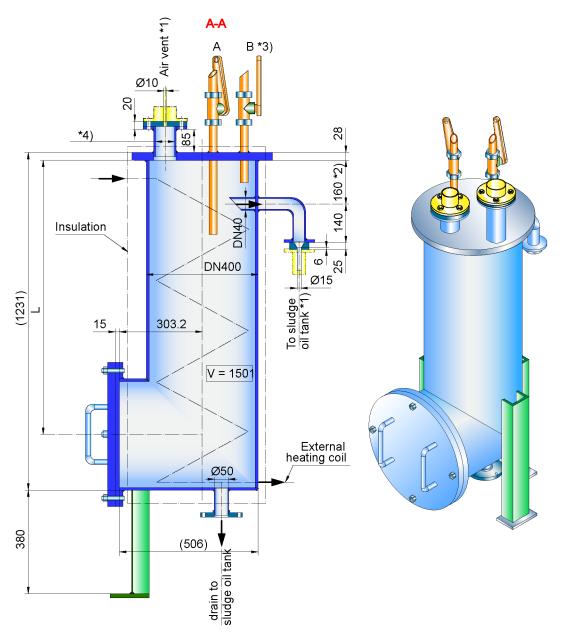
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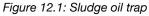
12. Leakage Collection System

Dirty oil collected from the piston underside is led under a pressure of approximately 2.8 bar to the sludge oil trap and then to the sludge oil tank. The purpose of the sludge oil trap is to retain the large amount of solid parts contained in the dirty oil and to reduce the pressure by means of an orifice or throttling disc fitted at its outlet, so that the sludge oil tank is under atmospheric pressure. The dirty oil from the piston rod stuffing box, which consists of waste system oil, cylinder oil, metallic particles and small amounts of combustion products, is led directly to the sludge tank. Condensate from scavenge air is formed when the vessel is operating in a humid climate and is to be continually drained from the scavenge air receiver to avoid excessive piston ring and liner wear.

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

12.1 Sludge oil trap





NOTICE

*1) Orifice to be as shown.

- *2) Observe location of pipes with regard to each other.
- *3) Optional Alternatives, such as level sensors, are possible
- *4) diametre =

L = 550 mm

Capacity = 100 I

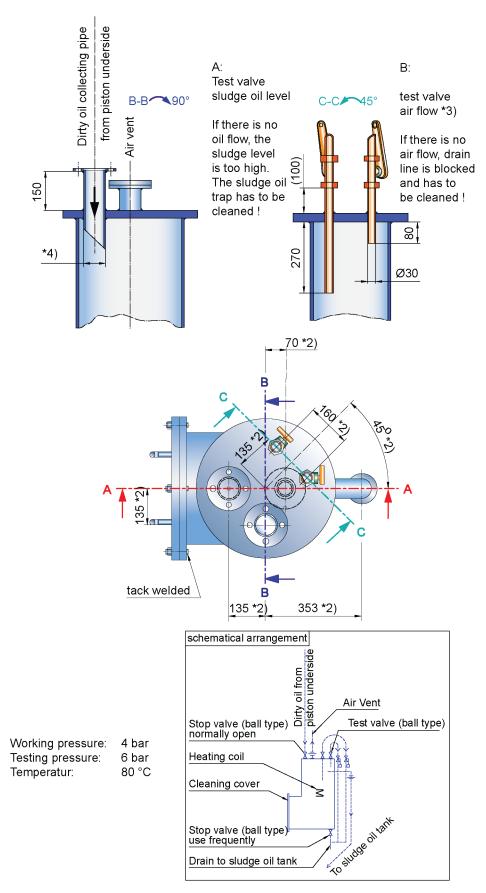
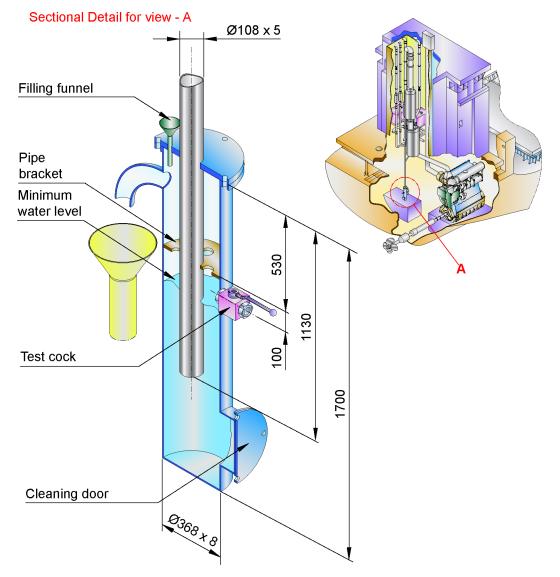


Figure 12.2: Sludge oil trap



Engine exhaust uptakes can be drained automatically using a system as shown in figure 12.3.

Figure 12.3: Arrangement of automatic water drain

For all relevant and prevailing information consult the drawings in section 'Drawings' at the end of this chapter.

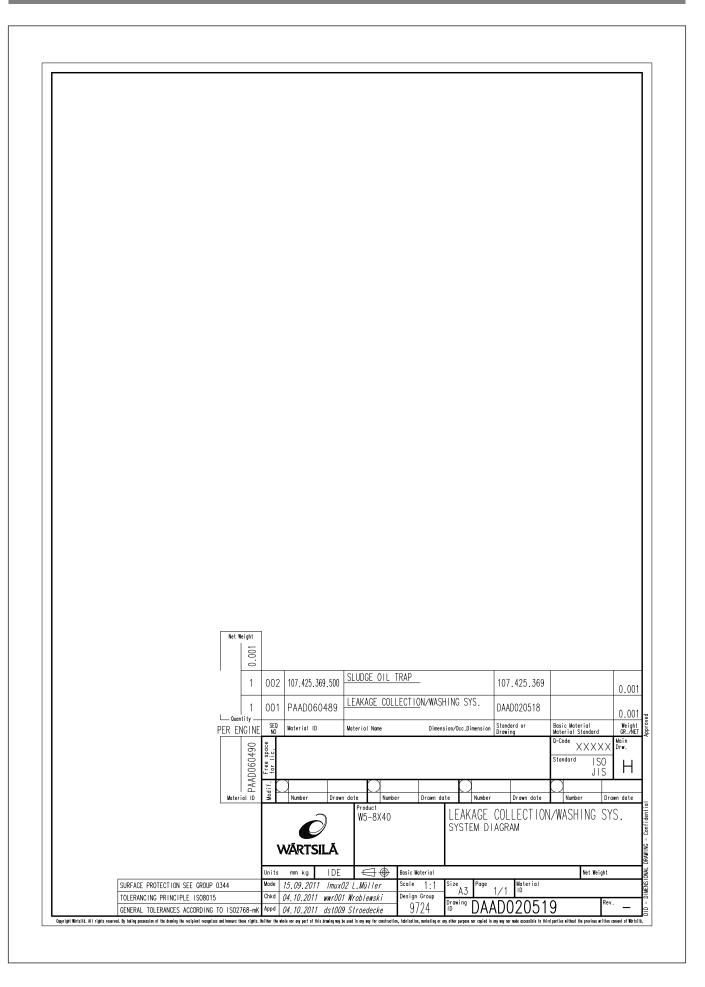
12.2 Air vents

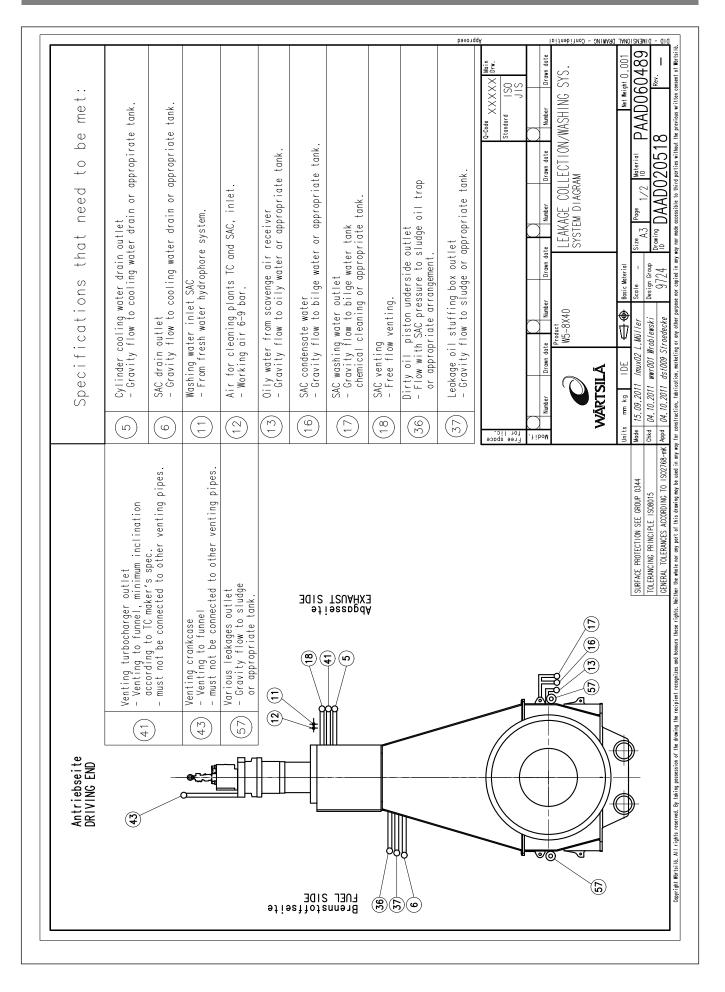
The air vent pipes of the ancillary systems have to be fully functional at all inclination angles of the ship at which the engine must be operational. This is normally achieved if the vent pipes have an uninterrupted inclination of min. 5%.

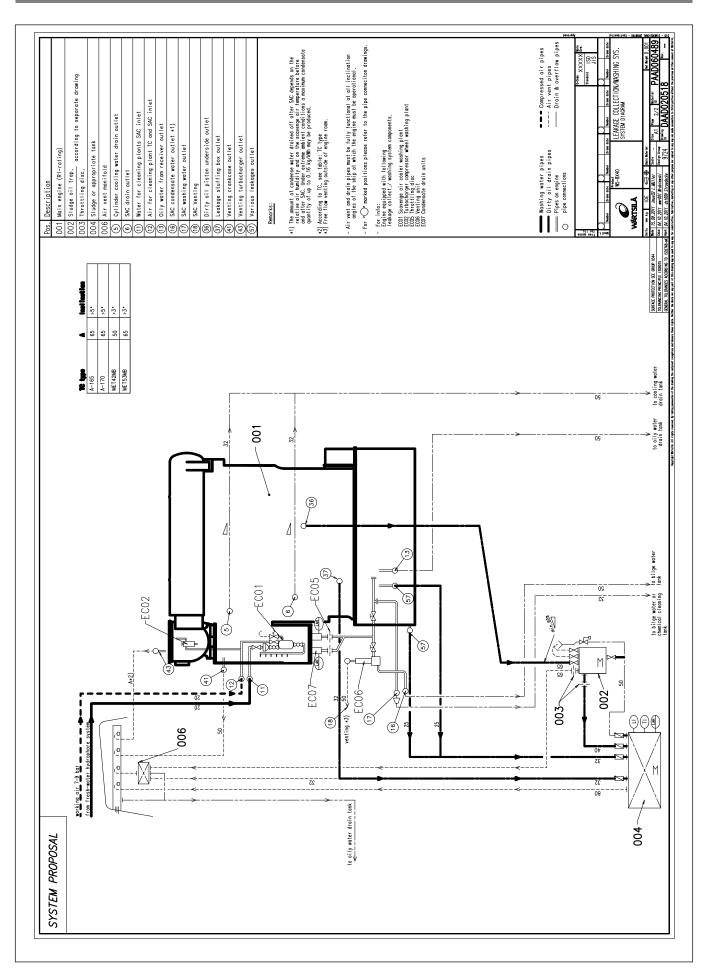
Such an arrangement enables the vapour to separate into its air and fluid components, discharging the air to atmosphere and returning the fluid to its source.

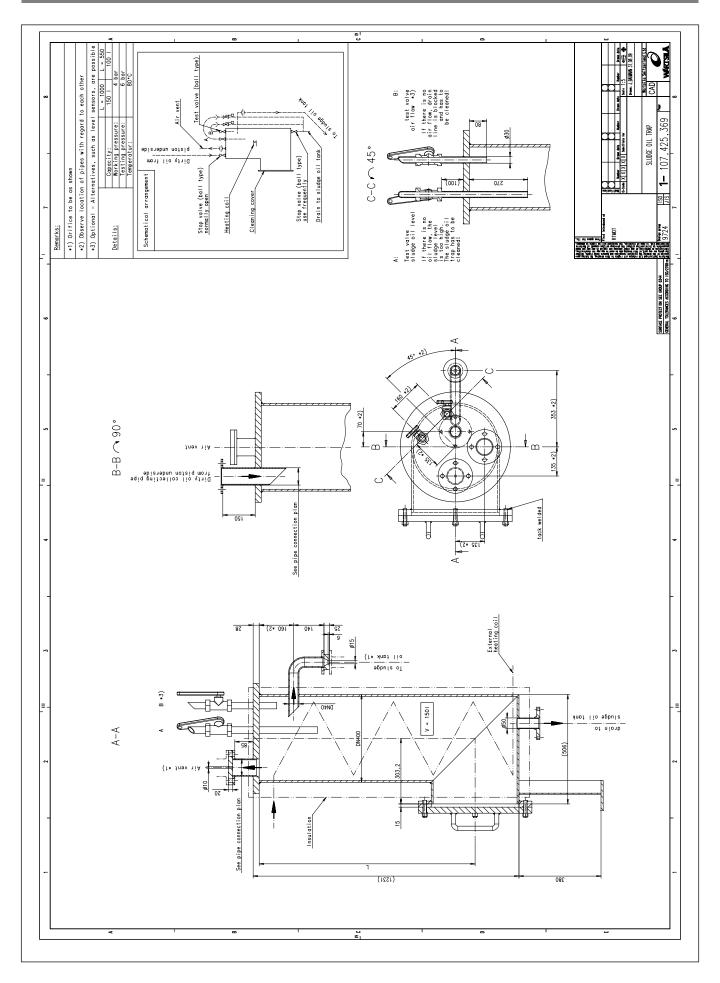
12.3 Drawings

DAAD020519 -	Leakage Collection/Washing Sys., System Diagram, W5-8X40	12-126
DAAD020518 -	Leakage Collection/Washing Sys., System Diagram, W5-8X40	12-128
107.425.369 -	Sludge Oil Trap, W5-8X40	12-129









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13. Exhaust Gas System

The following gas velocities are indicated as a guideline for an optimised exhaust gas system.

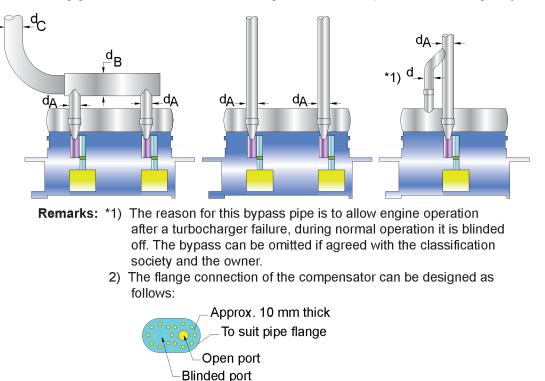


Figure 13.1: Determination of exhaust pipe diameter

13.1 Recommended gas velocities:

Pipe A 40 m/s

Check the back pressure drop of the whole exhaust gas system (not to exceed 30 mbar).

13.2 Exhaust gas pipe diameters

Refer to winGTD and netGTD.

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14. Engine-room Ventilation

The engine room ventilation is to conform to the requirements specified by the legislative council of the vessel's country of registration and the classification society selected by the shipowners. Calculation methods for the air flows required for combustion and keeping the machinery spaces cool are given in the international standard ISO 8861 *'Shipbuilding - Engine-room ventilation in diesel engined ships; Design requirements and basis of calculations'*.

Based on ISO 8861, the radiated heat, required air flow and power for the layout of the engine room ventilation can be obtained from the *winGTD and netGTD* on the Licensee Portal.

The final layout of the engine room ventilation is, however, at the discretion of the shipyard.

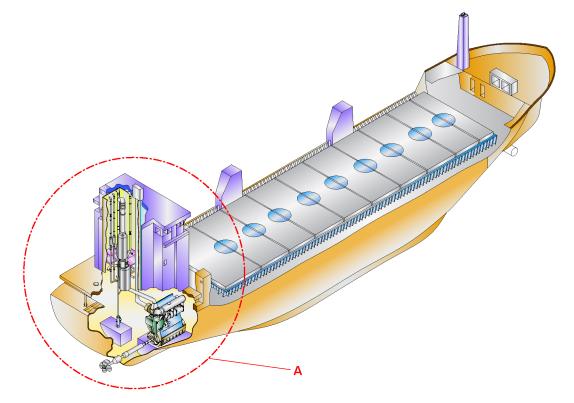


Figure 14.1: Direct suction of combustion air - main and auxiliary engine

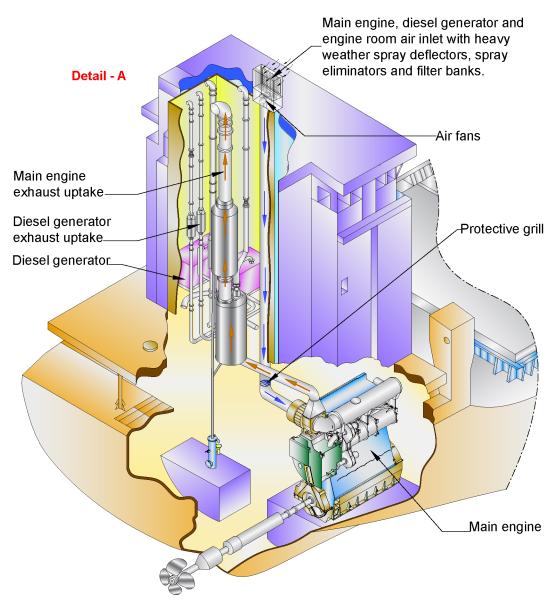


Figure 14.2: Direct suction of combustion air - main and auxiliary engine

14.1 Engine air inlet - Operating temperatures of 45 to 5°C

Due to the high compression ratio, the W-X40 engine does not require any special measures, such as pre-heating the air at low temperatures, even when operating on heavy fuel oil at part load, idling and starting up. The only condition which must be fulfilled is that the water inlet temperature to the scavenge air cooler is not lower than 25°C.

This means:

- When the combustion air is drawn directly from the engine room, no pre-heating of the combustion air is necessary.
- When the combustion air is ducted in from outside the engine room and the air suction temperature does not fall below 5°C, no measures have to be taken.

The central freshwater cooling system allows recovering the heat dissipated from the engine and maintains the required scavenge air temperature after the scavenge air cooler by recirculating part of the warm water through the low-temperature system.

14.1.1 Arctic conditions at operating temperatures of less than 5°C

Under arctic conditions the ambient air temperatures can meet levels of more than minus 50°C. If the combustion air is drawn directly from outside, the engine may operate over a wide range of ambient air temperatures between arctic condition and tropical (design) condition (45°C).

To avoid the need of providing an expensive combustion air preheater, a system has been developed that enables the engine to be operated directly with cold air from outside.

If the air inlet temperature drops to less than 5°C, the air density in the cylinders increases to such an extent that the maximum permissible cylinder pressure is exceeded. This can be compensated by blowing off a certain amount of the scavenge air through a blow-off device as shown in figure *14.3*.

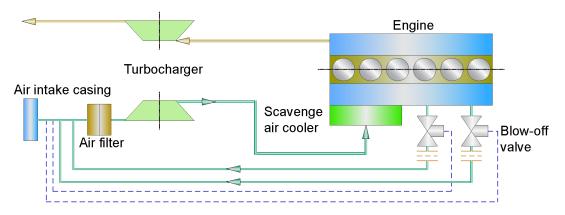


Figure 14.3: Scavenge air system for arctic conditions

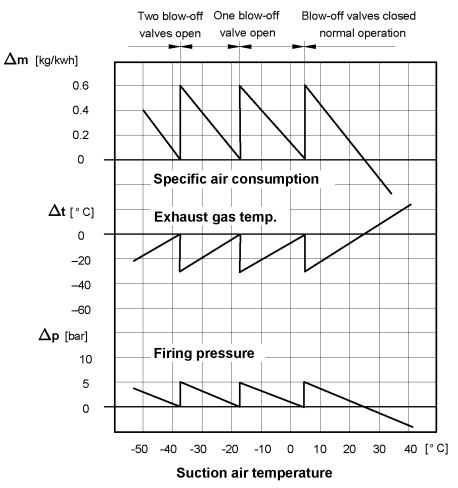


Figure 14.4: Blow-off effect under arctic conditions

There are up to three blow-off valves fitted on the scavenge air receiver. In the event that the air inlet temperature to the turbocharger is less than $+5^{\circ}$ C the first blow-off valve vents. For each actuated blow-off valve, a higher suction air temperature is simulated by reducing the scavenge air pressure and thus the air density. The second blow-off valve vents automatically as required to maintain the wanted relationship between scavenge and firing pressures. Figure 14.4 shows the effect of the blow-off valves on the air flow, the exhaust gas temperature after turbine and the firing pressure.

Control of the blow-off valves is effected by means of a signal generated by the temperature sensors in the inlet piping. Care is to be taken that no foreign particles in the form of ice gain access to the turbocharger compressor in any way, because they could lead to its destruction. Reduction of the pipe's cross sectional area by snow is also to be prevented.

NOTICE

The scavenge air cooling water inlet temperature is to be maintained at min. 25°C. This means that the scavenge air cooling water will have to be preheated in the case of low-power operation. The required heat is obtained from the lubricating oil cooler and the engine cylinder cooling.

15. Pipe Sizes and Flow Details

15.1 Pipe velocities

The velocities given in table *Recommended fluid velocities and flow rates for pipework* are for guidance only. They have been selected with due regard to friction losses and corrosion. Higher velocities compared with those stated may be acceptable when short piping runs, water properties and ambient temperature are taken into consideration.

	Medium	Seav	vater	Fresh	water	Lubrica	ating oil	Marine o	diesel oil	Heavy	fuel oil	
Nominal pipe dia- meter	Pipe material	steel ga	lvanized	mild	steel	mild	steel	mild	steel	mild steel		
meter	pumpside	suction	delivery	suction	delivery	suction	delivery	suction	delivery	suction	delivery	
	[m/sec]	1.0	1.4	1.5	1.5	0.6	1.0	0.9	1.1	0.5	0.6	
32	[m ³ /h]	3.5	4.9	5.2	5.2	2.1	3.5	3.1	3.8	1.7	2.1	
40	[m/sec]	1.2	1.6	1.7	1.7	0.7	1.2	1.0	1.2	0.5	0.7	
40	[m ³ /h]	5.7	7.6	8.1	8.1	3.3	5.7	4.7	5.7	2.4	3.3	
50	[m/sec]	1.3	1.8	1.9	1.9	0.8	1.4	1.1	1.3	0.5	0.8	
50	[m ³ /h]	9.5	14.0	14.8	14.8	6.2	10.9	8.6	10.1	3.9	6.2	
05	[m/sec]	1.5	2.0	2.1	2.1	0.8	1.5	1.2	1.4	0.6	0.9	
65	[m ³ /h]	16.7	22.0	23.3	23.3	8.9	16.7	13.3	15.6	6.7	10.0	
00	[m/sec]	1.6	2.1	2.2	2.2	0.9	1.6	1.3	1.5	0.6	1.0	
80	[m ³ /h]	27.5	36.1	37.8	37.8	15.5	27.5	22.3	25.8	10.3	17.2	
100	[m/sec]	1.8	2.2	2.3	2.3	0.9	1.6	1.4	1.6	0.7	1.2	
100	[m ³ /h]	53	65	68	68	27	47	31	47	21	36	
125	[m/sec]	2.0	2.3	2.4	2.5	1.1	1.7	1.5	1.7	0.8	1.4	
125	[m ³ /h]	93	107	112	116	51	74	70	79	37	65	
150	[m/sec]	2.2	2.4	2.5	2.6	1.3	1.8	1.5	1.8	0.9	1.6	
150	[m ³ /h]	148	161	168	175	87	114	101	121	60	107	
200	[m/sec]	2.3	2.5	2.6	2.7	1.3	1.8	-	-	-	-	
200	[m ³ /h]	267	291	302	314	151	198	-	-	-	-	
Aluminium	[m/sec]	2	.6	-	-	-	-	-	-	-	-	
brass	[m ³ /h]	30)2	-	-	-	-	-	-	-	-	
050	[m/sec]	2.5	2.6	2.7	2.7	1.3	1.9	-	-	-	-	
250	[m ³ /h]	458	476	494	494	238	330	-	-	-	-	
Aluminium	[m/sec]	458 476		-	-	-	-	-	-	-	-	
brass	[m ³ /h]	49	94	-	-	-	-	-	-	-	-	
200	[m/sec]	2.6	2.6	2.7	2.7	1.3	1.9	-	-	-	-	
300	[m ³ /h]	676	676	702	702	338	494	-	-	-	-	

15. Pipe Sizes and Flow Details

	Medium	Seav	vater	Fresh	water	Lubrica	ating oil	Marine of	diesel oil	Heavy	fuel oil	
Nominal pipe dia- meter	Pipe material	steel galvanized		mild steel		mild	steel	mild	steel	mild steel		
motor	pumpside	suction	delivery	suction	delivery	suction	delivery	suction	delivery	suction	delivery	
Aluminium	[m/sec]	2.	.8	-	-	-	-	-	-	-	-	
brass	[m ³ /h]	728		-	-	-	-	-	-	-	-	
250	[m/sec]	2.6	2.6	2.7	2.7	1.4	2	-	-	-	-	
brass	[m ³ /h]	817	817	848	848	440	597	-	-	-	-	
Aluminium	[m/sec]	2.	.8	-	-	-	-	-	-	-	-	
brass	[m ³ /h]	80	00	-	-	-	-	-	-	-	-	
400	[m/sec]	2.6	2.6	2.7	2.7	1.4	2	-	-	-	-	
400	[m ³ /h]	1,067	1,067	1,108	1,108	575	780	-	-	-	-	
Aluminium	[m/sec]	2.	.8	-	-	-	-	-	-	-	-	
brass	[m ³ /h]	1,1	49	-	-	-	-	-	-	-	-	
450	[m/sec]	2.6	2.7	2.7	2.7	1.4	2	-	-	-	-	
450	[m ³ /h]	1,351	1,403	1,403	1,403	727	987	-	-	-	-	
Aluminium	[m/sec]	2.	.9	-	-	-	-	-	-	-	-	
brass	[m ³ /h]	1,5	07	-	-	-	-	-	-	-	-	
500	[m/sec]	2.6	2.7	2.7	2.7	1.5	2.1	-	-	-	-	
500	[m ³ /h]	1,678	1,743	1,743	1,743	968	1,227	-	-	-	-	
Aluminium	[m/sec]	2.	.9	-	-	-	-	-	-	-	-	
brass	[m ³ /h]	1,8	572	-	-	-	-	-	-	-	-	

Table 15.1: Recommended fluid velocities and flow rates for pipework

NOTICE

The velocities given in the above table are guidance figures only. National standards can also be applied.

15.2 Piping symbols

\bowtie	Stop valve	\triangleright	Safety valve blow-off free to atmosphere	R	Diaphragm operated three-way valve
\bowtie	Gate valve	<u> </u>	Vacuum breaker	Ā	Angle valve
Å	Self closing valve		Deaerator	A	Self closing angle valve
M	Float valve		Non-return valve	\mathbf{k}	Angle relief valve
$\bar{\mathbb{A}}$	Quick closing valve remote controlled		Screw down non-return valve		Angle non-return valve
Ŕ	Control valve	\mathbf{A}	Spring loaded, relief and non-return valve	† ∡	Angle screw down non-return valve
Xa	Electrically operated valve	X A A A A A	Pressure reducing valve		Cock
Ka	Solenoid valve		Pressure reducing valve with safety valve	函	Three-way cock (T port)
K	Hydraulically operated valve	\bowtie	Three-way valve	₩.	Two-way cock (L port)
X®	Electric motor operated valve	\mathbf{k}	Automatic three-way control valve	Q 1	Angle cock
K	Diaphragm valve		Three-way valve (electrically operated)		Butterfly valve
$\mathbb{X}_{\mathbf{v}}$	Safety valve or relief valve	$\mathbb{A}_{\mathbb{Z}}$	Three-way solenoid valve		Butterfly type, temperature control valve
24	Regulating valve or needle valve		Hydraulically operated three-way valve		Non-return valve, swing type
	Flow regulating valve for control air	\mathbb{A}	Electric motor operated three-way valve		

Figure 15.1: Piping symbols 1/3

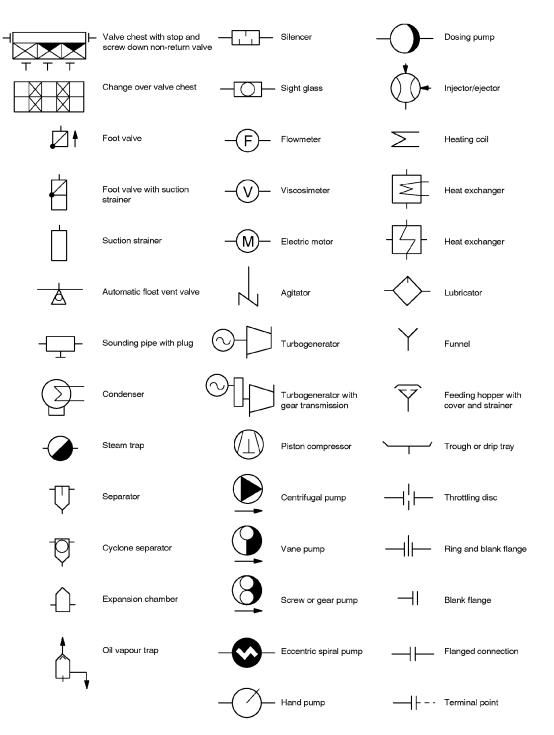


Figure 15.2: Piping symbols 2/3

	Screwed connection	-///-	Flexible hose connection	-<	Air filter condensate drain
D	Transition piece (adapter)	-[////-]-	Screwed flexible hose connection	O	Filter
╌╌	Quick connection	HVVVHF	Flanged flexible hose - connection	\mathbf{e}	Duplex filter
-Ò-	Quick-acting coupling with non-return valve female piece	\sim	Rubber hose	$\overline{\bigcirc}$	Strainer
- (-	Quick-acting coupling with non-return valve male piece	-()-	Expansion piece		Air intake filter
\rightarrow	Quick-acting coupling female piece		Packed sliding joint		
\leftarrow	Quick-acting coupling male piece	\mathbb{U}	Syphon		Pressure indicator (local) Level indicator (local)
	Quick-acting coupling complete with two non-return valves	\bigcap	Air vent		Pressure indicator (remote)
	Quick-acting coupling complete with one non-return valve	டு	Air vent with flame arrestor		Level indicator (remote)
\rightarrow + \leftarrow	Quick-acting coupling complete	\uparrow	Air vent with air release valve	PAL	Pressure alarm, low
_X _	Pipe fixed point		Spray nozzles		Differential pressure alarm, high
		0			Level alarm, low
	Pipe sliding point	Värtsilä	Limit of supply		Level alarm, high
	Pipe sliding fixed point				Level switch, low

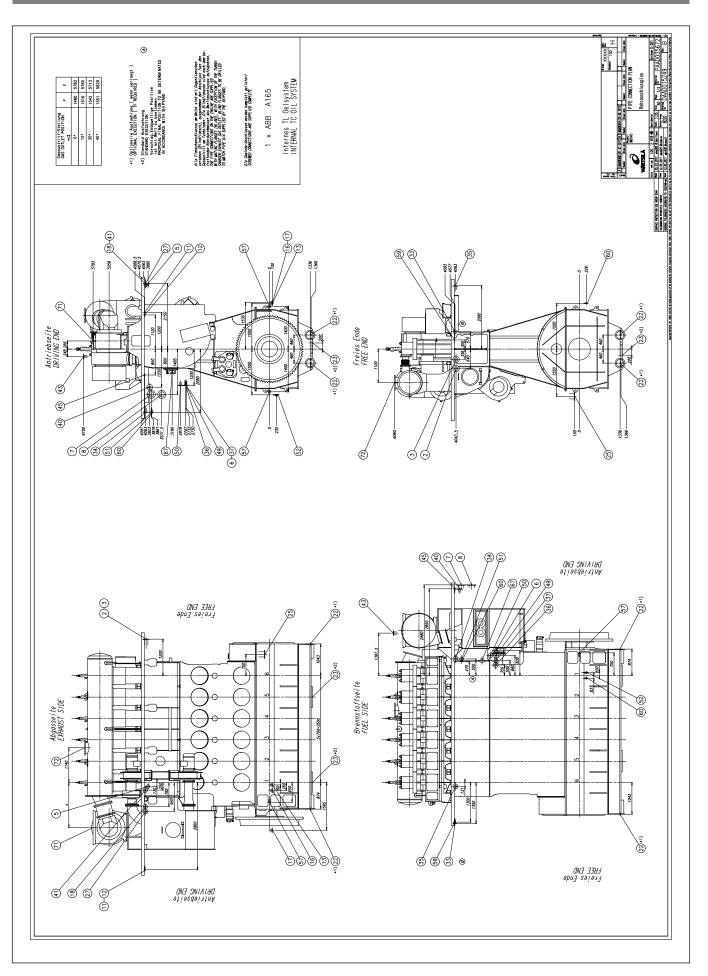
Figure 15.3: Piping symbols 3/3

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16. Pipe Connections

16.1 Drawings

DAAD015249 b	Pipe Connection Plan, W6X40	16163
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38 9603 8919 978 978 978 978 978 978 978 978 978 97		8744	8742	5748		8745	874 874		2 8810 X	2 8810 6 8810	8812	8812	8820	1 5238			2 8830 6	1038	800		9059	8103 8106			
	Rail Unit DN								Begleitheizung Brennstoff DN 12 Einfritt TRACE HEATING FUEL PN 16			Begleitheizung Brennstoff DN Austritt TRACE HATING FUEL PN	Begleitheizung Brennstoffzirkuletion DN Einfritt TRACE HATING FUEL CIRCULATION FN	Begleitheizung Brennstoffzirkuletion DN Asstritt TRAGE HATING FVEL CIRCULATION PN					Fewerlossch Anlage Rail Unit DN Einfritte Extinguiseine FLMT RaiL UNIT PN		Agges Turbolader Austritte Enwust aus Turboowneek OUTET	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~			
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	Schniercel Turboloder DN Eintritt UL TURBOCHNRER DN LUBBICATING OIL TURBOCHNRER PN		Soveloel Automotikiiiter DN Austritt Eutoshiko Olu Autoukiic Filter PN OUTLET	Schmutzeel Ablauf Versorgungseinheit DN Austritt DIRTY OIL DRAIN SUPPLY UNIT PN OUTLET	Schmiercel Kreuzkopf Eintritt LUBBICKTING OLL CROSSNEND PN INLET	Lectorgen von Notor Austritt DRY OIL LEXXXE FRON ENGINE PN	Zyrlinder Schmieroel DN Eintritt Crunder LUB. OIL PN		8		seite		Delablowf149. Versorgungseinheit DN Austritt OIL PIPE DRAIN SUPPLY UNIT PN OUTEF	Lectogesblowf Zylinderblock DN Austrift LEVAUGE DRAIN CTLINDER BLOCK PN OUTLET		2	Entimettung Moste Gate Austritt VENTING MASTE GATE OUTLET		Entimetiung Zylinderkuehlæsser DN Mustritt VENTING CYLINDER 000LING MATER PN 00/TLET	Stewer luftversorgung Eintritt couneou AIR SUPPLY PN IM.ET	Stewarluftversorgung Eintritt couneou AIR SuPPLY PN INLET				ecklauf
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	58	58	58	N N Sun N			5 2	58	5.5	38		und SLK		55	8 E 5		5.5	3.8						5 E	5 8
	Zyl inderkuch lesseer Eintritt Crumer cool no water INLET	Zyl inderkuehtwasser Eintritt Cyr inder ood ind water INLET	Zyl i nderkwehl wesser Austritt Cruincer coou no water OunuET	Zylinderkuehimsser Entlueftung Entlueftung Criminer coolins mitter ventins Ventins	Zylinderkuehlessser Entleerung Austritt Crinder coolins Mater DRAIN OUTLET	SLK Entleerung Austritt SAC DBAIN OutleT	SLK-MT-Kuehlmasser Eintritt Skc-LT-cool ING MATER INLET	SLK-MT-Kuehlmasser Austritt SkC-LT-COOLING WATER OUTLET	SLK-HT-Kuehlwasser Eintritt SkC-HT-COOLING WATER INLET	SLK-HT-Kuehlmasser Austritt Skc-HT-colling mater Outlef	Messer four Reinigungsanloge TL und SLK Eintritt WATER FOR CLEANING PLANT TC AND SAC INLET	Luft fuer Reinigungsonloge TL und SLK Eintritt AIR FOR CLEANING PLANT TC AND SAC	Deliges Wasser von Receiver Austritt OULY WATER FROM RECEIVER OULLET	Turboloder Schmutzwasser Austritt TUBBOCHARGER DIRTY WATER OUTLET	Ablauf vom Masserabscheider Austritt WATER DRAIN FROM MATERSEPERATOR OUTLET	SLK Kondensmosser Austritt SAC CONDENSATE WATER OUTLET	SLK Waschwasser Austritt Skc WksHiNS WATER OUTLET	SLK Entiueftung Entiueftung SAC VENTING VENTING				Delablauf Grundplatte Horizontal Olt DRAIN BEDPLATE HORIZONTAL	Delablauf Grundplatte Vertikal OLL DRAIN BEDPLATE VERTICAL	Zylinder Schmieroel Austrikt Cylinger LUB. Oll OUTLET	Houp technier oel Eintritt Muin Lubricatino oil Inlet
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17. Engine Automation

Developments in Automation & Controls at Wärtsilä are focussed on the latest trends in ship automation that tend to still higher integration levels.

The standard electrical interface, designated DENIS-UNIC (**D**iesel **E**ngine Co**N**trol and optImizing **S**pecification), assures a perfect match with approved remote control systems, while the UNIC (**W**ärtsilä **E**ngine **C**ontrol **S**ystem) takes care of all RT-flex-specific control functions.

All those systems provide data bus connection to the ship automation to facilitate installation and make specific data available wherever required. Complete ship automation systems provided by one of the leading suppliers approved by Wärtsilä offer the degree of integration demanded in modern shipbuilding while being perfectly adapted to the engine's requirements.

Applying a single supplier strategy for the entire ship automation shows many other advantages in terms of full responsibility, ease in operation and maintenance.

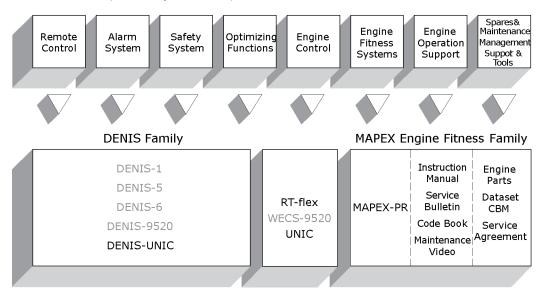


Figure 17.1: EMA concept comprising DENIS, UNIC

- DENIS The DENIS family contains specifications for the engine management systems of all modern types of Wärtsilä two-stroke marine diesel engines. The diesel engine interface specification applicable is DENIS-UNIC.
- UNIC Under the designation of UNIC, Wärtsilä Switzerland Ltd. provides a fully embedded engine control system. The UNIC system is handling e.g. tasks related to fuel injection, exhaust valve control, cylinder lubrication, engine crank angle measurement and speed/load control. The system uses modern bus technologies for safe transmission of sensor- and other signals.

17.1 UNIC - engine control system interface

17.1.1 Concept

The concept of UNIC meets the requirements of increased flexibility and higher integration in modern ship automation and provides the following advantages for shipowners, shipyards and engine builders:

Clear interface definition

The well defined and documented interface results in a clear separation of the responsibilities between engine builder and ship automation supplier. It allows authorised suppliers to adapt their systems to the RT-flex engines with reduced engineering effort. The clear signal exchange simplifies troubleshooting.

Approved propulsion control systems

Propulsion control systems including remote control, safety and telegraph systems are available from suppliers approved by Wärtsilä. This cooperation ensures that these systems fully comply with the specifications of the engine designer.

Easy integration in ship management system

Providing data bus communication between UNIC, the propulsion control and the vessel's alarm and monitoring system enables an easy integration of the different systems. The human-machine interface (HMI) of the vessel's automation can therefore also handle the additional MMI functions attributed to the UNIC.

Ship automation from one supplier - integrated solution

Automation suppliers approved by Wärtsilä can handle all ship board automation tasks. Complete automation systems from one supplier show advantages like easier engineering, standardisation, easier operation, less training, fewer spare parts, etc.

The UNIC is well suited to support this integrated automation concept by providing redundant data bus lines that deliver all necessary information for propulsion control, alarm / monitoring system and man-machine interface. The HMI of the UNIC can provide additional features when using such an integrated solution.

Ship automation from different suppliers - split solution

In case the propulsion control and alarm / monitoring systems are from different suppliers, the UNIC also supports such a split solution by providing two separate redundant data bus lines, one each for the propulsion control and the alarm / monitoring system. In that case the MMI functions are also split within propulsion control and alarm / monitoring system.

UNIC describes the signal interface between the RT-flex engine and the ship automation...

UNIC specification does not include any hardware. It summarises all the data. UNIC specification is presented in two sets of documents:

UNIC engine specification

This file contains the specification of the signal interface on the engine and is made available to engine builders and shipyards.

- It consists basically of the control diagram of the engine, the signal list including a minimum of functional requirements, and gives all information related to the electrical wiring on the engine
- It lists also the necessary alarm and display functions to be realised in the vessel's alarm and monitoring system.
- The UNIC engine specification covers the engine-built components for control, alarm and indication.

UNIC remote control specification

This file contains the detailed functional specification of the remote control system.

• The intellectual property on this remote control specification remains with Wärtsilä. Therefore this file is licensed to remote control partners of Wärtsilä only. The companies offer systems which are built exactly according to the engine designer's specifications, tested and approved by Wärtsilä.

17.1.2 Propulsion control system

The propulsion control system is divided in the following sub-systems:

- Remote control system
- Safety system
- Telegraph system

The safety and the telegraph systems work independently and are fully operative even with the remote control system out of order.

17.1.3 Approved propulsion control systems

Wärtsilä has an agreement with each of the following marine automation suppliers concerning the development, production, sales and servicing of remote control and safety systems for their engines. All approved propulsion control systems listed below comprise the same functionality specified by Wärtsilä

Supplier / company		Remote control system
Kongsberg Maritime		
Kongsberg Maritime AS P.O. Box 1009 N-3194 Horten Norway	km.sales@kongsberg.com Tel. +47 81 57 37 00 Fax +47 85 02 80 28	AutoChief C20
NABTESCO Corporation		
NABTESCO corp., Marine Control Systems Company 1617-1, Fukuyoshi-dai 1-chome Nishi-ku Kobe, 651-22413 Japan	Tel. +81 78 967 5361 Fax +81 78 967 5362	M-800-III
SAM Electronics GmbH / Lyngsø	Marine	
SAM Electronics GmbH Behringstrasse 120 D-22763 Hamburg Germany	Tel. +49 40 88 25 0000 Fax +49 40 88 25 4116	DMS2100i
Lyngsø Marine AS 2, Lyngsø Allé DK-2970 Hørsholm Denmark	Tel. +45 45 16 62 00 Fax +45 45 16 62 62	

Table 17.1: Suppliers of remote control systems

Modern remote control systems consist of electronic modules and operator panels for display and order input for engine control room and bridge. The different items normally communicate via bus connections. The engine signals described in the UNIC specification are connected via the terminal boxes on the engine to the electronic modules placed in the engine control room.

These electronic modules are built to be located either inside the ECR console or in a separate cabinet to be located in the ECR. The operator panels are to be inserted in the ECR console's surface.

17.1.4 Interface to alarm and monitoring systems

General layout - operator interface (OPI)

Hardwired signals from alarm sensors mounted on the engine had to be connected to the vessel's alarm and monitoring system. Additional sensors with hardwired connections are fitted in order to monitor RT-flex-specific circuits of the engine. In addition to that, the RT-flex engine control system (UNIC) provides alarm values and analogue indications via data bus connection to the ship's alarm and monitoring system as part of the operator interface of the engine. Connection from UNIC to engine automation can be made in two ways.

Integrated solution

Propulsion control system and alarm / monitoring system from same supplier:

- This allows connecting both the propulsion control system and the alarm / monitoring system through one redundant bus line only (CANopen) to the UNIC.
- By using the integrated solution the testing and commissioning can be done already at the engine builders testbed. The wiring during installation to the ship is kept to a minimum consisting of power cables and bus communication.

Split solution

Propulsion control system and alarm / monitoring system from different suppliers except Kongsberg:

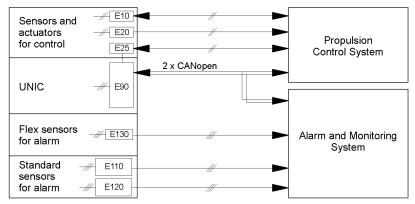
- The propulsion control system is connected through one redundant bus line (CANopen) to the UNIC.
- For the separate alarm / monitoring system an additional redundant Modbus RTU serial connection is available.
- Wärtsilä provides modbus lists specifying the display values and alarm conditions as part of the UNIC engine specification.

Requirements for any alarm / monitoring system to be fulfilled in a split solution:

- Possibility to read values from a redundant Modbus line according to standard Modbus RTU protocol.
- Ability to display analogue flex system values (typically 20 values) and add alarm values provided from UNIC to the standard alarm list (100-200 alarms depending on engine type and number of cylinders).

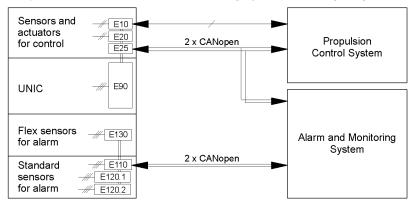
Integrated solution

Propulsion Control and Alarm and Monitoring System from same suppliers



Integrated solution

Propulsion Control and Alarm and Monitoring System from Kongsberg



Split solution

Propulsion Control and Alarm and Monitoring System from different suppliers

Sensors and actuators for control	-# E10 -# E20 E25		Propulsion Control System
		2 x CANopen	_
UNIC	-#~ E90	2 x Modbus	•
Flex sensors for alarm	-#- E130		Alarm and Monitoring System
	# E110		-
sensors for alarm	-#E120	///	-

Figure 17.2: Integrated/split solution

Alarm sensors and safety functions

The classification societies require different alarm and safety functions, depending on the class of the vessel and its degree of automation. These requirements are listed together with a set of sensors defined by Wärtsilä in the tables below.

The time delays for the slow-down and shut-down functions given in tables below are maximum values. They may be reduced at any time according to operational requirements. When decreasing the values for the slow-down delay times, the delay times for the respective shut-down functions are to be adjusted accordingly. The delay values are not to be increased without written consent of Wärtsilä.

Included in the standard scope of supply are the minimum of safety sensors as required by Wärtsilä for attended machinery space (AMS). If the option of unattended machinery space (UMS) was chosen, the respective sensors have to be added according to the requirements issued by Wärtsilä.

There are also some additional sensors defined for the monitoring of flex system-specific engine circuits.

The extent of delivery of alarm and safety sensors has to cover the requirements of the respective classification society, Wärtsilä, the shipyard and the owner. The sensors delivered with the engine are basically connected to terminal boxes mounted on the engine. Signal processing is performed in a separate alarm and monitoring system usually provided by the shipyard.

Alarm sensors and safety functions (part 1)

	Α	larm and safety functions			Values					
Medium	Phys. Value	Location	Signal No.	Function	Level	Setting	Delay [s]			
Cylinder cooling w	vater	1	L			1	1			
			DTIIOIA	ALM	L	2.0 bar	0			
	Pressure	Engine Inlet	PT1101A	SLD	L	1.8 bar	60			
			PS1101S	SHD	L	1.5 bar	60			
		Engine Inlet	TE1111A	ALM	L	65 °C	0			
	Temperature		TE1101 00A	ALM	Н	90 °C	0			
		Outlet each cyl.	TE1121-28A	SLD	Н	95 °C	60			
Scavenge air cooli	ing water	1	L			1	1			
	Pressure	Inlet cooler	PT1361A	ALM	L	2.0 bar	0			
fresh water single- stage	- .	Inlet cooler	TE1371A	ALM	L	25 °C	0			
stage	Temperature	Outlet cooler	TE1381A	ALM	Н	80 °C	0			
Main bearing oil	1	I				1	1			
				ALM	L	3.8 bar	0			
	Pressure	Supply	PT2001A	SLD	L	3.6 bar	60			
			PS2002S	SHD	L	3.1 bar	10			
			DTOOOOA	ALM	L	3.8 bar	0			
	Pressure	Before injectors	PT2003A	SLD	L	3.6 bar	60			
				ALM	Н	50 °C	0			
	Temperature	Supply	TE2011A	SLD	Н	55 °C	60			
				ALM	Н	65 °C	0			
	Temperature	Oultet Bearing 2-10	TE2102-10A	SLD	Н	70 °C	60			
Servo oil						<u> </u>				
	Flow *1)	Pump inlet	FS2061-62A	ALM	L	no flow	0			
Leakage monitoring	Level	Supply Unit	LS2055A	ALM	Н	max.	0			
Thrust bearing oil		-				<u> </u>				
-				ALM	Н	65 °C	0			
	Temperature	Outlet Thrust rad. bearing	TE2101A	SLD	Н	70 °C	60			
Thrust bearing pac	ds	1	1	1		1	1			
				ALM	Н	80 °C	0			
		Fore side	TE4521A	SLD	Н	85 °C	60			
	Temperature		TE4521S	SHD	Н	90 °C	60			
		Aft side	TE4522S	SHD	Н	90 °C	60			
Oil mist concentra	tion	1]	1		1	1			
	Concentra-		AS2401A	ALM	Н		0			
	tion	Crankcase	AS2401S	SLD	H		60			
	Failure	Detection unit	XS2411A	ALM	F		0			

	Α	larm and safety functions				Values	
Medium	Phys. Value	Location	Signal No.	Function	Level	Setting	Delay [s]
Piston cooling oil		1					
	- .		TEOEO (ALM	Н	80 °C	0
	Temperature	Outlet each cyl.	TE2501-08A	SLD	Н	85 °C	60
	Flow	Inlet each cyl.	FS2521-28S	SHD	L	no flow	15
Turbocharger oil	1	I				1	1
			PT2611A	ALM	L	1.0 bar	5
ME bearing oil sup-	Pressure	Inlet each TC	*2)	SLD	L	0.8 bar	60
ply			PS2611S	SHD	L	0.6 bar	5
ABB A100-L				ALM	H 80 °C H 85 °C L no flow L 0.8 bar L 0.6 bar H 120 °C H 120 °C H 0.7 bar L 0.4 bar L 0.4 bar H 120 °C H 120 °C H 120 °C H 90 °C L 1.4 bar H 85 °C H 90 °C H 35 °C H 50 °C H 35 °C H 20 cSt H 20 cSt H 50 °C L 13 cSt	0	
	Temperature	Outlet TC	TE2601A	SLD	Н	120 °C	60
				ALM	L	0.7 bar	5
ME bearing oil sup-	Pressure	Inlet each TC	PT2611A	SLD	L	0.6 bar	60
ply			PS2611S	SHD	L	0.4 bar	5
IHI MET	_			ALM	Н	85 °C	0
	Temperature	Outlet TC	TE2601A	SLD	Н	90 °C	60
Geislinger damper	oil	I		1			
	Pressure	Casing inlet	PT2711A	ALM	L	1.0 bar	0
Axial damper (detu	ner) oil	I		1			
	_	Aft side	PT2721A	ALM	L	1.7 bar	60
	Pressure	Fore side	PT2722A	ALM	L	1.7 bar	60
Cylinder lubricating	g oil			1			I
				ALM	Н	50 °C	0
	Temperature	Supply unit inlet	TE3101A	ALM	L	35 °C	0
Fuel oil		I		1			I
				ALM	Н	20 cSt	0
	Viscosity	Before supply unit		ALM	L	13 cSt	0
			TE3411A	ALM	Н	50-160 °C	0
	Temperature	Before supply unit	*3)	ALM	L	20-130 °C	0
		After fuel pump	TE3431-32A	ALM	D	-30 °C	30
	Pressure	Before supply unit	PT3421A	ALM	L	7 bar	0
		Rail unit	LS3444A	ALM	Н	max.	0
Leakage	Level	Fuel pipe	LS3446A	ALM	Н	max.	0
Heating	Failure	Fuel pipe	XS3463A	ALM	F		0

	Α	arm and safety functions				Values	
Medium	Phys. Value	Location	Signal No.	Function	Level	Setting	Delay [s]
Exhaust gas							
				ALM	Н	515 °C	0
	Tomoreture	After each culinder	TT2701 084	ALM	D	<u>+</u> 50 °C	0
	Temperature	After each cylinder	TT3701-08A	SLD	Н	530 °C	60
				SLD	D	<u>+</u> 70 °C	60
		Defere each turbacharger	TE0701A	ALM	Н	515 °C	0
	Townson	Before each turbocharger	TE3721A	SLD	Н	530 °C	60
	Temperature		TE0701A	ALM	Н	480 °C	0
		After each turbocharger	TE3731A	SLD	Н	500 °C	60
Scavenge air							
				ALM	L	25 °C	0
		After each cooler	TE4031A *4)	ALM	Н	60 °C	0
	Temperature			SLD	Н	70 °C	60
		-	TE (004,004	ALM	Н	80 °C	0
		Each piston underside	TE4081-88A	SLD	Н	120 °C	60
			1.0.4074.4	ALM	Н	max.	0
Condensation water *5)		Water separator	LS4071A	SLD	Н	max.	60
	Level		1.0.4075.4	ALM	Н	max.	0
		Before water separator	LS4075A	SLD	Н	max.	60
Staring air							
	Pressure	Engine inlet	see UNIC list	Start inte	erlock		
Air spring air	1	·	L			1	1
				ALM	Н	7.5 bar	0
	Duran		PT4341A	ALM	L	5.5 bar	0
	Pressure	Distributor		SLD	L	5.0 bar	60
			PS4341S	SHD	L	4.5 bar	0
Leakage oil	Level	Exh. Valve air	LS4351A	ALM	Н	max.	0
Control air							
Supply			PT4401A	ALM	L	6.0 bar	0
<u>.</u>	Pressure	Engine inlet	PT4411A	ALM	L	5.5 bar	0
Stand-by supply			PT4421A	ALM	L	5.0 bar	0
UNIC control syste	m						
	Power failure	Pwr. supply box	XS5056A	ALM	F		
Engine	1	1				1	1
Overspeed	Speed	Crankshaft	ST5111-12S	SHD	Н	110%	0
*1) ALM has to be s	uppressed at l	ow load.	I			1	1

*2) The indicated alarm and slow-down values and the values indicated are minimum settings allowed by the TC maker. In order to achieve an earlier warning, the ALM and SLD values may be increased up to 0.4 bar below the minimum effective pressure measured within the entire engine operation range. The final ALM/SLD setting shall be determined during commisioning / sea trial of the vessel.

*3) ALM vale depending on fuel viscosity.

	AI	arm and safety functions			Values				
Medium	Medium Phys. Value Location Signal No. Function								
*4) For water separators made from plastic material the sensor must be placed right after the separator.									
5) Alternatively, low temperature alarm or condensation water high level alarm.									
Table 17.2: Table of alarm sensors and safety functions (part 1)									

Alarm sensors and safety functions (part 2)

Alarm and s	afety functions	;	min.	. WCH requ ments	uire-		Red	ques	st of c	lassif	icat	ion s	soci	eties	for L	JMS	
Medium	Signal No.	Function	for AMS	add. to AMS for UMS	add. flex sig- nals	IACS	ABS	вv	ccs	DNV	GL	KR	LR	MRS	NK	PRS	RINA
Cylinder coo	oling water					-								-	_		
	PT1101A	ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
	FILIDIA	SLD	•			•	•	•	•	•	•	•	•	•	•	•	•
	PS1101S	SHD	•								•						
	TE1111A	ALM		•							•						•
	TE1101 00A	ALM		•		•	•	•		•	•	•	•	•	•	•	•
	TE1121-28A	SLD		•		•	•	•	•	•	•	•	•	•	•	•	•
Scavenge a	ir cooling wate	r															
	PT1361A	ALM		•													
Fresh water single-stage	TE1371A	ALM		•													
Single-Stage	TE1381A	ALM		•													
Main bearin	g oil	1	1	I		1			1					1			1
		ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
	PT2001A	SLD	•			•			•		•		•		•	•	
	PS2002S	SHD	•			•	•	•	•	•	•	•	•	•	•	•	•
		ALM															
	PT2003A	SLD															
		ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
	TE2011A	SLD		•			•	•	•		•			•		•	•
		ALM				•	Α	A	Α	A	A	A	A	Α	A	Α	А
	TE2102-10A	SLD									A						
Servo oil		020															
	FS2061-62A	ALM	•														
Leakage monitoring	LS2055A	ALM	•														
Thrust bear	ing oil																
		ALM				•	Α	А	Α	Α	A	A	A	A	A	Α	А
	TE2101A	SLD									A						
Thrust beari	ing pads																<u> </u>
		ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
	TE4521A	SLD		•		•	•	•	•	•	•				•	•	
	TE4521S	SHD		-		•	•	-	•	-	-	-			-	•	
	TE45215	SHD				-	-	-	-								
Oil mist con																	
	AS2401A	ALM	•			•	В	В	В	В	В	В	В	В	В	В	В
	AS2401A AS2401S	SLD	•			•	В	В	B	В	B	В	В	В	В	В	В
						-	D	D		D		D			D	D	D
	XS2411A	ALM	•								•		•				

Alarm and s	afety functions	5	min.	WCH request ments	uire-	Request of classification societies for UMS											
Medium	Signal No.	Function	for AMS	add. to AMS for UMS	add. flex sig- nals	IACS	ABS	вv	ccs	DNV	GL	KR	LR	MRS	NK	PRS	RINA
Piston cooli	ng oil																
		ALM		٠		•	•	•	•	•	•	•	•	•	•	•	•
	TE2501-08A	SLD		•		•	•	•	•	•	•	•	•	•	•	•	•
	FS2521-28S	SHD	•						•		•						
Turbocharg	er oil																
	DTooldA	ALM		•							•					•	
ME bearing	PT2611A	SLD		٠													
oil supply	PS2611S	SHD	•														
ABB A100-L	TEOROLA	ALM		•					•		•					•	
	TE2601A	SLD	•														
		ALM		٠							•					•	
ME bearing oil supply MHI MET	SLD		•														
	PS2611S	SHD	•														
MB	TE2601A	ALM		•					•		•					•	
		SLD	•														
Geislinger d	lamper oil																
	PT2711A	ALM		•													
Axial dampe	er (detuner) oil																
	PT2721A	ALM		•													
	PT2722A	ALM		•													
Cylinder lub	pricating oil																
	_	ALM															
	TE3101A	ALM															
Fuel oil																	
		ALM		•		D	D	D	D	D	D	D	D	D	D	D	D
		ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
		ALM		•							С						
	TE3411A	ALM		•		С	С	С	С	С	C	С	С	С	С	С	С
	TE3431-32A	ALM			•		-	-		-	-					-	-
	PT3421A	ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
	LS3444A	ALM			•												
	LS3446A	ALM			•												
Failure	XS3463A	ALM															
	7004004																

Wärtsilä X40 Marine Installation Manual

Alarm and s	afety functions	6	min.	. WCH requents	uire-	Request of classification societies for UMS											
Medium	Signal No.	Function	for AMS	add. to AMS for UMS	add. flex sig- nals	IACS	ABS	вv	ccs	DNV	GL	KR	LR	MRS	NK	PRS	RINA
Exhaust gas	5																
		ALM		•		•	•	•	•	•	•	E	•	•	•	•	•
	TT3701-08A	ALM		•		•	•	•	•	•	•	F	•	•	•	•	•
	113701-00A	SLD		•		•	•	•	•	•	•	•	•	•	•	•	G
		SLD		•							•					•	•
	TE0701 A	ALM				•			•		•				•	•	•
	TE3721A	SLD															Н
		ALM				•			•		•		•		•	•	
	TE3731A	SLD								•							
Scavenge a	ir				1	1								1			
		ALM		•			Ι				Ι	•		0	•	•	I
	TE4031A	ALM		•			•		1		•	•		0	•	•	•
		SLD							1								
		ALM		•		•	•	•	ĸ	•	•	•	•	•	•	•	•
	TE4081-88A	SLD		•		•	•	•	K	•	•	•	•		•	•	•
		ALM		•		•	K	•	•		K		•		•		К
Condensa-	LS4071A	SLD		•													
tion water		ALM		•		•	K	•	•		K				•		К
	LS4075A	SLD		•													
Starting air		011															
Start inter- lock	see UNIC list			•		•	•	•	•	•	•	•	•	•	•	•	•
Air spring a	ir			I	1	1		1	1					1	1		I
		ALM	•	•		•											
	PT4341A	ALM	•			•			•		•						
		SLD	•			•											
	PS4341S	SHD	•			•											
Leakage oil	LS4351A	ALM	•			•											
Control air			<u> </u>	<u> </u>												L	<u> </u>
Supply	PT4401A	ALM		•		•	•	•	•	•	•	•	•	•	•	•	•
	PT4411A	ALM		•					•								
Stand-by supply	PT4421A	ALM		•					•		•						
UNIC contro			<u> </u>														<u> </u>
	XS5056A	ALM			•												
Engine	A00000A	, /LIVI															
Overspeed	ST5111-12S	SHD	•			•	•	•	•	•	•	•	•	•	•	•	•
Overspeed	515111-125		-			-	•	-		•				-		•	-

Table 17.3: Table of alarm sensors and safety functions (part 2)

Classification societies

IACS	International Association of Classification Societies
ABS	American Bureau of Shipping
BV	Bureau Veritas
CCS	Chinese Classification Society
DNV	Det Norske Veritas
GL	Germanischer Lloyd
KR	Korean Register
LR	Lloyd's Register
MRS	Maritime Register of Shipping (Russia)
NK	Nippon Kaiji Kyokai
PRS	Polski Rejestr Statkow
RINA	Registro Italiano Navale

Table 17.4: Classification societies

Request of classification societies

R	equest of classification	tion societ	ies for UMS:	Special	Special request for AMS:				
•	Request	A or B		•	Request for AMS only				
0	Recommendation	C or D		•	Additional request to UMS for AMS				
AMS	Attended ma- chinery space	E or F	are requested altern- atively						
UMS	Unattended ma- chinery space	G or H							
		l or K							

Table 17.5: Request of classification societies

Functions and level

	Function:	Level:					
ALM	Alarm	Н	High				
SLD	Slow down	L	Low				
SHD	Shut down	D	Deviation				
		F	Failure				

Table 17.6: Functions and level

17.2 Drawings

DAAD007603 a

1034	GENERAL IULERANCES ACCURDING IU IJUL DOTION		S	PE De	ITE CIF INI		CE ATIC NIC)N	
	1	006	PAAD012765	INTERFACE	E SPECIFICAT MODBUS TO	TION AMS-SIGN,LIST	DAAD023074		0.001
	1	005	PAAD020618	INTERFACE	E <u>SPECIFICAT</u> MODBUS	TION S TO AMS-SPEC.	DAAD010110		0.01
	1	004	PAAD017073	BLOCK DI	IGRAM		107.428.695		0.001
	1	003	PAAD012690	ELECTRIC	POWER DIAGR	AM POWER SUPPLY	DAAD007443		0.001
	1	002	107.382.086.500	CONTROLS	SPECIFICATIO	N PROJECT DATA	107.382.086		0.001
	1	001	PAAD012736	INTERFACE	E SPECIFICAT DENIS-UN		107.430.751		0.001
	QTY	SEQ NO	Material ID	Material Nam		nsion/Occ.Dimension	Standard or Drawing	Basic Material Material Standar	Weight d GR./NET
on of the drawing the whole nor any n, fabrication, de accessible rtsilä	Free space for lic.								SO SO SO SO SO SO SO SO SO SO SO SO SO S
g possessi . Neither onstructio way nor ma	Modif.	A EAAD Numb	083290 02.02.2012 er Drawn date	2 Number	Drawn d	late Number	Drawn date	Number	Drawn date
Logyright Marcisto. All rights reserved by forcing possession of the arowing the resignent recognizes and honours these rights. Melher the whole nor only port of this draving may be used in only way for construction, fabrication, marketing or ony other purpose nor copied in only way nor made accessible to third porties without the previous written consent of Marisila	Units			oduct 5-8X35 5-8X40	Basic Material		ITERFACE SF c / content		ON eight 0.006
S A G G	Made	30.07.	•		Scale 1:1	Size Page A4	Material 1/1 ID	PAADO	12694
indrts ofentr bientr por ar									

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18. General Installation Aspects

The purpose of this chapter is to provide information to assist in planning and installation of the engine. It is for guidance only and does not supersede current instructions.

The illustrations in this chapter do not necessarily represent the actual configuration or the stage of development, nor the type of your engine.

For all relevant and prevailing information consult section 'drawings' of this chapter.

18.1 Engine Dimensions and masses

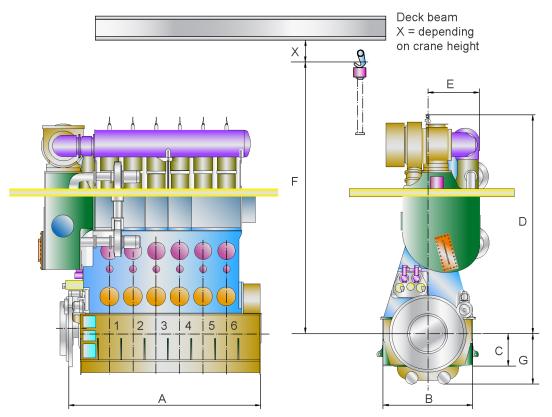


Figure 18.1: Engine dimensions

Number of cylinders		5	6	7	8			
	Α	5,107	5,807	6,507	7,207			
	В	2,610						
	С	950						
Dimensions in mm with a tolerance of approx. ±10 mm	D	6,344						
	E	1,430 *1)						
	F	7,700						
	G		1,4	11				
Net engine mass (without oil/water) [tonnes]	109	125	140	153				
Minimum crane capacity [kg]	1,500							

NOTICE

F: Min. height to crane hook for vertical piston removal.

- Mass estimated according to nominal dimensions of drawings, including turbocharger and SAC, pipings and platforms.

*1) Dimension E depends on type of turbocharger

18.1.1 Dimensions and masses of main components

Number of cylinders			5	6	7	8	
Dedulate including bearing sinders	length	[mm]	4,935	5,635	6,335	7,035	
Bedplate including bearing girders	mass	[kg]	18,000	20,000	22,000	24,000	
Orealisheft	length	[mm]	4,750	5,450	6,150	6,850	
Crankshaft	mass	[kg]	20,000	23,000	26,000	29,000	
Flywheel (light)	diametre	[mm]		2,2	230		
Column complete (menchleel)	length	[mm]	4,110	4,810	5,510	6,210	
Column, complete (monoblock)	mass	[kg]	12,540	14,520	16,720	18,810	
	length	[mm]		4,0)25		
Tie rod complete	mass	[kg]		5	0		
Culinder block	length	[mm]	3,729	4,429	5,129	5,829	
Cylinder block	mass	[kg]	9,010	10,617	12,250	13,865	
O dia dan linan	height	[mm]	1,990				
Cylinder liner	mass	[kg]	880				
Connecting red without bearing covers	length	[mm]	2,362				
Connecting rod without bearing covers	mass	[kg]	825				
Creechard complete with guide charge	length	[mm]		73	30		
Crosshead, complete with guide shoes	mass	[kg]		59	90		
Distan, complete with red	height	[mm]		2,4	120		
Piston, complete with rod	mass	[kg]		4	55		
	length	[mm]	3,850	4,550	5,250	5,950	
Scavenge air receiver	mass	[kg]	1,228	1,460	1,692	1,924	
	height	[mm]		1,0	005		
Exhaust valve, complete	mass	[kg]	745				
	length	[mm]		ø 696	x 330		
Cylinder cover	mass	[kg]	458				

Table 18.1: Dimensions and masses of main components

18.1.2 Thermal expansion at the turbocharger expansion joint

Before making expansion pieces, enabling connections between the engine and external engine services, the thermal expansion of the engine has to be taken into account. The expansions are defined (from ambient temperature 20°C to service temperature 55°C) as follows (see also fig. *18.2*):

Distance from

Transverse expansion (X): crankshaft centerline to centre of gas outlet flange Vertical expansion (Y): bottom edge of bedplate to centre of gas outlet flange Longitudinal expansion (Z): engine bedplate aft edge to centre of gas outlet flange

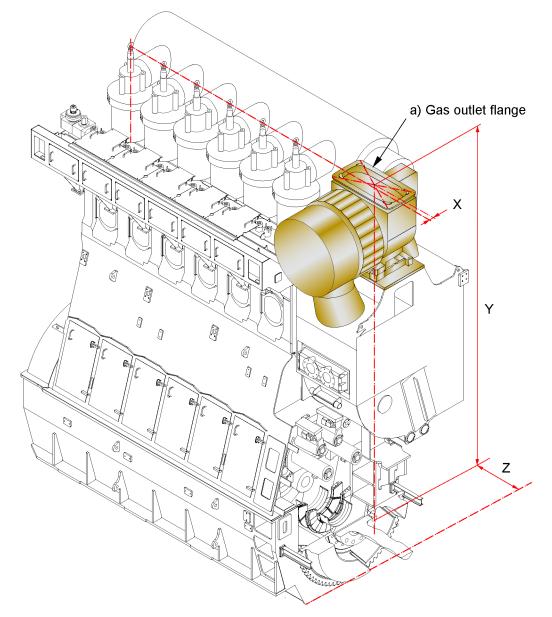


Figure 18.2: Thermal expansion, dim. X, Y, Z

18.1.3 Contents of fluid in the engine

No. of cyl.	Lubricating oil	Cylinder cooling water	Freshwater in scavenge air cooler(s) *1)	Total of water and oil in engine *2)
	[kg]	[kg]	[kg]	[kg]
5	414	135	110	659
6	447	153	110	710
7	531	171	145	847
8	572	256	145	973

Table 18.2: Fluid quantities in the engine

NOTICE

*1) The given water content is approximate.

*2) These quantities include engine piping except piping of scavenge air cooling.

18.1.4 Crane requirements

- An overhead travelling crane of min. 1,500 kg is to be provided for normal engine maintenance.
- The crane is to conform to the requirements of the classification society.

As a general guide Wärtsilä Switzerland Ltd. recommends a two-speed hoist with pendent control, allowing to select high or low speed, i.e. high 6.0 m/minute, low 0.6-1.5 m/minute.

18.1.5 Piston and tie rod dismantling heights

Piston dismantling heights

For the possibility of reducing the standard piston dismantling height applying special tools and/or tilted piston position please ask Wärtsilä Switzerland Ltd. These dimensions are for guidance only and may vary depending on the crane dimension, handling tools and dismantling tolerances.

These dimensions are absolutely not binding. However, please contact Wärtsilä Switzerland Ltd. or any of its representatives if these values cannot be maintained or more detailed information is required.

See section 'Drawings' in this chapter.

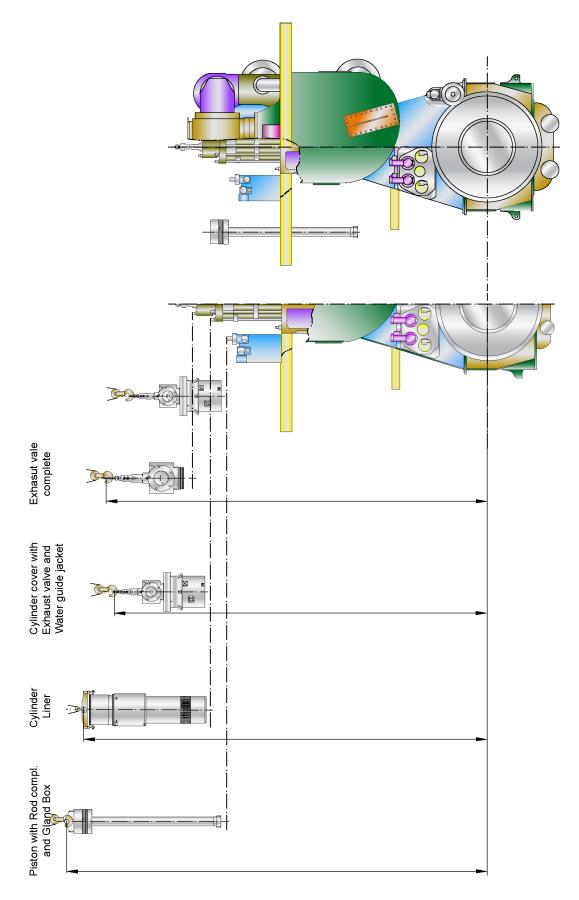


Figure 18.3: Space requirements and dismantling heights for vertical piston lifting

18.1.6 Dismantling of scavenge air cooler

To facilitate dismantling of the scavenge air coolers, an adequate lifting facility may be provided.

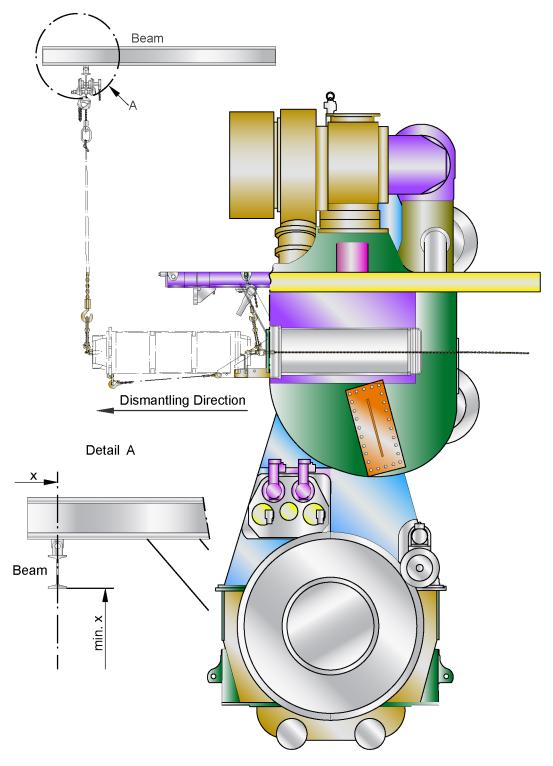
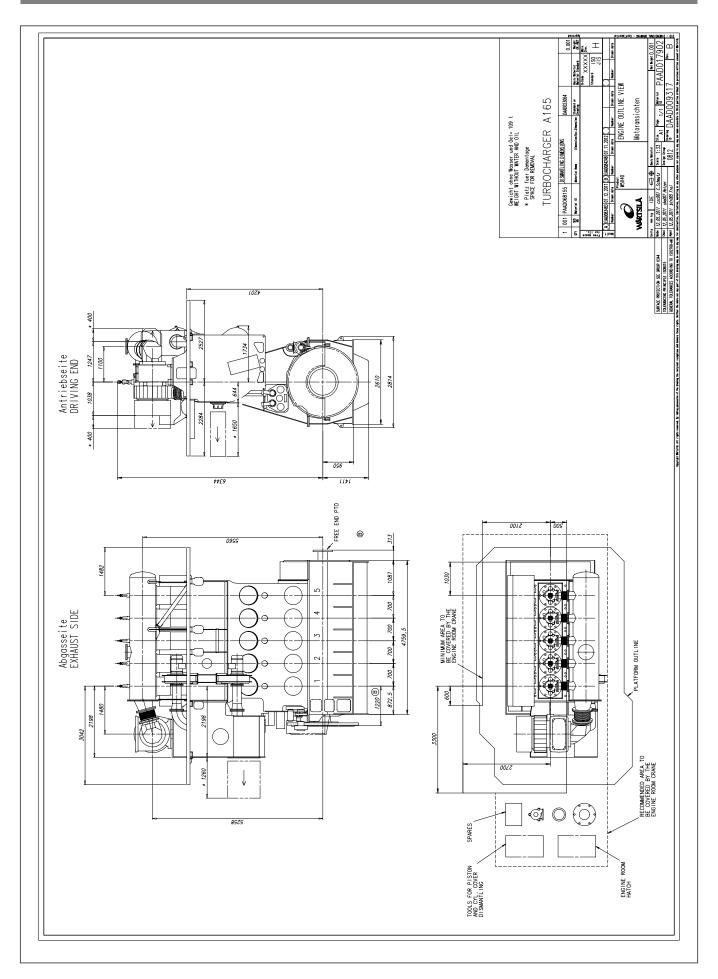


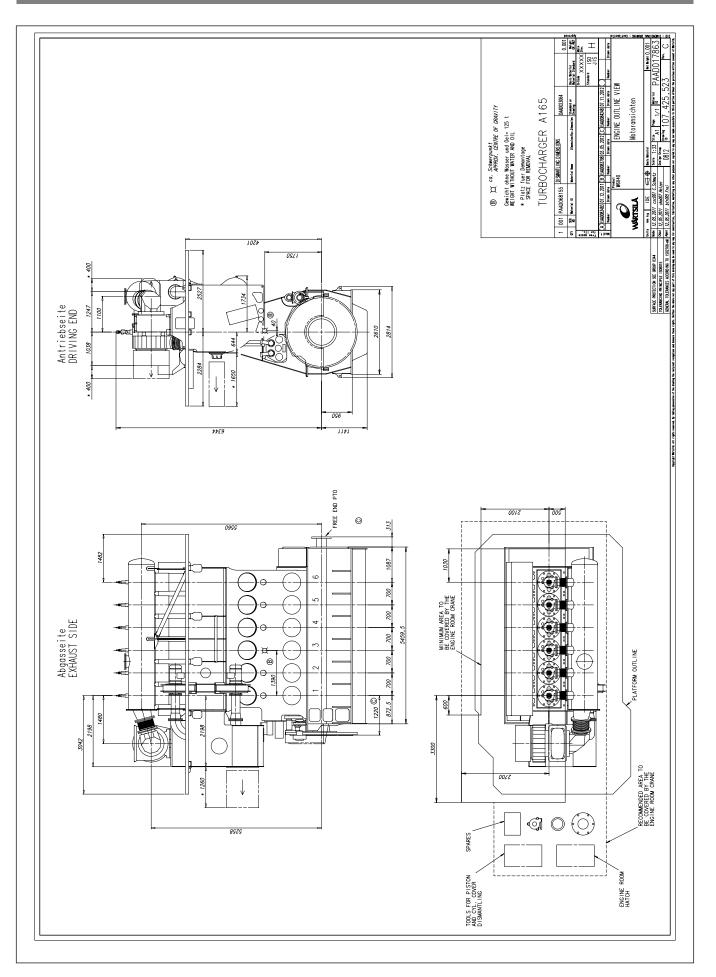
Figure 18.4: Dismantling of SAC

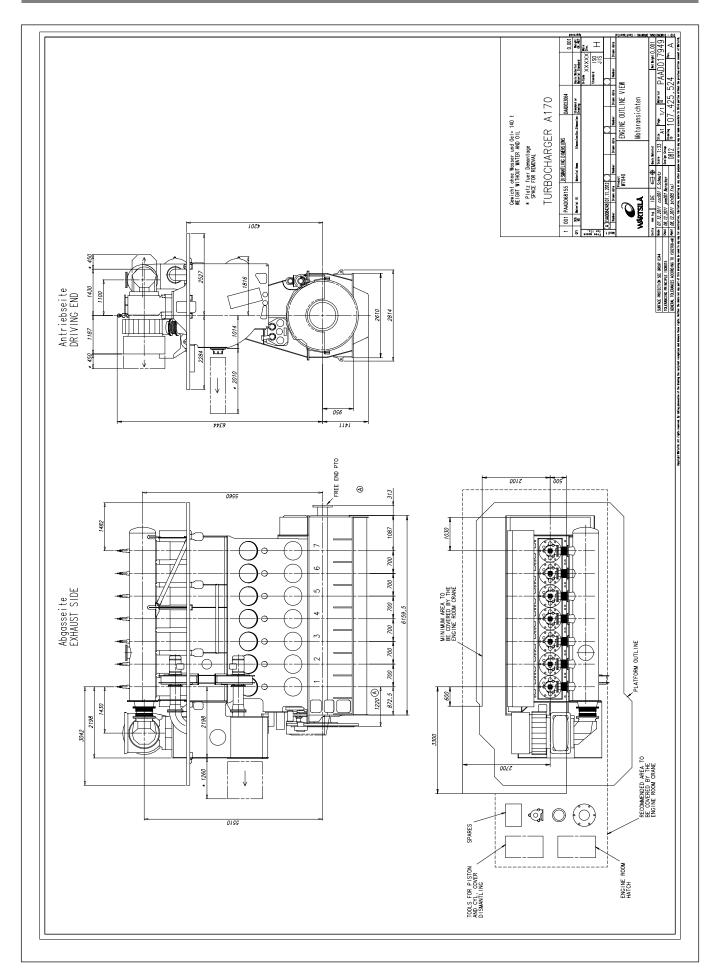
18.2 Outlines

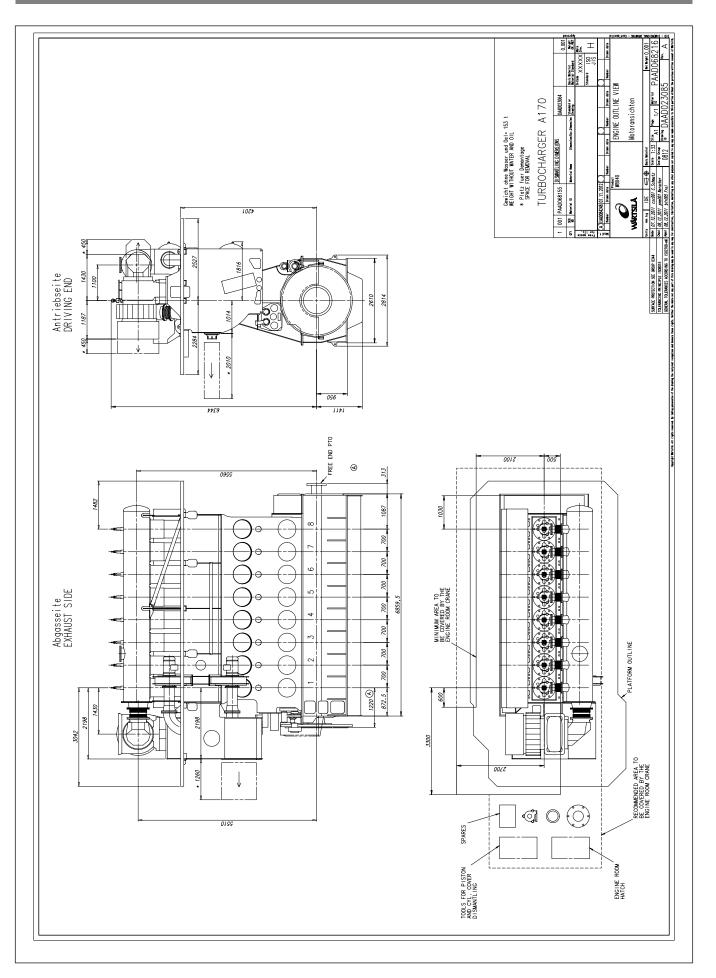
18.2.1 Drawings

DAAD009317 b	Engine Outline View, W5X40	. 18889
107.425.523 c	Engine Outline View, W6X40	
107.425.524 a	Engine Outline View, W7X40	
DAAD023085 a	Engine Outline View, W8X40	









18.3 Platform arrangements

18.4 Engine seating

The engine seating is integral with the double-bottom structure and has to be of sufficient strength to support the weight of the engine, transmit the propeller thrust, withstand external couples and stresses related to propeller and engine resonance.

The longitudinal beams situated under the engine are to extend forward of the engine room bulkhead by at least half the length of the engine, and aft as far as possible.

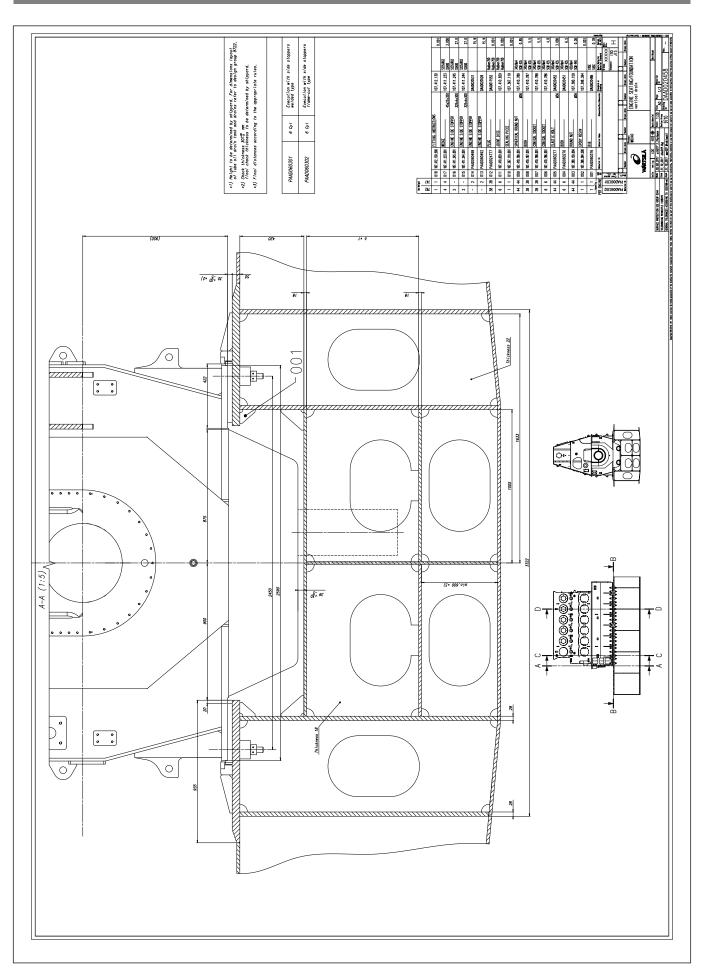
The maximum allowable rake is 3° to the horizontal.

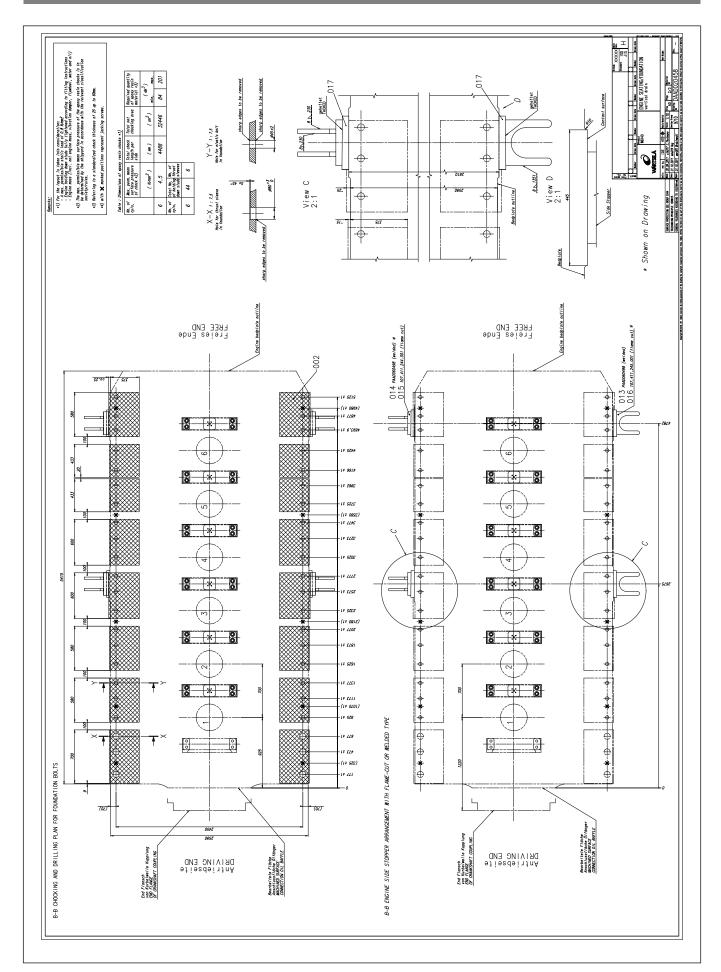
Before any engine seating work can be performed, make sure the engine is aligned with the intermediate propeller shaft.

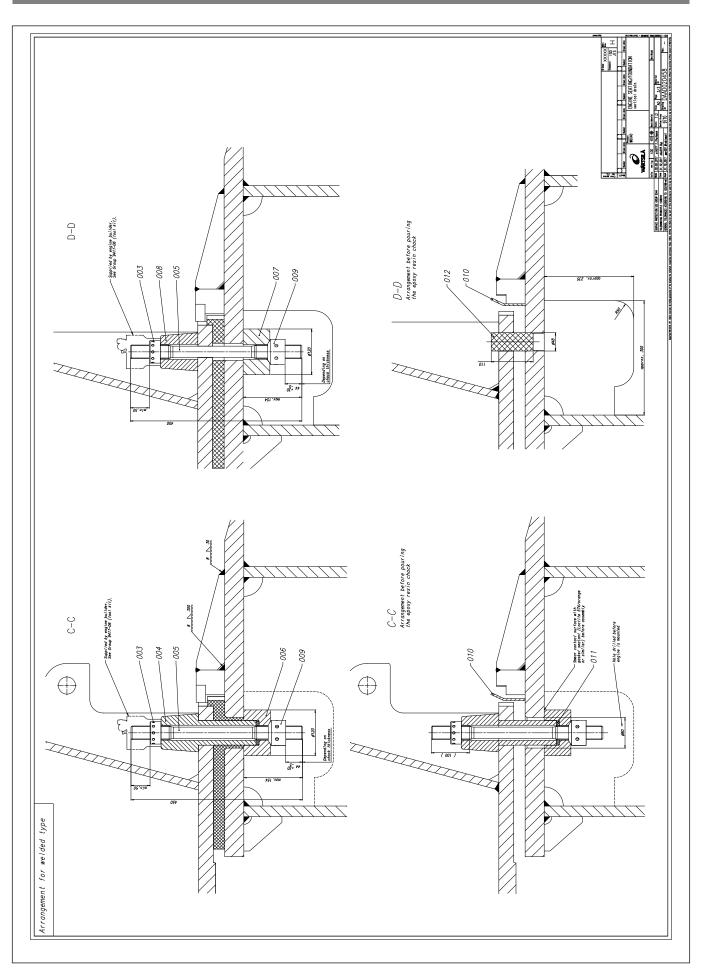
18.4.1 Drawings

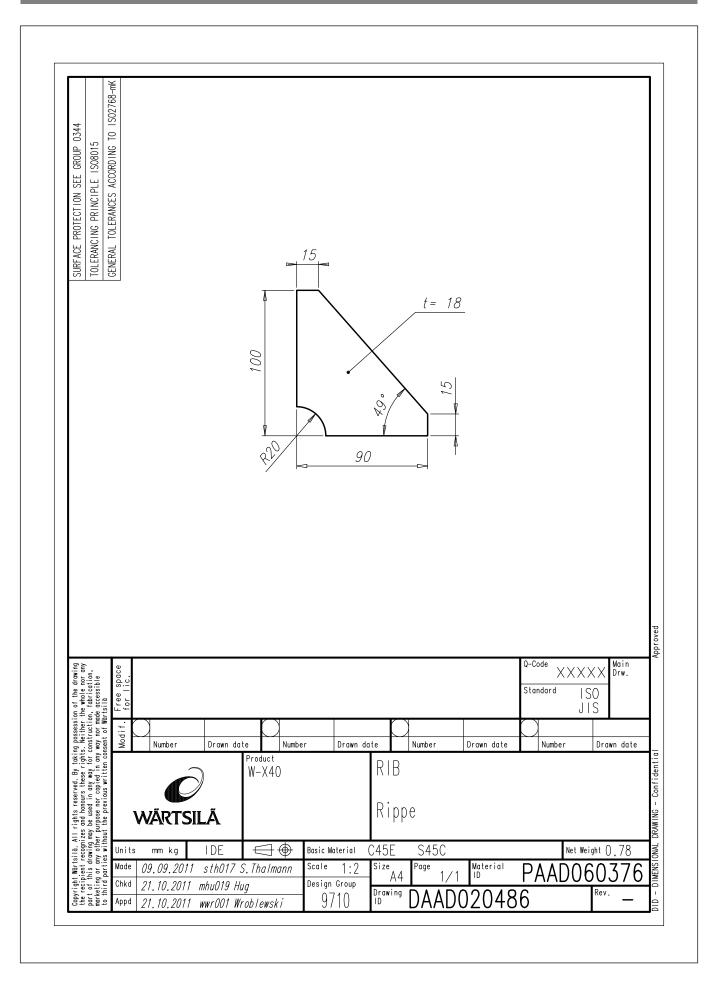
DAAD020458 -	Engine Seating/Foundation, Vertical Drain, W6X40	3666
DAAD020486 -	Rib, W6X40	
107.398.394 -	Epoxy Resin, W6X40	36688
107.380.159 b	Round Nut, W5-8X40	3889
DAAD020451 -	Bush, W6X40	
DAAD020452 a	Elastic BoLT, W6X40	
107.427.450 a	Material and Test Specification, W5-8X40	
107.427.386 c	Material and Test Specification, W5-8X40	38831
107.385.952 c	Heat Treatment Specification, Quench Temper Low Alloy Steel,	
	W5-8X40	
107.385.948 b	Testing Specification, Evaluation Mechanical Properties, W5-8X40 8	
107.385.946 a	Testing Specification, Hardness Testing, W5-8X40	
107.385.944 b	Testing Specification, Chemical Analysis Of Materials, W5-8X40	
107.131.611 a	Quality and Test Specification, BoLTs and Studs Sheet 1-, W5-8X40.8	
107.410.786 -	Conical Socket, W6X40	
107.410.788 -	Conical Socket, W6X40	
107.410.787 -	Bush, W6X40	
107.410.789 -	Spherical Round Nut, W6X40	
107.367.119 a	Sealing Piece, For Chocking Fast, W6X40	
107.410.829 -	Joint Disc, W6X40	
DAAD011552 -	Plug, For Chocking Fast, W6X40	
DAAD020526 -	Engine Side Stopper, Welded Type, W6X40	
107.411.232 -	Flat Bar, To Engine Side Stopper, W6X40	
107.411.235 -	Flat Bar, To Engine Side Stopper, W6X40	
DAAD020531 -	Engine Side Stopper, Welded Type, W6X40	
107.411.231 -	Flat Bar, To Engine Side Stopper, W6X40	
107.411.233 a	Wedge, To Engine Side Stopper, W6X40	
107.412.130 -	Fitting Instructions, To Eng. Seat. W. Epoxy Resin Chock, W6X40	
107.411.244 a	Engine Side Stopper, Execution "Flame Cut", W6X40	
107.411.245 a	Engine Side Stopper, Execution "Flame Cut", W6X40	3389

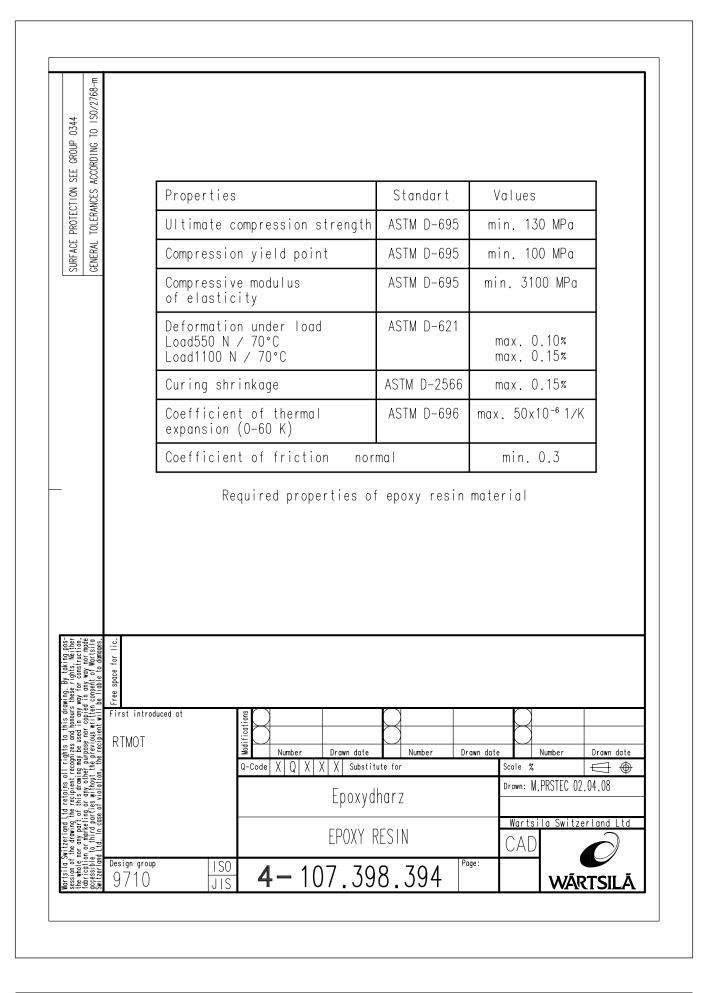
18. General Installation Aspects

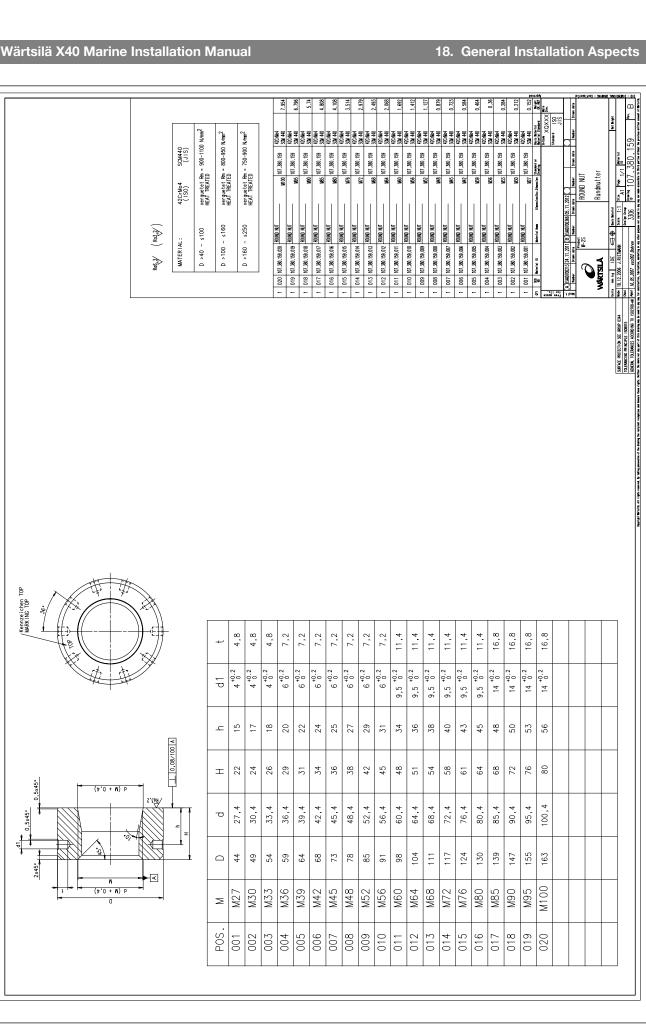




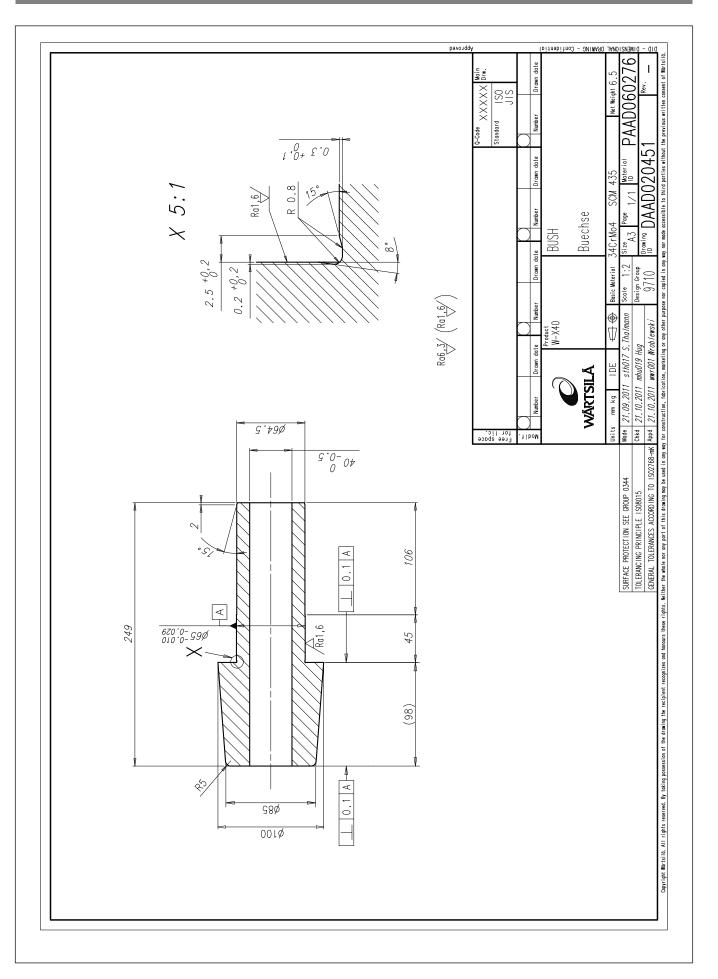


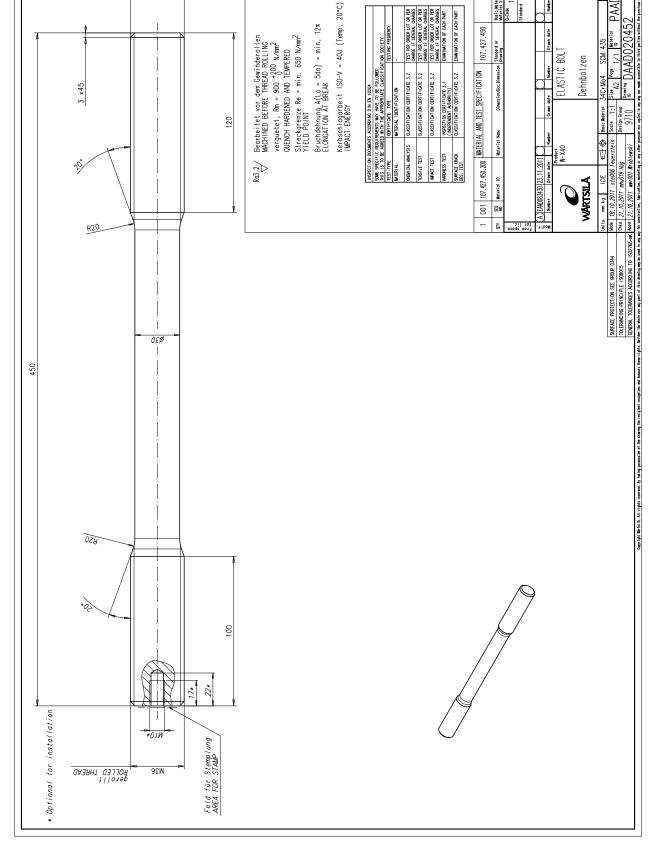






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Material and Testing Specification: Elastic bolt

Table of contents

1	General2
1.1	Scope2
1.2	Range of Application
1.3	References
2	Material2
2.1	Heat Treatment
2.2	Mechanical Properties
2.3	Chemical Composition4
3	Non-Destructive Testing (NDT)5
3.1	Visual Testing (VT)5
3.2	Magnetic Particle Testing (MT) or Dye Penetrate Test (PT)5
4	Reporting5
APPENDIX	(: Material Data Sheets6

General

1.1 Scope

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drawing, the

This specification is valid for the elastic bolt for Wärtsilä R-engines.

The quality of the finished parts must meet the requirements of this specification.

1.2 **Range of Application**

This specification describes the quality aspects of the elastic bolt, such as material and quality standards and testing.

Deviations from the content of this specification must be previously agreed by Wärtsilä Switzerland Ltd (WCH) in written form by RAE (request of alternate execution).

This specification (together with the drawing) overrules the Parts Acceptance List and Material Specification List of group 400.

1.3 References

In addition to the requirements of this specification, the requirements of the following shall also apply:

EN 10083-3:2007	"Steels for quenching and tempering-alloy steels"
JIS G 4053:2003	"Low alloyed steels for machine structural use"
GB/T 3077-1999	"Alloy structure steels"

2 Material

42CrMo4 according to EN 10083-3:2007, SCM 440 according to JIS G 4053:2003 and 42CrMoA according to GB/T 3077-1999.

34CrMo4 according to EN 10083-3:2007, SCM 435 according to JIS G 4053:2003 and 35CrMo according to GB/T 3077-1999.

34CrNiMo6 according to EN 10083-3:2007, SNCM 439 according to JIS G 4053:2003 and 40CrNiMoA according to GB/T 3077-1999.

The material has to fulfill the requirements given on the drawing and in this specification.

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2.1 **Heat Treatment**

2.1.1 Quench hardening and tempering

Quench hardening and tempering has to be performed in order to achieve the required mechanical properties (see material data sheets in the appendix).

The specification 107.427.450 position 002 applies here.

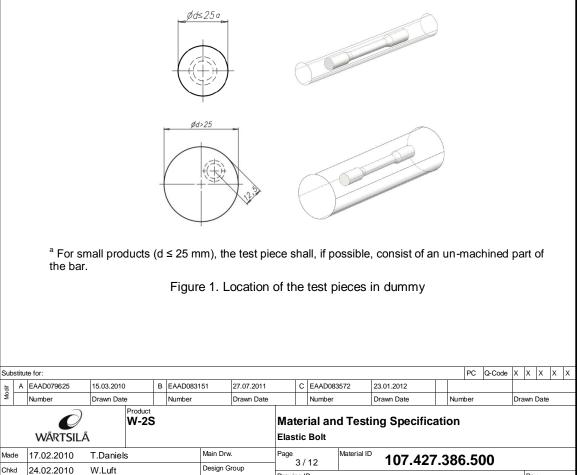
2.2 **Mechanical Properties**

The following mechanical properties must be determined and meet the requirement of corresponding standards, see relevant Material Data Sheets in the appendix. If different values are specified in the drawing, the mechanical properties must meet the requirement of drawing.

2.2.1 **Tensile test**

The tensile tests have to be performed on one tensile test specimen from the dummy with the same diameter after final heat treatment. The specimen for tensile test has to be machined from certain position which is based on the size of the original part, as shown in Figure 1.

The tensile test has to be performed according to specification 107.427.450 position 003.



Drawing ID

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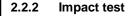
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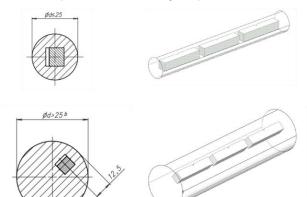
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The impact test has to be performed on three impact test samples from bars machined from the dummy with same diameter after final heat treatment. The specimen for impact energy test has to be machined from certain position which is based on the size of the original part, as shown in Figure 2.

The impact test has to be performed according to specification **107.427.450** position **003**.



^a For small products (d \leq 25 mm), the test piece shall, if possible, consist of an un-machined part of the bar.

^b For round bars the longitudinal axis of the notch shall be about parallel to the direction of a diameter.

Figure 2. Location of the test pieces in dummy

2.2.3 Hardness testing

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For all types of hardness testing the specification 107.427.450 position 004 is valid.

The hardness has to be measured on a polished area using the Brinell method.

2.3 Chemical Composition

The chemical analysis has to be preformed for each raw material batch (material from one melt). The chemical composition of the material has to meet the specification given on the material data sheets in the appendix, please refer to specification **107.427.450** position **005**.

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3 Non-Destructive Testing (NDT)	3	Non-Destructive	Testing	(NDT)
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VT has to be done on each finished part.

MT or PT has to be performed on each finished part.

Instructions and acceptance criteria are given below and in the specification 107.427.450 position 006.

3.1 Visual Testing (VT)

All parts have to be free of cracks, crack-like indications, laps, seams, folds or other injurious indications. No burrs, dents, debris or dirt are allowed.

The specification 107.427.450 position 006 applies here.

3.2 Magnetic Particle Testing (MT) or Dye Penetrate Test (PT)

Following the Magnetic Particle Test, the part has to be demagnetized: max 3 Oertsted. The specification 107.427.450 position 006 applies here.

4 Reporting

A test report has to be provided with the following information given in a 3.1 or 3.2 inspection certificate, which is defined on drawing, according ISO 10474 / EN10204:

- 1. Purchaser and order number
- 2. Number (stamp) of the part and corresponding batch number
- 3. Material used / specified on the drawing
- 4. Test results
 - Chemical analysis report from each raw material batch (mill sheet) a.
 - b. Tensile test result (R_m, R_e, A and Z) of each test batch
 - c. Impact energy of each test batch
 - Brinell hardness of each part d.
- 5. NDT inspection report
- 6. All reports from heat treatments have to be attached
- 7. Name and address of laboratory
- 8. Date, name and signature of responsible person

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	•	42CrMoA	(GB/T 3077-19	99								
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	•	SCM 435		JIS G 4053:20	03								
	•	35CrMo	(GB/T 3077-19	99								
	•	34CrNiMo6	E	EN 10083-3:2	007								
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Material Condition quench hardened and tempered (QT) d / t [mm] ds16 16 4C <ds100< td=""> 100<ds160< td=""> 160<dds250< td=""> Rm [MPa] 1100 1300 1000 1200 900 12750 2650 2550 2500 2 Re [MPa] 2900 2750 2650 2550 2500 2 144 A [%] Long. 210 211 212 213 214 Imag. 100. 240 245 250 255 210 Z [%] Long. 240 245 250 255 235 Imag. 100. 235 235 235 235 235 235 235 235 Imag. Ima</dds250<></ds160<></ds100<>	
Material Condition quench hardened and tempered (QT) d/t [mm] ds16 16 40 100 100 100 100 450 1 1 1 1 1 1 1 1 1 1 1 1 1 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 2 1 1 2 1 1 2 1 1 2 1 1 1 2 1	
Rm [MPa] 1100-1300 1000-1200 900-1100 800-950 750-900 Re [MPa] ≥ 10 ≥ 173 ≥ 13 ≥ 14 A [%] long. ≥ 10 ≥ 11 ≥ 12 ≥ 13 ≥ 14 Z [%] long. ≥ 10 ≥ 11 ≥ 12 ≥ 13 ≥ 14 Z [%] long. ≥ 40 ≥ 45 ≥ 50 ≥ 55 IsoV ^a [J] long. ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 > 35 BO-V ^a [J] long. ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 35 > 35 ≥ 35 <t< td=""><td></td></t<>	
Re [MPa] ≥ 900 ≥ 750 ≥ 650 ≥ 550 ≥ 500 A [%] long. ≥ 10 ≥ 11 ≥ 12 ≥ 13 ≥ 14 Z [%] long. ≥ 40 ≥ 45 ≥ 50 ≥ 55 ≥ 10 Z [%] long. ≥ 35 ≥ 35 ≥ 50 ≥ 55 $=$ $=$ Iso-V a) [J] trans. $=$ <td></td>	
A $[\%]$ long. ≥ 10 ≥ 11 ≥ 12 ≥ 13 ≥ 14 Z $[\%]$ long. ≥ 40 ≥ 45 ≥ 50 ≥ 50 ≥ 10 Z $[\%]$ long. ≥ 40 ≥ 45 ≥ 50 ≥ 50 ≥ 55 $=$ IsO-V ⁹ [J] long. ≥ 35 ≥ 35 ≥ 35 ≥ 35 ≥ 25 $=$	
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Z [%] long. ≥ 40 ≥ 45 ≥ 50 ≥ 55	
Z Imag. Trans. Imag. Iong. 235 235 235 235 235 235 Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag. Imag.	
ISO-V */ [J] long. ≥ 35 ⇒ 35 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36 ⇒ 36	
ISO-V a) Image: Trans. <	
Hardness [HBW] Image: converted into HBW according to ISO 18265:2004 2) Rm values converted into HBW according to ISO 18265:2004 Rm [MPa] 1100-1300 1000-1200 900-1100 800-950 750-900 Hardness [HBW] calc. 346-411 315-379 283-346 251-299 236-283 Comments: For the dimension 250 < d ≤ 500 according to SEW 550: Rp0.2 = 460 N/mm2	
*) Temperature for measurement of impact energy: +23 ± 5 °C (RT) 2) Rm values converted into HBW according to ISO 18265:2004 Rm [MPa] 1100-1300 1000-1200 900-1100 800-950 750-900 Hardness [HBW] calc. 346-411 315-379 283-346 251-299 236-283 Comments: For the dimension 250 < d ≤ 500 according to SEW 550: Rp0.2 = 460 N/mm2	
2) Rm values converted into HBW according to ISO 18265:2004 Rm [MPa] 1100-1300 1000-1200 900-1100 800-950 750-900	
Rm [MPa] 1100-1300 1000-1200 900-1100 800-950 750-900 Hardness [HBW] calc. 346-411 315-379 283-346 251-299 236-283 Comments: For the dimension 250 < d ≤ 500 according to SEW 550: Rp0.2 = 460 N/mm2 - For the dimension 500 < d ≤ 750 according to SEW 550: Rp0.2 = 390 N/mm2	
Hardness [HBW] calc. 346-411 315-379 283-346 251-299 236-283 Comments: For the dimension 250 < d ≤ 500 according to SEW 550: Rp0.2 = 460 N/mm2	
Comments: For the dimension 250 < d ≤ 500 according to SEW 550: Rp0.2 = 460 N/mm2	
- For the dimension 500 < d ≤ 750 according to SEW 550: Rp0.2 = 390 N/mm2	
	ode X X X 3
W-2S Material and Testing Specification	
WÄRTSILÄ Elastic Bolt	
ade 17.02.2010 T.Daniels Main Drw. Page 7/12 Material ID 107.427.386.500	
nkd 24.02.2010 W.Luft Design Group 7/12 107.427.386.500 Drawing ID 4.07.407.000 0.000	

WÄRTSILÄ				F	errous Mate	erials Alloyed
						42CrMo4
Forming and Heat Tr	reatment					
	ave to be performed that are me			material and testin	ng specification of	the part.
ne given temperatures are for g Process	uidance only. The temperature	must be chosen part	Descript	ion		
Forging	1050 - 850 °C		2000			
Normalising	840 - 880 °C					
Soft Annealing Stress Relief Annealing	680 - 720 °C 530 - 670 °C					
Quench Hardening	820- 860 °C (in wate	r or oil)				
Tempering	540- 680 °C (min. 1h)				
Similar Standards						
	atasheet are based on the grey	highlighted standard				
Grade	Standard			Comm	ents	
42CrMo4 (1.7225)	EN 10083-3:2007					
SCM440 42CrMo	JIS G 4053:2008 GB/T 3077-1999					
Obsolete Standards						
Grade	Standard	4		Comm	ents	
42 CrMo 4	EN 10083-1:1996-10		alid; replaced	with: EN 10083-		
Additional Informatio	n					
	n		Descrint	ion		
Attribute	n hot deformable, cold	compressible	Descript	ion		
Attribute Forming Weldability	hot deformable, cold limited weldability		Descript	ion		
Attribute Forming Weldability Machinability	hot deformable, cold limited weldability well machinable at H		Descript	ion		
Attribute Forming Weldability Machinability Scaling Resistance	hot deformable, cold limited weldability well machinable at H up to 540 °C		Descript	ion		
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable	B max. 241	-		PC Q-	Code X X X X X X
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du	B max. 241	s, cranks, cog		PC Q-	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du	B max. 241	s, cranks, cog	5	PC Q-	Code X X X X >
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range Application Range State of the state of th	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du	B max. 241 Initiation of the second s	EAAD083572 Number	S 23.01.2012 Drawn Date	Number	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range Application Range Status Situte for: A A EAAD079625 15.03.2010 Number Drawn Dat	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du	B max. 241 Interief of the second sec	EAAD083572 Number	23.01.2012	Number	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range Application Range Status stitute for: A A EAAD079625 15.03.2010	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du	B max. 241 Initiation of the second s	EAAD083572 Number	S 23.01.2012 Drawn Date	Number	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range stitute for: A A EAAD079625 15.03.2010 Number Drawn Dat	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du intervention b B EAAD083151 ie Number	B max. 241 Interface of the second s	EAAD083572 Number ial and Tes Bolt	23.01.2012 Drawn Date ting Specific	Number	Drawn Date
Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range Stitute for: A EAAD079625 15.03.2010 Number Drawn Dat	hot deformable, cold limited weldability well machinable at H up to 540 °C magnetisable for parts with high du intervention b B EAAD083151 ie Number	B max. 241 ctility; studs, shaft 27.07.2011 C Drawn Date Elastic Page 8 /	EAAD083572 Number ial and Tes Bolt 12	23.01.2012 Drawn Date tting Specific 1D 107.42	Number	Drawn Date

"Similar Standa Acc. min./max.: Acc. Min Min. Max. Acc. Max. Comments: Fo -	Compo ata cover a ds". accepted 0.30 0.37 0.40 e: remain al Prop al can be p	Disition all materia limits for c Si 0.40	e of further req Is included in "Si inemical compos Mn P 0.40 0.60 0.90 0.020	milar Standa	ards". Witt	hin the g			ased upon agreeme			4Crl
The following di "Similar Standa Acc. min./max.: Acc. Min Min. Max. Acc. Max. Comments: Fo - - Mechanica The raw materia	ata cover a rds". accepted 0.30 0.37 0.40 e: remain al Prop al can be p	all material limits for c Si 0.40	hemical compose Mn P 0.40 0.60	ition accordi	ing to sim	-	ey area th	ne values r				
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Acc. Min Min. Max. Acc. Max. Comments: Fo - - Mechanica The raw materia	С 0.30 0.37 0.40 е: remair	Si 0.40	Mn P 0.40 0.60		-	nai stan	larda an l		•	-	gnieu Siand	Jaru II
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Max. Acc. Max. Comments: Fo - - Mechanica	0.37 0.40 e: remain al Prop				0.80	0.15					┿╾┯┿╸	
Comments: Fo	e: remair al Prop	ıder		0.035	1.20	0.30						
- Mechanica The raw materia	al Prop	nder	0.95 0.035				0.30	0.30				
- Mechanica The raw materia	al Prop	aer										
The raw materia	al can be p											
The raw materia	al can be p											
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The raw materia	al can be p	erties										
			with or without h	eat treatmor	nt Heat +	reatmont	which do	ermines #	e final mechanical pro	nerties	an also he n	erform
				- 4	, . 1001 U	Jaanoill		u	aoonamoar pro	,	a.so be p	2.1011
	values ar	e given on	the drawina or i	n the materia	al specific	ation. al	mechania	al properti	es are mandatory for	final produ	ucts.	
Only in case ter	sile tests	or impact							any other case the val			ie val
1) are only for in	formation											
1)												
Material Co	ndition		quench ha	rdened and	d temper	red (QT)					
d/t	[mm]		d ≤ 16	16 ≤ds		40≤d≤′		100≤d≤16				
Rm	[MPa]		1000-1200			800-9		750-900				
Re	[MPa]		≥ 800	≥65		≥550		≥500	≥450		\downarrow	
	[%]	long.	≥ 11	≥ 12	2	≥ 14		≥ 15	≥ 15			
Α		tang.		_								
	F0/ 1	trans.	> AE	\ F(\ E F		> ==	> 60	+	+	
z	[%]	long. tang.	≥ 45	≥ 50	<u> </u>	≥ 55		≥ 55	≥ 60		<u> </u> -	
-		trans.	1									
	[J]	long.	1	≥ 4(0	≥ 45		≥ 45	≥ 45		+ +	
ISO-V ^{a)}	-	tang.										
		trans.	_									
Hardness	[HBW]											
^{a)} Te	emperatu	re for me	easurement of	impact ene	ergy: +23	3 ± 5 ℃	(RT)					
2)		es conver	ted into HBW acc							_		_
Rm	[MPa]		1000-1200			800-9		750-900				
Hardness	[HBW]	calc.	315-379	283-3	846	251-2	99	236-283	220-268			
Comments:												
-												
bstitute for:			-	-					-	PC	Q-Code X	X
A EAAD07962	5 15	.03.2010	B EAAD08	3151 2	27.07.2011		C EAADO	83572	23.01.2012	1		
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Number	\sim		oduct	-								
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Number		"										
						Elas	ic Bolt					
Number	SILA	Daniels		Main Drw.		Derr						
WÄRT						Page		Material II			~ ~	
WÄRT	10 T.I			Desis 0		Page	9/12	Material II	[°] 107.427.3	386.5	00	
WÄRT	10 T.I	Luft		Design Gro	^{Dup}		- 10		ີ 107.427.: 7.386	386.5	00	Rev

Wärtsilä						Fe	errous Mat		
	ot Trootmo							34C	rMo4
Forming and He Donly heat treatment proce			are mentioned on	the drawing and	l/or in the	material and testin	a specification o	of the nart	
The given temperatures a							g opcomoutor o	n ino puni.	
Process		50 000 00			Descript	ion			
Normalising Forging		350 - 890 °C 1050 - 850 °C							
Soft Annealing		680 - 720 °C							
Stress Relief Anneali	3	650 - 680 °C							
Quench Hardening Tempering		330- 870 °C (in 540- 680 °C	water or oil)						
rempening	·	040-080 C							
Similar Standard									
The material properties of Grade	n this datasheet		grey highlighted : ndard	standard.		Comm	onte		
Grade 34CrMo4 (1.7220)	F	Star EN 10083-3:200				Comm	ents		—
SCM 435		JIS G 4053:200	8						
35CrMoA	(GB/T 3077-1999	9						
				1					
Obsolete Standa	ards								
Grade		Star	ndard			Comm	ents		
34 CrMo 4	E	EN 10083-1:199	96-10	invalid; re	eplaced	with: EN 10083-3	3:2006		
	l								
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Additional Inform	nation								
Additional Inform					Descript	ion			
Attribute Forming	ł		old compressible		Descript	ion			
Attribute Forming Weldability	ł	imited weldabili	ty		Descript	ion			······
Attribute Forming Weldability Machinability	li v		ty		Descript	ion			
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	r I V	imited weldabili well machinable up to 540 °C magnetisable	ty 9)					······
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties	r I V	imited weldabili well machinable up to 540 °C magnetisable	ty 9)		ion , valve control u			
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Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range		imited weldabili well machinable up to 540 °C nagnetisable or parts with hig	ty gh ductility; crar	ks, shafts, pis	ston rods	, valve control u		2-Code X X	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range	r I V	imited weldabili well machinable up to 540 °C magnetisable	ty 9)	ston rods			2-Code X X	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range	6.03.2010	mited weldabili well machinable up to 540 °C nagnetisable or parts with hig between the second second second second second second second between the second	ty gh ductility; crar	ks, shafts, pis	ston rods	valve control u 23.01.2012 Drawn Date	PC C		
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range stitute for: A EAAD079625 15 Number Dr	i.03.2010	mited weldabili well machinable up to 540 °C nagnetisable or parts with hig between the second second second second second second second between the second	ty gh ductility; crar	ks, shafts, pis	ston rods	, valve control u	PC C		
Attribute Forming Weldability Scaling Resistance Magnetic Properties Application Range	6.03.2010	mited weldabili well machinable up to 540 °C nagnetisable or parts with hig between the second second second second second second second between the second	ty gh ductility; crar 27.07.2011 Drawn Date	ks, shafts, pis	ston rods	valve control u 23.01.2012 Drawn Date	PC C		
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range	3.03.2010	mited weldabili well machinable up to 540 °C nagnetisable or parts with hig B EAAD083151 Number	ty gh ductility; crar 27.07.2011 Drawn Date	ks, shafts, pis	ston rods	23.01.2012 Drawn Date	PC C Number	Drawn	
Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range stitute for: A EAAD079625 15 Number Dr WÄRTSILÄ Ie 17.02.2010 T.	i.03.2010 i.03.2010	mited weldabili well machinable up to 540 °C nagnetisable or parts with hig B EAAD083151 Number Mair	ty gh ductility; crar 27.07.2011 Drawn Date	ks, shafts, pis	iton rods	23.01.2012 Drawn Date	PC C	Drawn	
Attribute Forming Weldability Machinability Scaling Resistance Magnetic Properties Application Range stitute for: A EAAD079625 15 Number Dr WÄRTSILÄ le 17.02.2010 T. d 24.02.2010 W	3.03.2010	mited weldabili well machinable up to 540 °C nagnetisable or parts with hig B EAAD083151 Number Mair	ty gh ductility; crar 27.07.2011 Drawn Date	ks, shafts, pis	eston rods	23.01.2012 Drawn Date	PC C Number	Drawn	Date

Info Chemical (The following dat "Similar Standard Acc. min./max.: a		mpliance o	f further requi										34Crl
The following dat "Similar Standard	Compo		i fuither requi	rements	from the	e classi	fication	societie	s based u	pon agree	ement.		
The following dat "Similar Standard	Compo		-										
The following dat "Similar Standard	Jumpl	sition											
	ta cover a		ncluded in "Sim	ilar Stand	ards". Wit	thin the	grey area	a the valu	es are give	en as define	ed in the l	highlighte	əd Standa
		imits for che	mical composit	ion accord	ling to sin	nilar star	ndards, a	as long as	mechanic	al propertie	s are fulf	illed	
					-			-			1		
A Min	С	_	Mn P	S	Cr	Мо	Ni	Cu					
Acc. Min Min.	0.30	-	.40		0.60	0.15	1.25						
Max.	0.38	-	.80 0.025	0.035	1.70	0.30	1.70						
Acc. Max.	0.44	C	.90 0.035				2.00	0.30					
Mechanica The raw material pre-machined sta Unless different v Only in case tens 1) are only for infi	can be pl ate values are sile tests c	urchased wi	e drawing or in	the mater	ial specifi	cation, a	all mecha	anical pro	perties are	mandatory	for final j	products.	
1)													
Material Con			quench hard				-				1.46 = -	1	
d/t Rm	[mm] [MPa]		d ≤ 16 1200-1400		≤d≤40 00-1300)≤d≤100 00-120	-	0≤d≤160 00-1100		d≤250 -950		+
Re	[MPa]		≥ 1000		≥ 900		≥ 800	0 3	≥ 700		- <u>950</u> 600		-
	[%]	long.	≥9		≥ 10		≥ 11		≥ 12	≥	13		
A		tang.								_			
	[%]	trans. long.	≥ 40		≥ 45		≥ 50		≥ 55	>	55		-
z	[/0]	tang.	= 10		- 10		- 00		- 00		00		
		trans.			> 45		> 45		> 45		45		-
ISO-V ^{a)}	[J]	long. tang.			≥ 45	_	≥ 45		≥ 45	2	45		
		trans.								-			
	[HBW]												
^{a)} Ter	mperatur	e for meas	urement of in	npact ene	ergy: +2	3 ± 5 °(C (RT)						
2)	Rm value	s converted	into HBW acco	ording to Is	SO 18265	:2004							
,	[MPa]		1200-1400	-	00-1300		00-120	0 9	00-1100	800	-950		Τ
Hardness	[HBW]	calc.	379-444	34	46-411	3	15-379		283-346	251	-299		
bstitute for: A EAAD079625 Number		33.2010 wn Date	B EAAD083 Number		27.07.2011 Drawn Dat		C EAA	.D083572 iber	23.01 Drawr		Nurr		Code X >
A EAAD079625 Number		Produ	ct						1				
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WÄRTSILÄ		Ferrous Materials Alloyed
Forming and Heat Tre	atmont	34CrNiMo
		the drawing and/or in the material and testing specification of the part.
The given temperatures are for gu	uidance only. The temperature must be cho	osen part-related.
Process Forging	1100 - 850 °C	Description
Soft Annealing	650 - 680 °C	
Normalising Quench Hardening	850 - 880 °C	
Tempering	830 - 860 °C (water or oil) 540 - 660 °C	
Similar Standards	ntasheet are based on the grey highlighted s	standard.
Grade	Standard	Comments
34CrNiMo6 (1.6582) SNCM439	EN 10083-3:2006 JIS G 4053:2008	
40CrNiMoA	GB/T 3077-1999	
SNCM 439	KS D 3709:1990	
36 CrNiMo 6	ISO 683-18:1996	
	100 003-10.1990	
Obsolete Standards	-	
Grade 34 CrNiMo 6	Standard EN 10083-1:1996	Comments invalid: replaced with: EN 10083-3:2006
34 CrNiMo 6 34 CrNiMo 6	EN 10083-1:1996 DIN 17200:1969	invalid: replaced with: EN 10083-3:2006 invalid: replaced with: EN 10083-3:2006
Additional Information)	
Attribute	·	Description
Weldability	limited weldability, welding shou	ould be done after QT-treatment, pre-heating to 300-400 °C
Forming	hot deformable, cold compressi	sible
Machinability Scaling Resistance	well machinable up to 500 °C	
Magnetic Properties	magnetisable	
Application Range	parts with specially high load; g	gears, studs, bolts, shafts, cogs
		PC Q-Code X X X X
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Number Drawn Date	Product W-2S	C EAAD083572 23.01.2012 Number Drawn Date Number Drawn Date Number Drawn Date
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	contents				
1	Introduction				2
2	Range of Application				2
3	General quality requirem	-	-	-	
3.1	Requirements according to	the drawing			2
4	Heat treatment process s	pecifications			2
4.1	Charging of the parts				2
4.2	Cleaning of the parts				2
4.3	Preheating				3
4.4	Hardening temperature, Ho	lding time			3
4.5	Quenching				3
4.6	Washing				3
4.7	Hardness testing				3
4.8	Tempering				4
4.9	Hardness testing				4
4.10	Sand blasting				4
5	Quality assurance				4
5.1	Test specimens for metallu	raical investia	otione		4
5.2	Documentation				
5.2	Documentation				

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Introduction

Parts made of low-alloy steels are quenched and tempered in order to achieve the required mechanical properties.

Range of Application

This specification is applicable for parts made of low-alloy steels which are subjected to a subsequent surface heat treatment (e.g. quench and temper, nitriding, nitrocarburizing, case hardening).

3 General quality requirements on quenched and tempered parts

3.1 Requirements according to the drawing

The requirements given on the drawing must be fulfilled. The tensile strength has to be tested only for first time production and frequent checking procedures. The hardness measurement has to be done on a polished surface with Brinell or Rockwell (mentioned in the drawing) hardness testing on one part per batch. The impact energy has to be tested if required.

Tensile test, impact energy test and hardness test have to be carried out according to WCH specification "Evaluation of Mechanical Properties" (**107.385.948**) and "Hardness Testing" (**107.385.946**). In this specification all applicable standards, also for hardness – tensile strength conversion are given.

4 Heat treatment process specifications

4.1 Charging of the parts

For each batch the parts have to be charged vertically in baskets or on grids with enough distance between each other to guarantee a good heat transfer during heating up and a good cooling behavior while quenching.

4.2 Cleaning of the parts

All the parts have to be thoroughly cleaned by alkaline washing. Grease, oil; emulsion and dust have to be removed completely. For this suitable cleaning agents have to be used. This is necessary as otherwise the oil and grease evaporating can disturb to the protective atmosphere of the gas.

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4.3 Preheating The preheating has to be done in a pre-heating furnace in air. The preheating has to be carried out between 400 - 450 °C for min. 90 minutes. Depending on the cross section of the parts, the pre-heating time can take as long as 180 minutes. Afterwards the batch has to be transferred to the seal quench furnace immediately. 4.4 Hardening temperature, Holding time The whole process in the seal quench furnace has to be carried out in protective atmosphere in order to prevent decarburization or carburization of the parts. The carbon potential in the atmosphere has to be chosen in correspondence with the chemical analysis of the material. The hardening temperature has to be chosen according the used material (see material data sheets). The holding time on hardening temperature depends on the cross section of the part. The holding time is defined by: 1 h + 1 h per 25 mm wall thickness of the part e.g.: round bar Ø 200 mm: 1 h + 4 h (wall thickness 100 mm) = 5 h total holding time 4.5 Quenching At the end of the holding time, the batch has to be guenched directly in oil. The oil temperature should be between 60 and 80°C. Depending on the geometry of the parts, the person responsible for the heat treatment has to choose the agitation of the oil bath in order to prevent too much distortion. The parts have to remain in the oil bath until the core of the parts has reached the same temperature as the oil. If the parts are taken out of the oil too early, this can cause cracking during the subsequent washing process. part of this 4.6 Washing After quenching the parts have to be washed properly before tempering. The washing temperature in alkaline bath should be between 70 and 80°C. 4.7 Hardness testing idht After washing the hardness has to be checked on the parts. This is important in order to choose the appropriate tempering temperature PC Q-Code X X X X X Substitute for A EAAD073008 B EAAD700229 19.12.2011 C EAAD084038 10.08.2012 28.05.2009 Modif Drawn Date Number Drawn Date Number Drawn Date Number Drawn Date Number **W-2S Heat Treatment Specification** WÄRTSILÄ Quench and Temper of Low Alloy Steels Main Drw. Material ID 09.01.2009 Made M. Damani Page 107.385.952.500 3/7Design Group Chkd 09.01.2009 W.Luft Drawing ID Rev 0330 107.385.952 С 09.01.2009 W.Luft Appd

4.8 Tempering

Tempering has to be carried out in neutral atmosphere, e.g. nitrogen or in air (in case of air atmosphere sand blasting is obligatory, see 4.10). The tempering temperature has to be chosen according to the hardness of the parts after hardening and the specified value for tensile strength or hardness of the material.

The holding time on tempering temperature should be at least the same as the holding time on hardening temperature.

4.9 Hardness testing

After finishing the tempering process, the hardness of the parts has to be checked again and the hardness has to correspond to the specified value on the drawing (in case only the tensile strength is given a conversion is admissible; see WCH specification "Evaluation of mechanical properties" (**107.385.948**). The surface has to be properly ground before hardness testing is carried out.

4.10 Sand blasting

All parts which have been tempered in air have to be sand blasted before delivery in order to achieve a suitable surface condition for the further production steps.

5 Quality assurance

5.1 Test specimens for metallurgical investigations

5.1.1 Tensile tests

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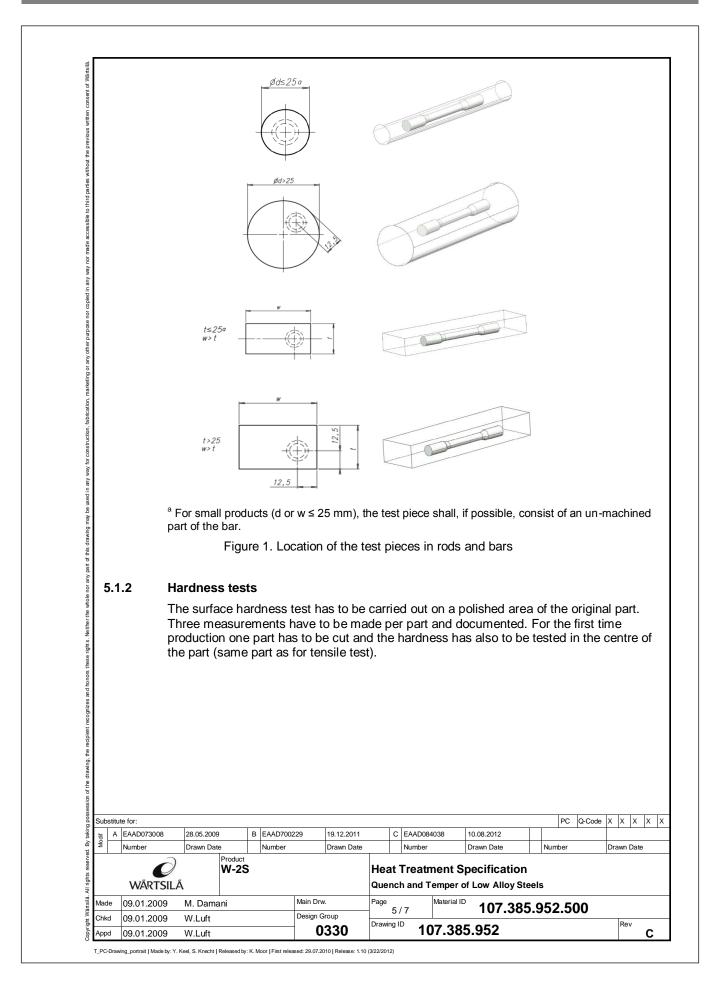
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The specimen for tensile test has to be machined from certain position which is based on the size of the original part, as shown in Figure 1. If there are sketches for location of the tensile test sample specified in particular first time production approval specification or material and testing specification, then position of the test sample has to be chosen according to particular specification. This test part has to be heat treated in the same hardening batch as the other parts. The position of the test part has to be in the middle of the batch.

Hardness measurements have to be carried out on the same part. The measured values are valid for comparison for batch production testing.

For batch production only hardness measurements have to be carried out in order to prove the required tensile strength. Conversion has to follow ISO 18265 : 2004.

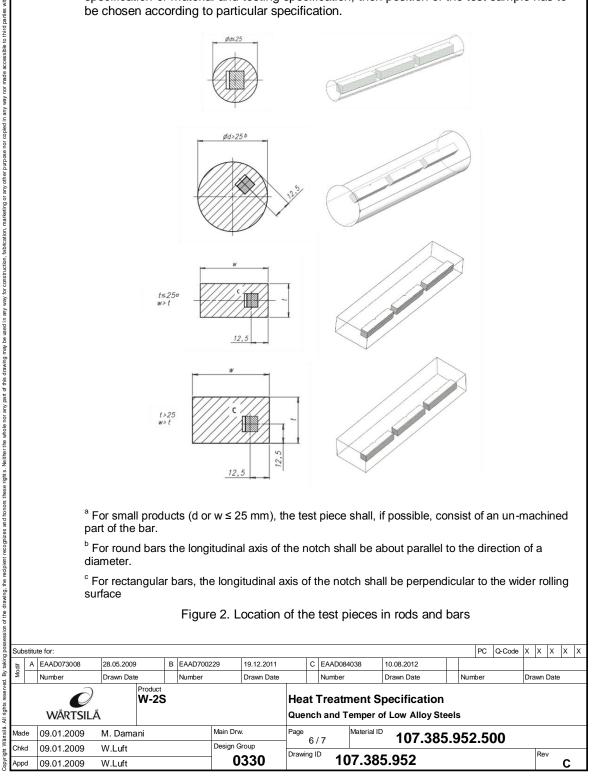
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5.1.3 Impact energy

If required the impact energy has to be determined (ISO-V notch samples).

The specimen for impact energy test has to be machined from certain position which is based on the size of the original part, as shown in Figure 2. . If there are sketches for location of the impact test sample specified in particular first time production approval specification or material and testing specification, then position of the test sample has to be chosen according to particular specification.



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	of contents						
1	Introduction						2
2	Relevant stand	ards					2
2.1	Tensile Tests						2
2.2	Notch Bar Impac	ct Tests					2
3	Sample Geome						
3.1	Tensile Tests						
3.2	Notch Bar Impac	ct Tests (ISO-∖	/)				5
4	Documentation						0
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Introduction

Tensile testing and notch bar impact testing are important test methods for material characterisation. In order to achieve comparable results some rules have to be followed. Both test methods are well defined in international standards. This specification gives a summary of all relevant standards and defines sample geometries for testing.

2 Relevant standards

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	J	IS Z 220	02: 19	998		Tes	t pieces	for i	mpact	test fo	r metallic m	ate	erials	
	J	IS Z 224	42: 20	005		Met	hod for a	char	py per	dulum	impact test	of	metallic ma	aterials
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		SO 7500				Met	allic Mat	eria	ls – ve	rificatio	on of static u	una	axial testing	
	-	GB/T 228					-				esting at am			ture
	-	IS Z 22	-							-	r metallic m	-		
		IS Z 224	41 · 19	998			m tempe			for met	allic materia	als		
	ļ	SO 6892	2-1: 19	998						nsile te	sting - Part	1:	Method of t	est at
	ŀ	SO 377:	1997	7							cation and p al testing	ore	paration of	samples
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2.1	1 1	ensile	Test	S										
	E	EN 1020	4: 200	04		Met	allic Pro	duct	s - Ty	bes of i	nspection d	oc	uments	
		SO 1047						•		-	ection docum			

Sample Geometry and Size

3.1 Tensile Tests

Tensile tests shall be performed in proportional round bar samples according to EN°10002-1/ISO 6892. Alternative standards JIS Z 2201, JIS Z 2241 and GB/T 228 can also be used. Alternative geometries can be used, provided the part geometry and tolerances are according to one of the mentioned standards. Test equipment shall be fully compliant with ISO 7500-1/Class 1 or better.

The following values have to be determined by tensile tests:

•	Tensile strength:	R _m	[MPa]
---	-------------------	----------------	-------

- Yield strength: R_e [MPa]
- Proof Strength: R_p [MPa]
- Elongation: A [%]
- Reduction of area: Z [%]

3.1.1 Sample size and requirements of Steel forgings, Non-Ferrous alloys and Cast Iron It is recommended to use the standard sample *Sample A* for steel forgings and non-ferrous alloy samples. For cast iron it is recommended to use *Sample B*, for grey cast irons it is recommended to use *Sample C* according to EN 1561.

In case of test samples machined from specific test location, use should preferably be made of short proportional test specimens with an initial gauge length of:

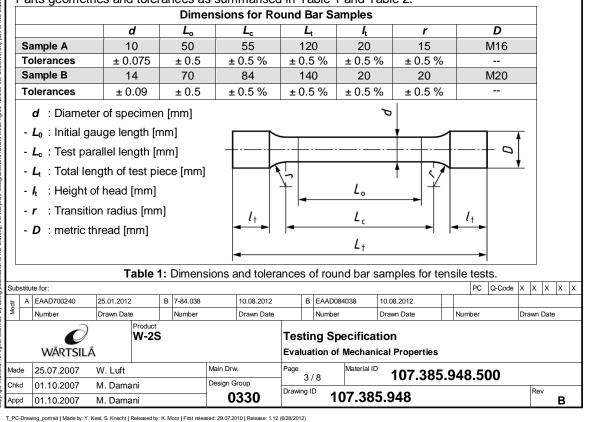
$$L_o = 5,65 \times \sqrt{S_o} = 5 \times d$$

*L*_o is the original gauge length

 S_0 is the original cross section area of the test piece

d is the diameter of the test piece along the gauge length

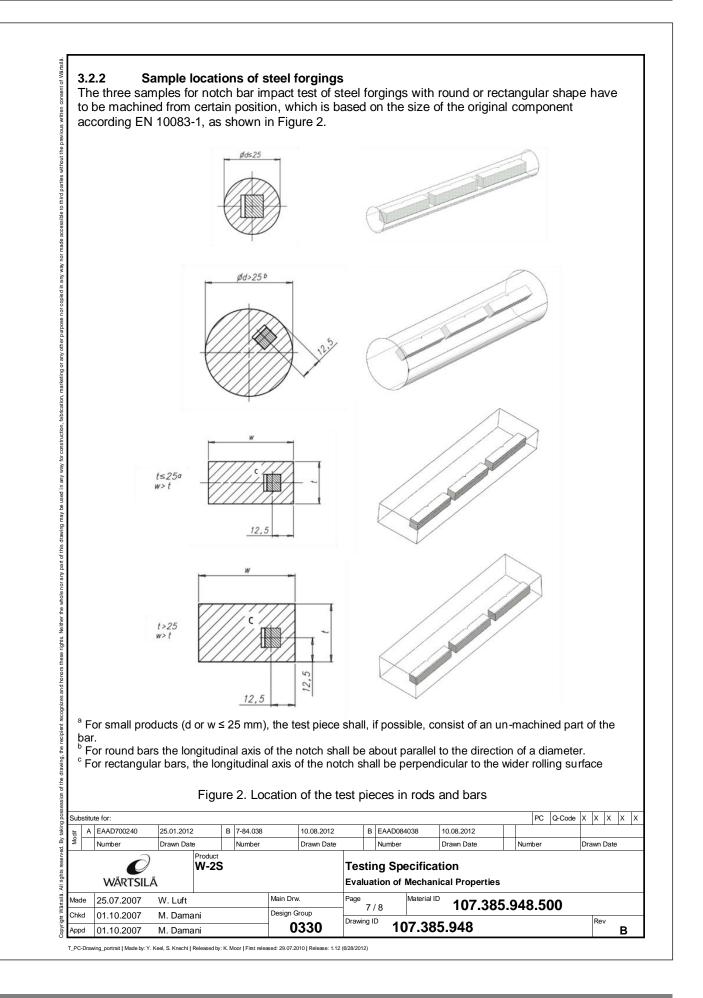
Parts geometries and tolerances as summarised in Table 1 and Table 2.



			Dimensio	ons for Rou	nd Bar Samp	les	
	d	Ls	L _p	L _t	d ₁	d ₂	
Sample C	20	36	a	102	23	M30	
Tolerances	± 0.1	± 0.5 %	± 0.5 %	± 0.5 %	± 0.5 %		
d : Diamete	er of speci	men [mm]			ام	1	
- L _{s :} Thread I	-				s a		
		-					
- <i>L</i> _p : Plain en	-						
- Lt : Threade	ed test pie	ce total					d_1
length [I	mm]			L _p b	020		
- d1 : Diamete	er for plain	ends [mm]		p	R25	- − p →	-
- d ₂ : Thread	type for th	readed test			~		
piece [n					/		
	-	<u> </u>			/		
•		mping device					
Та	able 2: Dir	nensions an	d tolerances of	f round bar s	amples for ter	nsile tests of grey	/ cast iron.
The main test	•					ve as guideline.	
Ctucin note	Testi		ons for Detern		Tensile Stren	gth	
Strain rate		- for R _e : m	1ax. 0.0025 s ⁻¹ 1ax. 0.008 s ⁻¹				
Surface Roug	hness	max. N6 (F	R _a ≤ 0.8 μm)				
				1			
Surface Quali	ity		rooves allowe				
Temperature		Room tem	perature: RT	= 23 ± 5 °C			
Temperature Method of Gri 3.1.2 Sa In general the If there are ske approval speci	ipping Table imple loc test sam etches fo ification c	Room tem Wedges, s a 1: Paramet ations ple has to b r location of or material a	perature: RT crewed grips, ers for determ be taken from f the tensile to and testing sp	$= 23 \pm 5 \circ C$ parallel jaw 1 ination of ter the locatio est sample becification,	nsile strength n according specified in i		me productio
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	t≤25ª w> t		w				T	
	t>25 w>t		w	12,5				
		d or w ≤	25 mm), †	the test piece	shall, if	possible, c	consist of an	un-machined part of the
	For small products (o par.	Figur	e 1: Loca	ation of the t	est piec	es in rods	and bars	
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Dimensions V-notch Samples Sample Length Sample Width 10 mm ± 0.60 mm Width of Sample : - Normal Size 10 mm ± 0.05 mm Width of Sample : - Normal Size 10 mm ± 0.05 mm Width of Sample : - Normal Size 10 mm ± 0.05 mm Notch Angle 45° ± 2° Height at Notch Base 8 mm ± 0.025 mm Notch Angle 27.5 mm ± 0.025 mm Distance: Notch Centre - Sample Ends 27.7 mm ± 0.024 mm Angle between algacent longitudinal faces 90° ± 2° Angle between adjacent longitudinal faces 90° ± 2° Table 3: Dimensions and tolerances of samples for impact tests. Table 3: Dimensions and tolerances of samples for impact tests. Taper angle for each anvil 11° ± 1° Taper angle for each anvil 11° ± 1° Taper angle of pendulum 30° ± 1° Mm Angle between anvil/Support Angle between anvil/Support 90° ± 0.1° Testing Temperature 23 ± 5 °C Taper angle of pendulum 5 to 5.5 m/s Angle between anvil/Support 30° ± 10.3 <td< th=""><th>Dimensions of V-notch Sam</th><th>ples for Impact T</th><th>esting</th><th></th><th></th></td<>	Dimensions of V-notch Sam	ples for Impact T	esting		
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$\begin{array}{c c c c c c c } \hline & & & & & & & & & & & & & & & & & & $	longitudinal axis	90°	±	: 2°	
$\begin{array}{c c c c c c c } \hline 55 & \hline 10 & \hline 1$	Angle between adjacent longitudinal faces	90°	±	: 2°	
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Max. pendulum face thickness 18 mm Striking velocity of pendulum 5 to 5.5 m/s Angle between anvil/support 90° ± 0.1° Testing Temperature 23 ± 5 °C Testing Impact Energy 300 ± 10 J Table 4: Testing conditions for impact tests S.2.1 Sample locations n general the test sample has to be taken from the location according the relevant standard. f there are sketches for location of the notch bar impact test sample specified in individual first production approval specification or material and testing specification, then position of the test sample has to be chosen according to individual specification. stitute for: PC Q-Code X A EAAD700240 25.01.2012 B 7-84.038 10.08.2012 Number Number Drawn Date Number Drawn Date Number Drawn Date Number Drawn Date Number Drawn Date	Spacing between anvils Anvil radius	$(40_{0}^{+0.2}) \text{ mm}$ $(1_{0}^{+0.5}) \text{ mm}$.	
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4	Do	cumentatio	on						
	A test report has to be provided with the following information given in a 3.1 or 3.2								
	inspection certificate, which is defined on drawing, according ISO 10474 / EN10204:Purchaser and order number								
	2.						ng batch numb	er	
	3.	Material use	a / specifi	ea on the	e draw	ing			
	4. 5	Test results	rocult (D	D or D	۸	and 7)			
	5. C	Tensile test							
	6. 7	Notch Bar In				ues and	average)		
	7. 8.	Name and a				vible per	reon		
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1.	Introduction2
2.	Relevant standards2
2.1	Vickers hardness testing2
2.2	Brinell hardness testing2
2.3	Rockwell hardness testing2
2.4	Conversion of hardness values2
2.5	Determination of case depth of case hardened parts
2.6	Determination of nitriding depth and surface hardness of nitrided parts
2.7	Determination of case depth of induction or flame hardened parts
3.	Additional information3
3.1	Remark on determination of hardness profiles
3.2	Used abbreviations for surface hardening parameters
3.2.1	For case hardening3
3.2.2	For flame and induction hardening4
3.2.3	For nitriding4
4.	Choice of method and load4
7.	
 5.	Sample preparation and number of tests4
	Sample preparation and number of tests4 Documentation4
5. 6.	Documentation
5.	
5. 6. de <u></u>	Documentation
5. 6. de <u></u>	Documentation

1. Introduction

Hardness testing is an important test method for material characterisation. In order to achieve comparable results some rules have to be followed. Depending on the material condition and the requirements different hardness testing methods are applicable. All methods are well defined in international standards. This specification gives a summary of all relevant standards and additional information on hardness testing.

2. Relevant standards

2.1 Vickers hardness testing

Applications:	Hardness profiles, surface hardness, micro hardness measurements, etc.
DIN EN ISO 6507	Metallic materials – Vickers hardness test
JIS Z 2244	Vickers hardness test – Test method

2.2 Brinell hardness testing

Applications:	Core/bulk hardness of metallic materials
	(macro hardness)

DIN EN ISO 6506Metallic materials- Brinell hardness testJIS Z 2243Brinell hardness test – test method

Important Notice: The standard Brinell hardness testing method shall be as following unless specified differently on the drawing or in a material and testing specification: **HBW10/3000** with a loading time of 10-15 seconds for steel and 30 seconds for

HBW10/3000 with a loading time of 10-15 seconds for steel and 30 seconds for cast iron parts.

2.3 Rockwell hardness testing

Applications:	Core/bulk hardness of hardened metallic materials (also surface hardness)
DIN EN ISO 6508 JIS Z 2245	Metallic materials – Rockwell hardness test Rockwell hardness test – Test method
.	

to tensile strength

Conversion of core hardness of metallic materials

Metallic materials - Conversion of hardness

2.4 Conversion of hardness values

Applications:

DIN EN ISO 18265 values

<i>C</i> WÄRTSILÄ		RTMOT		Testing Specification Hardness Testing	Group 0330
		M. Damani	15.07.07	4-107.385.946	2/4
Wärtsilä Switzerland Ltd.	verified:	W. Luft	01.10.07		2/7

2.5	Determination of case de	epth of case hardened parts	
	DIN EN ISO 2639	Steel: Determination and verification of the c	lepth of
	JIS G 0557	carburized and hardened cases Methods of measuring case depth hardened carburizing treatment for steel	l by
2.6	Determination of nitridin	ng depth and surface hardness of nitrid	ed parts
	DIN 50 190-3 JIS G 0562	Härtetiefe Wärmebehandelter Teile (only in 6 Method of measuring nitrided case depth for steel	
	JIS G 0563	Method of measuring surface hardness for n iron and steel	nitrided
2.7	Determination of case de	epth of induction or flame hardened pa	irts
	DIN EN 10328	Iron and Steel: Determination of the convent depth of hardening after surface heating	tional
	JIS G 0559	Methods of measuring case depth for steel h by flame or induction hardening process	nardened
3.	Additional information	on	
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3.2.2	For flame and induction hardeni Designation: OLD : Rht		
	having a hardness of 80% of the m	5787 ndicular distance between surface and ninimal surface hardness (= hardness micro section; according DIN EN 1032	limit)
3.2.3	For nitriding Designation: OLD : Nht NEW :NHD; according DIN ISO 15	5787	
		ce between surface to hardness limit (a polished micro section; according D	
4.	Choice of method and loa The method for hardness testin the drawing.	ad g and the required load is usually g	iven on
5.	properly to obtain defined hardnes deter-mined on polished (to mirror	ent the surface has to be ground (and s indents. The hardness profiles have	to be
6.	Documentation A test report has to be provided wi • Number (stamp) of the part and • Material specified on the drawing • Applied test method and used to • Measured hardness values (all v • Hardness profile (if applicable) • Measured core hardness value(s • Name and address of laboratory • Date, name and signature of res	corresponding batch number g bad values and average) s) and converted tensile strength (if ap	oplicable)
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Table	of contents										
1	Introdu	ction									2
2	Materia	ls to be	analy	/zed							2
3	General	requir	ement	ts							2
3.1	Assessr	nent / C	hoice	of a labo	ratory	/					2
3.2	Choice of	of Analy	vsis Te	chniques	s and	Proc	edures				3
4	Docume	entatio	n								5
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3.1

Introduction

Chemical analysis is required in order to check the material composition in comparison with the material specification. For this laboratories with suitable facilities and competences are required. In this specification the appropriate methods for various analysis tasks and the requirements are given.

Materials to be analyzed

On the base of the necessities exposed by Wärtsilä, following groups of materials were defined:

- 1. Cast iron
- 2. Steel
- 3. Bronce

Very small samples, having sizes inferior to some cm, may require alternative analysis techniques, which are generally less precise than those used for the analysis of larger samples. Due to this difference, it is reasonable to define a further group of specimens:

4. Small size samples (microanalysis required)

3 General requirements

Assessment / Choice of a laboratory

General requirements for the assessment of the competence of testing laboratories may be obtained from the standard ISO /IEC 17025:2005. It specifies the minimal criteria to be assured when testing materials not only by standard methods but also using non standard methods and laboratory-developed methods. The criteria are applicable to laboratories regardless of the number of personnel and of the extent and scope of the testing activities. Laboratory clients, regulatory authorities and accreditation bodies may also use it in confirming or recognizing the competence of laboratories. If testing and calibration laboratories fulfill the requirements of this International Standard they will operate on a quality system (for their testing and calibration activities) that also meets the requirements of ISO 9001, when they engage in the design/development of new methods and/or develop test programs combining standard and non-standard test and calibration methods. In the case of standard methods they will operate on a quality system that meets the requirements of ISO 9002.

From the general point of view, when evaluating the activities of a testing laboratory, the following criteria should be fulfilled:

 A specialized materials testing laboratory is preferable to any other kind of laboratories which also perform chemical analysis (environmental laboratory; etc.).

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Substitute for:	PC Q-Code X X X X
	Atomic Absorption Spectroscopy (AA)
	Inductively-Coupled Plasma Analysis (ICP)
	 Scanning Electron Microscopy (SEM) with associated Energy Dispersive X-Ray Analysis (EDX)
	Electron Probe Microanalysis (EPMA / WDX)
	techniques are suitable. The following can be recommended:
3.2.3	Methods recommended for small size samples (microanalysis required) For the chemical analysis of very small samples (< 1 cm) only a few analytical
	Carbon and sulphur: Combustion Analysis
	Inductively-Coupled Plasma Analysis (ICP)
	• X-Ray Fluorescence Spectrometry (XRF) - wave length dispersive systems only
3.2.2	Method recommended for cast iron
	Gas hot extraction
	Nitrogen/oxygen/hydrogen (steel):
	Glow Discharge Optical Emission Spectrometry (GDOES)
	Optical Emission Spectroscopy (OES)
	Combustion Analysis
	Carbon and sulfur (steel):
	Atomic Absorption Spectroscopy (AAS)
	Glow discharge Optical Emission Spectrometry (GDOES)
	Inductively-Coupled Plasma Analysis (ICP)
	Optical Emission Spectroscopy (OES)
	• X-Ray Fluorescence Spectrometry (XRF) - wave length dispersive systems only
	Major and trace elements:
3.2.1	Methods recommended for steel and bronze
	As already noticed, sample preparation should be kept as constant as possible. Particular emphasis should be applied on the preparation of carburized/nitrided samples. In this case, the carburized/nitrided zone has to be eliminated by cutting and/or grinding the material up to a depth of some millimeters.

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1. Validity range

Important bolts and studs for Diesel engines according to instructions on drawing.

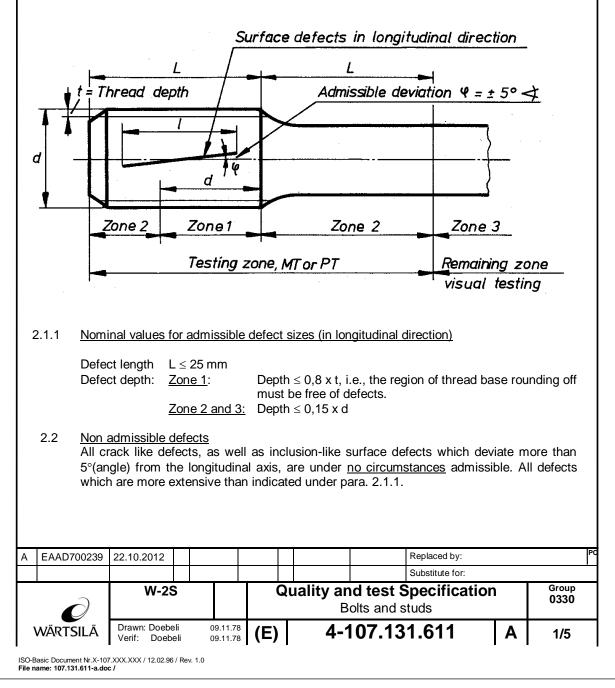
2. Quality standard

2.1 Admissible defects

On principle no surface cracks are accepted in the testing zones 1 and 2.

Exception:

Isolated indications are admissible for dye-penetrant (PT) or magnetic particle (MT) process on the surface according to data in figure below, if these are only linear inclusions and not crack-like defects.



3. Testing

3.1 <u>Scope of testing</u> In the machined state all surfaces are to be tested.

3.2 Testing method

<u>Testing zone</u> see Fig.1: by means of magnetic particle (MT) or dye-penetrant (PT) process.

Remaining zone through visual inspection

3.3 <u>Clarification of defects</u>

If necessary, for clarification of defects in the remaining zone an MT or PT test is to be carried out.

4. <u>Records</u>

The test results are to be recorded in the individual sheet (enclosures) per manufacturing series.

Enclosures:	sheet MT,	Enclosure 1
	sheet PT,	Enclosure 2
	sheet MT/PT,	Enclosure 3

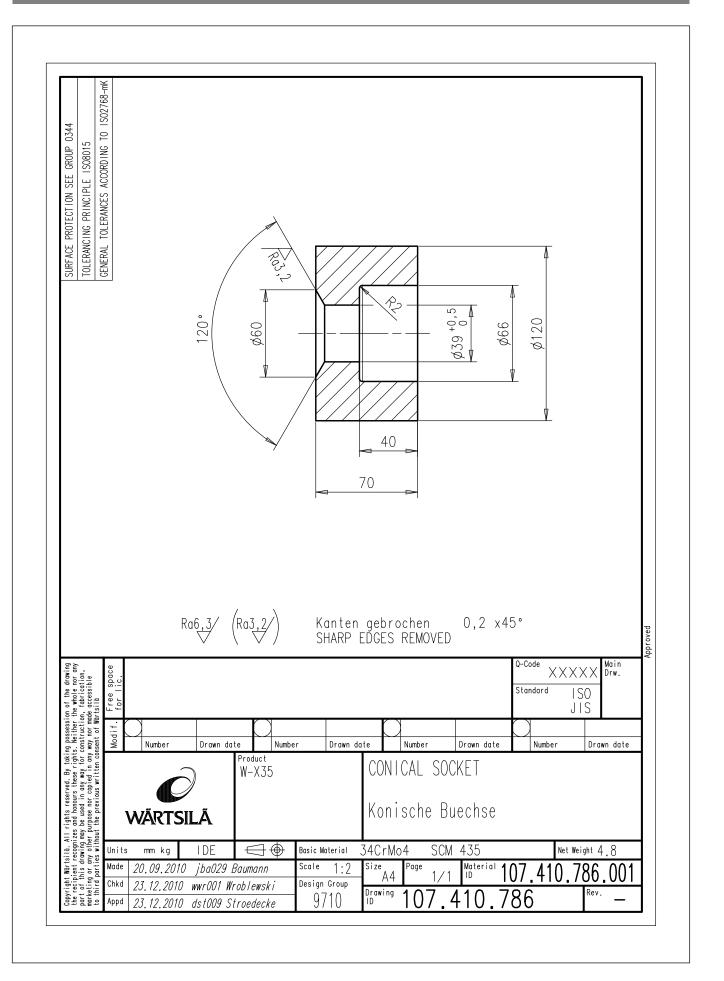
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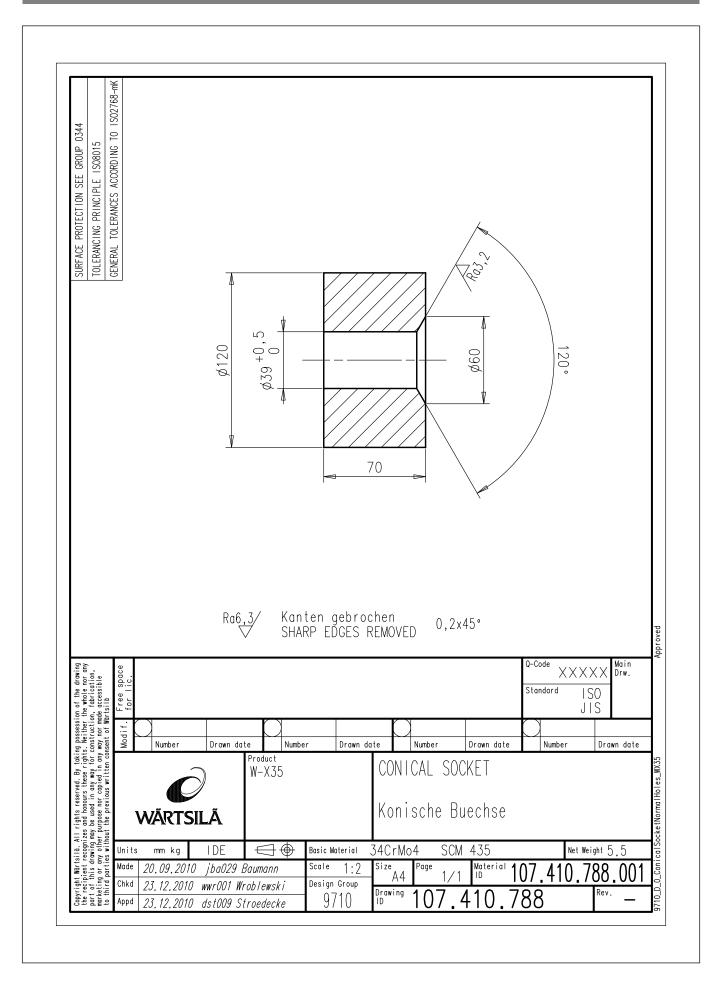
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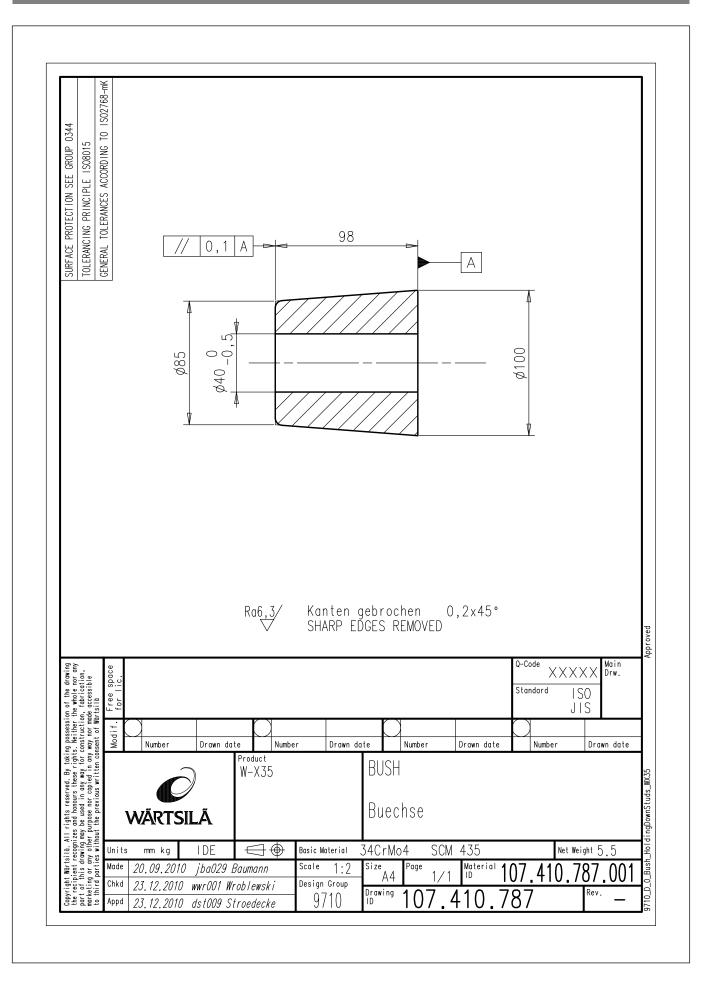
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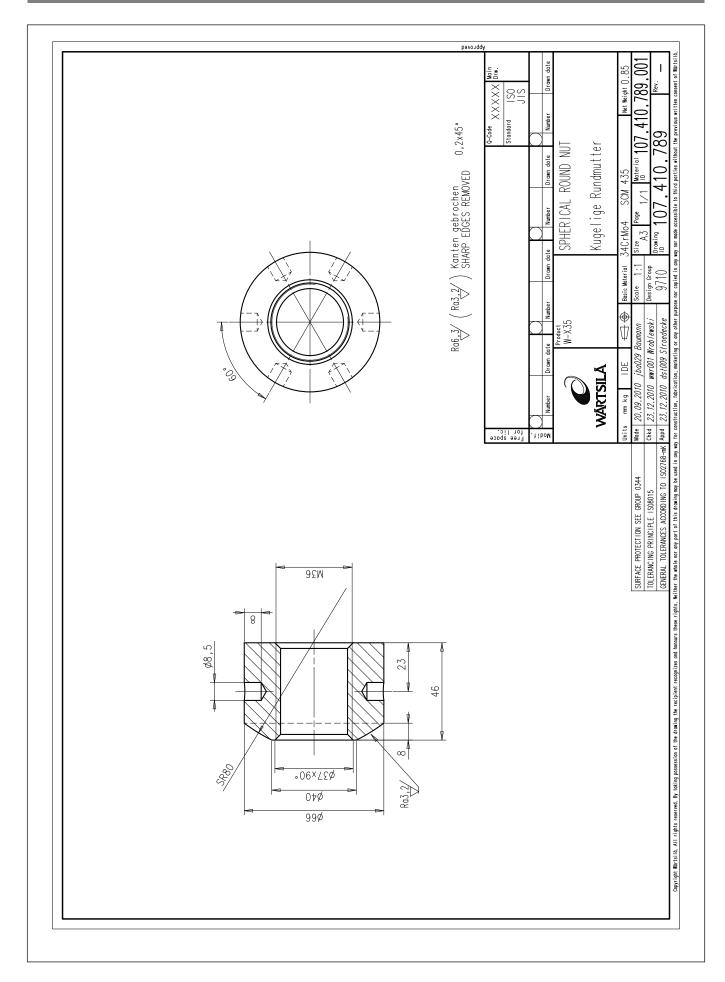
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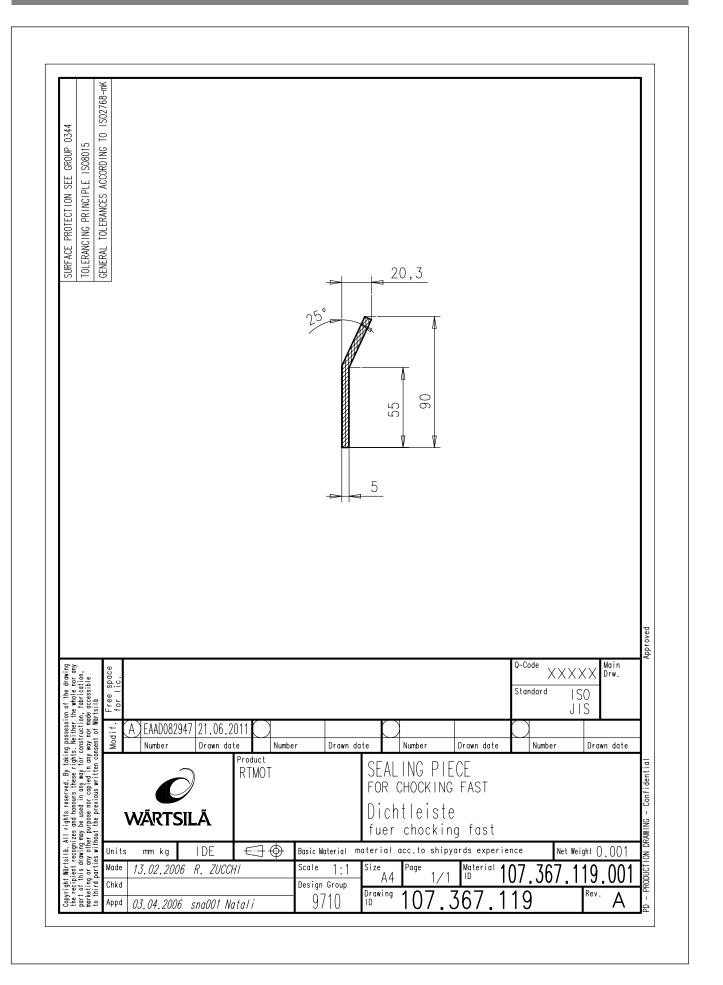
18. General Installation Aspects

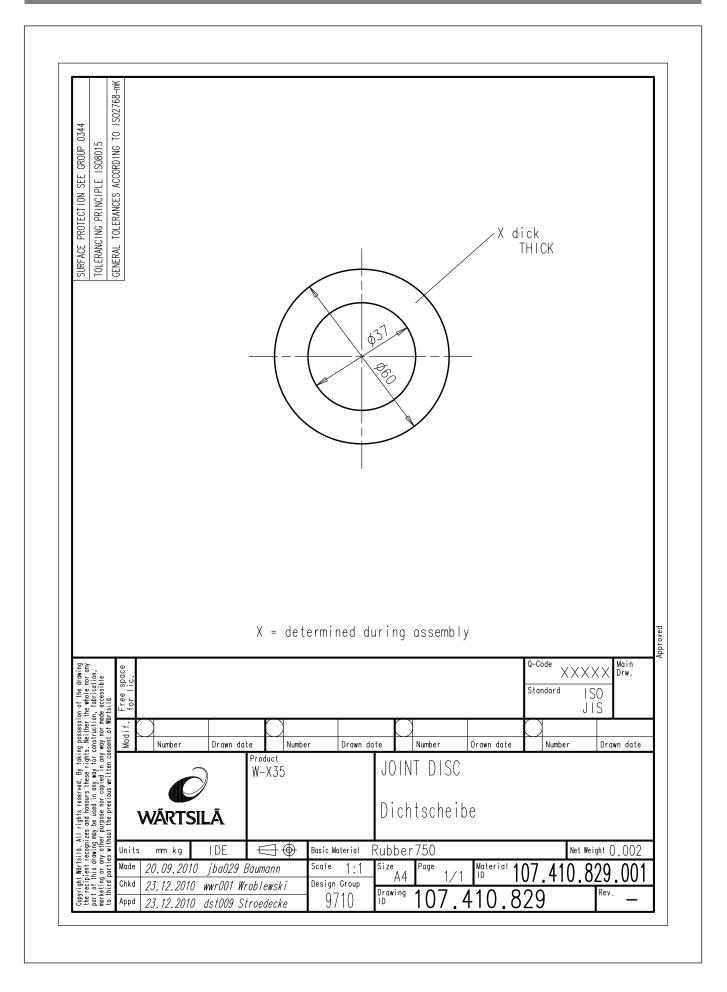


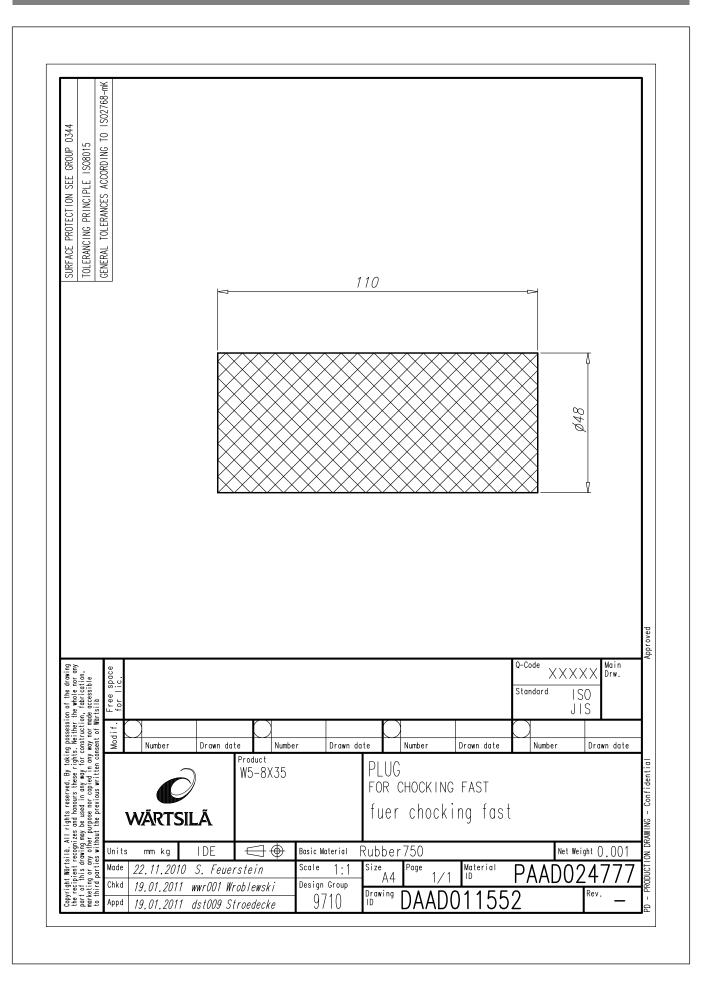


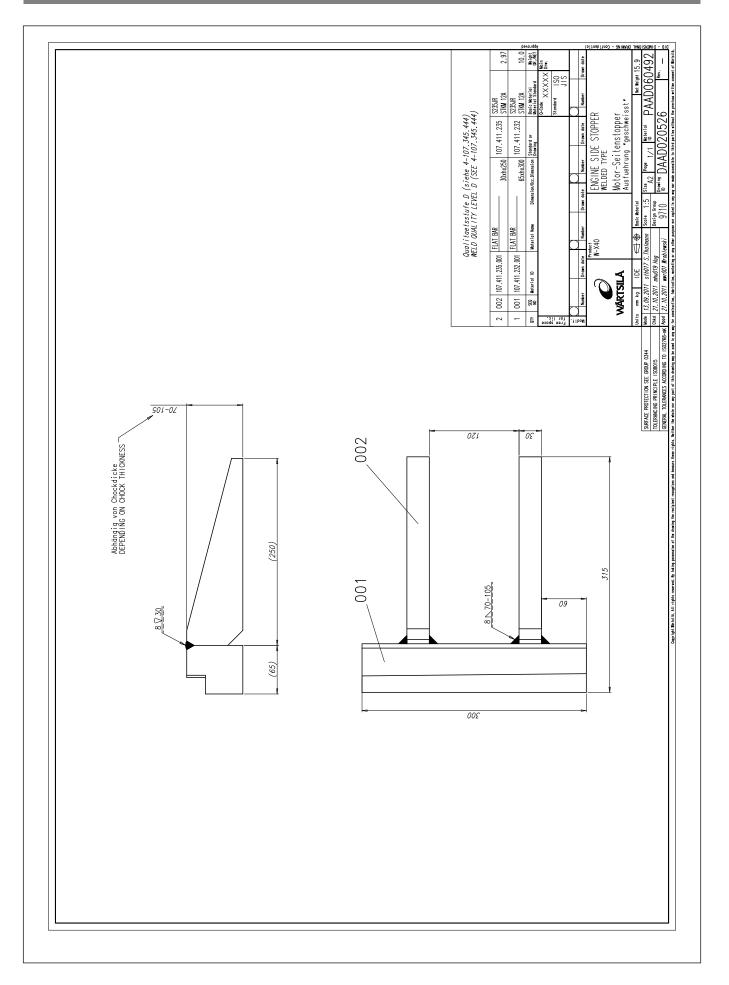


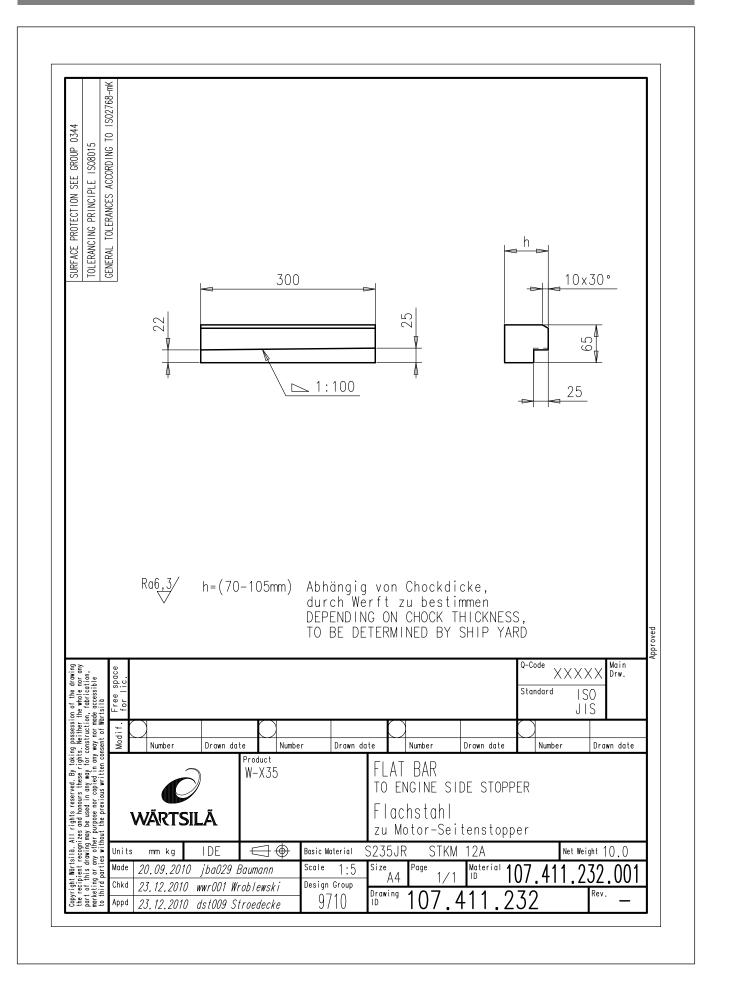


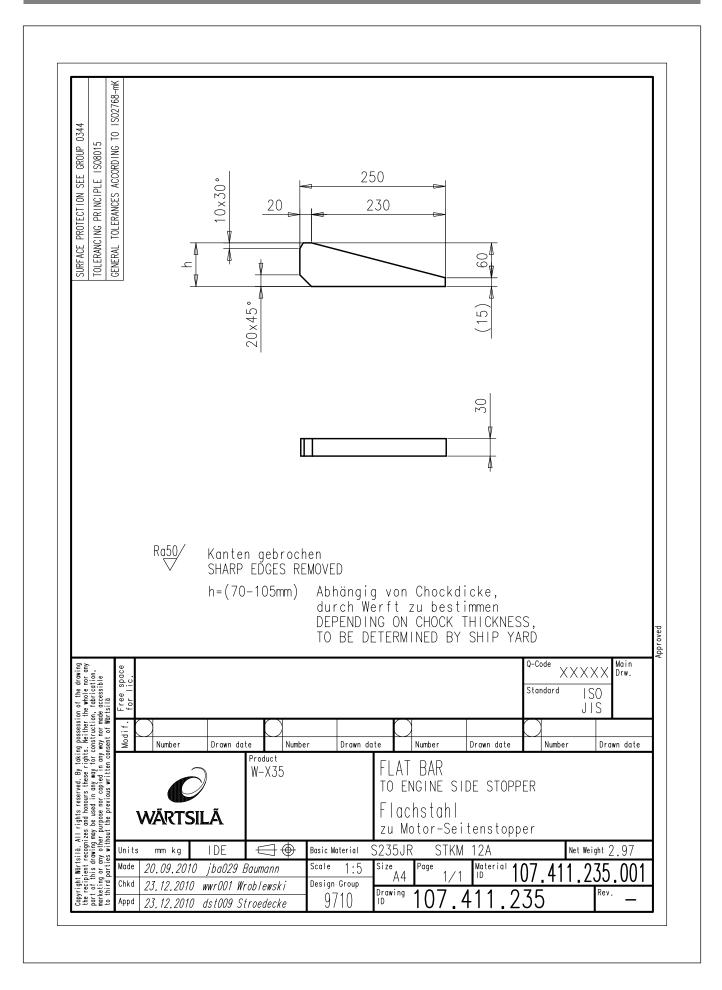


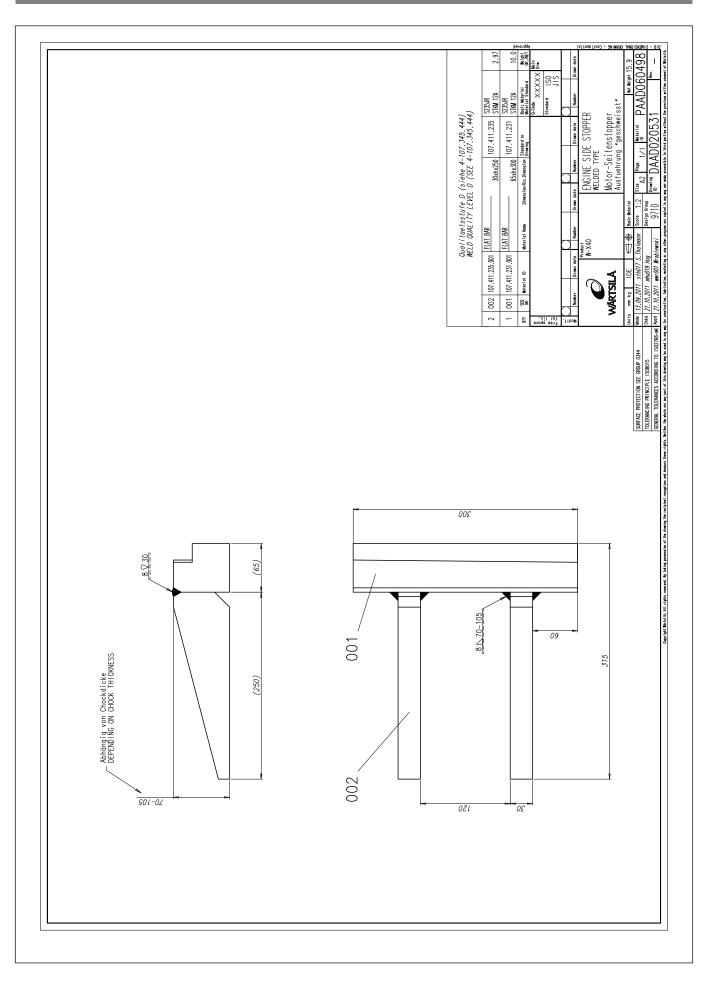


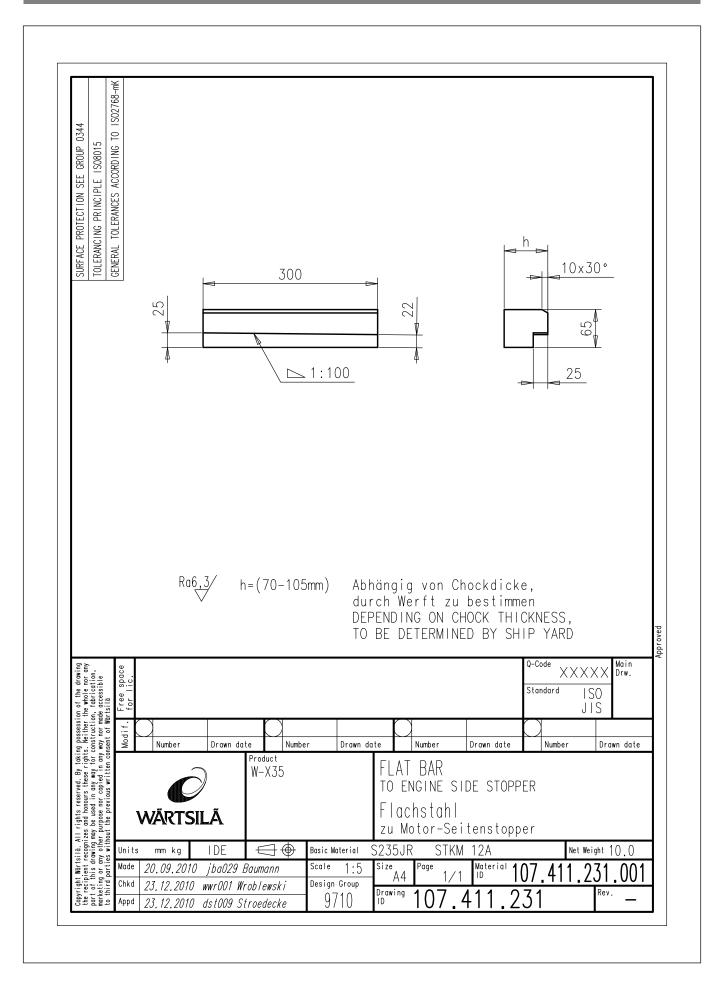


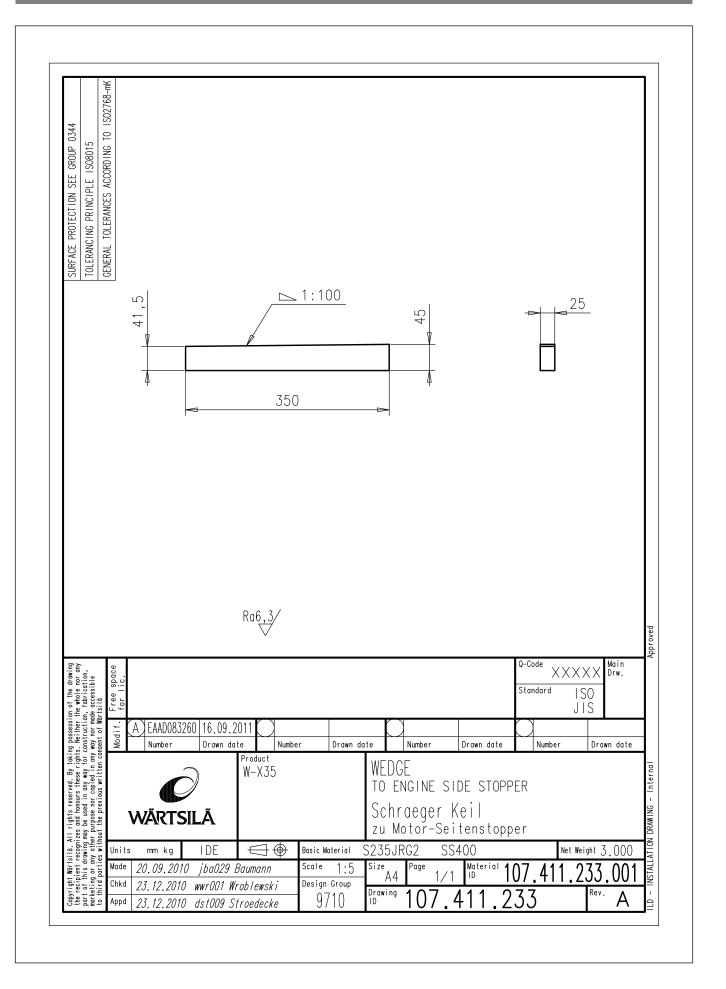












Introduction

1

Apart from the normal conventional engine holding down stud used to fasten the engine to the tank top plate, a different design is to be applied for the propeller thrust transmission. The propeller thrust is transmitted from the engine thrust bearing to the bedplate and to the tank top plate which is part of the ship's structure by means of thrust sleeves located adjacent to the engine thrust bearing.

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2 Thrust sleeve

2.1 Fitting

The thrust sleeve is fitted in the bottom plate of the engine bedplate and cast in the tank top plate. The diameter of the flame-cut or drilled hole for the thrust sleeve in the tank top plate is larger than the diameter of the sleeve to allow engine alignment without remachining of the hole. The sleeve in the tank top plate hole is then fixed with epoxy resin material as used for the chocks. The engine holding down stud is inserted in the sleeve and tightened in the same way as the normal holding down studs. This hydraulically tightened holding down stud is of the same design, as the normal holding down stud used to fasten the engine to the tank top plate. Drilling and reaming of the holes in the engine bedplate is carried out by the engine manufacturer. The thrust sleeves with the final tolerance and the holding down studs are supplied by the shipyard.

2.2 Drilling of the holes in the tank top plate

The holes for the thrust sleeves must be drilled or flame-cut in the tank top plate before setting the engine in position. These holes are prepared while observing the dimensions given on the drawing 'Chocking and drilling plan, section B-B'. The holes for the normal holding down studs can be drilled or flame-cut either before or after setting the engine in position.

2.3 Chock thickness

of this drawing may be used in any

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Since the chock thickness cannot be precisely determined before engine alignment is finalized, the standard design of the holding down stud, thrust sleeve and conical socket, allows for the application of chock thicknesses from 25 up to 60 mm. To avoid additional machining of the sleeve to adjust its length, the conical socket is provided with a larger bore compared to the sleeve's external diameter. The sleeve can protrude beyond the top plate more or less, the space in the conical socket allows for this variability. If chock thickness needs to be more than 60 or less than 25 mm, the length of the thrust sleeve and its corresponding holding down stud as well as the length of the normal holding down stud must be in- or decreased accordingly. Please note: In any case, if the minimum thickness is less than 25 mm, the epoxy resin supplier must be consulted.

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3

Pouring of the epoxy resin chocks

3.1 Conditions before pouring

- Engine fully aligned
- All side stoppers welded in place, wedges not fitted
- For thrust sleeves (see figure 1): Thrust sleeves and their accompanying holding down studs inserted into the corresponding holes with the studs/nuts tightened by hand. The bush and the sponge rubber sealing fixed correctly under the tank top plate. Contact surface conical socket/top plate smeared with gasket sealant.
- For normal holding down studs (see figure 2): Sponge rubber plugs or similar inserted into bedplate where normal studs are applied.

3.2 Pouring

Pouring of the epoxy resin chocks together with its preparatory work must be carried out either by experts of the epoxy resin manufacturers or by their representatives. Their instructions must be strictly observed. In particular, no yard work on the engine foundation may proceed before completion of the curing period of the epoxy resin chocks. Epoxy resin material for the thrust sleeve holes is identical to that used for the chocks.

The epoxy resin material applied for the chocking of the engine has to fulfill the following requirements:

- Approved by the major classification societies
- The following materials properties are met:

Properties	Standard	Values
Ultimate compression strength	ASTM D-695	min. 130 MPa
Compression yield point	ASTM D-695	min. 100 MPa
Compressive modulus of elasticity	ASTM D-695	min. 3100 MPa
Deformation under load: Load 550 N / 70°C Load 1100 N / 70°C	ASTM D-621	max. 0.10 % max. 0.15 %
Curing shrinkage	ASTM D-2566	max. 0.15 %
Coefficient of thermal expansion (0-60 K)	ASTM D-696	max. 50 • 10 ⁻⁶ 1/K
Coefficient of friction - normal		min. 0.3

Table 1: Required properties of epoxy resin material

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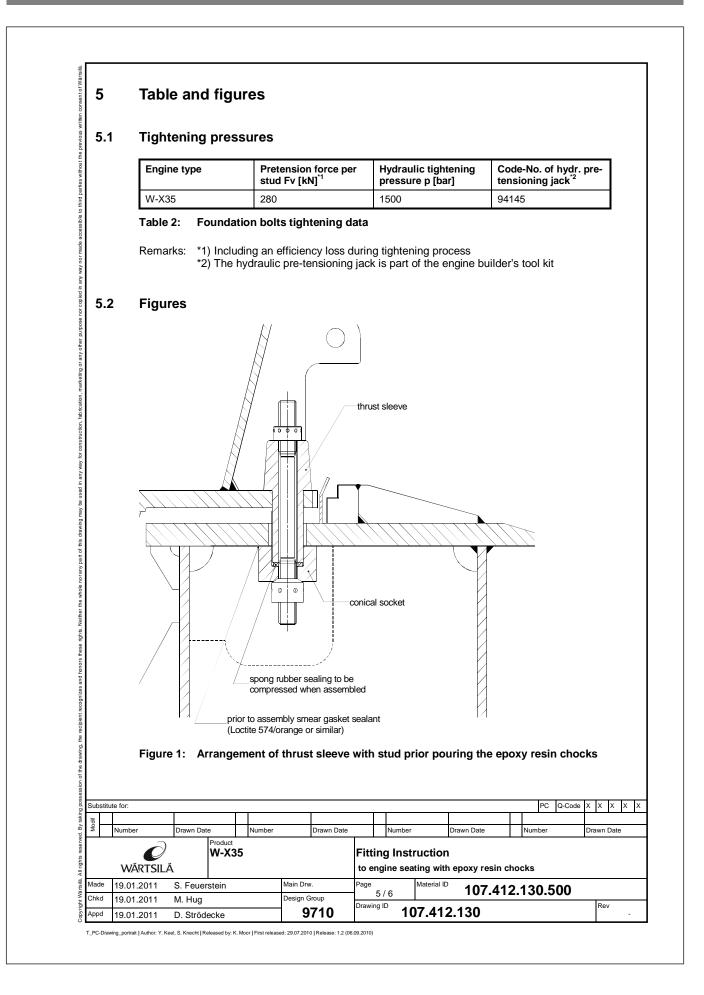
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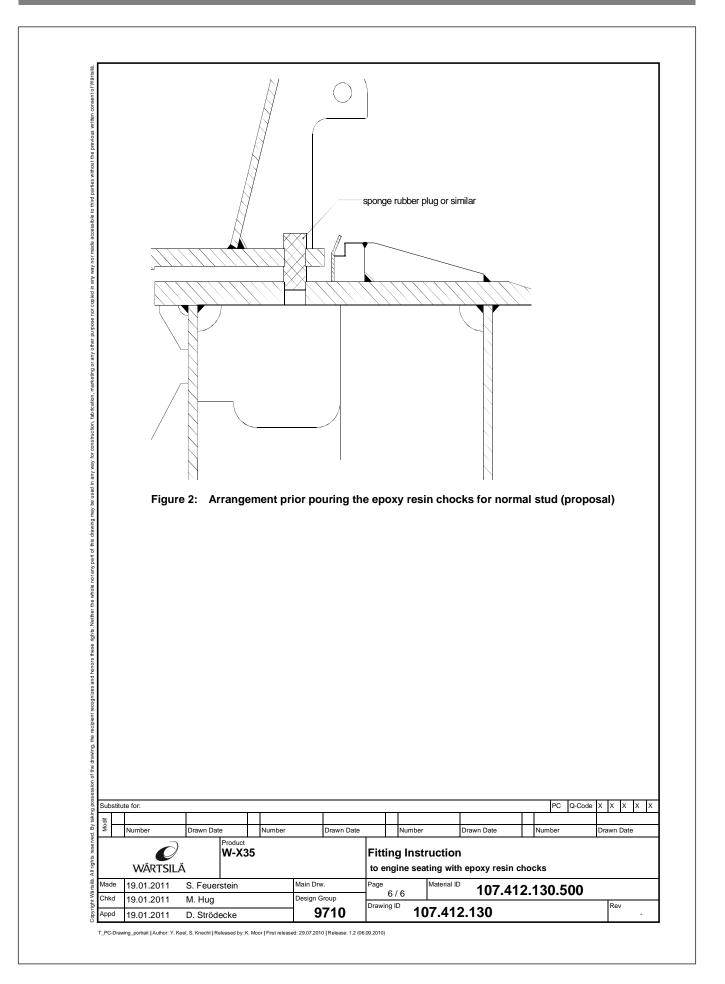
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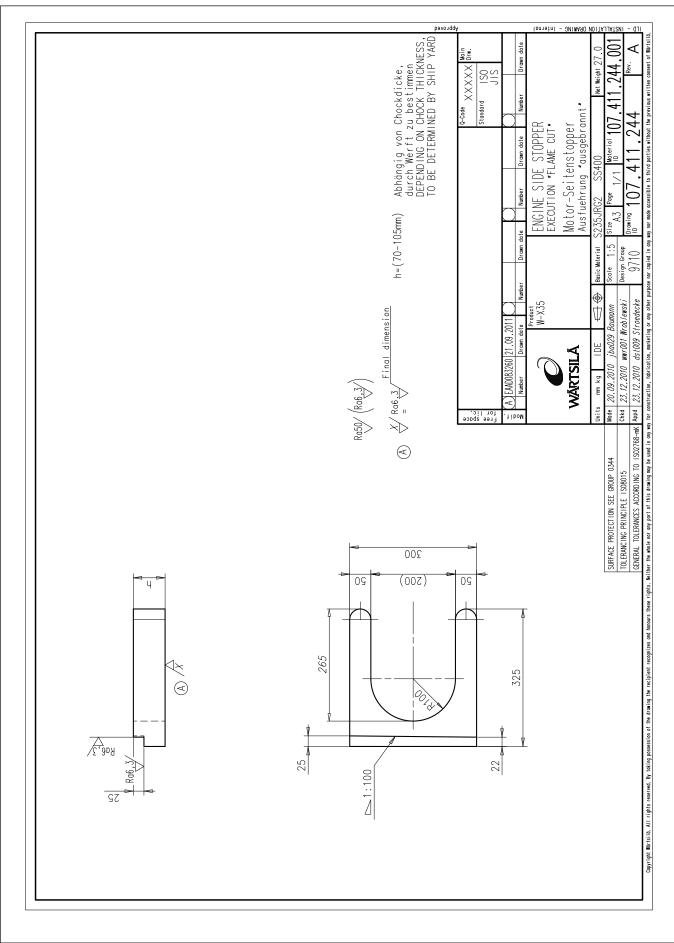
4 Tightening the holding down studs

The instructions of the epoxy resin manufacturers or their representatives concerning the curing period must be strictly observed before any work on the engine foundation may proceed. On completion of the curing period, the supporting devices, i.e. jacking screws, jacking wedges, etc., must be removed before the holding down studs are tightened. All engine's holding down studs are tightened by means of a hydraulic pretensioning jack. The tightening procedure begins at the driving end and continues alternating from side to side or in parallel on both sides in the direction of the engine free end. After tightening all engine holding down studs, fit the side stopper wedges.

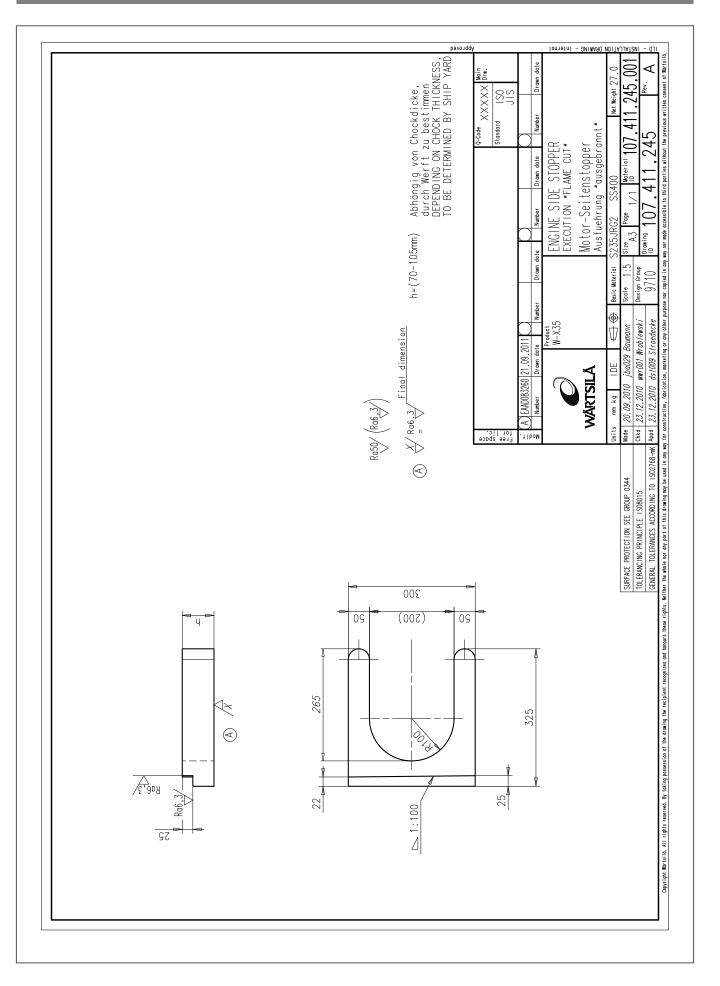
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18.5 Engine coupling

18.5.1 Fitting of coupling bolts

Drilling and reaming of the engine and shaft couplings is to be carried out using a computer controlled drilling machine or an accurately centred jig. Great care is to be taken in matching and machining mating flanges together. Fitted bolt hole tolerances are to be H7 and fitted bolts are to be available for inserting in the holes on completion of reaming. Each fitted bolt is to be stamped with its position in the coupling, with the same mark stamped adjacent to the hole. In the event of a pitch circle error leading to a misalignment of bolt holes, the situation has to be remedied by applying joint cylindrical reaming to an oversize hole and fitting an individually machined fitted bolt. Fitted bolts are to locate with a medium fit, but not requiring heavy hammer blows. If there is any doubt that a fitted bolt is too slack or too tight, refer to the classification society surveyor and a representative of the engine builder.

The connection crankshaft/propeller shaft with bore, bolt and nut is part of the engine designer's submission to the Classification Societies for Design Approval.

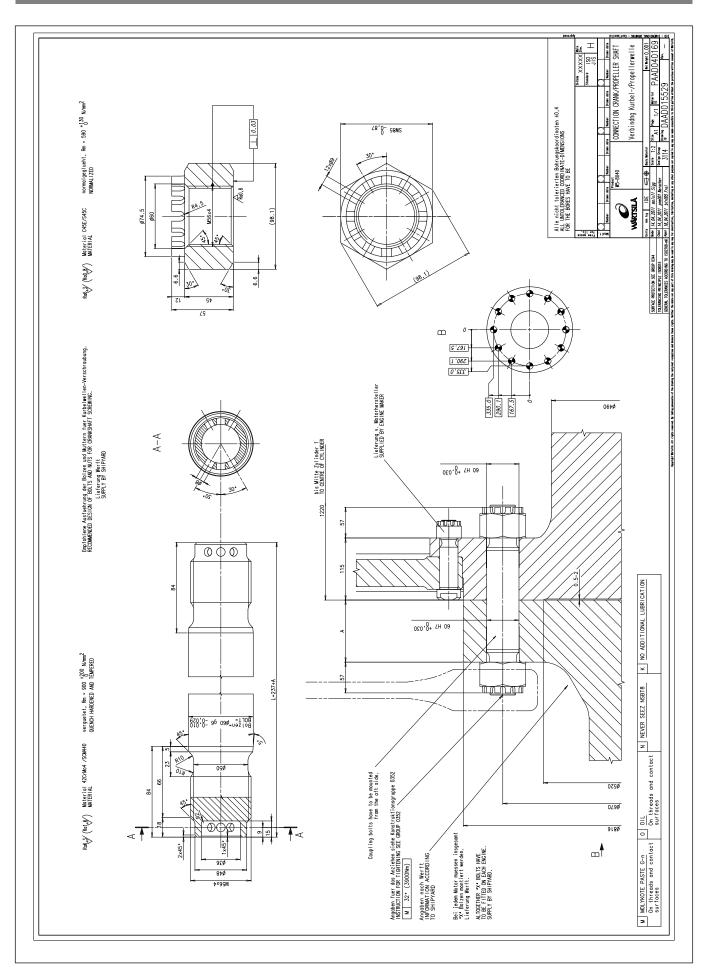
When tightening the coupling bolts it is essential to work methodically, taking up the threads on opposite bolts to hand-tight, followed by sequential torque tightening.

Mark each bolt head in turn, 1, 2, 3, etc., and tighten opposite nuts in turn to an angle of 32°, making sure the bolt head is securely held and unable to rotate with the nut.

Castellated nuts are to be locked according to the requirements of class with either locking wires or split pins. Use feeler gauges during the tightening process to ensure that the coupling faces are properly mated with no clearance.

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Drawings
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DAAD015529 - Connection Crank/Propeller Shaft, W5-8X40



18.6 Engine earthing

Electric current flows when a potential difference exists between two materials. The creation of a potential difference is associated with 'thermoelectric' by the application of heat, 'tribo-electric' between interactive surfaces, 'electrochemical' when an electrolytic solution exists, and 'electromagnetic induction' when a conducting material passes through a magnetic field. Tracking or leakage currents are created in machinery by any of the above means and, if they are not adequately directed to earth, can lead to component failures or in some cases result in fires and interference with control and monitoring instrumentation.

18.6.1 Preventive action

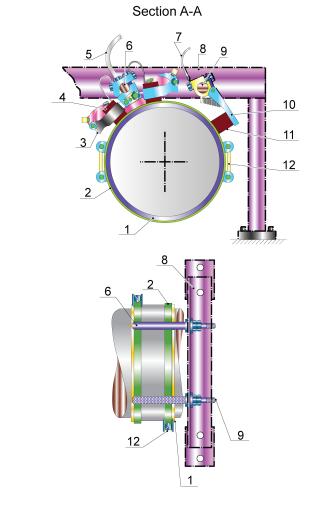
Using earthing brushes in contact with slip-rings and bonding the chassis by braided copper wire are common ways of protecting electric machines. Where operating loads and voltages are comparatively low, then the supply is isolated from the machine by an 'isolating transformer', often with handheld power tools. The build specification dictates the earthing procedure to be followed and the classification society is to approve the final installation. On vessels with star-wound alternators the neutral is considered to be earth, and electrical devices are protected by automatic fuses. Ensure that instrument wiring meets the building and classification society specifications and that it is shielded and isolated to prevent induced signal errors and short circuits. In certain cases large items of machinery are isolated from their foundations, and couplings are isolated to prevent current flow, e.g. when electric motors are connected to a common gear box. Retrospective fitting of earthing devices is not uncommon, but due consideration is to be given at the design stage to adequate shielding of control equipment and earthing protection where tracking and leakage currents are expected. Magnetic induction and polarisation are to be avoided and degaussing equipment incorporated if there is likely to be a problem.

18.6.2 Main shaft earthing system

Figure *18.5* shows a typical shaft earthing system. The slip-ring (1) is supplied as matched halves to suit the shaft and secured by two tension bands (2) using clamps (12). The slip-ring mating faces are finished flush and butt jointed with solder. The brushes (4) are housed in the twin holder (3) clamped to a stainless steel spindle (6) and there is a monitoring brush (11) in a single holder (10) clamped to an insulated spindle (9). Both spindles are attached to the mounting bracket (8). The electric cables are connected as shown in figure *18.6* with the optional voltmeter. This instrument is at the discretion of the owner but it is useful to observe that the potential to earth does not rise above 100 mV.

Different combinations of conducting material are available for the construction of the slip-rings. However, alloys with a high silver content are found to be efficient and hard wearing.

Wärtsilä Switzerland Ltd. recommends installing a shaft earthing device on the intermediate shafting as illustrated in figure 18.5.



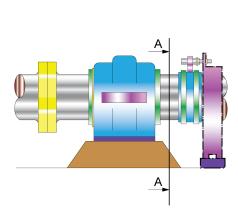


Figure 18.5: Shaft earthing arrangement

	View on 'A' - Brush gear omitted								
1	Slip ring	7	Connection to the voltmeter						
2	Tension bands	8	Mounting bracket						
3	Twin holder	9	Insulated spindle						
4	Brushes	10	Single holder						
5	Connection to the ship's hull	11	Monitoring brush						
6	Steel spindle	12	Clamps						

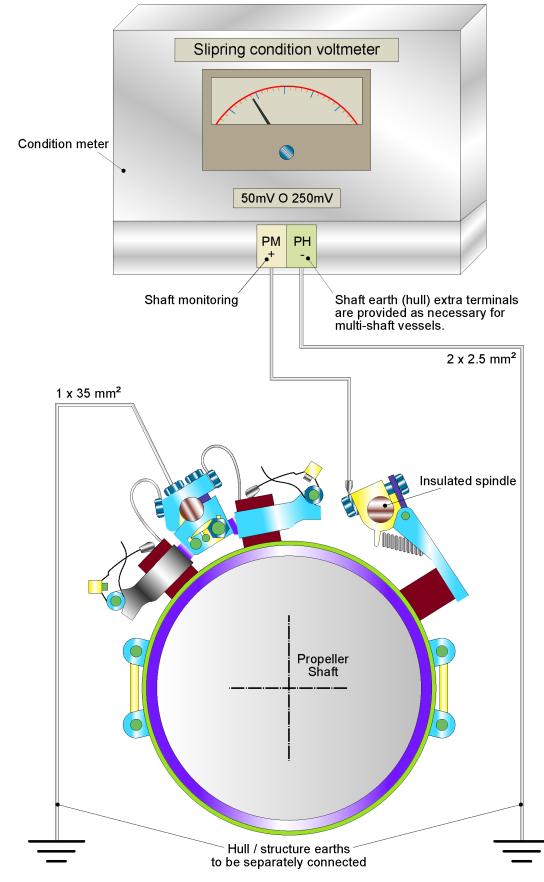


Figure 18.6: Shaft earthing with condition monitoring facility

18.7 Engine stays

The engine seating is integral with the double-bottom structure and has to be of sufficient strength to support the weight of the engine, transmit the propeller thrust, withstand external couples and stresses related to propeller and engine resonance.

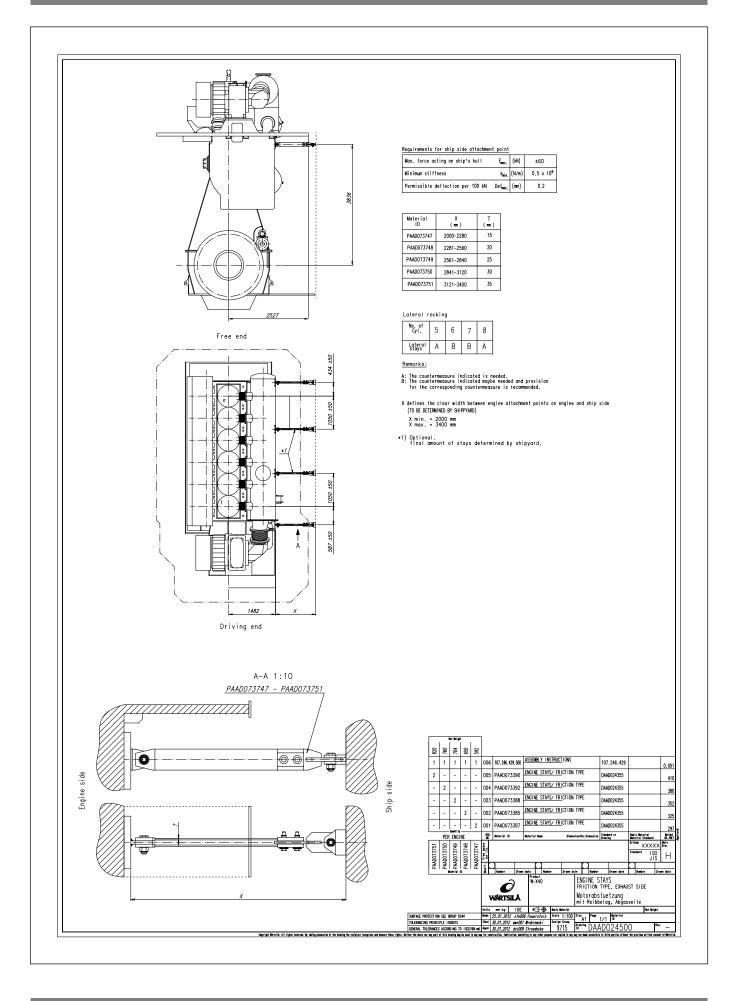
The longitudinal beams situated under the engine are to extend forward of the engine room bulkhead by at least half the length of the engine, and aft as far as possible.

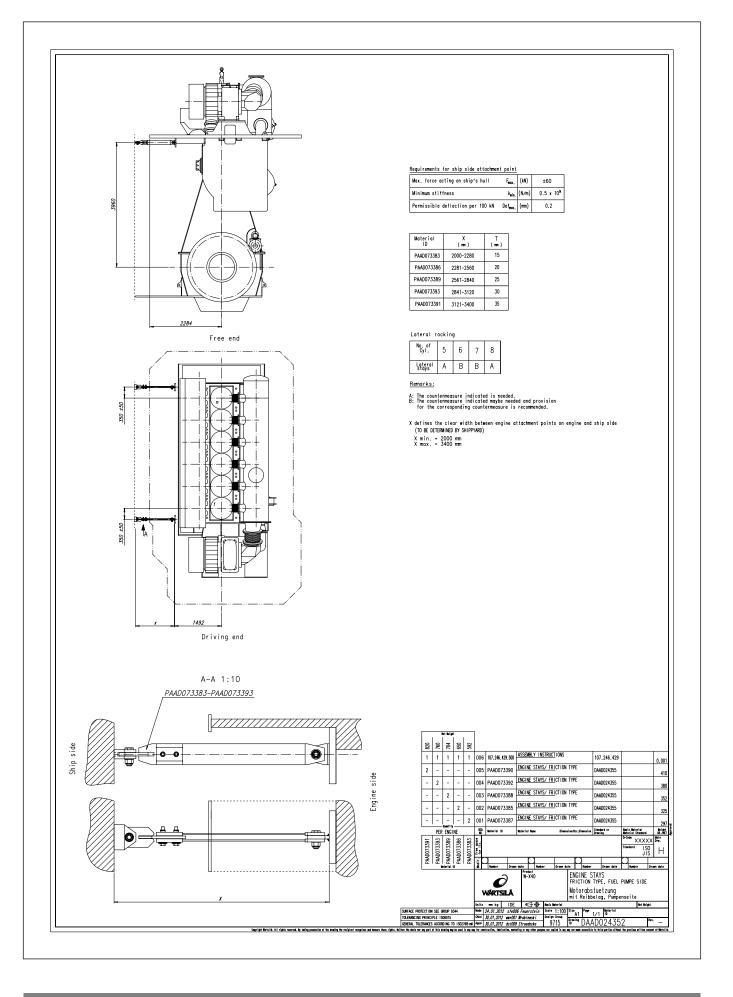
The maximum allowable rake is 3° to the horizontal.

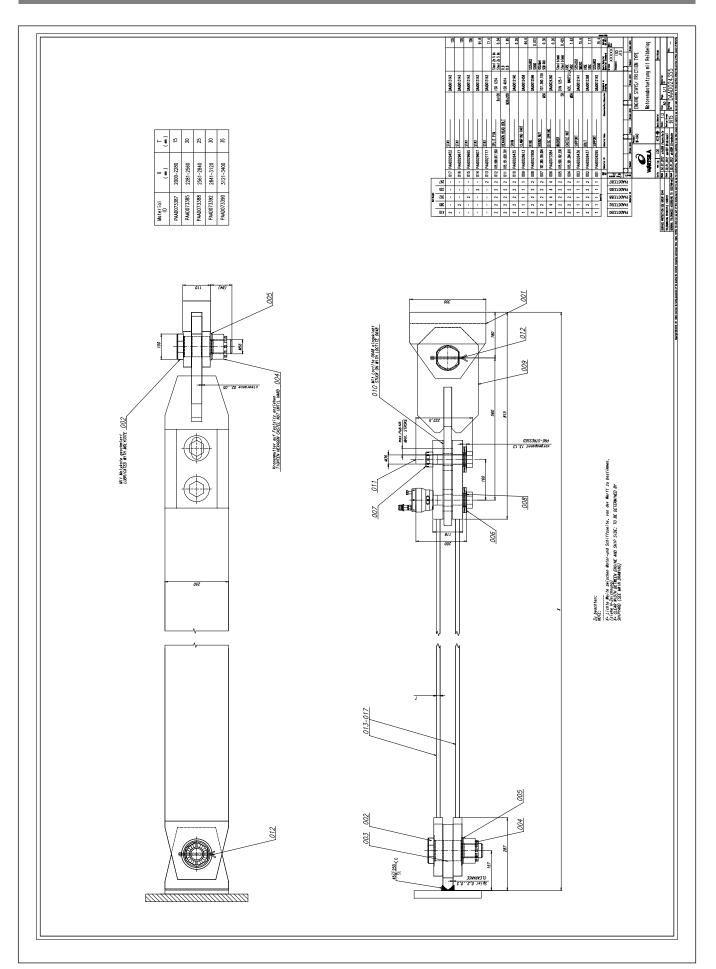
Before any engine seating work can be performed, make sure the engine is aligned with the intermediate propeller shaft.

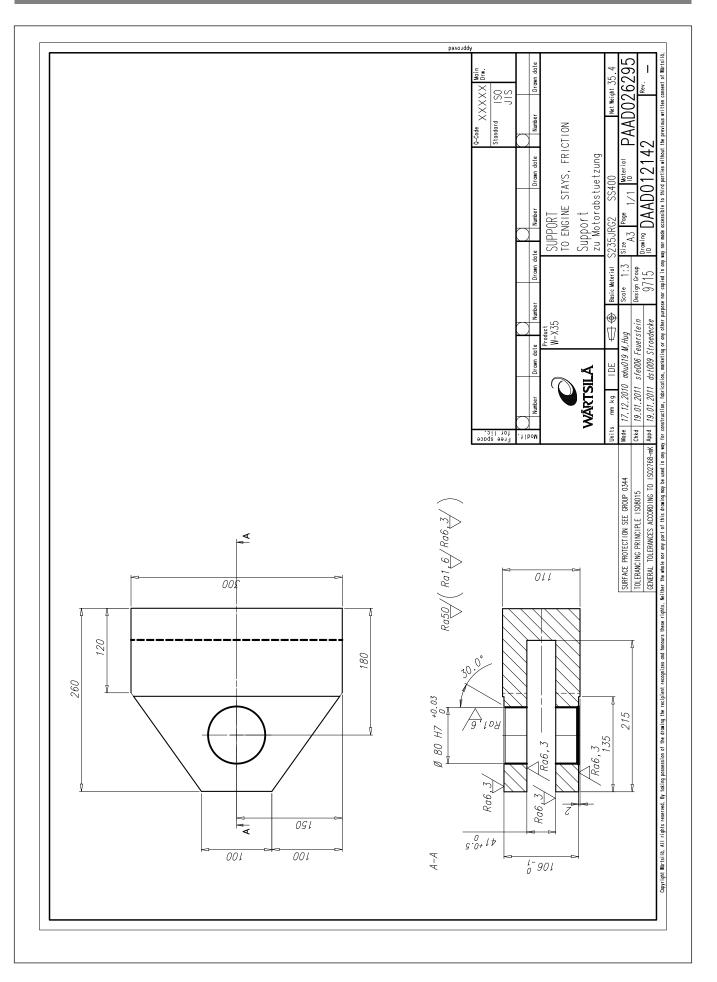
18.7.1 Drawings

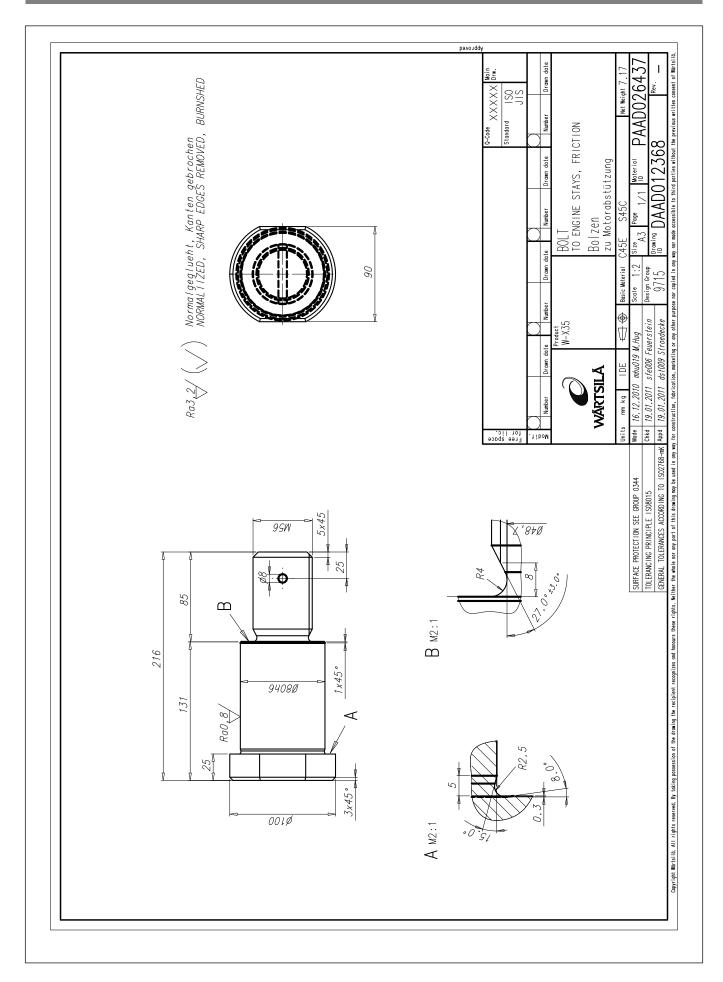
DAAD024500 -	Engine Stays, Friction Type. Exhaust Side, W5-8X40	8889
DAAD024352 -	Engine Stays, Friction Type. Fuel Pumpe Side, W5-8X40	188692
DAAD024355 -	Engine Stays/ Friction Type, W5-8X40	188633
DAAD012142 -	Support, To Engine Stays. Friction, W5-8X40	
DAAD012368 -	BoLT, To Engine Stays. Friction, W5-8X40	8885
DAAD012141 -	Support, To Engine Stays. Friction, W5-8X40	188836
DAAD024360 -	Disc Spring, To Engine Stays. Friction, W5-8X40	
107.380.159 b	Round Nut, W5-8X40	
DAAD012596 -	Ring, To Engine Stays. Friction, W5-8X40	
DAAD012458 a	Clamping Part, Machined. To Engine Stays, W5-8X40	188800
DAAD012457 a	Clamping Part, Welded. To Engine Stays, W5-8X40	
DAAD012140 -	Shim, To Engine Stays. Friction, W5-8X40	
DAAD013143 a	Stay, Machined. To Engine Stays, W5-8X40	
DAAD013130 a	Stay, Welded. To Engine Stays, W5-8X40	
DAAD013130 a	Plate, Welded. To Engine Stays, W5-8X40	
107.246.429 e	Assembly Instructions, To Engine Stays Friction, W5-8X40	
DAAD020880 -	Engine Stays, Hydraulic Type, W5-8X40	
107.165.800 g	Hydraulic Cylinder, To Engine Stays, W5-8X40	
107.165.801 f	Cylinder, W5-8X40	
107.165.802 a	Piston, W5-8X40	
107.165.803 d	Cover, W5-8X40	
107.165.804 b	Valve Spindle, W5-8X40	
107.165.808 a	Connecting Piece (Sw41), W5-8X40	
107.165.806 a	Pointer, W5-8X40	
107.165.809 -	Bearer, W5-8X40	
107.165.810 a	Treaded Sleeve, Engine Stays, W5-8X40	
107.165.815 -	Support, W5-8X40	
107.165.821 a	Ring, W5-8X40	
107.245.489 -	Ball Valve, Order Drawing, W5-8X40	
107.165.811 -	Piston Guide, Order Drwg., W5-8X40	
107.165.812 -	Pressure Gauge, Order Dr., W5-8X40	
107.329.413 a	Bladder Accumulator, Order Drawing, W5-8X40	
107.165.814 -	Plug, Order Drwg., W5-8X40	
107.165.820 b	Hydraulic Lateral Device, For Main Engine, W5-8X40	
107.165.818 b	Testing and Filling Device, Order Drwg., W5-8X40	
107.165.817 a	Instruction For Pressure Test, 250 Bar, W5-8X40	
DAAD006100 -	Round Bar, W5-8X40	
107.165.822 -	Male Union, Order Drwg., W5-8X40	
107.165.813 b	Prec. Seamless Pipe, Order Drwg., W5-8X40	. CCCH

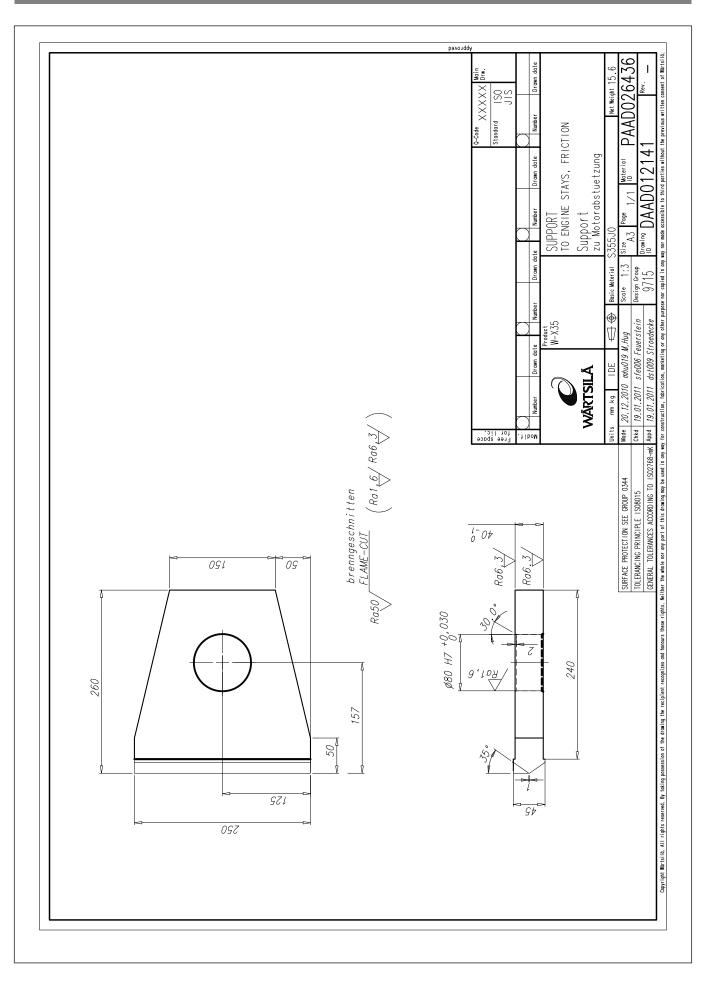


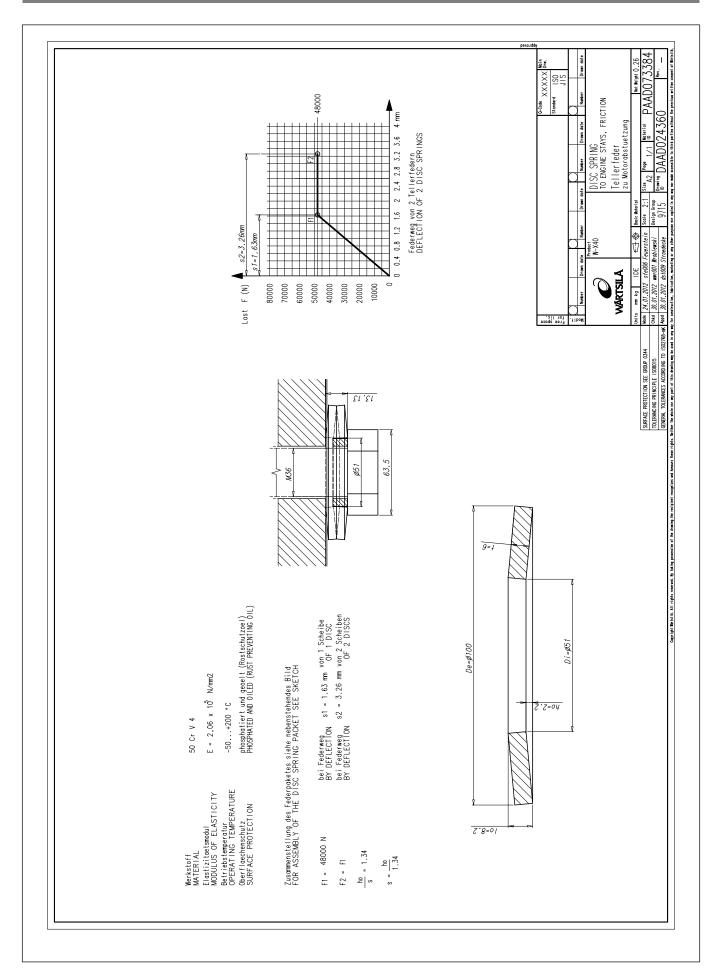


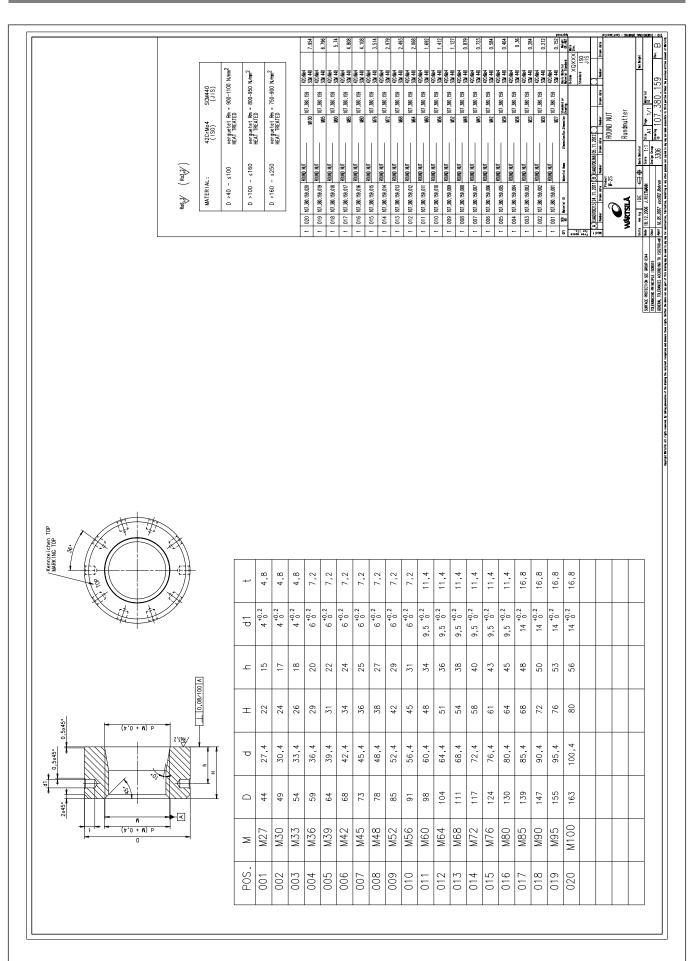


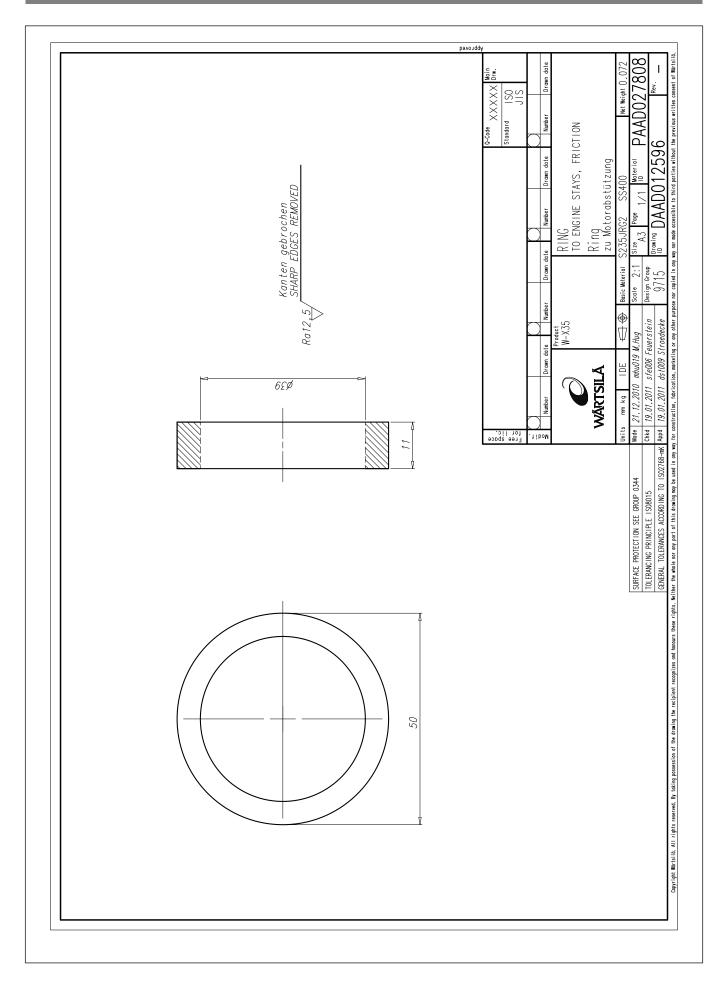


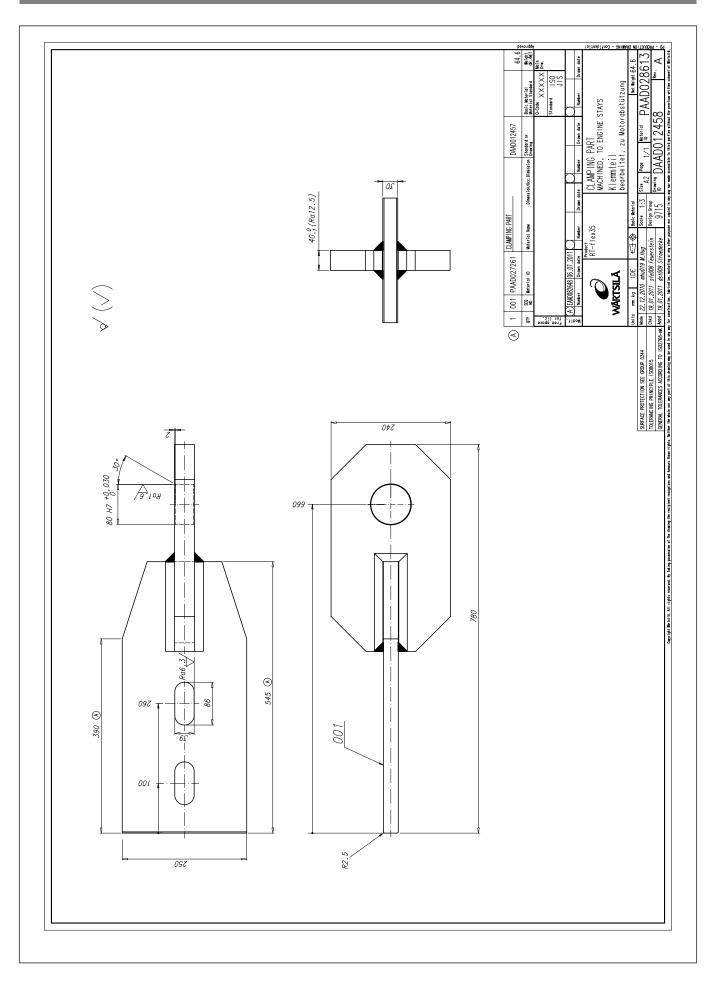


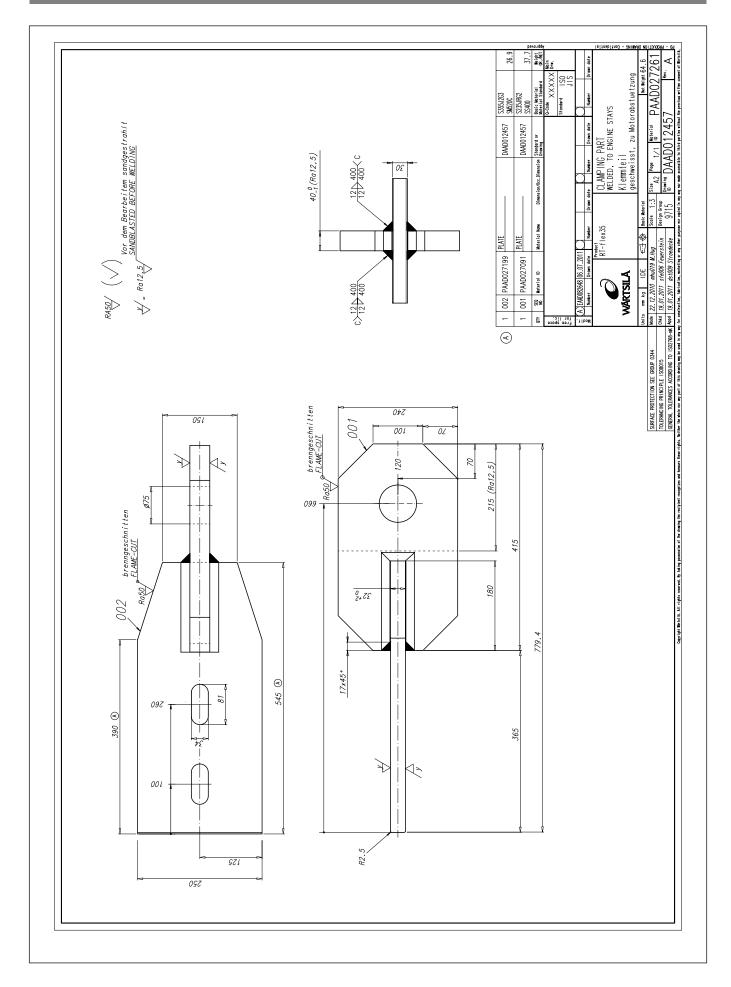


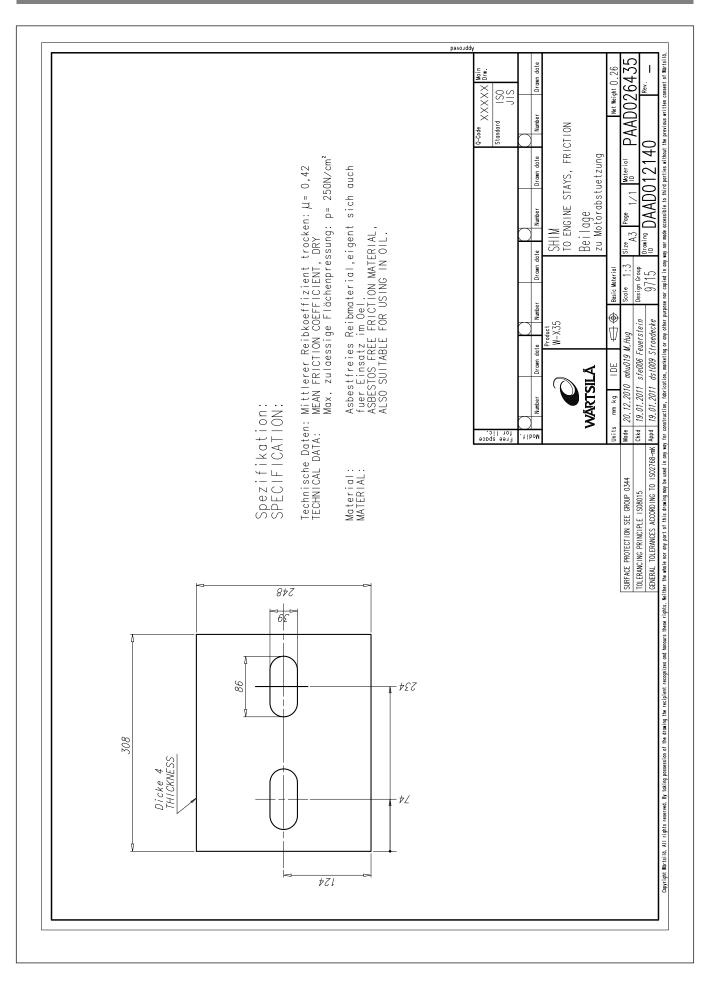


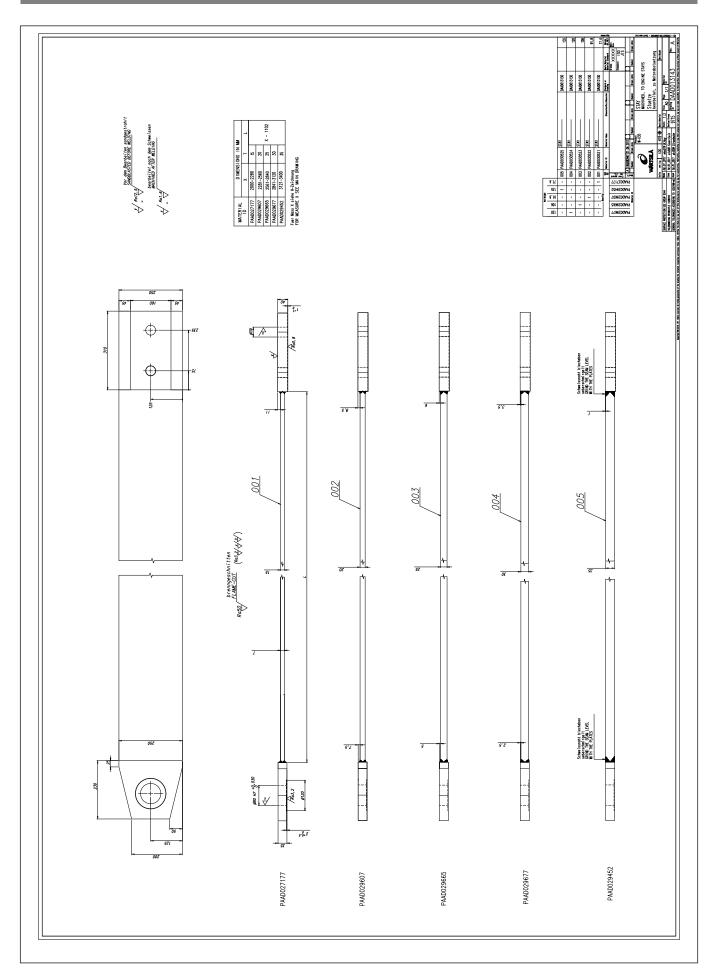


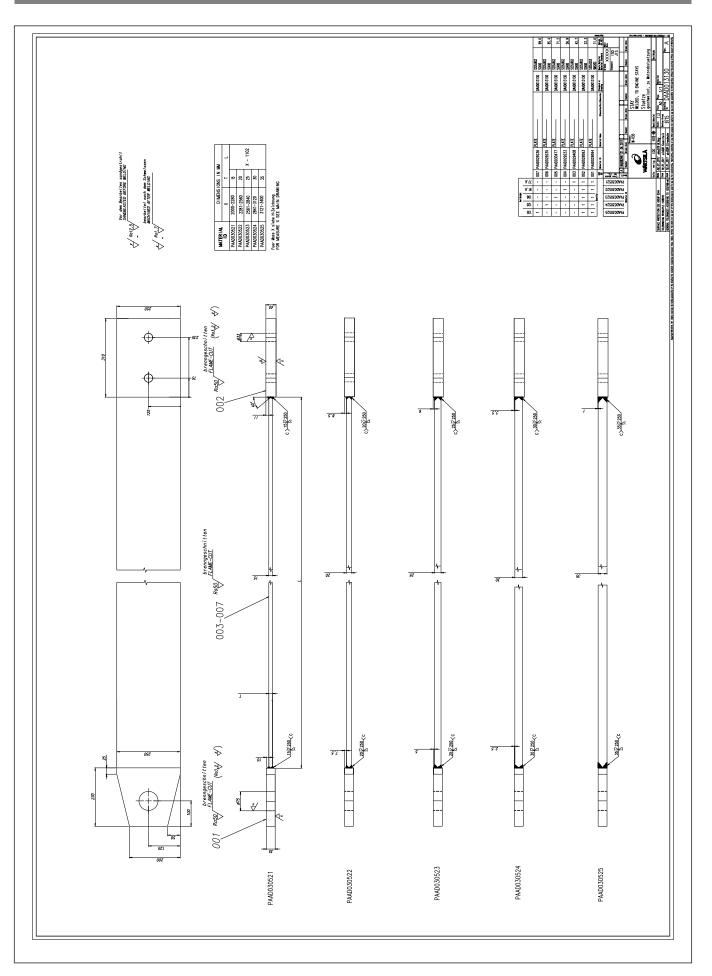


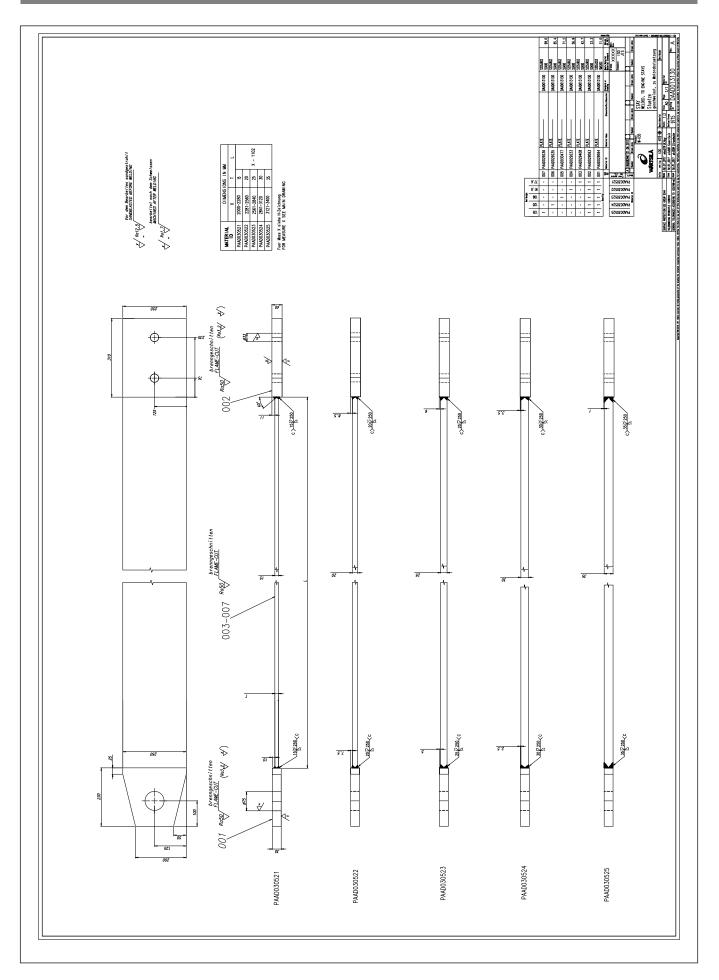












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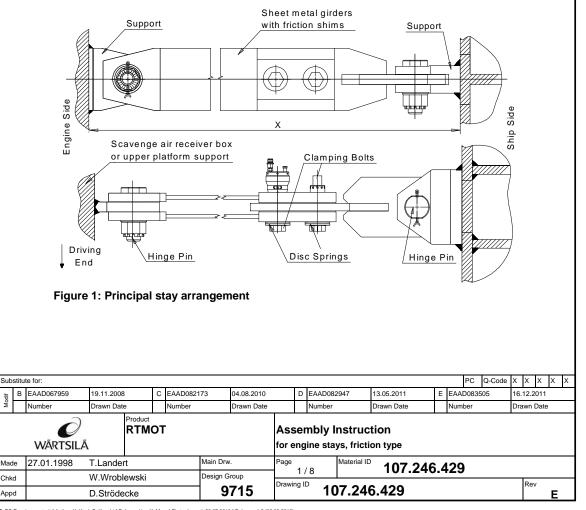
Introduction

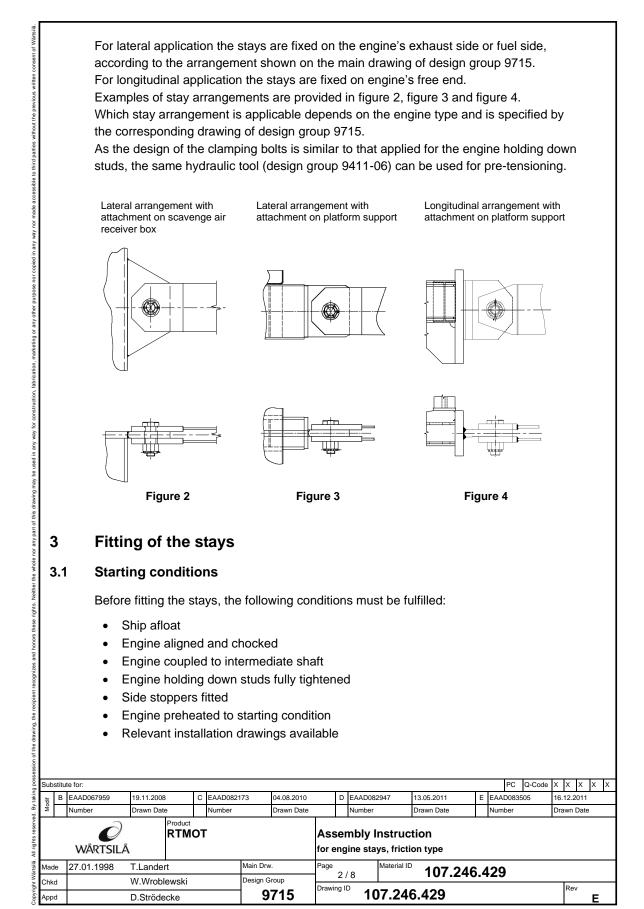
Lateral and longitudinal stays are installed where countermeasures against dynamic effects are necessary (for indications refer to Marine Installation Manual, chapter Engine Dynamics). For stay arrangement and details refer also to the relevant installation drawings of the corresponding design group 9715. It is vital that the stays are fitted correctly to ensure proper operation and to prolong the lifetime of the components.

2 Description and function

The stays are fitted between the engine and the ship hull. They transmit lateral, respectively longitudinal forces, from the engine via friction shims and sheet metal girders to the ship hull. The clamping force of the two clamping bolts is adjusted in such a way that during engine operation the engine's pulsating forces are transmitted to the ship hull. During loading and unloading, the stay is able to adapt the deformations of the ship's hull within its stroke.

To reduce material stress in the stay itself and also in the attachment points, hinge pins are provided in the supports to allow movements in both vertical and longitudinal directions.





- The attachment points of the stays on engine and ship hull side are marked in the final position according to the relevant main drawing of design group 9715
- Hydraulic tensioning device is ready for use (engine builder's tool kit, code-No. 94145)

Note:

When fitting the stays it is very important that the engine is preheated to starting condition. This is necessary to reduce any possible misalignment of the stay due to engine thermal expansion between fitting and service condition. Excessive horizontal and vertical misalignment of the stay between the engine's and the ship's attachment points may restrict the stay's function. It may even lead to buckling or cracking of the stay. For admissible tolerances refer to table 2. During positioning and fitting use a crane to avoid overstress to the stay.

3.2 Installation steps

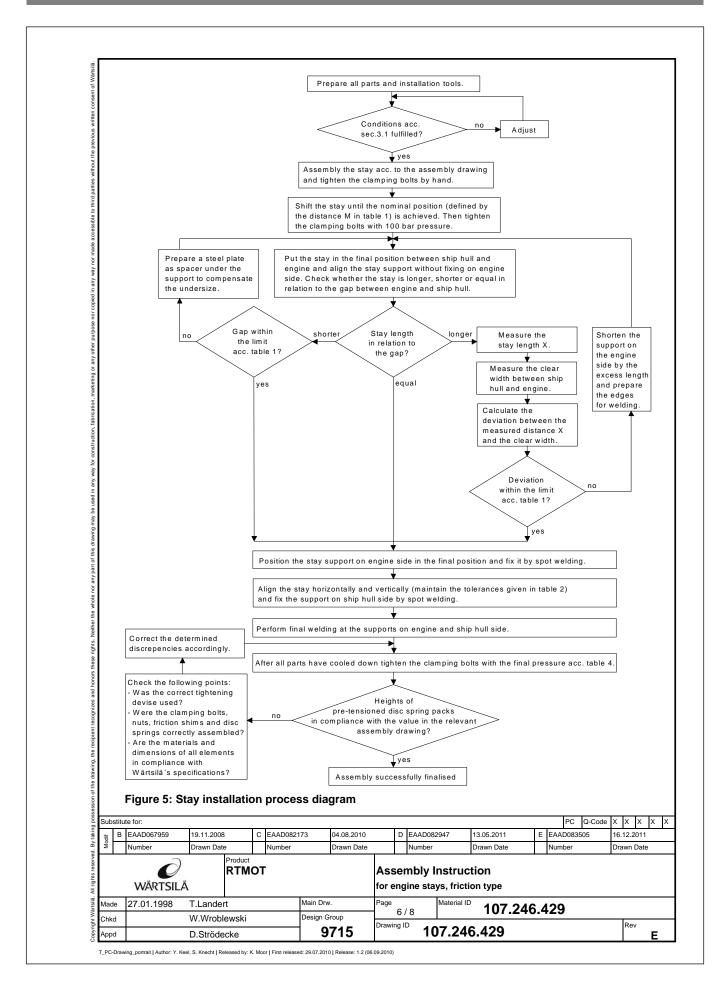
- 1. Prepare all parts and installation tools.
- 2. Make sure that all starting conditions according to section 3.1 are fulfilled.
- 3. Assemble the stay according to the relevant assembly drawing of design group 9715 and tighten the clamping bolts slightly by hand.
- 4. Shift the stay until the nominal position (defined by the distance M in table 1) is achieved. Then tighten the clamping bolts with 100 bar pressure.
- 5. Check at the marked attachment points on ship hull and engine side that there is no platform support, piping or something else which could collide with the stay. In particular pay attention to the space requirements of the hydraulic tensioning device in order to allow proper tightening of the clamping bolts.
- 6. Put the stay in the final position between ship hull and engine and align the stay's support without fixing on engine side. Check whether the stay is longer, shorter or equal in relation to the clear width between engine and ship hull.
 - In case the stay is **longer** than the clear width between ship hull and engine, measure its overall length X. Then measure the clear width between ship hull and engine and calculate the difference to the overall stay length X. If the difference exceeds the maximum allowed value limited by the tolerances in table 1, the support on the engine side has to be shortened and the edges must be prepared for welding.
 - In case the stay is **shorter** than the clear width between ship hull and engine, measure the gap between stay end and ship hull directly.

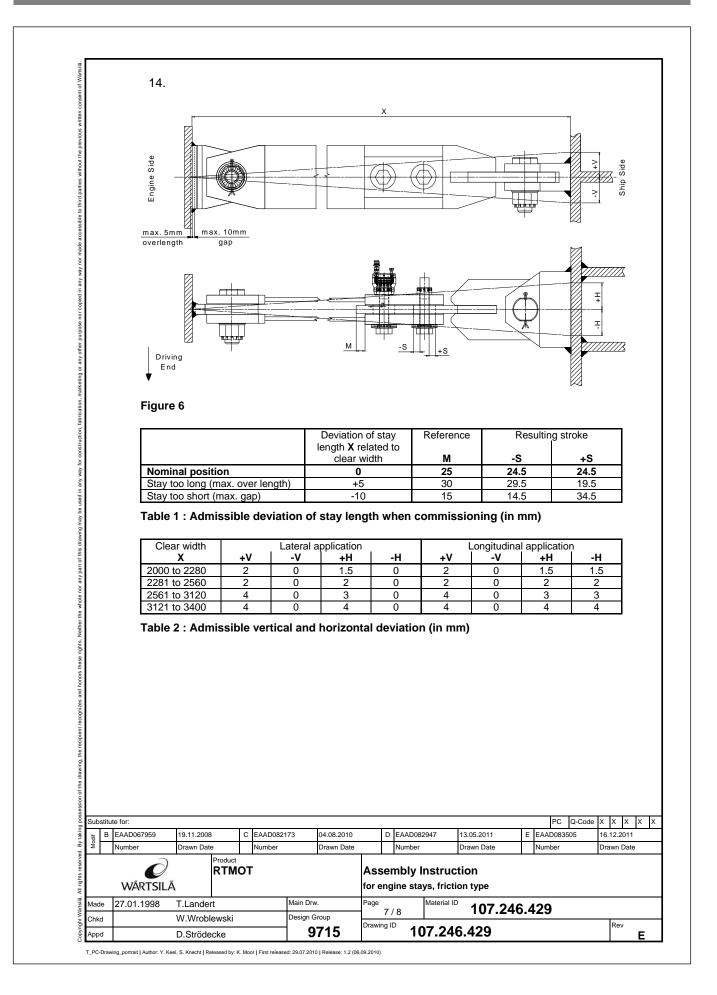
If the gap exceeds the maximum allowed value limited by the tolerances in table 1, a steel plate has to be added as spacer under the support to compensate the undersize.

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Align the stay horizontally and vertian and fix the support on ship hull side. 10. Before accomplishing the final weld material stress due to thermal expansion. 11. Perform final welding at the support of the support. 12. After all parts have cooled down, tig according to table 4. 13. Measure the height of each pre-tent relevant assembly drawing of design to Wärtsilä's specifications. If the height deviates from the giver the support of t	 no modifications are necessary. Note: During loading, the ship's hull tends to deform the respectively to engine side. Therefore it is sugge correct or rather 'too short' than with overlengthe longitudinal direction (see table 1). 7. Make sure that the surfaces of the receiver box attachment points are clean. 8. Attach the stay on engine side in the final positive welding. 9. Align the stay horizontally and vertically (observe and fix the support on ship hull side by spot well. 10. Before accomplishing the final welding, loosen material stress due to thermal expansion. 11. Perform final welding at the supports on engine according to table 4. 13. Measure the height of each pre-tensioned discording to table 4. 14. Measure the height of each pre-tensioned discording to table 4. 15. Measure the height of each pre-tensioned discording to table 4. 16. Measure the height of each pre-tensioned discording to table 4. 17. Measure the height of each pre-tensioned discording to table 4. 18. Measure the height of each pre-tensioned discording to table 4. 19. Measure the height of each pre-tensioned discording to table 4. 11. Measure the height of each pre-tensioned discording to table 4. 13. Measure the height of each pre-tensioned discording to table 4. 14. Measure the height of each pre-tensioned discording to table 4. 15. Measure the height of each pre-tensioned discording to table 4. 16. 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Before accomplishing the final welding, loosen the clamping both material stress due to thermal expansion. 11. Perform final welding at the supports on engine and ship hull side 2. After all parts have cooled down, tighten the clamping boths with according to table 4. 13. Measure the height of each pre-tensioned disc spring pack and relevant assembly drawing of design group 9715 whether the height deviates from the given value the following need to Wärtsilä's specifications. If the height deviates from the given value the following need to a state of the support of the	 Note: During loading, the ship's hull tends to deform towards the ship's centre line, respectively to engine side. Therefore it is suggested to fit a stay of a length ju correct or rather 'too short' than with overlength, in order to allow an extra struction individual direction (see table 1). Make sure that the surfaces of the receiver box/platform support and the ship attachment points are clean. Attach the stay on engine side in the final position and fix the support by spot welding. Align the stay horizontally and vertically (observe the tolerances given in table and fix the support on ship hull side by spot welding. Before accomplishing the final welding, loosen the clamping bolts in order to a material stress due to thermal expansion. Perform final welding at the supports on engine and ship hull side. After all parts have cooled down, tighten the clamping bolts with the final press according to table 4. Measure the height of each pre-tensioned disc spring pack and check with the relevant assembly drawing of design group 9715 whether the height is accord to Wärtsilä's specifications. If the height deviates from the given value the following need to be checked: Was the correct tensioning device used for tensioning the clamping bolts?

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4 Operational check and final adjustment

4.1 During sea trial

During service check whether relative movements between the ship side attachment device and the sheet metal girders occur. If this is the case, the following might be the cause:

- Insufficient or incorrect tightening of the clamping bolts
- Dirty or damaged friction shims
- · Material or quality of friction shims is not according to WCH specification
- Incorrect assembly of the stays
- Incorrect fitting or alignment, i.e. welding

4.2 After sea trial

After sea trial, when the engine and machinery space are still in hot condition, check whether measure 'M' remained within the limits given in table 3 and check also whether the stays are still in line with the engine (horizontally and vertically). If not, it may help to loosen the clamping bolts. The sheet metal girders can then move within the clearance of the through holes of the ship side attachment device. Undesirable tension in the stay can release and possible misalignment may be compensated.

At a later stage, when the vessel has been loaded and unloaded, check whether a displacement between engine and ship hull has taken place to make sure the stays work properly. Check also whether measure 'M' remained within the limits given in table 4. If this is not the case, refer to the possible causes listed under 4.1 For maintenance repeat the above mentioned checks i.e. check the pretension of the

bolts at intervals as scheduled for the maintenance of the engine holding down studs.

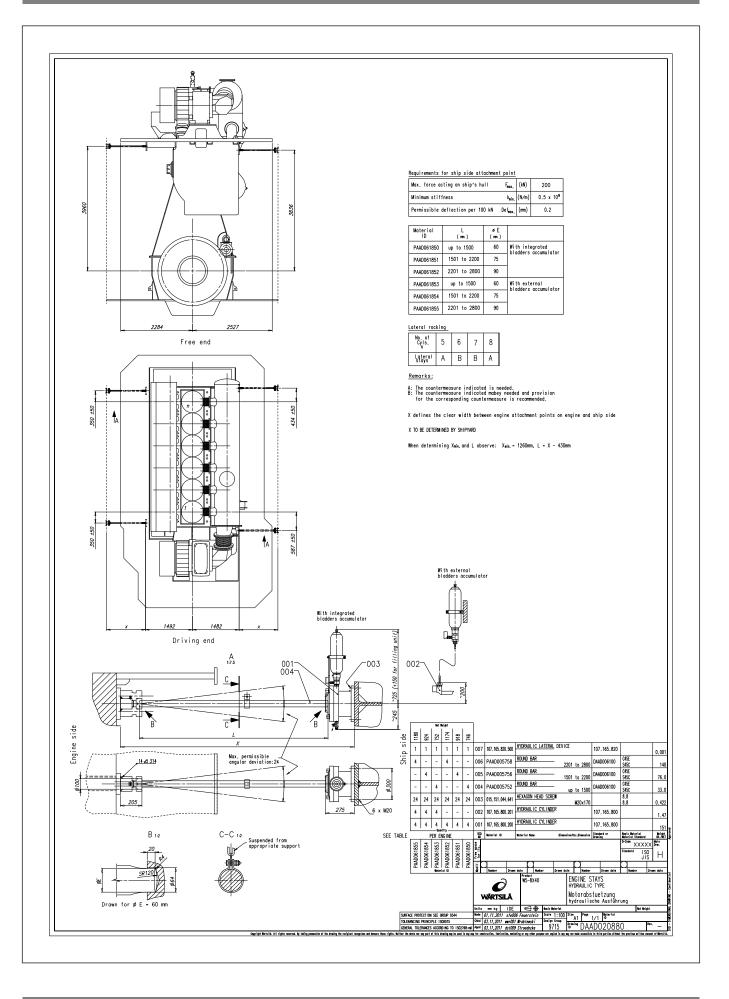
	Reference M (mm)	Loaded state
absolute minimum	2	ballast condition
absolute maximum	48	fully loaded

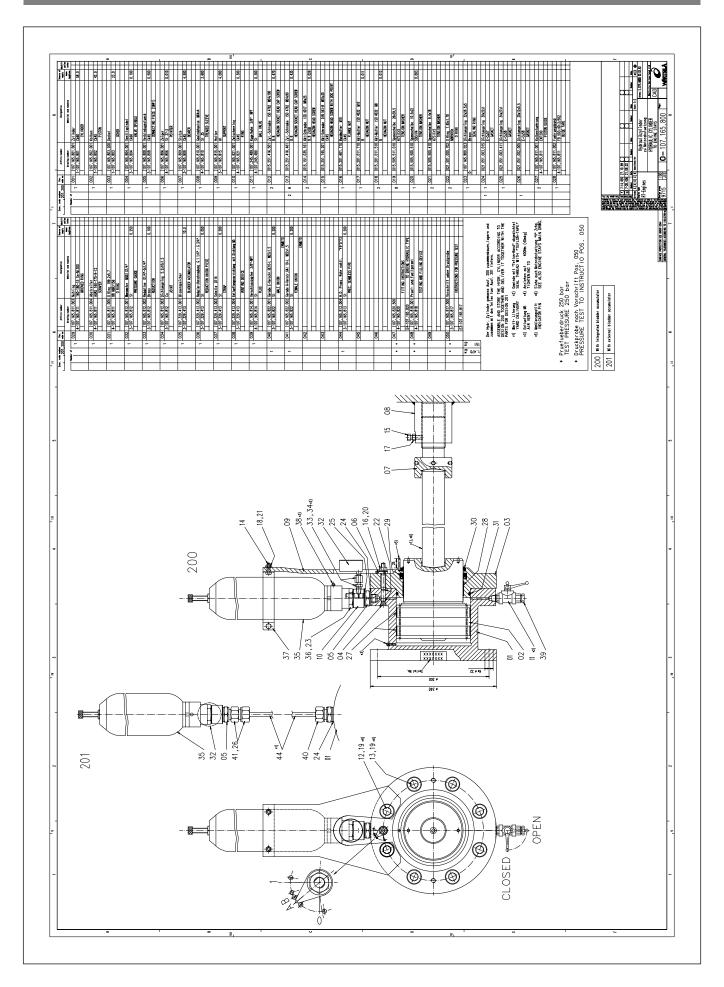
Table 3 : Admissible values for 'M' in service

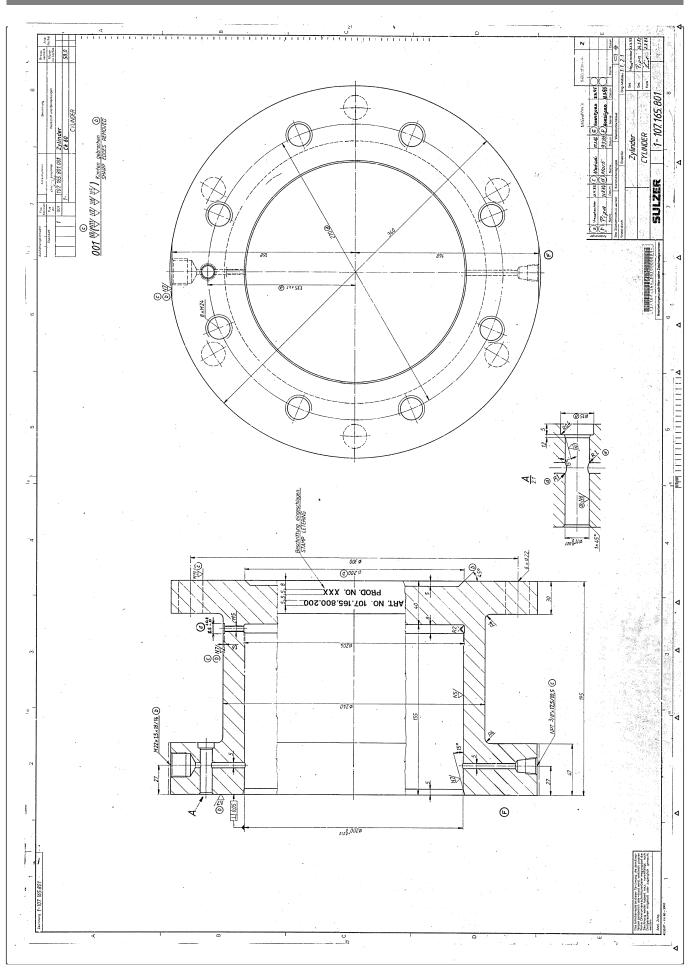
Hvdr. pressure for lateral and Engine type longitudinal application (bar) 230 W-X35 W-X40 250 RT-flex48T-D 180 RT-flex50-B/-D 310 RT-flex58-D V2 150 RTA/RT-flex68-D 120 RTA/RT-flex82C/T 170 RTA/RT-flex84T-D 150 RTA/RT-flex96C-B 200

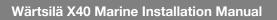


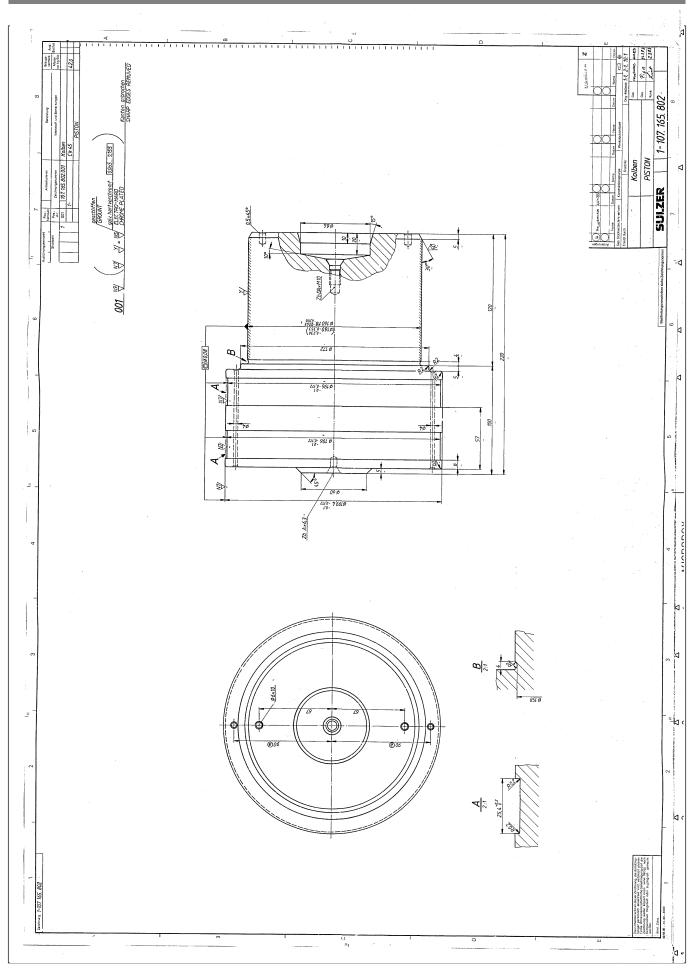
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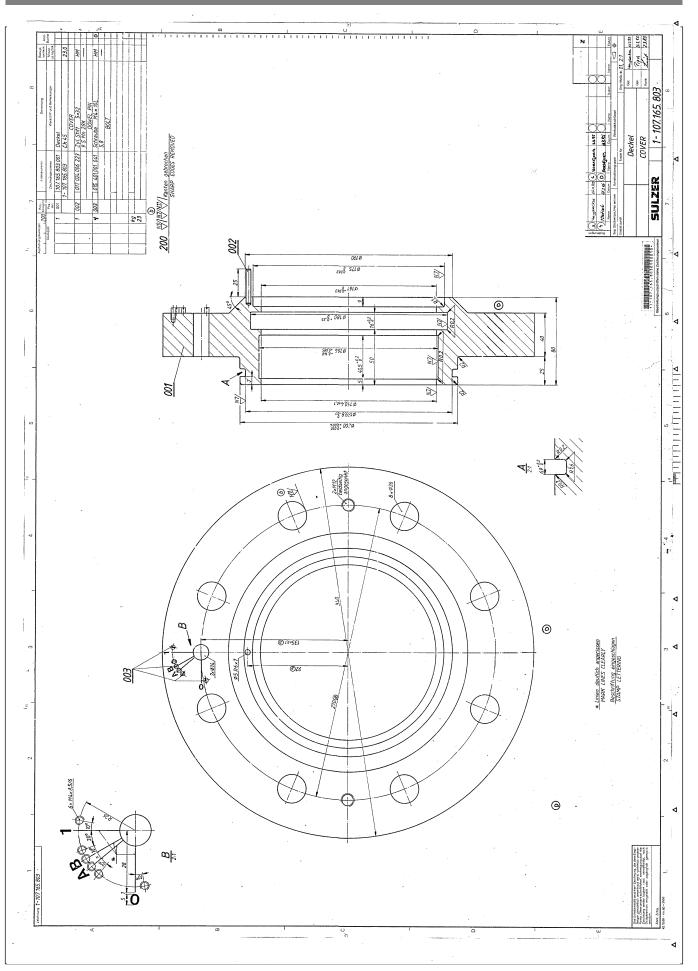




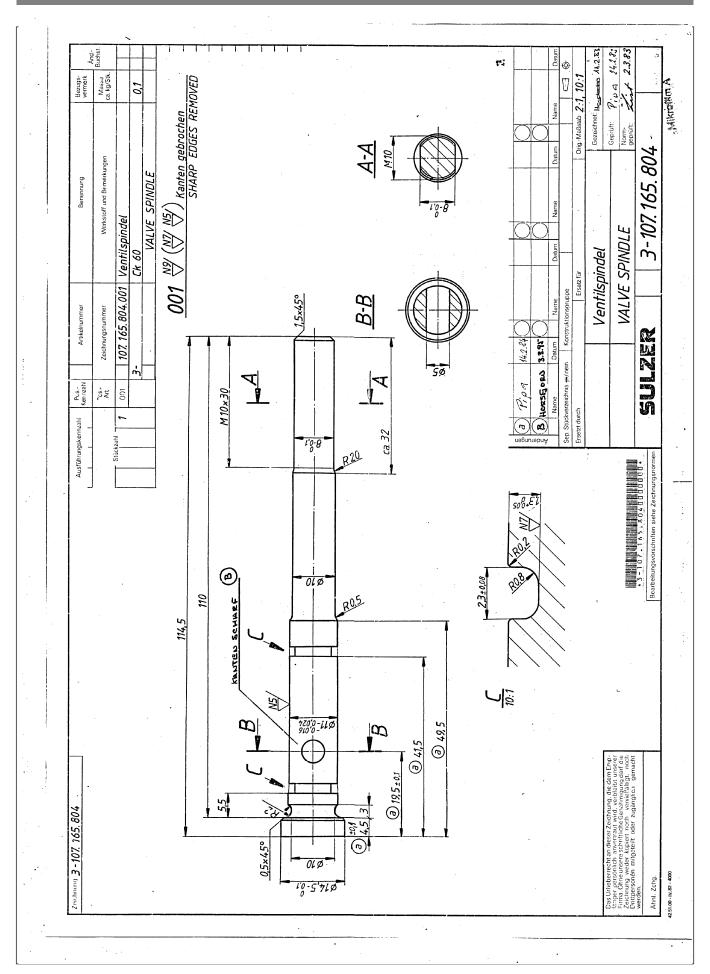


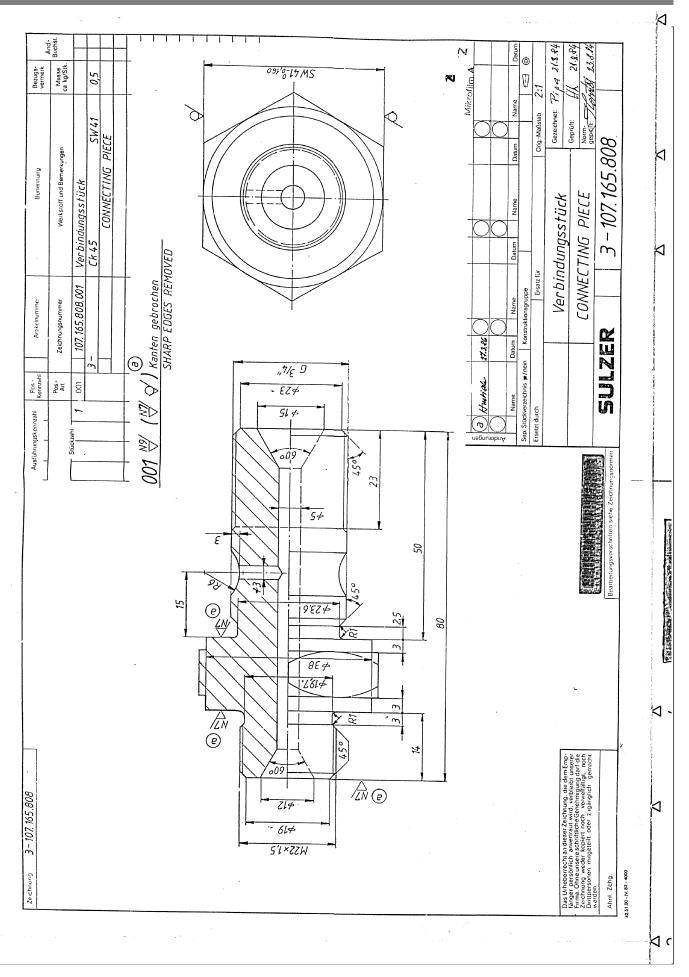




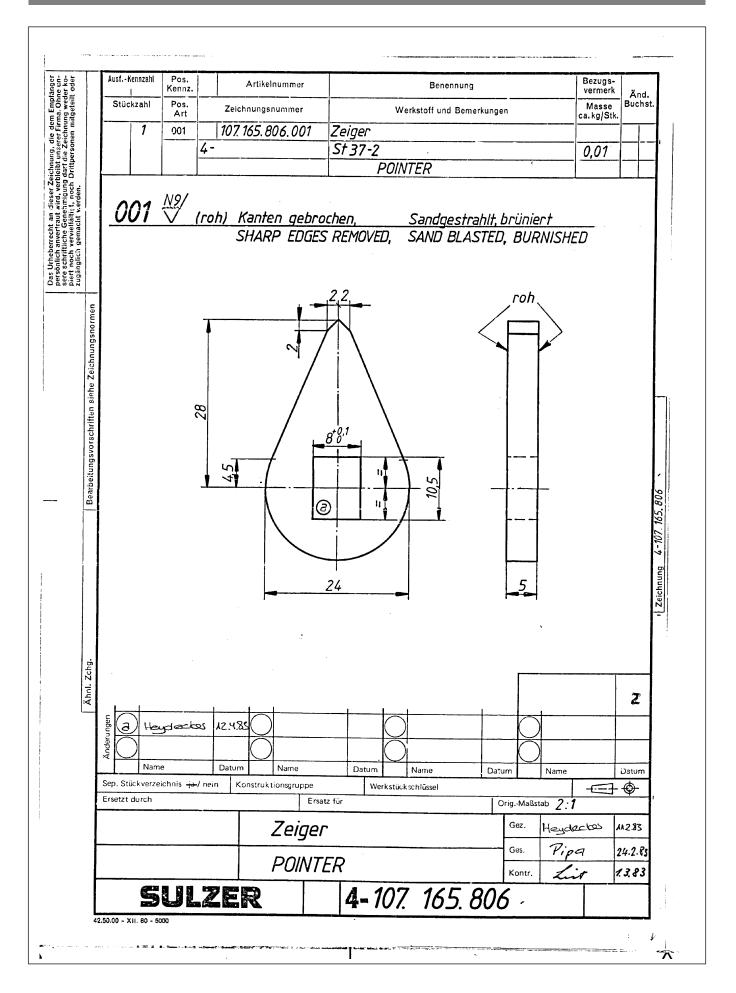


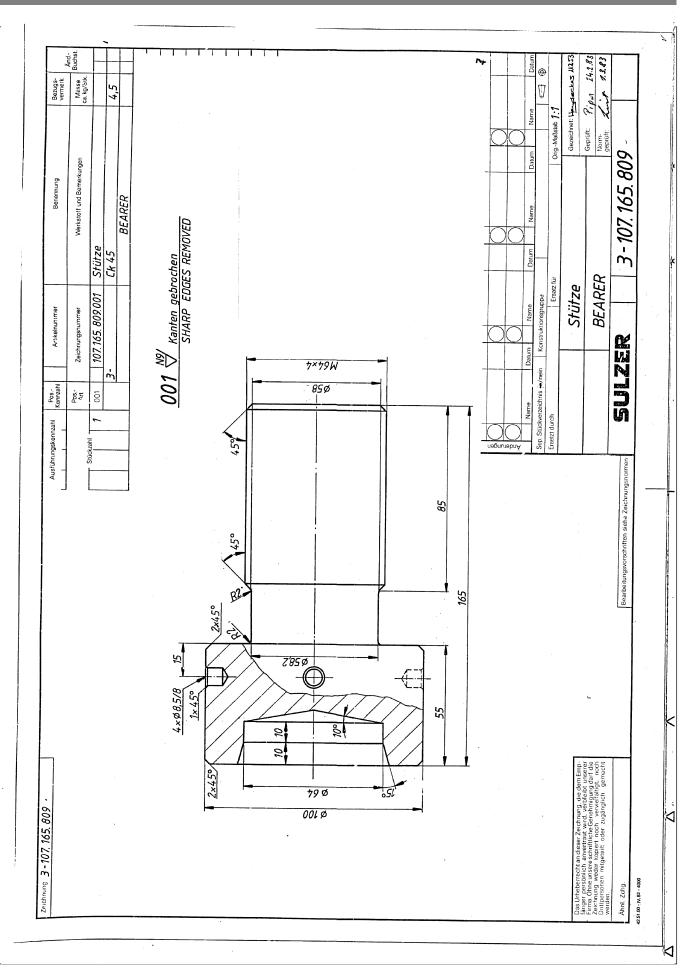
Wärtsilä X40 Marine Installation Manual

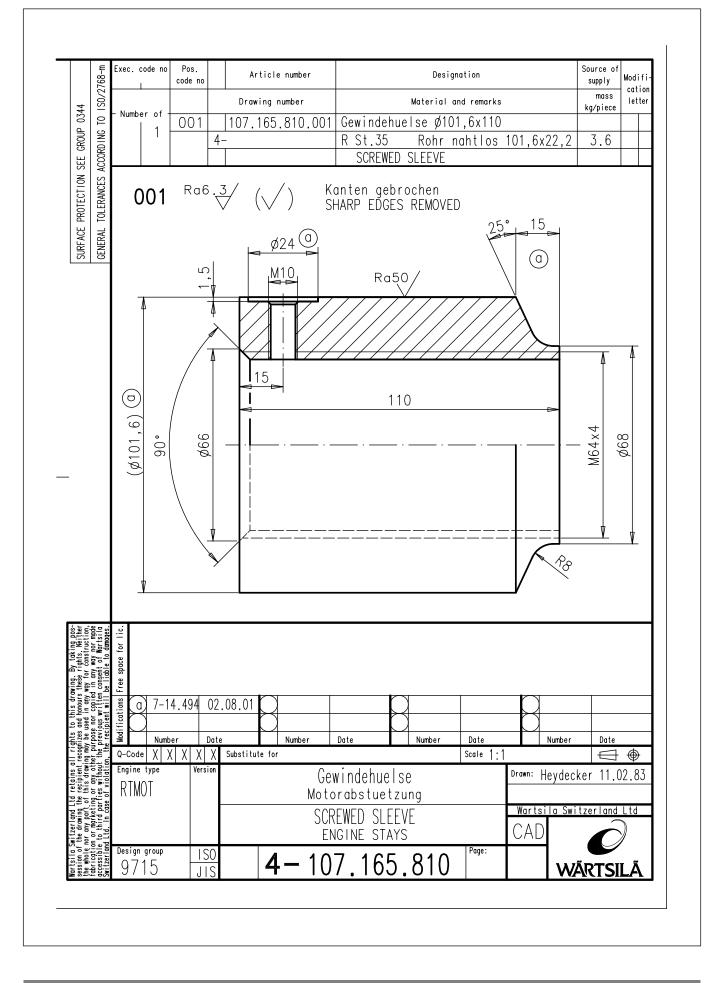


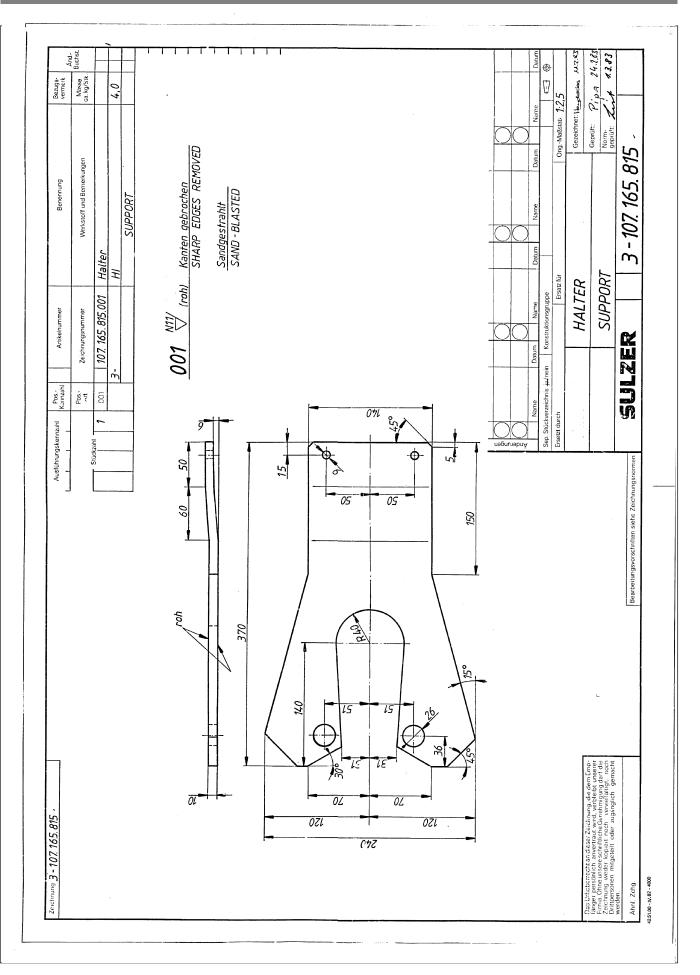


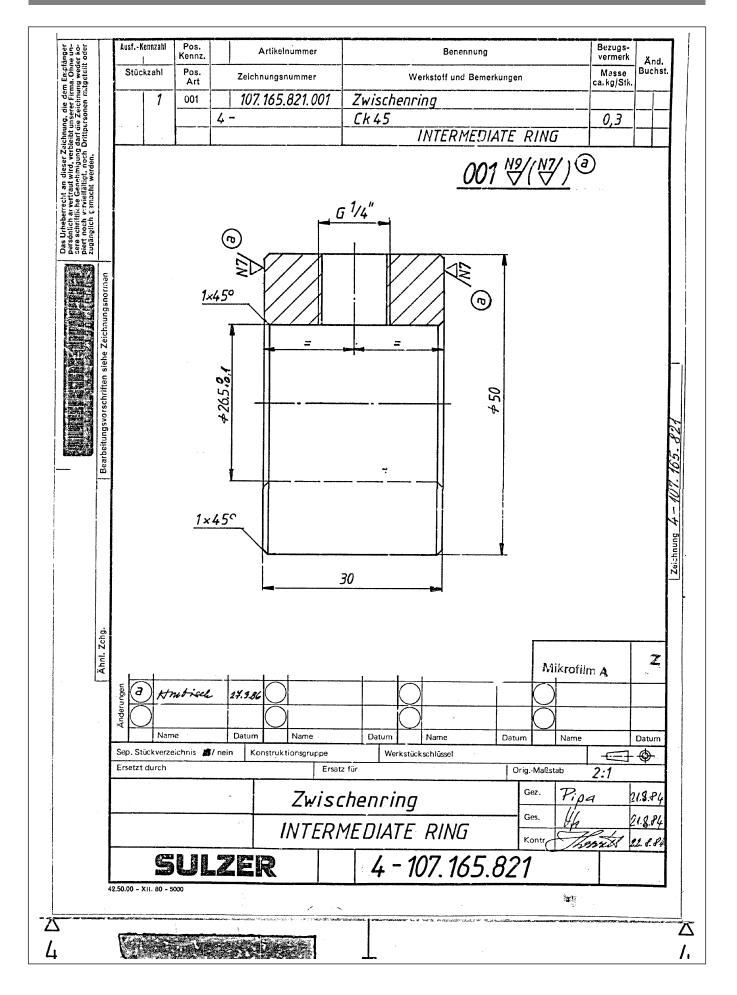
Wärtsilä X40 Marine Installation Manual

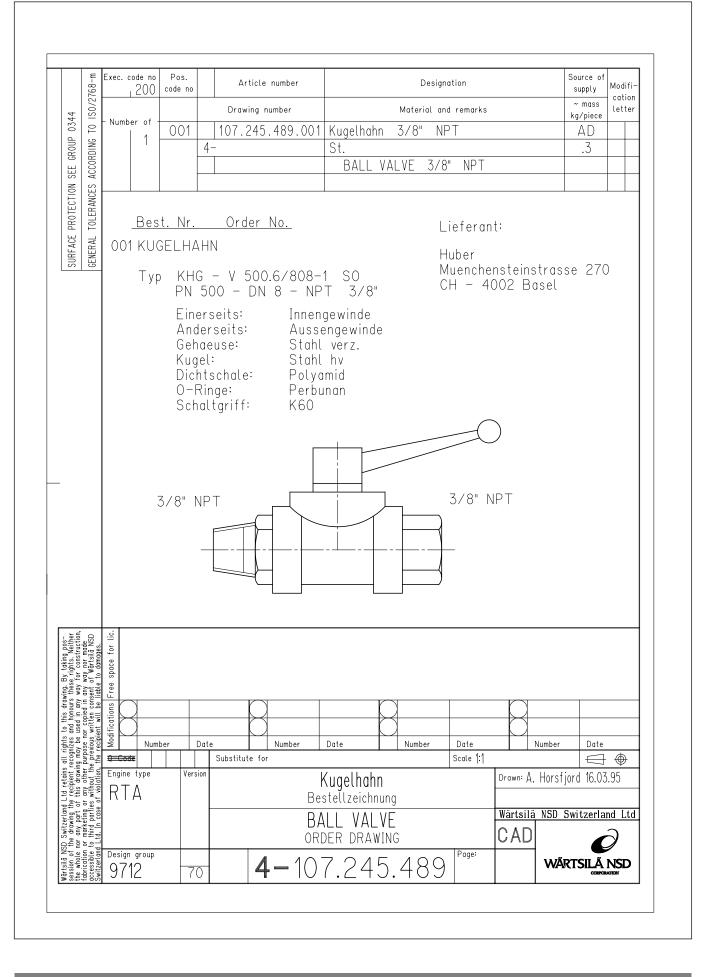




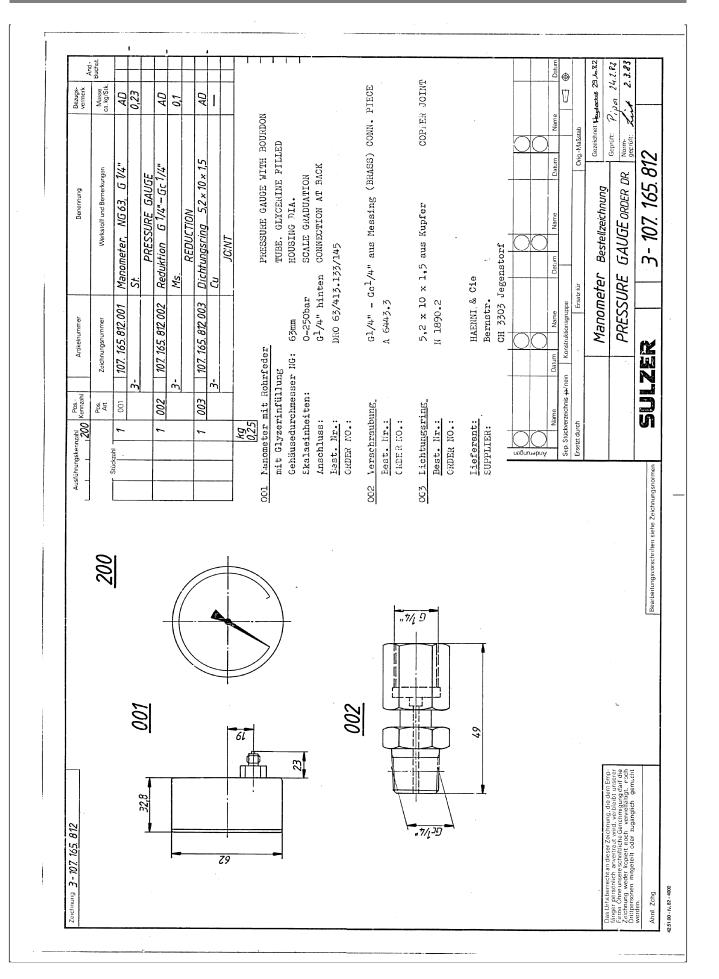


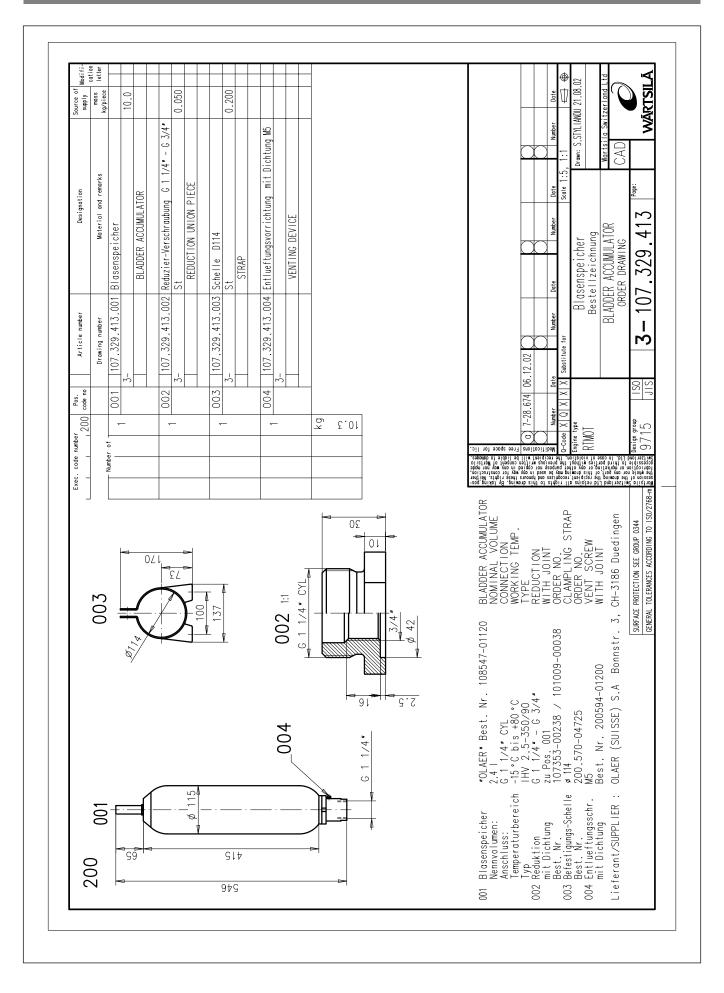


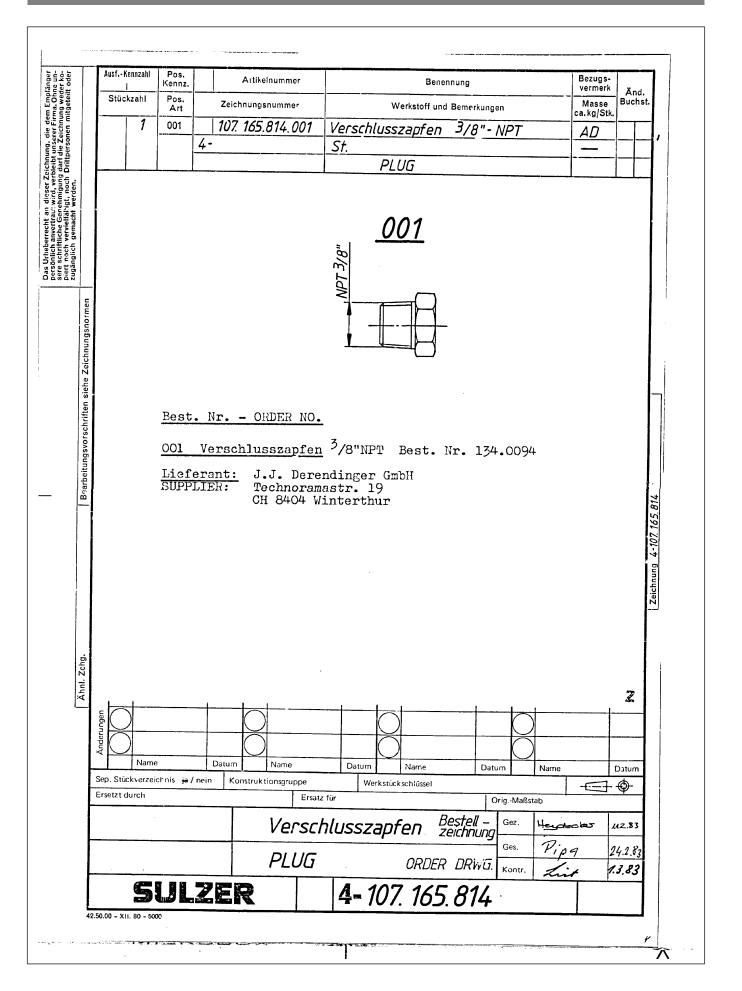




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		2 001	107. 165.811.001	Kolbenführung	AD	
			4-	EKF 200		
				PISTON GUIDE		
		1 002	107. 165. 811. 002	Führungsband	AD	
			4-	FB 503 - 40 - 2 / 552		
		`		GUIDE TAPE		
		1 <u> 003</u>		Nutring	AD	
			4-	160 - 180-15 Sn - NI 300		
				GROOVED RING		
-	1	1 004	107. 165. 811.004	Abstreifer	AD	
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1. General

Installation drawingsee page 2Sectional view drawingsee page 3

Hydraulic transverse stays are used to shift the natural frequency when resonance can be expected in the normal operating range of the engine.

The applied arrangement enables:

- The adjustability of the pretension force.
- The adaptability to the slow movement of the ship's hull when loading or unloading the ship.

2. Description

The hydraulic lateral fixation device consists of:

- Hydraulic cylinder with differential piston, fitted with hydro accumulator and pressure gauge.
- Stays for lateral fixation of the engine to the ship's structure.
- Adjusting screw, fixed to the engine.

Accessories per ship for single main engine installation

(for multiple main engine installation the engine supplier is to be consulted)

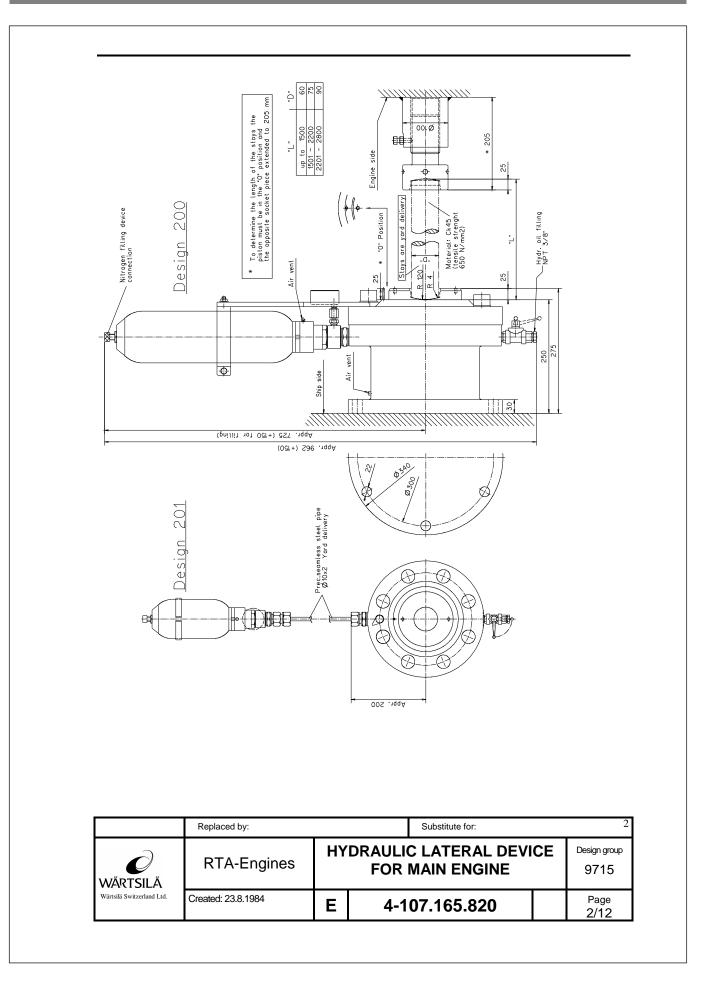
- Hydraulic cylinders either to design 200 or 201 with adjusting screw (stays are yard delivery)

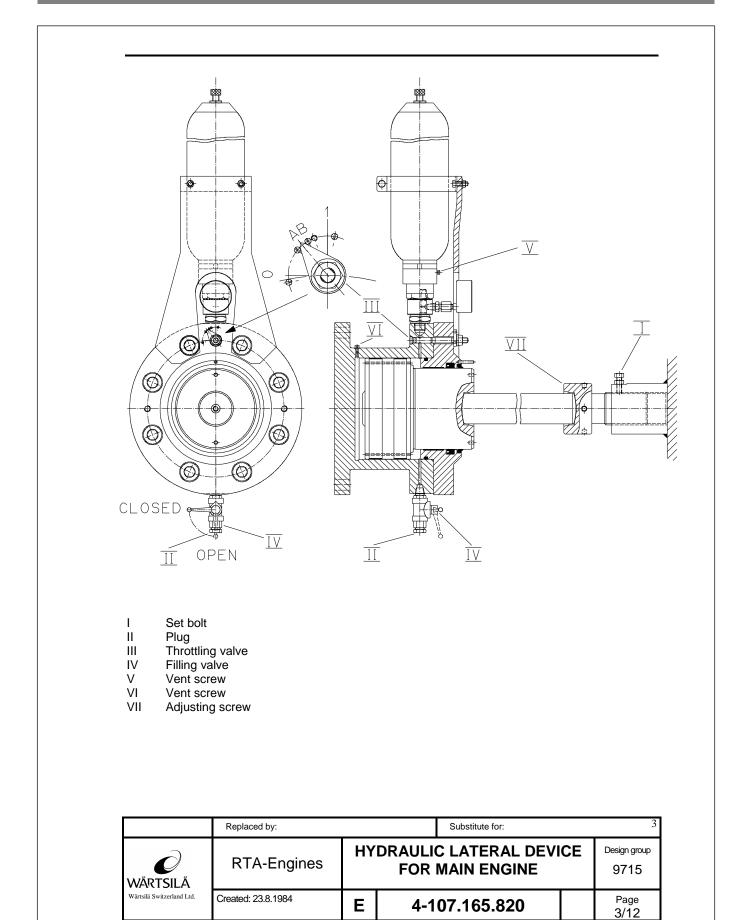
Design 200: Compact execution

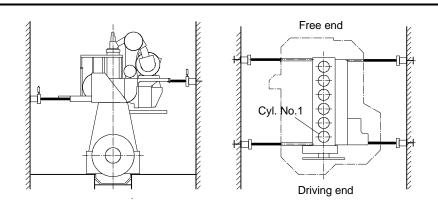
Design 201: Hydro accumulator detached for separate installation (Fittings included, but connection steel pipe ø 10 x 2 is yard delivery)

- Tester and pressurizer VGU 250 TS3 for nitrogen (for details see page 9)
- Hand pump for hydraulic oil (contained in the standard engine tool set)

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For details see drawing "Engine stays, hydraulic type" of the relevant engine.

3. Function

Transverse vibrations of the engine cause rapid pressure fluctuations in the hydraulic cylinder. Thereby the unit behaves like a strong spring. By using the throttling valve III (page 3), the spring rate can be adjusted such that the rapid pressure fluctuations are practically filtered off and do not continue into the hydro accumulator. The hydraulic cylinder nevertheless adjusts itself to the slow deformations of the ship's hull.

4. Installation

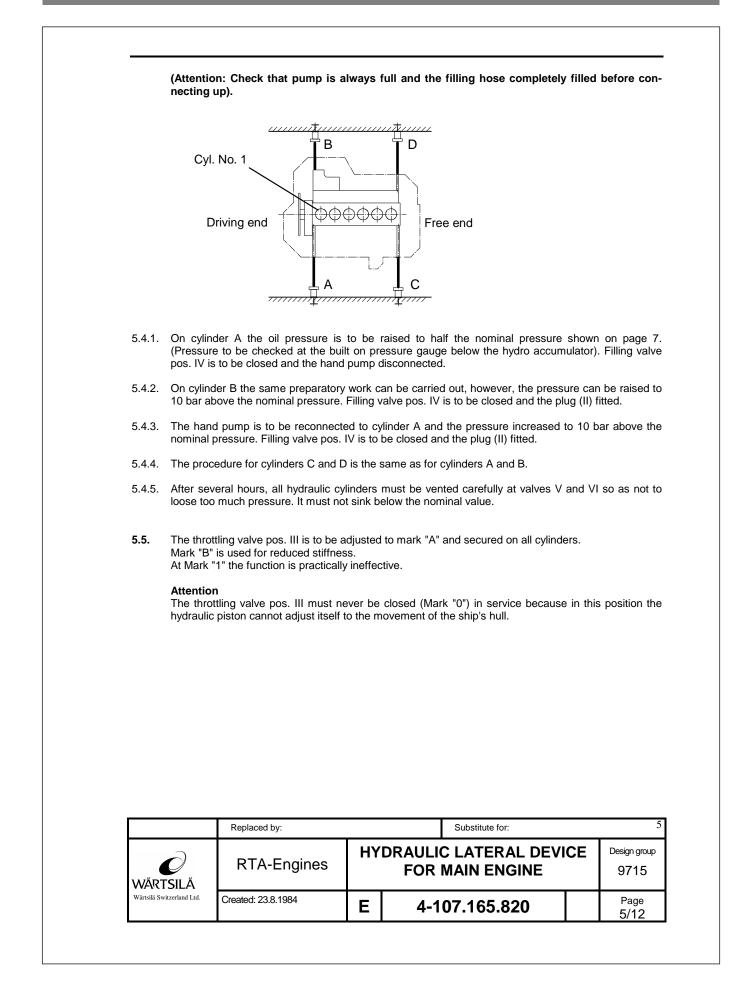
The hydraulic cylinders are to be bolted to the reinforced attachment points on the ship structure. The adjustments screws are welded on the engine at position shown on the relevant arrangement drawing from the engine builder. Stay length "L" shown on page 2 is to be determined and the diameter "D" taken from the table or from the arrangement drawing.

5. Commissioning

Commissioning of the hydraulic cylinders should be carried out shortly before the sea trial as follows:

- **5.1.** The stay is to be fitted between the hydraulic cylinder and the adjusting screw on engine side and secured against dropping. The adjusting screw is to be set as shown on page 2 (axially: piston face and indicator pin to be on same plane; radially: pin and holes in line). Set bolt pos. I to be secured.
- **5.2.** The hydro accumulator will be delivered pre-pressurised to 10 bar. The pressure is to be raised to the figure shown on page 7 with the help of the tester pressurizer (see page 9).
- 5.3. Plug pos. II is to be removed for filling of the hydraulic oil and the flexible hose connected to the hand pump. Throttling valve pos. III and filling valve pos. IV must be open (throttling valve switched to mark "1") as well as vent screws pos. V on the hydro accumulator and pos. IV on the hydraulic cylinder.
- 5.4. Hydraulic oil to be pumped <u>slowly</u> into the hydr. cylinder (oil to be warmed when engine room is cold). After perfect venting, first close vent screw pos. IV on the hydr. cylinder and then vent screw pos. V on the hydro accumulator. The 4 hydr. cylinders must then be pumped up to service pressure as follows:

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6. Sea trial

The hydraulic cylinders must be checked frequently for oil pressure and general soundness.

- 6.1. At the end of the sea trial the following must be checked:
 - "0" position of the piston according to page 2

- pressure to be the nominal value as shown on page 7. If the pressure is too high it can be corrected with careful opening of the vent screw pos. V. Where the pressure is too low, it has to raised with the

hand pump.

7. Check when loading the ship fully for the first time

The position of the piston relative to the cylinder is to be checked when the ship is fully laden.

Should it occur that the piston is almost touching the bottom of the cylinder (this situation must not be allowed to occur, but it will happen when the piston is 15 mm on the inside of the "0" position) then the hydraulic lateral fixation device is to be shortened by about 7 mm with the adjusting screw pos. VII.

8. Regular checks

The oil pressures on the pressure gauges of the hydraulic cylinders are to be compared with each other at regular intervals. (The shown oil pressure may not be identical with the nominal pressure, because it varies according to the loading of the ship).

If one of the cylinders shows a considerably lower pressure, which could be caused by a leaking seal, the opposite hydraulic cylinder must be released of its pressure until the leaking seal has been replaced.

Afterwards both cylinders are to be put into service as mentioned under commissioning.

9. Spares

For spares see the following pages:

Pneumatic accumulator	page 8
Tester pressurizer	page 11
Hydraulic cylinder	page 12

Safety regulations regarding pressure vessels have to be adhered to

	Replaced by:		Substitute for:		6
<i>O</i> WÄRTSILÄ	RTA-Engines	ΗY	Design group 9715		
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Technical data

Hydraulic cylinder 200/160

Mass:	about 138 kg
Piston stroke:	± 15 mm
Oil Content:	about 2,5 l
Oil Type:	Hydraulic oil HL or HLP
Viscosity grade:	ISO VG 32/46 (20 - 30 mm²/s at 50° C)
Hydropneumatic accumulator type:	IHV 2,5 - 330/05 with bladder ref.: 105644-01120

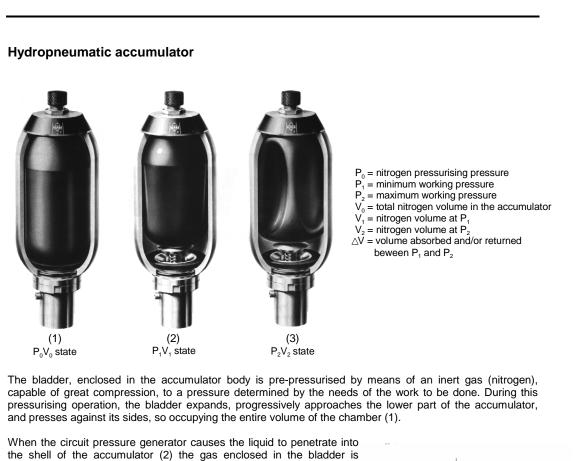
Engine type	RTA 68T-B, RTA72U/-B, RTA84T/-B/-D, RTA84C, RTA96C	RTA52U/-B, RTA62U/-B, RTA48T/-B, RTA58T/-B RTA60C
Pre-pressurising pressure (gas)	40 bar	20 bar
Nominal oil pressure 1)	80 bar	50 bar
Nominal pre-tensioning force F _{vo}	160 kN	100 kN
Dynamic spring rate	about 320 kN/mm Throttl.valve pos."A"	about 270 kN/mm
Minimum oil pressure	about 60 bar when piston is protruding 15 mm in cylinder	about 37 bar
Maximum oil pressure	about 115 bar when piston is recessed 15 mm in cylinder.	about 80 bar

1) piston in position "0" (see sketch on page 2):

 $Po_{max} = Po + 10 bar$

Po = above given nominal pressure

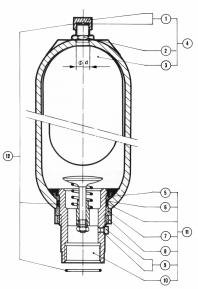
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<i>O</i> WÄRTSILÄ	RTA-Engines	ΗY	DRAULIC LATERAL DEVICE FOR MAIN ENGINE	Design group 9715
Wärtsilä Switzerland Ltd.	Created: 23.8.1984	Ε	4-107.165.820	Page 7/12



compressed and increases the pressure. The process comes to an end when the pressure of the liquid and of the gas reach equilibrium (3). In the reverse process, the return commences when the resisting pressure of the liquids is less than the pressure of the gas in the bladder. The lateral deformation of the latter in three lobes, forming a shamrock shape with three promontories excludes rubbing and inertia, and enables an efficiency of nearly 100% to be attained.



- 7. Gland-ring
- 8. Ring nut
 9. Venting screw and gasket
- 10. Fluid port sub-assembly 11. Fluid port assembly complete
- 12. Set of gaskets



	Replaced by:	Sub	bstitute for:	8	
Ø WÄRTSILÄ	RTA-Engines	ΗY		ATERAL DEVICE IN ENGINE	Design group 9715
Wärtsilä Switzerland Ltd.	Created: 23.8.1984	Е	4-107.	165.820	Page 8/12

TESTER AND PRESSURIZER VG U

DESCRIPTION

The VG U tester and pressurizer is used for charging of bladder, piston and membrane accumulators with nitrogen, and for testing or changing the pre-charge pressure. The instrument is suitable for all OLAER accumulators with $\frac{5}{8}$ flap valves, Schräder valves or screw plugs. It is screwed onto the gas inlet valve of the hydropneumatic accumulator, and connected to a standard nitrogen flask via a hose. If only the pre-charge pressure needs to be checked, the connection of the charging hose is not necessary.

Each unit comprises of:

- Tester and pressurizer with manometer, return valve on the charging hose, built-in release valve, valve spindle for opening the gas inlet valve on the accumulator.
- Charging hose, length 2.5m
- Connections for the accumulator ⁷/₈" - 14 UNF ⁵/₆" - 18 UNF 0.305" - 32 NFT M28 x 1,5
- Plastic protective case

KEY TO MODEL DESIGNATION

<u>250</u>

-

<u>TS 3</u>

Manometer ______ 6, 10, 250, 400 bar

| Charging hose TS 3: for Ch, D, N, S, A, FL, NL, DK, GUS Connector W24,32 x 1,814 245 bar (for other countries, see part no. 40 on page 11)



	Replaced by:		Substitute for:		9	
WÄRTSILÄ Wärtsilä Switzerland Ltd.	RTA-Engines	ΗY	_	C LATERAL DEVI MAIN ENGINE	CE	Design group 9715
	Created: 23.8.1984	Е	4-1	07.165.820		Page 9/12

INSTALLATION AND USE

Setting up (see figure on page 11)

Before any pre-charge checks and/or nitrogen pressurizing, the hydraulic fluid of the hydro-pneumatic accumulator must be discharged.

Accumulator with hydraulic valve:

- Completely screw the lobed hand-wheel (no. 6) outwards
- Unscrew the protective cap(s) of the accumulator gas inlet valve.
- Screw pressurizer with intermediary no. 23 or 26 (+ connector no. 30 for Schräder valves) onto the hydraulic valve. Move the manometer into a convenient position for reading, and tighten the intermediary (no. 5) by hand.
- Check that the release valve is closed. (close the lobed hand-wheel no. 18 in an clockwise direction).

Checking the charge pressure:

- Turn the lobed hand-wheel (no. 6) in an anti-clockwise direction. This causes the gas inlet valve or allen screw to open. The pressure may now be read on the manometer.

Reducing the charge pressure:

- Rotate the lobed hand-wheel (no. 18) of the release valve slowly in an anti-clockwise direction. The nitrogen is released into the surrounding air.

Pressurizing/raising the charge pressure:

- Connect the charging hose: one end to the return valve (no. 7) and the other to a standard nitrogen flask.
- Open the stop valve on the nitrogen flask carefully. Allow the nitrogen to flow into the accumulator slowly, till the desired pre-charge pressure is reached.
- Close the stop valve on the nitrogen flask. After 5-10 minutes (temperature stabilisation), check the charge pressure again and correct where necessary.

Dismantling:

- Turn the lobed hand-wheel (no. 6) back.
- Screw the lobed hand-wheel (no. 18) outwards
- Unscrew instrument.
- Tighten screw valve with allen key SW6.
- Check the gas inlet valve seal with a foam-forming substance.
- Screw the protective cap(s) back on and tighten by hand.

Caution:

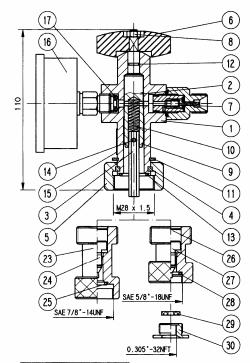
- Never use oxygen to inflate the accumulator.
- Where the nitrogen flask pressure is higher than the permitted accumulator working pressure, a pressure limitation valve must be fitted.

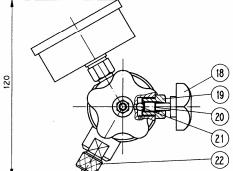
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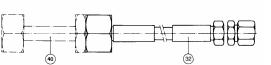
SPARE PARTS LIST FOR VG U TESTER AND PRESSURIZER

Spares

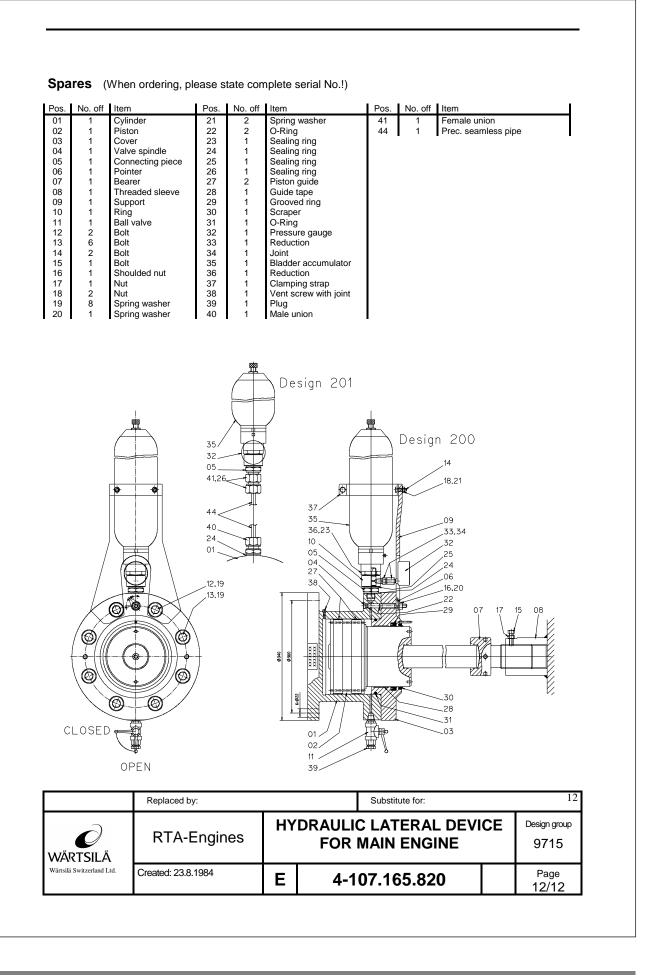
Part			Rec'd
No:	Quantity	Description	spares
1	1	Valve body	
2	1	Valve spindle	
3	1	Bolts	
4	1	Split ring	
5	1	Spigot nut	
6	1	Lobed hand-wheel	
7	1	Return valve	
8	1	Hexagon nut	
9	1	Snap ring	
10	1	Stand. press. spring	
11	1	Retaining ring	
12	1	O-Ring	х
13	1	O-Ring	х
14	1	Centre-grooved dowel pin	
15	1	Name plate	
16	1	Connect. for manom. G 1/4"	
17	1	Copper seal	х
18	1	Lobed hand-wheel	
19	1	Gland	
20	1	Valve spindle	
21	1	Valve ball	
22	1	Knurled can	
23	1	Adapter SAE ⁷ / ₈ " - 14UNF	
24	1	Valve spindle	
25	1	O-Ring	х
26	1	Adapter SAE ⁵ /8" - 18UNF	
27	1	Valve spindle	
28	1	O-Ring	
29	1	Flat seal	х
30	1	Connect. 0.305" - 32NFT	х
31	1	Gasket assembly	х
		(complete set)	
32	1	Charging hose	
40	1	Connections for foreign	х
		nitrogen flasks	
40b	GB/AUS	R ⁵ / ₈ " external	
40c	USA	24.51 x ¹ / ₁₄ " external	
40d	Italy	21.7 x ¹ / ₁₄ " external	
40e	Japan	$22 \text{ x}^{1}/_{14}$ " internal	
40f	Japan	W23 x ¹ / ₁₄ " external	
40g	Brazil	R 1/2" internal	
40h	F, B, E	21.7 x ¹ / ₁₄ " internal	
40i	China	M22 x 1.5 internal	
40k	China	⁵ / ₈ " internal	
40I	Malaysia	⁵ / ₈ " internal G ⁷ / ₈ " external	
40m	Trinidad	['] / ₈ " - 14UNF external	
40n	Bulgaria	3/4" internal	
40o	Philippines	W23 x ¹ / ₁₄ " left	





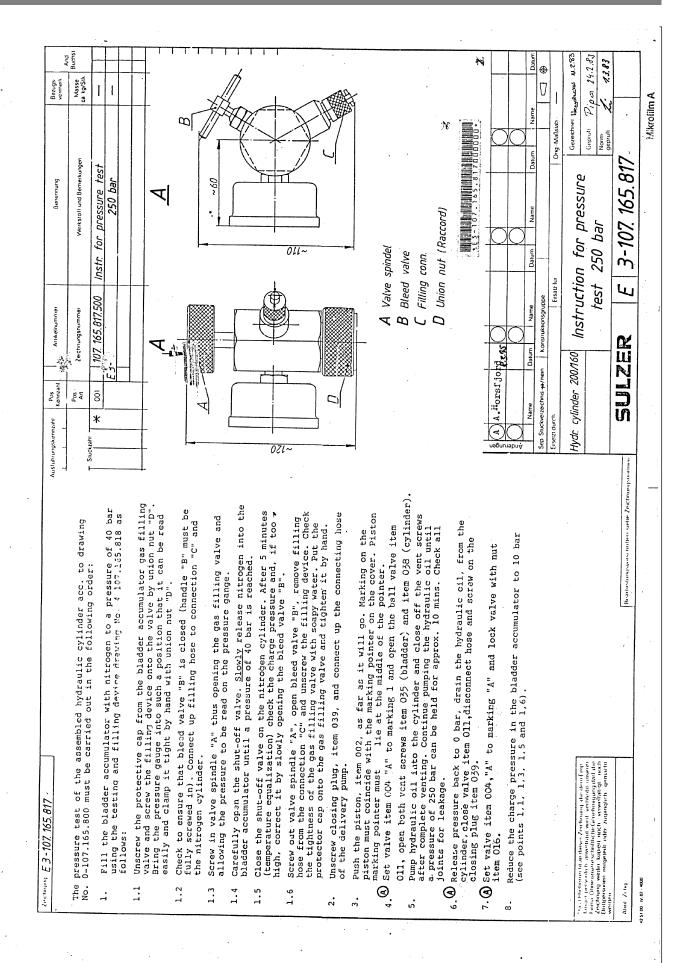


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Wärtsilä Switzerland Ltd.	Created: 23.8.1984	Е	4-1	07.165.820		Page 11/12



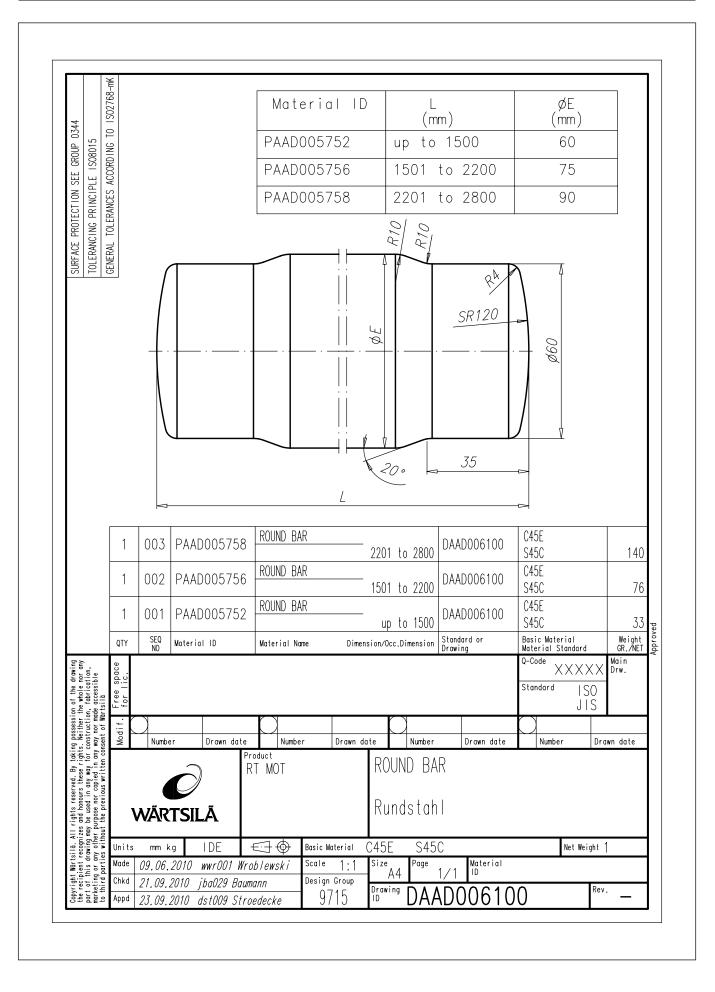
ORDER SHEET TESTER PRESSURIZER VG U - 250 - TS3 Ref. 202 182-07733 Comprises of: - Tester and pressurizer with manometer, return valve on the charging hose, built-in release valve, valve spindle for opening the gas inlet valve on the accumulator. - Charging hose, length 2.5m - Connections for the accumulator ⁷/₈" - 14 UNF ⁵/₆" - 18 UNF 0.305" - 32 NFT M28 x 1,5 - Plastic protective case - Additional nitrogen flasks connections for the following countries: 1) GB, AUS, NZ: R⁵/₈" external Part No. 993507-02800 21.7 x $^{1}/_{14}$ " internal 21.7 x $^{1}/_{14}$ " external 24.51 x $^{1}/_{14}$ " external 2) F, B, E: Part No. 993513-02800 Part No. 993509-02800 3) Italy: 4) USA: Part No. 993508-02800 5) Brazil: R¹/₂" internal Part No. 993512-02800 22 x $^{1}/_{14}$ " internal Part No. 993510-02800 6) Japan: W 23 x $^{1}/_{14}$ " external Part No. 993511-02800 7) Japan: **KEY TO MODEL DESIGNATION** <u>VG U</u> <u>250</u> <u>TS 3</u> Model -Charging hose Tester and Pressurizer TS 3: for Ch, D, N, S, Manometer -A, FL, NL, DK, GUS 6, 10, 25, 60, 100, 250, 400 bar Connector W24,32 x 1,814 245 bar SUPPLIER: **OLAER (SUISSE) SA** Bonnstrasse 3 CH- 3186 Duedingen e-mail: info@olaer.ch

a b	Pipa 7-14.418	21.08 10.11	-										
			Repl	aced by:				Substitute for:					
	O WÄRTSILÄ	Ä	RT	A-Engines	TEST AND FILLING UNITITO ENGINE STAYS (HYDRAULIC TYPE)				Design group 9715				
	Wärtsilä Switzerland	Ltd.	Create	d: 28.10.82	Ε		4-1	07.1	65.81	8			Page 1



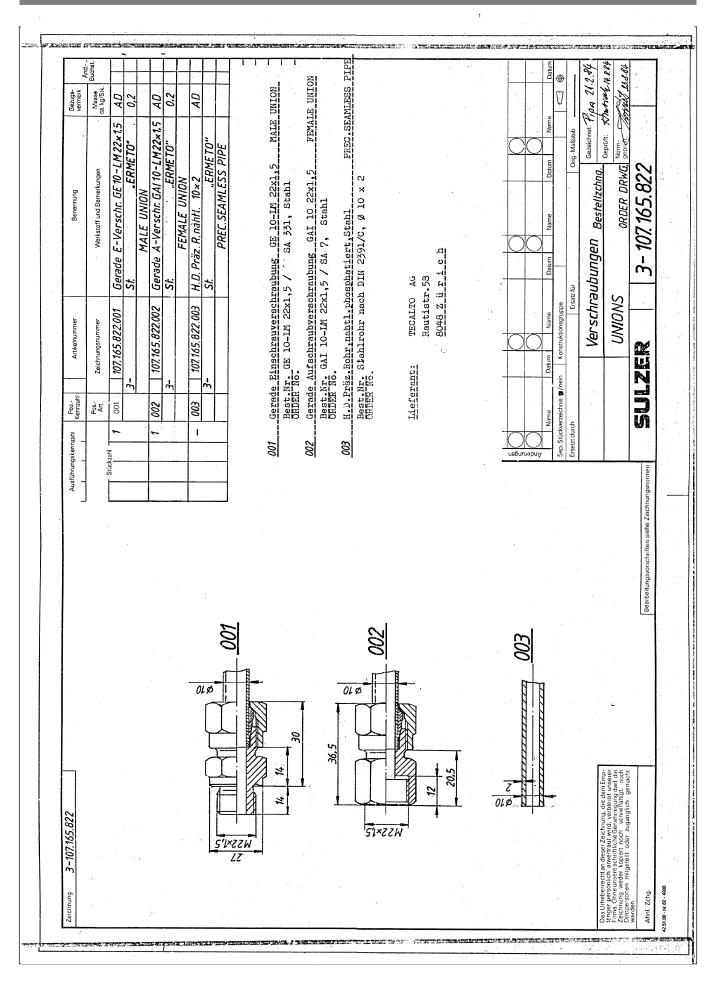
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18. General Installation Aspects

Wärtsilä X40 Marine Installation Manual



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	code number 1 200 code no	of 1 001 3-	002	003	004	001 Blasenspeicher Nennvolumen: Anschluss: Temperaturbereich Typ 002 Reduktion mit Dichtung Best. Nr. 003 Befestigungs-Schelle Best. Nr. 004 Entlueftungsschr.	Let contribute the repeat received and physical states of the states of
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18.8 Fire protection

Fires may develop in areas such as under-piston spaces and scavenge air receiver. The engine is fitted with a piping system which leads the fire extinguishing agent into the mentioned areas.

Where fire protection is required, the final arrangement of the fire extinguishing system is to be submitted for approval to the relevant classification society.

18.8.1 Extinguishing agents

Various extinguishing agents can be considered for fire fighting purposes. Their selection is made either by the shipbuilder or the shipowner in compliance with the rules of the classification society involved. Table gives the recommended quantity of 45 kg bottles of Carbon dioxide [CO₂] for each engine.

Steam as an alternative fire extinguishing medium is permissible for the scavenge air spaces of the piston underside, but may cause corrosion if countermeasures are not taken immediately after its use.

These countermeasures comprise:

- Opening scavenge spaces and removing oil and carbon deposits
- Drying all unpainted surfaces and applying rust protection (i.e. lubricating oil)

NOTICE

Steam is not suitable for fire extinguishing under-piston spaces, as this may result in damage to vital parts such as the crankshaft. If steam is used for the scavenge spaces at piston underside, a water trap is recommended to be installed at each entry to the engine and assurance obtained that steam shut-off valves are tight when not in use.

	Recommended total number of fire extinguishing bottles									
	Extinguishing medi-	Piston underside at bottom dead centre including common section of cylinder jacket								
No. cyl.	um	Volume [m ^{3/} cyl.]	Mass [kg/cyl.]	Size [kg]	Qty					
5					1					
6	Carla ara diavida [CO]	4.0	0	45	1					
7	Carbon dioxide [CO ₂]	1.6	6	45	1					
8					2					

Table 18.3: Recommended total number of fire extinguishing bottles

19. Engine Emissions

The International Maritime Organisation (IMO) is a specialized agency of the United Nations (UN), dealing with technical aspects of shipping. For more information see **http://www.imo.org**.

19.1 Exhaust gas emissions

19.1.1 Establishment of emission limits for ships

In 1973 an agreement on the International Convention for the Prevention of Pollution from ships was reached. It was modified in 1978 and is now known as **MARPOL 73/78**.

The **Annex VI** to MARPOL 73/78, entered into force in 2005, contains regulations limiting or prohibiting certain types of emissions from ships, including limitations with respect to the allowed air pollution. Following the entry into force of the annex, a review process was started, resulting in an amended Annex IV, which was adopted by the IMO in October 2008 and entered into force in July 2010. This amended Annex IV includes provisions for the further development of the emissions regulations until 2020.

19.1.2 Regulation regarding NO_X emissions of diesel engines

Regulation 13 of Annex IV specifies a limit for the nitrogen oxide (NO_X) emissions of engines installed on ships, which has a direct implication on propulsion engine design. Depending on the rated speed of the engine and the date of keel-laying of the vessel, the weighted average NO_x emission of that engine must not exceed the maximum allowable value as indicated by the respective curves in the following diagram.

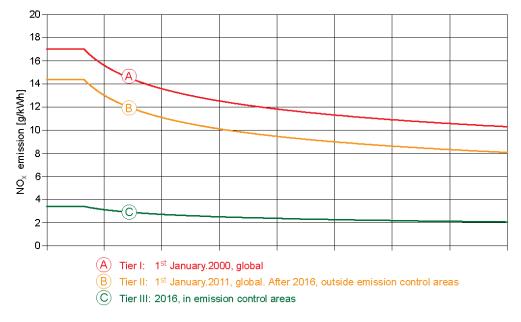


Figure 19.1: Speed dependent maximum average NO_x emissions by engines

The rules and procedures for demonstrating and verifying compliance with this regulation are laid down in the NO_x Technical Code, which is part of Annex VI and is largely based on the latest revision of ISO 8178.

19.1.3 Measures for compliance with the IMO regulation

In the whole rating field, the IMO regulation is fulfilled by use of the Low NO_x Tuning concept as shown in figure 19.2. No extended measures are necessary.

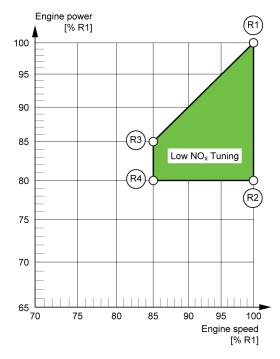


Figure 19.2: Compliance with IMO regulations

20. Engine Dispatch and Installation

Engines are transported as complete or part assemblies and protected against corrosion by rust preventing oils, **v**apour **p**hase **i**nhibitor papers (VPI) and wooden crates lined with jute reinforced bituminous paper.

20.1 Treatment against corrosion

Refer to document 4-107.426.585 (see attachment in section 'Drawings' of this chapter).

20.1.1 Drawings

107.426.585 - Treatment

Treatment against corrosion

GUIDELINE FOR ENGINE PROTECTION AFTER SHOP TEST

2.0 3.0 4.0.0	Introd											
	Respo		Introduction									
4.0.0		ons	ibility								4-5	
	Reaso	on f	or pro	oper co	orrosion	pro	otection				5	
4.0.1	Conse	equ	ences	s for fu	illy asse	emb	led engine	es on sto	re side		6	
5.0.0	Range	e of	appli	cation	: Engine	e de	elivery cor	dition			7	
5.0.1	Engin	e d	eliver	ed in f	ully ass	em	bled cond	ition			7	
5.0.2	Engin	e d	eliver	ed in 3	pre-as	sen	bled maid	or parts			8	
5.0.3									crankshaf			
											. 9	
5.0.4												
~ ~ ~	0							01				
6.0.0									ige			
6.0.1									J			
6.0.2											10	
6.0.3	For st	ora	ge of	engin	e or eng	jine	parts				10	
7.0.0	Draini	ina	& clea	anina	of engin	e p	arts after	shop test			10	
7.0.1												
7.0.2												
7.0.3.0							-					
7.0.3.1												
7.0.3.2									rankshaft)			
7.0.3.3									it crankshaf			
7.0.4												
7.0.5.0											15	
7.0.5.1												
7.0.6									system			
7.0.7	-				-			-				
7.0.8												
7.0.9												
7.1.0												
7.1.1												
7.1.2												
7.1.3					1						21	
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Wärtsilä Switzerland	Drawn: K.Luethi 27.10.09 H 4-107.426.585 Ltd. Verify: B.Schumacher 27.10.09 H 4-107.426.585	2/70
<i>O</i> WÄRTSIL	RTA / RT-flex GUIDELINE FOR ENGINE PROTECTION AFTER SHOP TEST	Group 0345
-	Π	
12.0.2	Installation of turning gear power supply	46
12.0.1	Installation and/or maintaining of dehumidifier operation	
12.0.0	Storage conditions at shipyard	
11.0.1	Sample sheet: Inspection of engine upon arrival at the destination	44 45
11.0.0	Inspection upon arrival (at shipyard)	
10.0	Protection condition during transport to shipyard	
9.0.0 9.0.1	Sample sheet : Final delivery Inspection (at engine maker)	
9.0.0	Final delivery Inspection (at engine maker)	
8.1.2	Turbocharger	
8.1.1	Dehumidifier installation	
8.1.0	Overview over flange connections to be sealed air tight	
8.0.9	Corrosion protection of piping	
8.0.8	Detailed overview of parts & spaces to be corrosion protected	
8.0.7.1	Quick overview of engine parts and the corrosion protection liquid	
8.0.7.0	Overview concerning the components to be corrosion protected	
8.0.6.3	RT-flex Engine	
8.0.6.2	RTA Engine	-
8.0.6.1	Electrical equipment.	
8.0.6.0	inspection purposes Corrosion protection of cooling water circuits	
8.0.5.7	Removal of the preservation material prior to fitting and for	00
8.0.5.6	Packaging	. 28
8.0.5.5	Mechanical protection of crankshafts for transport in boxes	
	thrust bearing flange	
8.0.5.4	Additional mechanical protection of the axial surfaces of the	
0.0.0.0	for open transport	. 27
8.0.5.2	Additional mechanical protection of the crankshaft pins	20-21
8.0.5.1	Preservation of crankshafts for land and sea transport	26 - 27
8.0.5.0	Preservation for indoor and temporary storage	
8.0.5.0	Crankshaft corrosion protection at engine shop	
8.0.4	Coating & corrosion protection of the components – General information	. 25
8.0.3	Checking the quality of the coating	. 25
8.0.2	Application of the corrosion protectors / coating	
8.0.1	Overview of the general application range	
8.0.0	Corrosion protection of machined surfaces / engine parts	
7.1.9		. 24
7.1.8	Supply Unit	
7.1.8	RT-flex Engine – ICU, IFA , Fuel Rail	
7.1.7	RT-flex Engine	
7.1.6	RTA Engine – Camshaft housing	
7.1.5	RTA Engine – Fuel pump	. 21

	47 47 - 48 48 - 49 49 50
13.0.1Once a week413.0.2Every two weeks413.0.3Every month413.0.4Overview inspection time-table414.0Recovery of corroded parts.615.0.0Tools needed for storage.615.0.1Dehumidifier.615.0.2Introduction.615.0.3Engine volume overview.5	47 - 48 48 - 49 49
13.0.2Every two weeks413.0.3Every month413.0.4Overview inspection time-table414.0Recovery of corroded parts.415.0.0Tools needed for storage.515.0.1Dehumidifier.515.0.2Introduction.515.0.3Engine volume overview.5	48 - 49 49
13.0.3 Every month 13.0.4 Overview inspection time-table 14.0 Recovery of corroded parts. 15.0.0 Tools needed for storage. 15.0.1 Dehumidifier. 15.0.2 Introduction. 15.0.3 Engine volume overview.	49
 13.0.4 Overview inspection time-table 14.0 Recovery of corroded parts	
14.0Recovery of corroded parts.15.0.0Tools needed for storage.15.0.1Dehumidifier.15.0.2Introduction.15.0.3Engine volume overview.5	
15.0.0Tools needed for storage15.0.1Dehumidifier15.0.2Introduction15.0.3Engine volume overview	50
15.0.1Dehumidifier15.0.2Introduction15.0.3Engine volume overview	51
15.0.2Introduction15.0.3Engine volume overview	51
15.0.3 Engine volume overview 5	51
	51
15.1.0 Tools for dehumidification & corrosion protector application	51 - 52
	52
15.1.1 Munters M120	52
15.1.2 Munters ML420	53
15.1.3 Munters ML690	53
15.2.0 Accessories	54
15.2.1 Humidity and temperature control	54
15.2.2 HygroLog NT3	54
15.2.3 Equipment for preservation oil spraying	55
16.0.0 Overview of liquids & application properties	55
16.0.1 Cleaning and degreasing agents	56
16.0.2 Corrosion Inhibitors for Wärtsilä 2-stroke diesel engines	
16.0.3 Overview of some corrosion protection product specifications	59
16.0.4 Dewatering Fluid WA	59
16.0.5 Tectyl 506	60
16.0.6 Tectyl 5006W	61
16.0.7 Tectyl 5805W	62
16.0.8 Tectyl 910 / Tectyl 930	63
16.0.9 Tectyl 175GW ; Tectyl 185 GW ; Tectyl 132	64
17.0.0 Overview of regular inspection lists during engine storage	65
17.0.1 Inspection List for general parts purpose	65
17.0.2 Inspection List for daily dehumidifier inspection	66
17.0.3 Inspection List for time-dependant inspections or moving of parts	
17.0.4. Inspection List for final delivery inspection / inspection upon	01
	68 - 69
18.0 Engine tools	69
19.0 Spare parts	70
	10
20.0 Health protection and safety at work	70
21.0 Disposal	70
C RTA / RT-flex GUIDELINE FOR ENGINE PROTECTION AFTER SHOP TEST	Group 0345
WARTSILA	
Wärtsilä Switzerland Ltd. Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09 H 4-107.426.585	3 / 70

2.0 Introduction

This document is an overview guide line for the application of corrosion protection coating after shop test of RTA and RT-flex engines as also for temporally undetermined storage at shipyard / final destination.

For the corrosion protection of the engine and its parts, as well as for the treatment of the cooling water circuits during engine assembling and shop test, the specification 107.215.543i and its amendments are still valid.

The way of application might differ and depend on the expected or agreed engine storage period and the conditions at final destination.

There are normally 3 different timeframes to which the coating thickness as also the regular main inspection intervals are referring.

- normal period storage (up to 6 months)
- long period storage (6 12 months)
- undefined period of storage due to unpredictable postponement of ship project (over 12 months)

This guide line covers re-coating after the shop test, as during final assembly of the engine parts and even more during engine running, most of the protective coating will have been flushed away.

Therefore a proper re-coating after shop test is crucial.

It was chosen to divide this document in various chapters and sub-chapters in order to have separate steps, thus not losing the principal information by overloading the chapters.

3.0 <u>Responsibility</u>

The orderer specifies the duration of protection and the special requirements for transport and storage.

The engine manufacturer will be responsible that the specified corrosion protection is executed with care and that packaging is carried out in a professional manner.

Reliable preservation is assured if the drying time of the applied coating is observed and the processes and products described in the following are properly applied.

As transition area of taking over the responsibility for further proper storage and corrosion preservation of the engine, the chapters

9.0 - Final inspection before delivery (at engine maker) &

11.0 - Inspection upon arrival (at shipyard) and their sub-chapters have been written.

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The manufacturers' specifications and safety sheets for these cleaning and coating products must be strictly observed. Other processes and products may be applied if they meet the specified requirements.

Wärtsilä Switzerland Ltd. will not accept any liability or responsibility for damage to the engine and its parts which is or has been sustained due to the none-observance of these preserving instructions, e.g. due to insufficient preservation, unsuitable storage or damaged preservation material.

Moreover, Wärtsilä Switzerland Ltd will not accept any liability for preservation measures that are carried out by the manufacturer or a third party.

It is in any case the responsibility of the orderer to check the engine and its parts for any corrosive damage promptly upon arrival.

Unless agreed differently in the purchase contract, any claim due to corrosion damage of the engine and its parts has to be made in writing to Wärtsilä Switzerland Ltd. within two weeks from the arrival of the engine and its parts to the final destination defined in the purchase contract.

Any claim made after the two weeks' notice period shall not be taken into account. The orderer shall be responsible for the preservation of the engine and its parts for further transport and final storage.

4.0.0 Reason for proper corrosion protection

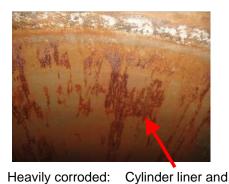
To give you an impression of corroded parts, respectively the possible or impossible access for repairing or replacing of them, the following short extract of pictures will illustrate the reasons for proper corrosion protection.

Without access by crane, available normally just in engine room condition, or proper storage warehouse, no proper repair or replacement work of heavy parts can be done!

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4.0.1 <u>Consequences for fully assembled engines on store side</u>

As e.g. the pistons and cylinder liners can be checked only through the scavenge air ports, a cleaning and possible recovery of the parts at time will not be possible. Further corrosion leads to such kind of material pitting that the parts must be exchanged at a later stage.



piston crown. At last the parts could be

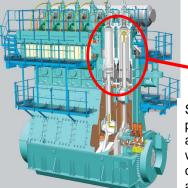
pulled or reached to be cleaned and judged

for further procedure (replacement).

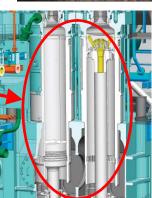


Repaired (cleaned of upper rust layer) cylinder liner (above) and piston crown (below) surface revealed that the pitting had been so heavy that the parts had to be replaced.





Situation of parts access without crane available



Situation of cyl.liner & piston crown in fully assembled condition.

Be aware: These are just samples !

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5.0.0 Range of application: Engine delivery condition

The intention of this chapter is to give an overview of different ways and engine stages the corrosion protection, the transport and the storage will be done, as this will affect either the way of corrosion protection application and even more the storage capabilities and additional re-coating work, which are required for long-term storage and unpredictable engine storage-time respectively.

Mainly for reasons of different crane capacities as also engine sizes either at engine maker or at shipyard, there are three different conditions of engine delivery:

- See 5.0.1 : Engine delivered in fully assembled condition.
- See 5.0.2 : Engine delivered in 3 major components (bedplate with crankshaft, column, cylinder jackets with cylinder liner installed).
- See 5.0.3. : Engine fully dismantled after shop test.

5.0.1 Engine delivered in fully assembled condition



Engine delivered in fully assembled conditions.

Engine stored in a tentlike warehouse. Engine stored outside and covered with a waterproof tarpaulin.

- It is recommended to install dehumidifiers for transportation already. It has to be assured that they are connected electrically at board side.

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5.0.2 Engine delivered in 3 pre-assembled major parts

In general it has to be mentioned that the storage of single parts, even major parts like bedplate with crankshaft, column with platforms as well as the cylinder jackets and all additional parts like pistons, connecting rods, etc. can be done with less expense of time and work if the protection and packing of the parts was properly done beforehand. Dehumidifiers have to be placed at each single major part.



Bedplates (2 parts) with crankshaft (in front) and column with fuel pumps (behind)



Connecting rods at cleaning stage at shipyard. The sea-trial date is fixed.



Main pistons and cylinder covers (still covered and exhaust cage closed by plate)



Cylinder jackets with scavenge air receivers



Cylinder liners at cleaning stage at shipyard.



Turbocharger prepared (openings closed by wooden plates)

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5.0.3 Engine delivered in 3 pre-assembled major parts & crankshaft delivered separately

It might occur quite often that the crankshaft has to be dismantled after shop test. This is mostly the case with bigger bore engines RTA/RT-flex 82; RTA/RT-flex 84; RTA/RT-flex96, but it might also be required for small bore engines. The principal reason is the crane load capacity either at engine maker or at the shipyard.

5.0.4 Engine delivered fully disassembled

Engine fully dismantled after shop test: All parts have been cleaned, protected and covered properly (bedplate, crankshaft, column, cylinder jacket as single components); all platforms and pipes are dismantled, all other parts like cylinder covers and exhaust valves, pistons, cylinder liners, connecting rods, crossheads and so on are packed and protected in wooden boxes.



Example of connecting rod with crosshead at transport packaging stage. Stored outside just after arrival at shipyard.

6.0.0 <u>Climatic conditions for: Cleaning – Coating – Storage</u>

As the many different climatic conditions are one of the major impacts in relation to the applicable corrosion protection work, this issue has to be clarified more closely.

- High humidity conditions with humidity values as high as 80-85% over nearly the whole year on the one hand, and the corrosion protection liquid properties on the other hand, implicate the recommendation of preferably low humidity values, as otherwise the fast accretion of moisture on the blank surfaces will complicate any proper procedure.

Therefore Wärtsilä Switzerland Ltd. recommends the a relative humidity value below 50% in general.

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	Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09	Н	4-107.426.585		9 / 70

6.0.1 For cleaning of machined surfaces – parts in general; before coating

The cleaning work has to be carried out in a well-ventilated room at a temperature between 15° C (min) and 35° C (max.). The relative humidity should be less than 50%.

6.0.2 For application of corrosion protection

The cleaning work has to be carried out in a well-ventilated room at a temperature between $15^{\circ}C$ (min) and $35^{\circ}C$ (max.). The relative humidity should be less than 50%.

6.0.3 For storage of engine or engine parts

The engine and its parts must be stored in well-ventilated rooms at a temperature between 15° C (min) and 35° C (max.). The relative humidity should be less than 50%.

7.0.0 Draining & cleaning of engine parts after shop test

The procedure described in this chapter has to be carried out hand in hand with chapter 8, taking into account that all painting work (coating of primer & top layer) has been done properly before engine assembly.

The application of corrosion protection has to be checked and renewed on all machined/blank surfaces, as the corrosion protection may be flushed due to the temperatures reached during engine running for shop test, or has melted away during the shop test itself or scraped away during assembly.

As general summary of this chapter 7, the following rule has to be considered stringently:

The clean and dry condition of the machined/blank surfaces is of outmost importance for a proper application of corrosion protection, as the adhesion of all applicants will be as good as cleaning and drying work was performed!

To accelerate the drying time, heaters with dry air fans for heating up the engine interior can be considered.

A heat venting system is probably even more useful in connection with drying of all water pipes and/or water cooling spaces.

Connection flanges at the transition between the venting system and the piping/ cooling spaces might be especially useful, as flange connections are easily adaptable to different engine sizes by the mere use of additional adaptors.

All parts which have been affected by carbon deposits during engine running have to be cleaned carefully, otherwise the carbon deposits will harm the parts, as there remains sulphuric acid which corrodes the material very much in connection with the long period of standstill.

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	Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09	Н	4-107.426.585		10 / 70

7.0.1 <u>General preparations</u>

- Heaters with dry air fans for heating up the engine internal can be considered due to the amounts of solvents as well as of the corrosion protectors used during a production year, and also to accelerate the drying time, in order to obtain a beneficial economical and environmental effect (one work carried out once) for the engine preservation work.

- A heat venting system is probably even more useful in connection with drying of all water pipes and/or water cooling spaces (see also 7.0.6).

- Connection flanges at the transition between the venting system and the piping/ cooling spaces might be especially useful, as flange connections are easily adaptable to different engine sizes by the mere use of additional adaptors.

The engine maker and probably also the shipyard(*) should take the following into account:

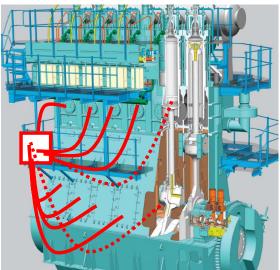
(*)= For the shipyards this might be interesting by reason of unpredictable anchoring of ships after sea-trails due to re-arranged final ship-delivery or other force majeure reasons.

As the cleaning-, and much more, the drying work after a shop test can be of a dangerously annoying stimulus due to the fact that especially the oil will flow time and again over already cleaned surfaces, or, as in our case, over machined/blank surfaces, a fast heating and drying-up of the crankcase as well as of the piston underside by a heating fan system should be considered just after shop test.

A thickened oil film is much easier and faster cleaned with much less solvent. Likewise the thickened oil will not flow quickly again over the surfaces cleaned/prepared for corrosion protection.



Sample of hose connection of dehumidifier system.



Heating fan with multi-connectable hose system & adaptable flange connectors.

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7.0.2 Tools & materials to be used for cleaning

The following tools and products are to be used for cleaning work in general:

- Acid-free cotton cloth
- Paper towels
- Wooden or plastic spatula/scraper
- Airgun or airless spray unit (see chapter 15..2.3)
- White spirit (e.g. Shellsol : see chapter 16.0.1)
- Petroleum
- Kerosene

NOT to be used under any circumstances:

- Metallic scraper

7.0.3.0 Crankcase – drying & cleaning

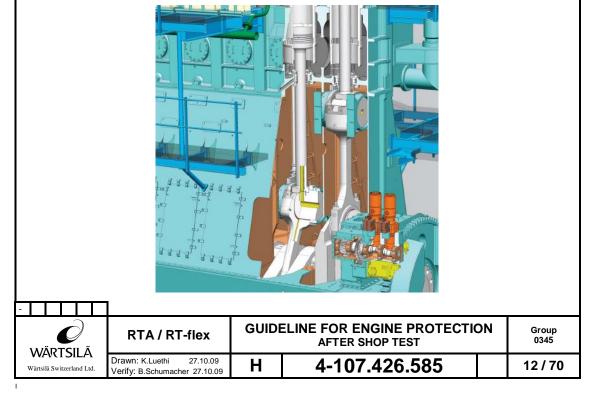
The crankcase can be cleaned and dried in usually three different engine stages:

- 7	.0.3.1	Engine full	ly assembled
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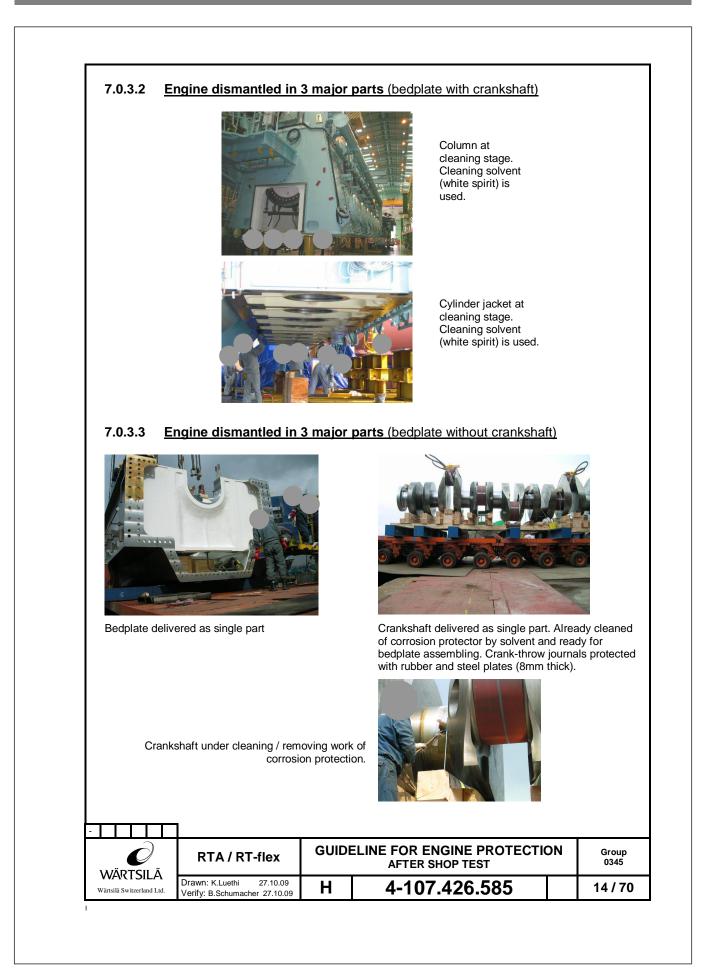
- 7.0.3.2 Engine dismantled in 3 major parts (bedplate with crankshaft)
- 7.0.3.3 Engine dismantled in 3 major parts (bedplate without crankshaft)

7.0.3.1 Engine fully assembled

The engine will not be dismantled for transport and installation at shipyard. All engine internal parts have to be dried and cleaned after shop test.



The cylinder protection w		ns have t	been removed for thei	r cleaning and	l corrosion
All engine in	ternal parts have to b	e dried a	nd cleaned after shop	test.	
Either of sys	tem oil, like				
- pistor	cooling oil				
	head lubrication bearing lubrication				
- servo	oil rail				
	oil pumps (Supply Ur charger lubrication	nit)			
		ither to t	he ingoing or outgoing	g of fluid flow,	
or of water re	esidues/deposits of th	ie cooling	g water system, like		
	er liner cooling space				
	er cover & exhaust va nge air receiver/coole				
			he ingoing or outgoing	g of fluid flow,	
or of air of th	e starting air- or cont	rol air sy	stem, like		
	ng air shut-off valve				
	ng air distributor ng air valve at cylinde	r cover			
			he ingoing or outgoing	g of fluid flow,	
or of fuel, lik	e				
	on Control Unit (ICU)	- RT-fle	k engines		
fuel rafuel p					
•	•	either to t	he ingoing or outgoing	of fluid flow.	
All engine ex	ternal machined surf	aces and	/or parts have to be c	leaned and dr	ried.
For all mach	ined surfaces a clean	ing solve	ent/white spirit should	be used. See	16.1.2.
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7.0.4 Main bearings & thrust bearing pads dismantled

If the crankshaft is delivered as single part, also the main bearing shells and bearing covers as well as the thrust bearing pads are to be removed from the bedplate. Carefully clean them with Shellsol / white spirit.

7.0.5.0 Crankshaft delivered as single part

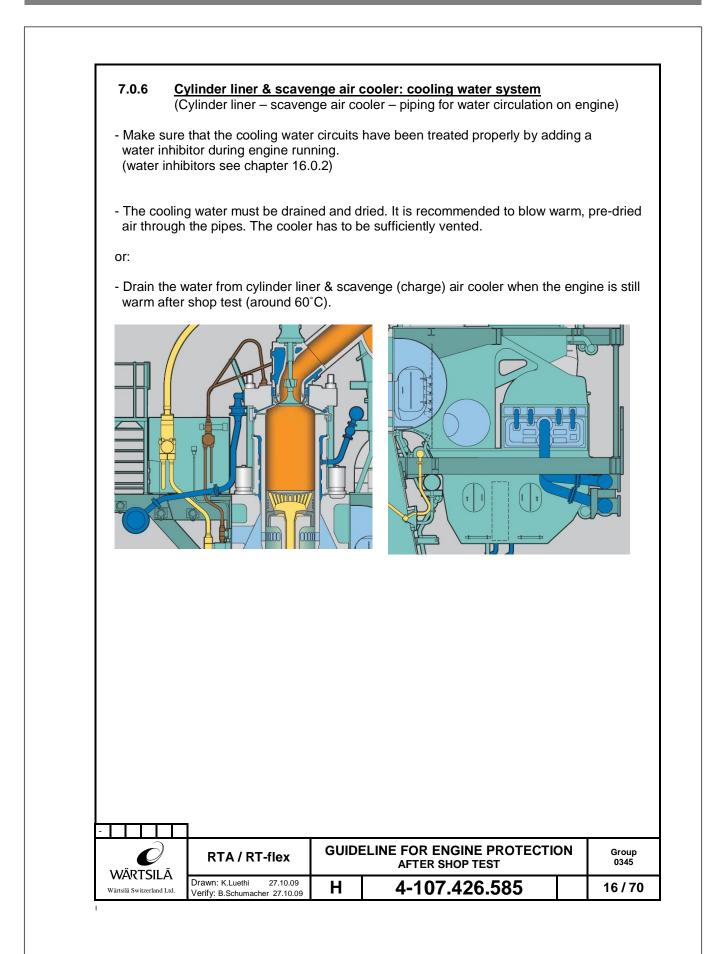
This chapter describes the handling of the separately delivered crankshaft.



7.0.5.1 Crankshaft cleaning

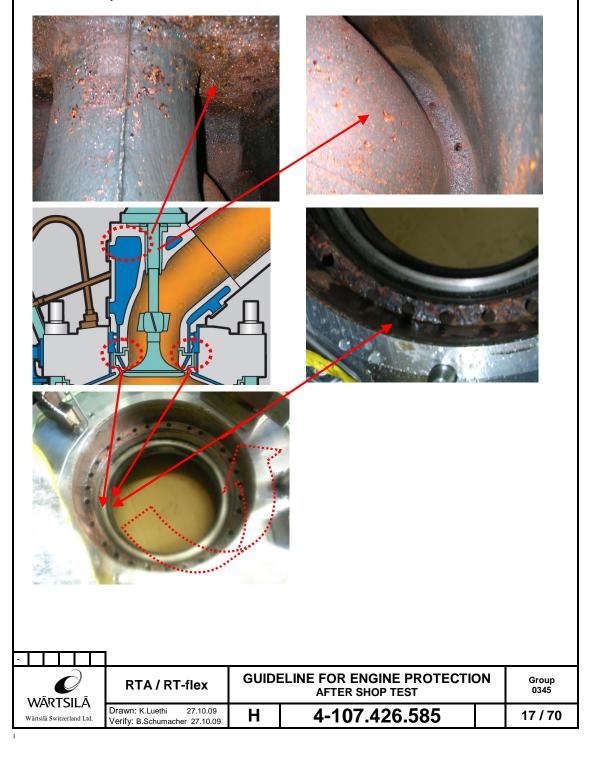
- Thorough manual cleaning of the entire crankshaft surface with acid-free cotton cloth (no rags), paper towels and clean solvent, e.g. white spirit, Shellsol or a similar product.
- Flushing of all bores with clean solvent.
- **Important:** From this moment the crankshaft must not be touched with bare hands anymore!
- Allow the crankshaft to dry completely.
- Check whether clean and free of rust. Do not touch the cleaned surfaces with bare hands.
- If there are signs of rust, the quality assurance department will decide whether additional work is necessary. If the traces of rust are only slight, they can be removed with emery cloth No. 220 (or finer) and petroleum. Repeat cleaning!

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7.0.7 <u>Consequences</u>

The non-use of proper water inhibitors and soluble oil for proper corrosion protection will lead to severe corrosion, mostly in water cooling spaces which are not traced without additional inspection regulations/requirements. The pictures/sketches below are for reference only.



7.0.8 Cylinder liner & piston

If the engine is not dismantled, make sure that also the piston inner parts, like spraying plate with nozzles, as well as the piston inside itself are protected in a practicable way. This could be achieved by using either the piston cooling pipe system or the flange connections for lever.

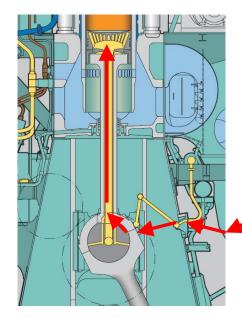
- Piston dismantling after shop test:

After shop test, mainly the piston crowns, the piston rings and probably the piston ring grooves are to be cleaned of combustion residues.

- Gland box piston rod: To be opened and properly cleaned of carbon and dirt oil deposits.

- Cylinder liner dismantling after shop test:

It has to be determined whether the cylinder liners will be dismantled after shop test. The cylinder liners can be cleaned still assembled to the cylinder jacket, as also the pistons will have to be dismantled.



If the engine is not dismantled, make sure that also the piston inner parts, like spraying plate with nozzles, as well as the piston inside itself are protected in a practicable way.

This could be achieved by using either the piston cooling pipe system or the flange connections for lever.

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7.0.9 Cylinder cover

After shop test, the cylinder covers will have to be dismantled to clean the combustion residues in the combustion chamber as well as the exhaust cage. Drain the cooling water carefully (check exhaust cooling water space) and use warm/heated-up air if necessary.



Combustion chamber with carbon deposit after shop test.



Combustion chamber after cleaning.

7.1.0 Starting- & control air system

7.1.1 RTA Engine

- Drain the complete starting air system including air spring.
- Drain the complete control air system.
- Remove all starting air valves, open them, clean all parts, oil the parts slightly with rust protection oil and reassemble them.

Option 1

The starting air valves can be refitted in the engine after overhaul.

Option 2 (recommended)

The starting air valves can also be kept separate from the engine. In this case the starting air valves should be stored in a dry place, well preserved and packed in VCI (Vapour, Corrosion, Inhibitor) paper. Note that the openings in the cylinder covers need to be closed air-tight with steel flange covers (draft prevention).

- Dismantle the shut-off valve for starting air, clean all parts and oil them with rust protection oil. Afterwards the valve can be refitted in closed position.
- Remove the end cover of the main starting air pipe and place silica gel desiccant bags inside. Afterwards refit the cover (as a precaution a marking must be applied outside to indicate that a silica gel desiccant bag has been stored inside).

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Overhaul the starting air distributor, extract the bushes and sleeves. All parts need to be cleaned and oiled before refitting. When extracting the valves, the air spaces of the housing can be cleaned and spray protected. The distributor control cam should be checked and spray coated as well.

7.1.2 RT-flex Engine

- Drain the complete starting air system including air spring.
- Remove all starting air valves, open them, clean all parts, oil the parts slightly with rust protection oil and reassemble them.

Option 1

The starting air valves can be refitted in the engine after overhaul.

Option 2 (recommended)

The starting air valves can also be kept separate from the engine. In this case the starting air valves should be stored in a dry place, well preserved and packed in VCI paper. Note that the openings in the cylinder covers need to be closed air-tight with steel flange covers (draft prevention).



- Dismantle the shut-off valve for starting air, clean all parts and oil them with rust protection oil. Afterwards the valve can be refitted in closed position.
- Remove the end cover of the main starting air pipe and place silica gel desiccant bags inside. Afterwards refit the cover (as a precaution a marking must be applied outside to indicate that a silica gel desiccant bag has been stored inside).

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7.1.3 Fuel injection system

7.1.4 Fuel injection valve RTA & RT-flex engines

All fuel injection valves are to be overhauled according to the instructions given in the Maintenance Manual. It is recommended to flush the overhauled fuel injection valves on a test bench using a special calibration fluid (for corrosion protection reasons no MDO should be used). After flushing the injection valves the tension of the springs should be released. The openings at the cylinder cover are to be sealed air-tight.

7.1.5 <u>RTA Engine – Fuel pump</u>

To achieve the highest level of corrosion protection for the RTA fuel injection components, it is recommended to drain the MDO from the fuel system. The fuel inlet and outlet lines need to be closed. After dismantling the delivery valve, the fuel pump block can be filled with rust-preventing engine oil. Note that during filling up of the fuel pump block the spill and suction valves should be manually lifted in order to fill the complete fuel pump block. The oil level needs to be checked from time to time and if necessary oil has to be replenished.

- After the engine has been shut down on MDO, drain the complete fuel system.
- Overhaul the fuel cocks in the inlet and outlet lines. Afterwards reassemble them in closed position.
- Remove the delivery valve and fill the fuel pump block manually with rustpreventing engine oil.
- All open ports, adapters, pipes, etc. need to be preserved against corrosion and sealed in order to prevent ingress of foreign particles.
- □ Clean and then spray coat the fuel pump blocks and moving parts (springs, pushrods, etc.) with rust-preventing engine oil.
- Lubricate the fuel linkage including the spring link on the eccentric shaft.

7.1.6 RTA Engine – Camshaft housing

Clean and then spray coat the camshaft, bearing cover rollers, roller guides, etc. with rust-preventing engine oil.

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□ For transport and storage of the engine, the fuel pumps as well as the exhaust valve actuators have to be cut out under any circumstances. Not doing so will harm the rollers and cams.

7.1.7 <u>RT-flex Engine</u>

To achieve the highest level of corrosion protection for the RT-flex fuel injection components it is recommended to drain the MDO from the fuel system and to remove the ICUs from the engine. Afterwards the fuel rail and the intermediate accumulator including the fuel pumps need to be filled with system oil or special rust-preventing engine oil.

Fuel pump

In general the fuel pumps can be left in place during the transport / storage. However, some special measures are required to protect them against corrosion. To guarantee lubrication and preservation of the internal parts, the non return valve bodies including compression springs inside the fuel pump need to be removed.

Note that the non return valves bodies should not be interchanged; therefore they have to be marked for correct positioning during re-installation.

- After the engine has been shut down on MDO, drain the complete fuel system including low pressure circuit, intermediate fuel accumulator and fuel rail.
- Close the valves in the fuel inlet and return lines (low pressure circuit).
- Clean the fuel pump from outside and protect all blank parts.
- Lubricate the fuel regulating linkage including regulating rack.
- All open ports, adapters, pipes, etc. need to be preserved against corrosion and sealed in order to prevent ingress of foreign particles.

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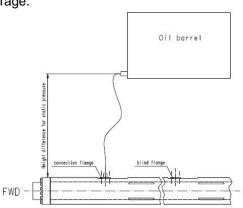
7.1.8 RT-flex Engine – ICU, IFA, Fuel Rail

All ICUs need to be removed from the engine; depending on the number of running hours it should be considered to send them to a Wärtsilä reconditioning workshop for overhaul. If the ICUs are not due they must be stored in an oil bath during the lay-up period. The openings on the fuel rail need to be sealed with blind flanges so that the fuel system can be completely filled with system oil or special rust-preventing engine oil.

- 1. After the engine has been shut down on MDO, make sure that the whole fuel system including low pressure circuit, intermediate fuel accumulator and fuel rail is completely drained.
- 2. Clean all ICUs as well as possible from outside.
- 3. Remove all rail valves and fuel quantity sensors from the ICUs. Preserve the fuel quantity sensors and rail valves and store them in a dry place.
- 4. Remove all ICUs from the engine and store them in an oil bath for corrosion protection. As soon as the ICU is in the oil bath, it is recommended to move the fuel quantity piston by manually carrying out a few strokes.
- 5. Blank off all openings on the fuel rail with blind flanges, except the one on the forward side. There a flange with a connection needs to be installed to supply oil into the fuel rail.
- 6. Blank off the control oil supply to the ICU to allow operating the control oil pumps.
- 7. Fill the fuel rail including rising pipes, intermediate accumulator and fuel pumps with system oil or special rust-preventing engine oil. As soon as the fuel system is completely air-free filled with oil, a small tank (oil barrel) can be connected to compensate slight leakages during the storage.

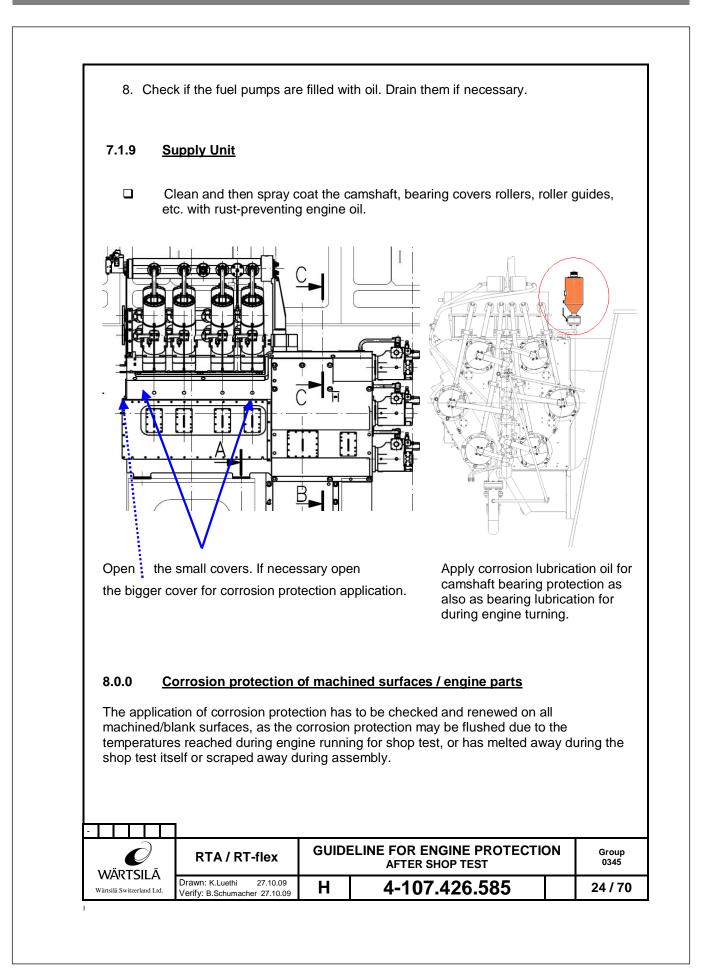


Additional lubrication oil tank connected to the fuel rail to keep it under constant static pressure.



Flange for oil supply to fuel rail and blind flange.

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8.0.1 <u>Overview of the general application range</u>

For exposed parts (engine external), the following description of layer application might be used as "general guidance" regarding corrosion protection application. (e.g. starting air distributor, manoeuvring linkage, camshafts for RTA engines, RTA fuel pump block, etc.)

Apply a first layer of "Tectyl 506" to all surfaces using an airless spray unit. Allow to dry for at least 5 hours at $10^{\circ}-20^{\circ}$ C (3 hrs at $20^{\circ}-25^{\circ}$ C; 2 hrs at $>25^{\circ}$ C).

A second coating of "Tectyl 506" must be applied to all surfaces, with the exception of the webs, using an airgun . Do not touch this coating. Allow to dry for at least 36 hours at $10^{\circ}-20^{\circ}C$ (24 hrs at >20°C).

A coating of "Tectyl 132" must be applied to all crankshaft surfaces by means of an airless spray unit. Allow to dry for at least 36 hours at $10^{\circ}-20^{\circ}C$ (24 hrs at >20°C).

8.0.2 Application of the corrosion protectors / coating

The climatic properties have been described under 6.1.2.

To avoid the accretion of moisture on blank surfaces, the components must show room temperature during the work.

The coating must be applied straight after cleaning to the dried surfaces.

For the recommended coating materials with details of their application see pages 10 to 12. The supplementary product specifications for the coating materials must be strictly observed.

8.0.3 Checking the quality of the coating

The inspection of the dry coating is made non destructively according to the magneticinduction method, e.g. with the measuring device "Minitest".

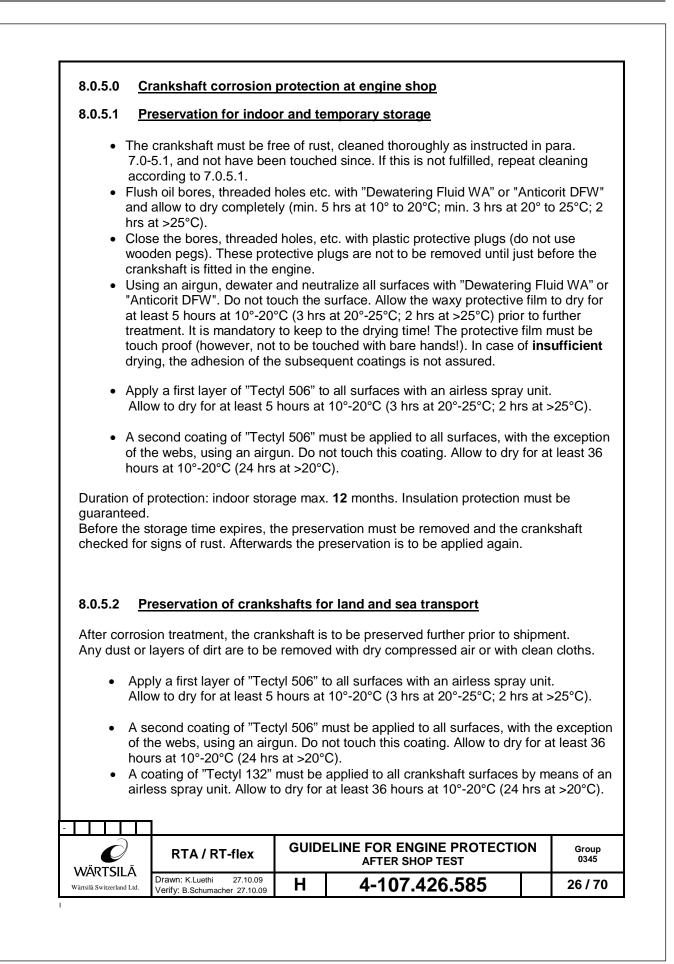
The adhesion of the coating is to be checked with a cross-cut test according to DIN 53 151 (Code GT 1). The damaged coating resulting from this inspection is to be ground over and applied anew.

In case of non-fulfilment of the quality standard, the manufacturer's quality assurance department will decide whether further inspections are necessary and if the coating should be renewed.

8.0.4 <u>Coating & corrosion protection of the components – General information</u>

The different surface protection measures are listed in the table "Coatings and corrosion protection general". The components and surfaces are shown in groups, thus allowing to be treated by the manufacturers in a corresponding manner.

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Wärtsilä Switzerland Ltd.	Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09	Н	4-107.426.585	25 / 70



Duration of protection: indoor storage max. **12** months, outdoor storage max. **6** months Insulation protection must be guaranteed.

8.0.5.3 Additional mechanical protection of the crankshaft pins for open transport

The journals and pins must be wrapped with the following materials:

- one layer of VCI paper (Volatile Corrosion Inhibitor)
- two layers of polyethylene foil
- one layer of Ethafoam foil, 5 mm thick (must not absorb water)
- three layers of Lamiflex laminae
- All layers are to be fixed with chlorine-free adhesive tape.

To avoid damage to the mechanical protection and the preservation material during lifting, the journals are to be protected as follows:

steel shells with a thickness of at least 8 mm are to be fitted.

Instructions to the effect "Do not lift here" are to be posted on all other pins and journals.

 Supplier information : Lamiflex lamellae Lamiflex AB Gasverksvägen 4-6 611 35 Nyköping - Sweden www.lamiflex.se

8.0.5.4 Additional mechanical protection of the axial surfaces of the thrust bearing flange

- one layer of VCI paper
- two layers of polyethylene foil
- one layer of Ethafoam foil, 5 mm thick
- plywood, 20 mm thick

8.0.5.5 Mechanical protection of crankshafts for transport in boxes

The crankshaft is to rest on the webs .To avoid damage to the preservation material during lifting, the corresponding journals are to be protected with thick and reinforced rubber.

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Wärtsilä Switzerland Ltd.	Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09	Н	4-107.426.585	27 / 70

8.0.5.6 Packaging

The engine maker is responsible for proper packaging. The crankshaft must rest on the webs, whatever the kind of transport. The surfaces of wooden supports must be treated in advance with a **neutralising preservation product**.

8.0.5.7 <u>Removal of the preservation material prior to fitting and for inspection</u> <u>purposes</u>

The corrosion protective products can be removed manually with acid-free cotton cloth soaked with petroleum or aromatic-free white spirit. A proven method is to wrap the bearing journals concerned in acid-free cotton cloths, which are then dowsed with a solvent, such as white spirit or Shellsol (for lack of solvents use diesel oil). After a sufficient application time (min. 1 hour), the cloths may be removed. The preservation layers can now been scraped off by means of a wooden spatula. **Attention:** metallic scrapers or other means, such as steam- or hot water cleaners, must not be used!

The preservation must be checked before the expiration of the duration of protection and, if necessary, renewed.

8.0.6.0 Corrosion protection of cooling water circuits

(Cylinder liner – scavenge air cooler – piping for water circulation at engine)

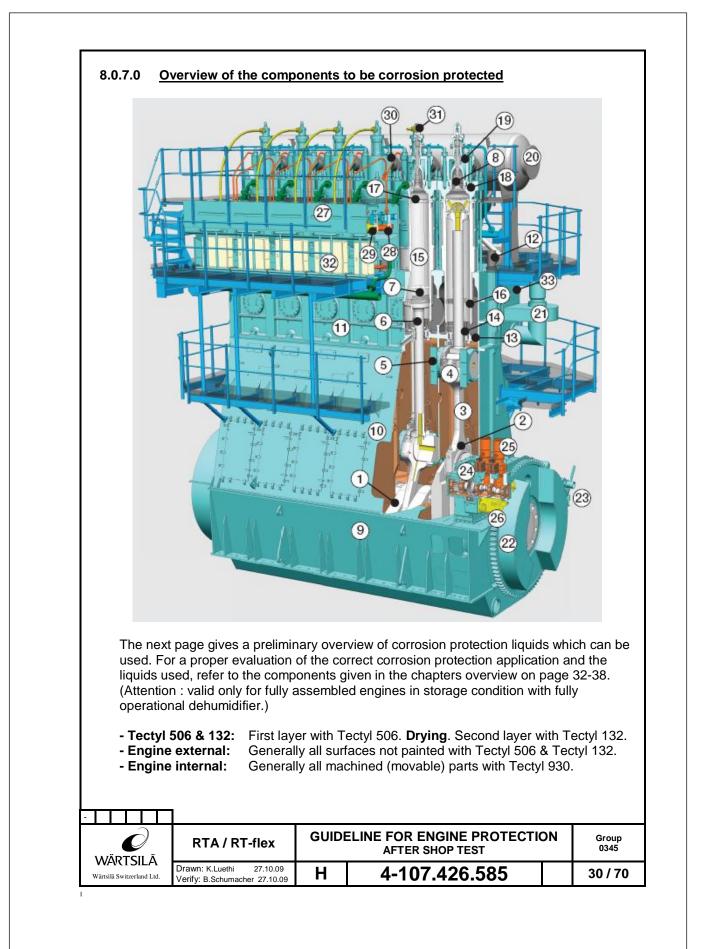
As the cooling water will be drained off after shop test, further treatment against corrosive attack is absolutely essential, i.e. the admixture of a so-called 'soluble oil' to the cooling water in order to protect the engine cooling water system. The concentration must be maintained at levels between 0.5 and 0.8 per cent by volume. Prior to the complete shutdown of the system, the circulating cooling water through the engine cooling water system is to be maintained at a pH value between 7 and 9 and the soluble oil inhibitor level increased to 1 per cent by volume. The cylinder temperature is not to exceed 90°C and circulation is to continue for at least three hours, allowing time for the soluble oil inhibitor to coat the internal surfaces.

Attention: The application of soluble oil might be just of helpful use, if the storage period is predicted as being very long (over 12 months). The reason is that the water circuits would have to be flushed at shipside after installation, before being finally connected to board circuit.

If the water circuits - especially the one for cylinder liners and cylinder cover cooling spaces with the cooling bores in the cylinder liner as well as the one in the cylinder cover - and exhaust valve cooling circuit are not flushed, the soluble oil foam, in connection with dust, will lead to clogging of the beforehand described cooling bores.

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	To carry out corrosion protection of water cooling pipes and spaces properly, the application of soluble oil has to be done right after shop test with still connected water circuit.
8.0.6.1	Electrical equipment
8.0.6.2	RTA Engine
	Make sure that the power supply for the heating of the electric motors is assured (if applicable).
	Place desiccant bags to all electrical connection boxes fitted on engine.
In	case RPLS/PLS is installed:
	Place desiccant bags in control boxes E40 and E41.N for Pulse Lubrication; make sure that all cable glands are tight. Open holes should be sealed.
8.0.6.3	RT-flex Engine
	Place desiccant bags in control boxes E85, E90, E95.N, E87 (for Bosch servo oil pumps) and/or E40, E41.N for Pulse Lubrication; make sure that all cable glands are tight. Open holes should be sealed.
	Place desiccant bags in control safety system boxes E10, E20, E25, E28.
	Place desiccant bags in alarm system boxes E110, E15.1, E120.n, E130, etc.
	Place desiccant bags in Boll & Kirch automatic oil filter control box.
	Make sure that the power supply for the heating of the electric motors is assured (if applicable).
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	1 Quick overview o corrosion protect		efer (please compare) to	o chapter 1	6.0.0!
Pos.	Part		Engine location	Protect	or type
1.	Crankshaft		Internal	B or F	
	Crank web		Internal	B or F	
	Crankpin: web jour	rnal & main iourna	al Internal	B or F	
	Gear wheels	,	Internal	B or F	
	Thrust bearing pac	ds	Internal	B or F	
2.	Bottom end bearing		Internal	B or F	
3.	Connecting rod		Internal	B or F	
4.	Crosshead bearing		Internal	B or F	
5.	Crosshead guide sho	es	Internal	B or F	
6.	Piston rod		Internal	B or F	
7.	Piston		Internal	B or F	
8.	Exhaust valve		Internal	B or F	
9.	Bedplate		Internal	B or F	
10.	Column (Guide rails)		Internal	B or F	
11.	Cylinder block		External	C	
12.	Tie rods		External	Č	
13.	Diaphragm		Internal	B or F	
14.	Piston rod gland		Internal	B or F	
15.	Cylinder liner		Internal	B or F	
16.	Scavenge ports		Internal	B or F	
17.	Anti-Polishing ring		Internal	B or F	
18.	Cylinder cover		External	C	
	Combustion space)	Internal	B or F	
19.	Exhaust valve cage		Internal	B or F	
20.	Exhaust manifold		External		
21.	Auxiliary scavenge air	· blower	External	Turn ele	ct. moto
22.	Flywheel		External	C & D	
23.	Turning gear				
	Electric motor		External		
	Wheel pin		External	C & D	
24.	RT-flex Supply Unit			-	
-	all flanged units		External	С	
25.	High-pressure fuel pu	mps	External	č	
26.	Servo oil pumps	1 -	External	C	
27.	Rail Unit		External	C C	
28.	Fuel oil rail with inject	on units	External	č	
29.	Servo oil rail with exh		-		
	exhaust valve con		External	С	
30.	High-pressure pipes t		External	č	
31.	Exhaust valve drive		Internal	B or F	
32.	Electronic cabinets		External	Silica G	el
33.	Scavenge air receiver				
	all relief valves		External	С	
				-	
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8.0.8 Detailed overview of parts & spaces to be corrosion protected

- Group 1: bedplate and tie rod ٠
- Group 2: cylinder liner and cylinder cover •
- Group 3: crankshaft, connecting rod and piston ٠ ٠
 - Group 4: engine control system and control elements
- Group 5: supply unit, servo oil pump, fuel oil pump and exhaust valve actuator
- Group 6: scavenge air & turbocharger system
 - Group 7: platforms (not mentioned in particular)
- Group 8: exhaust manifold; piping systems (see chapter 7.0.6) ٠
- engine monitoring Group 9: •

- Refer (please compare) to chapter 16.0.0!

- All corrosion protectors given under "C" are to be removed from engine internal spaces parts before starting the engine.

Group	Component	Comments	Preserving actions
1	Bedplate arrangement	All exposed machined surfaces to be coated	C; 2 layers
1	Bedplate oil drain	Seal drains with a suitably sized steel flange and airtight gasket	C ; 1 layer
1	Bedplate free end	Where applicable seal the crankcase vent	C ; 2 layers
1	Bedplate driving end	Coat all machined surfaces, in particular the thrust area; remove the thrust bearing saddle drain to prevent any potential clogging and moisture accretion, refit before engine use	C ; 2 layers
1	Main bearing shell	All exposed surfaces to be coated	B (ValvolineTectyl 930) or F (Shell Valvata 1000)
1	Main bearing cover	Coat all machined surfaces, pay attention to the stud threads where applicable	B (ValvolineTectyl 930) or F (Shell Valvata 1000)
1	Thrust bearing arrangement	Coat all exposed machined surfaces	B (ValvolineTectyl 930) or F (Shell Valvata 1000)
1	Thrust bearing pads	Coat all machined surfaces, prevent excessive dry turning	B (ValvolineTectyl 930) or F (Shell Valvata 1000)
2	Engine frame assembly parts		C; 2 layers
2	Column doors	Seal all crankcase relief valves, ensure that the valves are corrosion-free	C ; 1 layer
2	Casing free end	Coat all machined surfaces	C ; 2 layers
2	End casing driving end	Coat all machined surfaces	C ; 2 layers

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Group	Component		Co	omments	Preserving actions	9	
2	Oil baffle two-parts driving end			affle, be mindful of any otential damage to this	C ; 2 layers		
2	Tie rod			n bores are clear, fill with pection in order to flush	B (ValvolineTecty or F (Shell Valv 1000)		
2	Cylinder jacket grouping			nop trial to remove any mbustion by products	C ; 2 layers		
2	Supporting ring			r is drained completely, in area of the lower O-rings	C (external) o Water inhibito (internal)		
2	Cylinder liner	and m I - La disma piston u	nachined f engine i yer applic antled sta nderside	er is drained completely running surface coated is fully assembled: cation through bore of rting air valve and from or scavenge ports (piston bottom dead centre)	B (ValvolineTecty or F (Shell Valv 1000)		
2	Cylinder liner holder	Ensure	e that wat	er is drained completely	C; 2 layers		
2	Water guide jacket	Ensure	e that wat	er is drained completely	C ; 2 layers a Water inhibito (internal)		
2	Lubricating quill with accumulator for cylinder lubrication	inspec laye	tion or re er of " C ", ngs at wa	der oil and top up for moval, and store by one packed in VCI paper. ter supporting ring to be flanged air-tight.	C ; 1 layer VCI paper		
2	Lubricating quill for Pulse	inspec laye	Fill with cylinder oil and top up for inspection or removal and store by one layer of " C ", packed in VCI paper. Openings at water supporting ring to be closed / flanged air-tight.		C ; 1 layer VCI paper		
2	Gland box piston rod		e that all	machined surfaces are ention to garter springs	B (ValvolineTe 930) or F (Shell V 1000)		
2	Compression space	l - La	f engine i yer applio	t all machined surfaces. is fully assembled: cation through bore of d starting air valve	B (ValvolineTe 930) or F (Shell V 1000)		
2	Cylinder cover	Ensure All fue dism	that all w el injectior antled for sealed b over exter	vater spaces are drained. n and starting air valves r storage. All openings y flange air-tight. rnal surface: C ; 2 layers ver internal: B / F	C; 2 layers B (ValvolineTectyl 930) or F (Shell Valvata 1000) A; B (ValvolineTectyl 930) or F (Shell Valvata 1000)		
2	Fuel valve complete (Fuel injectors)	cleaned	ectors ren I on test b	noved from cyl. cover and bench with " A "; packed in rotection application			
2	Starting air valve		acked in	and apply protector, then VCI paper; flange bore in er cover air-tight	B (ValvolineTe 930) or F (Shell V 1000)		
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Group	Component		Co	omments	Preserving actions		3
2	Relief valve	store,	packed in cylinde	and apply protector, then VCI paper; flange bore in er cover air-tight	B (Valvoline or F (She 1000	ell Valv	
2	Indicator valve		ove and sto cover ai "B" or "F"	or F (She	B (ValvolineTectyl 930) or F (Shell Valvata 1000)		
2	Exhaust valve complete	s Seal c	paces are iff all openi funi Apply prote	e and ensure that cooling completely drained. ings (exhaust chamber to nel) air-tight. action to valve seat.	B (Valvoline or F (She 100	ell Valv	
2	Valve spindle for exhaust valve		e; ensure i trai	ve spindles should not no damage occurs during nsportation. ly protection.	B (Valvoline or F (She 100	ell Valv	
3	Complete crankshaft assembly	Coa		ed machined surfaces. he flywheel teeth.	See chapt	ter 8.0 .	.5.1
3	Vibration damper crankshaft	acces can b	s is possit e flushed v n inspectir	mpers are sealed and no ole. Spring type dampers with system oil; carry out ng the engine at regular intervals.	C ; 2 la	-	
3	Axial detuner	Flu	ush when i	nspecting periodically	B (Valvoline or F (She 1000	ell Valv	
3	Turning gear	Ensu		gearbox is filled and all nents are coated	C;2la Grease ge		ion
3	Connecting rod assembly			d uncoated surfaces to be I as the central oil bore	B (Valvoline or F (She 1000	ell Valv	
3	Bearing shell crankpin	Coat all exposed surfaces			B (Valvoline or F (She 100	ell Valv	
3	Upper bearing half of connecting rod top end bearing	Coat all exposed surfaces			B (Valvoline or F (She 1000	ell Valv	
3	Bearing shell for top end bearing		Coat all	exposed surfaces	B (ValvolineTectyl 930) or F (Shell Valvata 1000)		
3	Screwed connection piston rod - crosshead		that the the the the the the the the the th	nreads are coated, see nreads	B (ValvolineTectyl 930) or F (Shell Valvata 1000)		
3	Crosshead and guide shoe	Coat		ned and other uncoated surfaces	B (Valvoline or F (She 1000	ell Valv	
3	Piston assembly parts		d but may	be coated; system oil is not adhere as specific ducts would	B (Valvoline or F (She 100	ell Valv	
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Group	Component		Co	omments	Preserving actions	g
3	Piston cooling and crosshead lubrication	3-4b	ar pressui	pated. Operate pump with re force and connect to imn-exhaust entering.	B (ValvolineTecty or F (Shell Valv 1000)	
4	Pneumatic manoeuvring units		tely; apply	rol valves and store them / protector and then pack VCI paper	B (ValvolineTecty or F (Shell Valv 1000)	
4	Camshaft drive	See s	pecific inst	ructions on the following list	B (ValvolineTecty or F (Shell Valv 1000)	
4	Drive supply unit	See s	pecific inst	ructions on the following list	B (ValvolineTecty or F (Shell Valv 1000)	
4	Gear wheel on crankshaft	surfac bea	es; coat a rings whe sensiti	n and other machined Il uncoated surfaces. Fill n rotating. This item is ve to corrosion.	B (ValvolineTe 930) or F (Shell V 1000)	
4	Intermediate wheel for camshaft drive	surfac bea	es; coat a rings whe sensiti	n and other machined Il uncoated surfaces. Fill n rotating. This item is ve to corrosion.	B (ValvolineTe 930) or F (Shell V 1000)	
4	Gear wheel on camshaft	surfac	es; coat a rings whe	n and other machined Il uncoated surfaces. Fill n rotating. This item is ve to corrosion.	B (ValvolineTectyl 930) or F (Shell Valvata 1000)	
4	Intermediate wheel supply unit	surfac	es; coat a rings whe	n and other machined Il uncoated surfaces. Fill n rotating. This item is ve to corrosion.	B (ValvolineTe 930) or F (Shell V 1000)	
4	Camshaft/reversing servomotor	comp	onents to I not be as	ated surfaces, internal be filled with system oil; s effective as a dedicated eserving oil	B (ValvolineTe 930) or F (Shell V 1000)	
4	Fuel cam	Coat a		s, this item is sensitive to corrosion.	B (ValvolineTecty or F (Shell Valv 1000)	/ata
4	Actuator cam	Coat a		s, this item is sensitive to corrosion.	B (ValvolineTecty or F (Shell Valv 1000)	
4	Vibration damper camshaft			id dampers are used, no coat all external surfaces	C ; 2 layers	
4	Damper casing camshaft	Ren		amper access, coat all surfaces		
4	Bearing housing(s)		mach	tor " C " to all external ined surfaces. & surfaces: apply " B"/ " F "	C ; 2 layers B (ValvolineTe 930) or F (Shell V 1000)	ectyl alvata
4	Bearing housing ancillary parts		mach	tor " C " to all external ined surfaces & surfaces: apply " B"/"F "	C ; 2 layers B (ValvolineTe 930) or F (Shell V 1000)	ectyl
	т					
	RTA / RT-f	lex	GUIDE	ELINE FOR ENGINE F AFTER SHOP TES		Group 0345
ARTSILA	Drawn: K.Luethi 2	7.10.09	н	4-107.426.	E 0 E	35 / 70

Group	Component		Co	omments	Preservin actions	g	
4	Gearing for auxiliary drives		0	, sensitive to corrosion	B (ValvolineTecty or F (Shell Valv 1000)		
4	Starting air distributor		Internal : al pilot valv	Irface: "C" ; 2 layers surfaces: "B" / "F" es to be coated, sensitive o corrosion	C; 2 layers B (ValvolineTe 930) or F (Shell V 1000)	ectyl	
4	Valve unit for starting air distributor		holes air-ti	atic valves and blank all ght. Apply " B " / " F ". Store ly, packed in VCI.	B (ValvolineTe 930) or F (Shell V 1000)	/alvata	
4	Shut-off valve starting air	Coat all internal parts, removal is required for access. Apply silica gel, but mark outside.			B (ValvolineTecty or F (Shell Valv 1000)		
4	Reversing valve	Internal parts coated with system oil, not effective in the long term. To be packed in VCI paper and then stored. Apply "B" / "F " beforehand. Blank openings air-tight.			B (ValvolineTecty or F (Shell Valv 1000)		
4	Rotation direction safeguard	effecti A	nal parts co ve in the lo VCI pape pply " B " / " oper	tin B (ValvolineTectyl 930) or F (Shell Valva 1000)			
4	Control air supply	air us all pip valv	nnect supp ually conta es are dry es to be re < in VCI pa	B (ValvolineTectvl			
4	Valve unit reversing interlock		/holes. Ap	natic valves and blank all ply " B " / "F", pack in VCI d store separately.			
4	Valve group B by gearing for auxiliary drive		'F " and pad	es and store them. Apply ck in VCI paper. Blank all onnecting points.	B (ValvolineTe 930) or F (Shell V 1000)		
4	Control box local manoeuvring. stand		CI paper. B	es and store them, packed lank all ports/connecting Apply " B " / "F".	B (ValvolineTecty or F (Shell Valv 1000)		
4	Pick-up engine speed/TDC		/ed, pack i	rosion, seal or remove; if n VCI paper and seal the able ends	B (ValvolineTecty or F (Shell Valv 1000)	vata	
4	Control elements unit	Remo		es and store them; blank connecting points	B (ValvolineTecty or F (Shell Valv 1000)	vata	
4	Fuel interlock override device	Remo		al pipe/ports/connections. e separately.	B (ValvolineTecty or F (Shell Valv 1000)		
4	Local manoeuvring stand		All surfa	ces to be coated	C ; 2 layers		
4	Reversing interlock	Remo		al pipe/ports/connections. e separately.			
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Group	Component		Co	omments		erving ions	
4	Rod for local manoeuvring stand and pneumatic logic unit			to exclude moisture. All be adequately protected.	B (Valvolin or F (She 1000)	ell Valva	
4	Speed indication	R	emove an	d store in VCI paper			
4	Speed indication drive	En	sure that a	Il surfaces are coated	B (Valvolin or F (She 1000)	ell Valva	ata
4	Rotation counter	F	Remove and store separately in VCI paper. Blank off bore air-tight.			eTectyl ell Valva	
5	Governor and booster arrangement		move and	and electrical governors store as per makers' structions			
5	Safety cut-out device			ent sensitive to corrosion, no moisture remains	B (Valvo 930) or F (\$ 1000)		
5	Fuel pump block	Flush v		ting fluid and seal; top up in inspecting	Externa C; 2 la		e
5	Eccentric shaft injection pump		n system o	rrosion, to be lubricated il, but ineffective in the agth of time	B (Valvolin or F (She 1000)	eTectyl	
5	Plunger with bush		al lower are sure that fu	ea to prevent air entry. lel pump is cut out. No of roller and cam.	B (ValvolineTectyl 930) or F (Shell Valvata 1000)		
5	Valves injection pump	S		actions for fuel pump	B (ValvolineTectyl 930) or F (Shell Valvata 1000)		
5	Roller guide fuel pump			oated with system oil, not the length of time	B (Valvolin or F (She 1000)		
5	Gear wheel supply unit		B (ValvolineTectyl 930) or F (Shell Valvata 1000)				
5	Pump servo oil			tore separately; seal all and access points	B (Valvolin or F (She 1000)		
5	Supply unit		not effectiv	to be coated with system re in the length of time. external surfaces.	B (Valvo 930) or F (\$ 1000)		
5	Fuel pump			to be coated with system I external surfaces.	B (Valvolin or F (She 1000)		
5	Fuel pump plunger		sure that fu	ea to prevent air entry. lel pump is cut out. No of roller and cam.	B (Valvolin or F (She 1000)	ell Valva	ata
5	Rail unit	Coat a		Cabling and sensors are ve to corrosion.	B (Valvolin or F (She 1000)		
5	Fuel rail			. Cabling and sensors are rrosion (as for rail unit).	C ; 2 la	iyers	
	RTA / RT-	flex	GUIDE	ELINE FOR ENGINE F AFTER SHOP TES		ON	Group 0345
Silä Switzerland		27.10.09	Н	4-107.426.	E0 <i>E</i>		37 / 70

Group	Component		Co	omments	Prese actio		
5	Injection control unit			ctions 107.378.493. ed and stored in wooden box.			
5	Actuator (RTA only)	Interna		be coated with system oil; external surfaces.	C ; 2 lay	ers	
5	Roller guide actuator pump	Assem	bly to be c	o contact of roller & cam. oated with system oil, not ver longer periods.	B (Valvol 930) or F (Sl 1000)		
5	Servo oil rail	Coat a		Cabling and sensors are ve to corrosion.	C ; 2 lay	ers	
5	Exhaust Valve Drive / Partition Device / Assembly		at all parts be dismant	C ;2 laye	ers		
5	Regulating linkage arrangement	Co	at all parts	C ;2 laye	ers		
5	Regulating linkage air cylinder	:	Sensitive t	o internal corrosion	C ; 2 laye	ers	
5	Positioning unit VIT/FQS			Cabling and sensors are rrosion (as for rail unit).	C ; 2 laye	ers	
6	Scavenge air receiver	The internal and external surfaces should be coated; this is a large area which should be kept dry, use a dehumidifier			be coated; this is a large area which is painted		
6	Underslung separator	Ensu	re that wat	er is drained completely			
6	Turbocharger	Store	as per ma	nufacturers' instructions.			
6	Auxiliary blower	cori cov	The motor and bearings are sensitive to corrosion. Electric motors should be covered and heated where possible. Check winding resistance when inspecting.				
6	Auxiliary blower switch box	Keep	sealed an	d internal spaces warm, e silica gel			
6	Scavenge air cooler	draine	e that the d. This co prrosion, b	water side is completely mponent is less sensitive ut care should be taken transporting.	Inhibitor h use		en
6	Water separator scavenge air	Ensu		water side is completely drained			
6	Scavenge air waste gate			ponents should be free of pustion residue. Coat all parts.	C ; 2 laye	ers	
8	Exhaust gas manifold		Cle	an and seal			
8	Automatic oil filter		he system	rer's Operation Manual. and place silica gel bags h candle tube.			
	RTA / RT-f	lex	GUIDE	ELINE FOR ENGINE F AFTER SHOP TES		ON	G
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8.0.9 <u>Corrosion protection of piping</u>

See chapter 7.0.6.

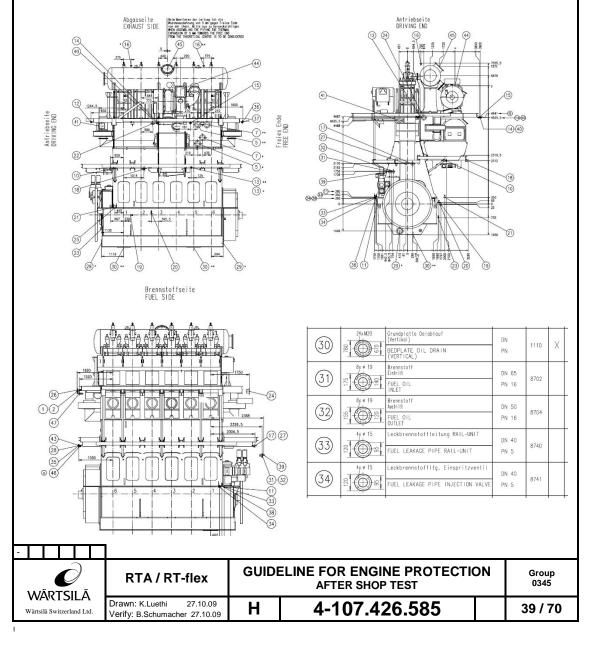
8.1.0 Overview of flange connections to be sealed air-tight

To provide an overview of the flange connection options, some sketches of the Pipe Connection Plan are given below for your reference. The drawings of each corresponding engine type are available at the Licensees.

The flange geometry can be used to produce proper steel flanges for air-tight sealing after the application of final corrosion preservation.

For checking the positions, see the parts list.

This Pipe Connection Plan differs with every engine type; therefore check carefully.



8.1.1 Dehumidifier installation

- □ Install a dehumidifier system to crankcase, piston underside and supply unit or camshaft housing (RTA).
- Install a real-humidity monitoring system to crankcase and piston underside to record real humidity and temperature during the lay-up period.

The dehumidifier needs to be connected with flexible hoses to the engine as described below. A real humidity of 40% - 50% inside the engine needs to be reached to keep the risk of corrosion low. The execution of the connection may vary depending on the dehumidifier system used and engine type. It is recommended to use a booster fan within the dehumidifier circuit to obtain a constant slight overpressure inside the engine.

- 1. Connect the dehumidifier to the piston underside, inlet on the AFT side and outlet on the FWD side of the engine (opposite direction is also possible).
- 2. Connect all camshaft housings together with the dehumidifier to one loop.
- 3. Connect the dehumidifier to the crankcase, inlet on the AFT side and outlet on the FWD side of the engine (opposite direction is also possible). The flexible hoses can either be connected to the crankcase door openings with a dummy plate, or two relief valves can be removed for the connection.
- 4. Record humidity values daily of each engine space given on the "Inspection List for Dehumidifier" see chapter 17.0.2.

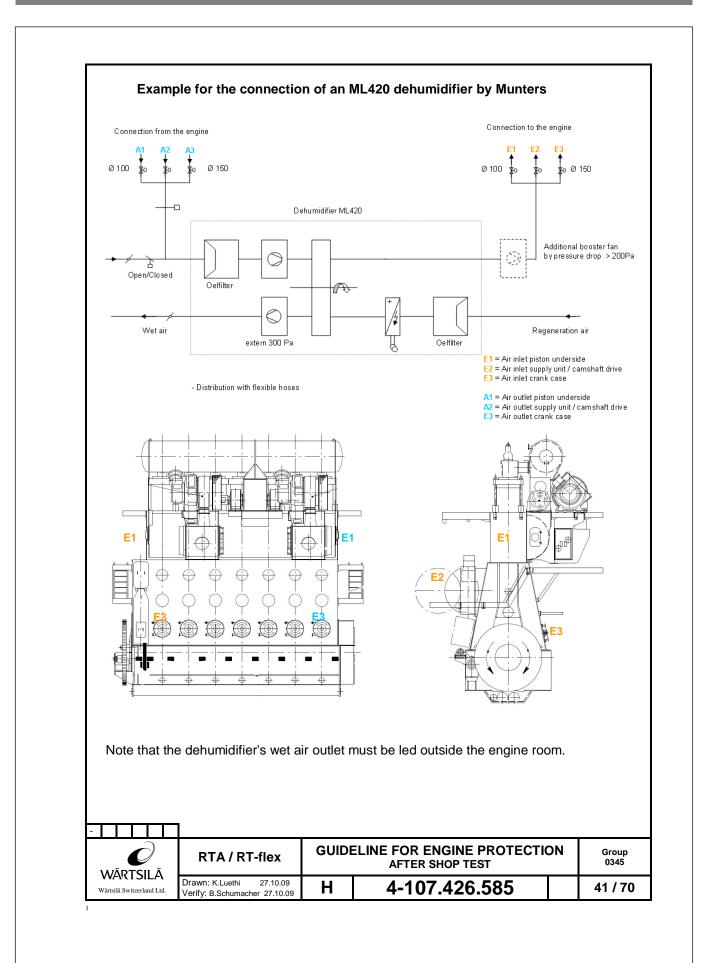


Sample picture of the installation of a Munters M120 dehumidifier



Dehumidifier outlet air taken from the crankcase

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8.1.2 <u>Turbocharger</u>

Generally the turbocharger manufacturer operation manual has to be consulted to carry out any kind of work. It has to be assumed that all cast- or flange-contact surfaces have been corrosion protected properly with Tectyl 506 as first layer and Tectyl 132 as second layer.

- It is of outmost importance that the turbochargers be sealed against moisture penetration, and also the sealing of the exhaust silencer by proper application of so-called VCI (Volatile Corrosion Inhibitor) foil has to be assured.
- It is strongly recommended that reliable re-commissioning of the turbocharger be carried out by an authorised service branch the manufacturers. This is mostly by reason of detecting the proper condition (e.g. VTR 4: concentricity of rotor, condition of bearing space and bearing, as also the proper measuring of the clearances thereof), if necessary carrying out further action and finally, assuring readiness for operation.



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9.0.0 Final Delivery Inspection (at engine maker)

Sample of a cover sheet of the Final Delivery Inspection The cover sheet is accompanied by the checking list given in chapter 17.0.4.

9.0.1 <u>Sample sheet : Final Delivery Inspection (at engine maker)</u> To be provided by the engine manufacturer

Engine Type: Corrosion-protective products applied

Conditions for storage

Indoors in dry conditions, protected against dirt and damage.

Duration of protection

After a period of X months, calculated from the date of shipment, the corrosion protection material is to be removed and the engine/engine parts inspected for signs of rust. After this, the preservation is to be renewed in accordance with the enclosed specification no. 107.426.585.

Inspection and removal of the preservation material

Final delivery inspection at engine maker

Inspection carried out on (Date YYYY-MM-DD :) ____-__:

- Engine / engine parts are checked according to the detailed parts list as attached. See inspection parts list in chapter 17.0.4.
 - The complete preservation is to be inspected for damage.

<u>Removal of the preservation material prior to fitting and for inspection</u> <u>purposes after the period of protection has expired</u>

The corrosion-protective products can be removed manually with acid-free cotton cloth soaked with petroleum or aromatic-free white spirit. Mechanical means, steam or hot water cleaners are not to be used.

The following products are recommended: white spirit, Shellsol If necessary, the preservation must be renewed.

Engine manufacturer's information

Date of preservation: Date of shipment: Name of manufacturer: Stamp of quality department and name of inspector: Documentation: Hand over the Guideline for Engine Protection 107.426.585 together with the signed Final Delivery Inspection sheet (chapter 9.0) to shipyard inspector

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10.0 Protection condition during transport to shipyard

As the engine and/or its parts have been checked at engine maker, see 9.0, and therefore the engine and/or its parts and the packaging are assumed to be in proper condition, the engine with connected dehumidifiers has to be checked on a daily basis for proper operation.

As transportation can take even several weeks and/or the discharge at arrival port may be postponed due to unexpected occurrences, the further inspection procedure has to be guaranteed.

11.0.0 Inspection upon arrival (at shipyard)

The inspection is to be carried out within **two weeks** after the engine/engine parts have arrived to the final destination. Any shortcomings because of an improper preservation are to be reported in writing to Wärtsilä Switzerland Ltd within this time limit. After this time limit, no claims about corrosion damage of the engine and the engine parts respectively shall be taken into account. See also para. 9.0.

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Campie of a cov	er sheet of the Fir	nal Delive	ery Inspection.	
The cover sheet	is accompanied b	by the ch	ecking list given in chapter 17.0.4.	
To be provide	d by the shipya	rd		
Engine Type:				
11.0.1 <u>Samp</u>	le sheet: Inspect	ion of e	ngine upon arrival at the destination	<u>on</u>
Inspection carr	ied out on (Date Y	YYY-MN	1-DD :):	
Engine / eng	gine parts are che	cked acc	ording to the detailed parts list as att	ached.
	parts list in chapt preservation is to			
Copy of the Fir Yes / No	nal Delivery Inspe	ction with	n the filled-out recording sheets is av	ailable
			naterial prior to fitting and for insp period of protection has expired	
Remo The corrosion-r soaked with pe water cleaners	purposes a protective product troleum or aroma are not to be use	fter the j s can be tic-free w d.		ection tton cloth
Remo The corrosion-p soaked with pe water cleaners The following p	purposes a protective product troleum or aroma are not to be use	fter the j s can be tic-free w d. nmendec	period of protection has expired removed manually with acid-free co rhite spirit. Mechanical means, steam t: white spirit, Shellsol	ection tton cloth
Remo The corrosion-p soaked with pe water cleaners The following p If necessary, th Da Da Na	purposes a protective product troleum or aromat are not to be use products are recon the preservation mu nufacturer's info te of preservation te of shipment: me of manufactur	fter the fter the s can be tic-free w d. nmendec ust be re ust be re <u>prmation</u> : er:	period of protection has expired removed manually with acid-free co rhite spirit. Mechanical means, steam I: white spirit, Shellsol newed.	ection tton cloth
Remo The corrosion-p soaked with pe water cleaners The following p If necessary, th Da Da Na	purposes a protective product troleum or aromat are not to be use products are recon the preservation mu nufacturer's info te of preservation te of shipment: me of manufactur	fter the fter the s can be tic-free w d. nmendec ust be re ust be re <u>prmation</u> : er:	period of protection has expired removed manually with acid-free co white spirit. Mechanical means, steam t: white spirit, Shellsol newed.	ection tton cloth
Remo The corrosion-p soaked with pe water cleaners The following p If necessary, th Da Da Sta	purposes a protective product troleum or aromat are not to be use products are recon the preservation mu nufacturer's info te of preservation te of shipment: me of manufactur	fter the f fter the f s can be tic-free w d. nmendec ust be re ust be re prmation : er: artment s	period of protection has expired removed manually with acid-free co white spirit. Mechanical means, steam t: white spirit, Shellsol newed.	tton cloth

12.0.0 Storage conditions at shipyard

The stored engine and/or engine parts will be checked.

12.0.1 Installation and/or maintaining of dehumidifier operation

The dehumidifier should have been installed already since final corrosion protector application has been carried out, if the climatic conditions (humidity) required this. If not done so, install according to chapter 8.1.1. Check the dehumidifier and record the humidity values daily.

12.0.2 Installation of turning gear power supply

The main power source required for generally all turning gear types is AC 440V - 60Hz. Please check beforehand on type plate of turning gear or verify with engine maker.

If the engine has been delivered fully assembled or part-wise (bedplate with crankshaft installed), it is necessary to turn the crankshaft once a week by minimum of 3-4 turns. If so, check if the

- main bearings,
- connecting rod bottom end bearing,
- crosshead bearing,
- guide rails; the 4 guide shoes respectively of each cylinder,
- cylinder liners,
- pistons (either through the starting air valve bores at the cylinder covers, or through the scavenge ports),
- gear wheel drive,
- RTA engines: camshaft bearings (assure that guide pistons for fuel delivery as well as exhaust actuator have been cut out),
- RT-flex engines: camshaft bearings

have been greased with Tectyl 930 or Valvata 1000.

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13.0.0 <u>Regular Re-inspection & re-coating of machined surfaces /</u> engine parts at yard condition

13.0.1 Once a week

(if possible at yard stage!)

• Operate the main engine system oil pump for 20 minutes while turning the engine. During this time the cylinder lubrication should be operated manually. The engine should be stopped each time in another position. Note that the dehumidifying system needs to be turned off prior to starting the lube oil pumps. Two hours after stopping the lube oil pumps the dehumidifier may be turned on again.

Important! The number of pulses / turns required to keep the cylinder liner surface properly lubricated must be verified by visual inspections of the liner surface and piston ring package from the piston underside space.

CLU-3 type lubricating system (if possible at yard stage!)

Operate the manual/emergency cylinder lubrication for 10 - 15 minutes. During this time, keep the engine turning with the turning gear.

Retrofit Pulse and Pulse Lubricating System (RPLS & PLS) (if possible at yard stage!)

Start the main lube oil pump and rotate the engine with the turning gear. Start the oil supply pump and set the delivery pressure to 12-14 bar by means of the oil supply unit's pressure regulating valve. Actuate manual cylinder lubrication. At such low pressure (normally 50 bar), the cylinder oil will not be injected but will flow along the liner wall. Give each cylinder approx. 100 pulses. During this time, keep the engine turning with the turning gear.

Pulse Feed Lubricating System (if possible at yard stage!)

Start the main lube oil pump and rotate the engine with the turning gear. Start the control oil pump, or the Servo Oil Service pump on engines without control oil pumps, in order to provide hydraulic pressure for driving the dosage pumps. The lubricating system servo oil pressure has to be adjusted to 12 to 14 bar by means of the pressure regulating valves which are, depending on the execution, either located inside or just outside the rail unit. Start manual lubrication to individual cylinders. At such low pressure (normally 50 bar), the cylinder oil will not be injected but will flow along the liner wall. Give each cylinder approx. 100 pulses. During this time keep the engine turning with the turning gear.

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	RTA / RT-flex GUIDELINE FOR ENGINE PROTECTION Group
	- pisions
	 cams and rollers (RTA - & RT-flex engines) pistons
	 camshaft (RTA - & RT-flex engines)
	gear wheelsguide rails
	 thrust bearings
CO	ndensation and rust traces, particularly on:
	en the crankcase (on one side) and piston underside doors and check for
13.0.2	Every two weeks
10.0.0	E constant and a
	o water pumps
	 X head pumps booster pumps
	 LO pumps X head pumps
Da	
the	re is no power supply to some pumps, they should be turned by hand on a weekly sis):
Ple	ease note: Always use pumps alternately, a long standstill could lead to detriments
•	Re-spray rust-preventive coating on piston rods if required.
-	Po-spray rust-proventive coating on piston rade if required
•	Open the drain cock of the turbocharger gas outlet casing for one minute (water check).
-	
•	Check the recorded relative humidity and temperature inside the engine on the dat logger.
•	The fuel linkage needs to be moved by hand; re-lubricate it if required.
	system (if required refill).
•	Check the level of the corrosion-protective oil which has been filled into the fuel
	system.
•	In case the cooling water system has not been drained, the cooling water pumps need to be operated for around 20 minutes to get some circulation in the cooling
ea	ch cylinder approx. 100 pulses.
	essure needs not be reduced. Start manual lubrication to individual cylinders. Give
	ler to provide hydraulic pressure for driving the dosage pumps. The servo oil
orc	ITOLOILDUMD. OF THE SO-CAILED SERVICE DUMD ON ENGINES WITHOUT CONTRAL OF DUMDE.
cor orc	nt the main lube oil pump and rotate the engine with the turning gear. Start the ntrol oil pump, or the so-called service pump on engines without control oil pumps, i

	owing liquid media (if possible at yard stage!) : em of the engine GUIDELINE FOR ENGINE PROTECTION AFTER SHOP TEST
eck by analysis the follo - cooling water - system oil	
eck by analysis the follo - cooling water - system oil	
eck by analysis the follo - cooling water	owing liquid media (if possible at yard stage!) :
	owing liquid media (if possible at yard stage!) :
have not been removed ed and checked	d after shop test for single part storage, they must be
ts	
	arting air valves, the indicator cocks, the injection control
	iccant in the automatic filter candles.
	iccant bags inside the main starting air pipe.
eplace the silica gel de	esiccant bags inside the control boxes.
	cover and check the journal pin for signs of corrosion. ioned parts with rust-preventing engine oil. For re- gine cylinder oil.
	any or and shark the journal sin for sizes of corrector
ntioned parts with rust-p	check for signs of corrosion. Spray-coat again all preventing engine oil. For re-assembling use steam engin
Every month	
riments.	
	ge air blower(s) by hand a few revolutions to avoid
	old for any moisture deposits or corrosion. charger(s) at an angle of 90° to avoid bending of the shaft.
eck the dehumidifying sy	system and clean/replace the filter(s).
	starting shut-off valve from time to time. Make sure that the r bottles is depressurised.
n oil when the engine is	s turned over.
	on blank parts in the crankcase that are not covered with
 cylinder liners 	o oil rail units
	 fuel rail- & server ssary re-spray coating oil when the engine is en and close the main s ply from the starting ail eck the dehumidifying s bect the exhaust manife in the rotor of the turboo in the auxiliary scaveng iments. Every month ft a crosshead pin and

13.0.4.	Overview	parts ins	pection	time-frame
---------	----------	-----------	---------	------------

	ļ,	Period of Inspection								
Main inspection parts	Daily	Every week	Every two week	Monthly	Every 3 month	Every 4 - 6 month	Remark			
De-Humidifier	•									
Bedplate				•	(3)	(4)				
Column				•	(3)	(4)				
Guide Rails Column		•			(3)	(4)				
Crankshaft		•			(3)	(4)				
Main Bearings				(5)	(3)	(4)				
Connecting Rod		•			(3)	(4)				
Bottom End Bearing				(5)	(3)	(4)				
Cross-Head Bearing				(5)	(3)	(4)				
Piston Head		•			(3)	(4)				
Piston Rod		•			(3)	(4)				
Gland Box Springs		•			(3)	(4)				
Cams & Camshaft		•			(3)	(4)				
Fuel pump block										
(RTA)			•		(3)	(4)				
Cyl. Liner Inside		•			(3)	(4)				
Cyl. Liner Outside		•			(3)	(4)				
Fuel rail pipe		•			(3)	(4)				
Servo rail pipe		•			(3)	(4)				
Exhaust Valve drive		•			(3)	(4)				
Injection Control Unit		•			(3)	(4)				
Starting Air Distributor		•			(3)	(4)				
Rotation Direction Safeguard		•			(3)	(4)				
Engine turning			•							
Ancillary Parts (*) installed at engine				(1)	(2)					
Ancillary Parts (*) stored in VCI paper & closed woodenbox					(1)	(2)				
(*) = Fuel Injection valves; Starting Air valves ; Indicator cock valve ; Injection Control Unit (ICU)										
(1) = Max. humidity 75	% & drv cor	dition at s	storage place				1			
(2) = Max. humidity 50										
()										
(3) = Max. humidity 75	% - dry cond	lition - sin	gle part							
(4) = Max. humidity 50										
(5) = To be opened for				-						
	/ RT-flex	GUIE	DELINE FOR AFTE	R ENGINE	-	CTION	Grou 0345			
VARTSILA Drawn: K.Lu		H	Δ_1	07.426	585		50/			
rtsilä Switzerland Ltd. Verify: B.Sch										

14.0 <u>Recovery of corroded parts</u>

If there are signs of rust, the quality assurance department will decide whether additional work is necessary. If the traces of rust are only slight, they can be removed with emery cloth No. 220 (or finer) and petroleum. Repeat cleaning! If the parts are too heavily corroded, contact your next Wärtsilä Ltd. Service Branch for further decision.

15.0.0 Tools needed for storage

15.0.1 <u>Dehumidifier</u>

It is up to the engine maker or shipyard to decide which tools are used, as long as the technical properties/specifications are complying with the samples attached.

15.0.2 Introduction

The requirements on a dehumidifier system always depend on the engine type/size (volume to be dried) and the storage location (temperature and real humidity). On the following pages three recommended dehumidifier products are shown which are able to cover the Wärtsilä 2-stroke engine portfolio, even in subtropical areas. The main task of a dehumidifier system is to maintain the real humidity inside the engine between 40% and 50%, in order to keep the level of corrosion as low as possible.

15.0.3 Engine volume overview

The list below can be used as a rough reference for the volume (crankcase, piston underside and camshaft housing) which needs to be dried in the engine. ~ Volume per cylinder in m³ (crankcase & scavenge air space & camshaft housings)

2		
RTA 84	63 m³	
RTA 76	48 m³	
RTA 72U/U-B	39 m³	
RTA 68T-B	40 m³	
RTA 68	36 m³	12 x 60 m ³ = <u>720 m³ total air volume</u> inside the engine
RTA 62U/U-B	24 m³	
RTA 58T/T-B	30 m³	to be dried in a 12RTA96C engine
RTA 58	23 m³	Example for the definition of the air volume
RTA 52U/U-B	17 m³	
RTA 48T/T-B	16 m³	

	WÄRTSILÄ Wärtsilä Switzerland Ltd.		RTA / RT-flex	GUID	ELINE FOR ENGINE PROTECTION AFTER SHOP TEST	Group 0345			
			Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09	Η	4-107.426.585	51 / 70			

RTA 84M	75 m³
RTA 84C(U)	60 m³
RTA 84T-(B,D)	68 m³
RTA 96C/C-B	60 m³

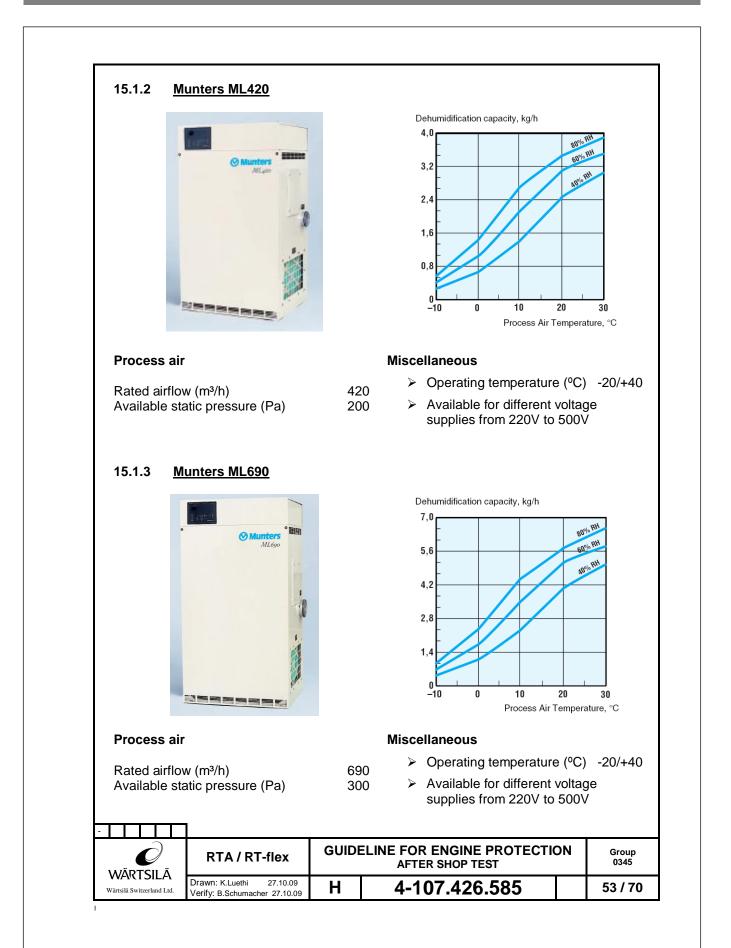
Depending on the lay-up location, temperature, humidity and engine type, the capacity of the dehumidifier system needs to be defined case by case.

15.1.0 Tools for dehumidification & corrosion protector application

Below is a recommendation for three types of absorption dehumidifiers made by the Munters company. The marine industry has already had positive experience with these dehumidifiers.

15.1.1. <u>Munters M120</u>

Image: state of the state o	
Process air Miscellaneous	
Rated airflow (m³/h) 120 Available static pressure 50Hz (Pa) 200 Available static pressure 60Hz (Pa) 360 Available for different voltage supplies from 115V to 240V	1
WÄRTSILÄ RTA / RT-flex GUIDELINE FOR ENGINE PROTECTION AFTER SHOP TEST Group 0345	
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15.2.0 <u>Accessories</u>

- Booster fan
- Oil filter elements (to assure the efficiency of the dehumidifier)
- Controller
- Pipe distributor with flaps
- Flexible hose Ø 80 mm
- Flexible hose Ø 125 mm
- Flexible hose Ø 160 mm
- Flexible hose Ø 200 mm
- Connecting T-pieces
- Transport frame

15.2.1 <u>Humidity and temperature control</u>

During the lay-up a humidity and temperature data logger must be fitted to the crankcase, piston underside and camshaft housing/supply unit, in order to monitor the conditions inside the engine and check proper working of the dehumidifier system. Below is a recommendation for a tool which can be used for this purpose.

15.2.2 HygroLog NT3

			 Relative humidity, temperation point or other calculated para probes to satisfy every a Measurements from 0 to 1 and -50200°C /-58392°F external probe) Optional internal humidity-temperature probe, protect unauthorized removal Monitoring of up to two exticontacts (door, relay contacts (door, relay	arameter e selection application 00%RH ^c (with eed against ernal ct, etc.) ulti- <i>i</i> th ard indard or errupting
<i>©</i> WÄRTSILÄ	RTA / RT-flex	GUIDE	LINE FOR ENGINE PROTECTION AFTER SHOP TEST	Group 0345
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Version a3

15.2.3 Equipment for preservation oil spraying

To spray coat engine components and blank metal parts, a portable oil sprayer may be used. There are different types and executions of oil sprayers. Below two examples are shown for reference only.



Airless spray unit, made e.g. by Wagner (www.wagner-group.com)



Airgun, e.g. type 405T, made by Gloria (<u>www.gloriagarten.de</u>)

16.0.0 Overview of liquids & application properties

Below a sample list has been compiled of fluids to be used for various applications, which have been summarized. Note that the fluids have been divided in various categories; they are referred to in the subsequent component tables. Where applicable the application method is referred to. The list is not complete: where the products referred to are not available locally, a suitable replacement can be used; however, the basic properties should remain the same. In all cases where cabling and sensors are concerned the compatibility of the preserving agent with the relevant cabling should be confirmed.

Please contact Wärtsilä Switzerland Ltd. or any other Wärtsilä Branch next to you, if any doubt remains.

	Product*				oduct*		Desc	cription	Class	Applica metho		
	Shell calibration fluid S9365 Shell Ensis Engine Oil 30 Valvoline Tectyl 930 Mobilarma 524			Ca	0	uid for testing fuel and pumps	А	Used in conjunction with a test pump/bench				
_				Mineral oils with excellent rust prevention properties Used for coating engine parts including cylinder liners, piston		В	Spray coating or brush. Where spraying is used, a manual pump is					
	RTA / RT-flez						GUIDELINE FOR ENGINE PROTECTION AFTER SHOP TEST				roup 345	
	WÄRTSILÄ Wärtsilä Switzerland Ltd.			Drawn: K.Luethi 27.1 Verify: B.Schumacher 27.	0.09 .10.09	Н	4-107.426.585			55	/ 70	

Total Osyris DWY 3500/5500	rods, gears, etc. Only used for engine storage.		preferred. Any air pumps must use moisture-free air.
Tectyl 502 EH Tectyl 506 H Tectyl 132 Chevron Rustproof Compound L Shell Ensis DW2462 Mobilarma 798 Castrol Safecoat DW33	Solvent cutback, soft-wax based, corrosion-preventive compound. Can be used to protect external blank metal parts, for example fuel pump blocks, rails, cylinder covers, etc.	с	Brush.
Pyroshield LE 5182 Klüberfluid CF Ultra	High-pressure grease which can be used for lubricating flywheel teeth.	D	Brush.
Mobilcut 200 Shell Dromus B / BX Total Lactuca MS 5000	Soluble oil inhibitors which are used to protect emptied cooling water spaces.	E	Added to cooling water.
Castrol Cresta SHS Chevron Cylinder oil 1000 Shell Valvata Oil 1000 Mobil 600 W Super Cylinder Oil Total Cyl 1000	High-viscosity steam engine cylinder oils with excellent corrosion protection and resistance to wiping. Used for bearing shells	F	Brush.

16.0.1 Cleaning and degreasing agents

(inodorous aliphatic hydrocarbons, free of aromatics)

White spirit is the generic term for the following Shell products:

- Shellsol TD
- Shellsol T

Valvoline product: Solvent FP68

	Pro	per	tie	S		Shellsol TD	Shellsol T	Solv	vent FP68		
Boiling range, at 760 mm Hg											
		Ŭ		beginning at °C		172	185	194			
				ending at °C		195	212	251			
Π	Density at 20°C in kg/m ³			t 20°C in kg/m ³		735	760	790			
(Colo	our	SA	YBOLT		+ 30	+ 30	+ 30			
	Aroi	mat	ic (content vol. %	:	$\leq 0,2$ $\leq 0,2$		≤ 0,5	5		
;	Sulp	bhu	r c	ontent weight %	ontent weight %	:	≤ 0,005	≤ 0,005	≤ 0,00	005	
(Сор	pe	r co	prrosion		1	1	1			
 ARTSILÄ			RTA / RT-flex	GUIDI		NGINE PROT	ECTIO		roup 345		
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Aniline point °C	84	84.5	75
Viscosity at 20°C in cst.	1.62	1.85	1.84
Relative evaporation time			
(ether = 1)	110	130	800
Flash point Abel °C	46	56	72
Drop ignition temperature°C	-	330	-
Danger class BVD	Fe-II/B	F-III/B	B-III
Transport danger class RID/ADR	Illa2301/a	Illa2301/a	Cl. 3 Pt. 32c
Poison class	5	5	free
Max. permissible concentration ppm	500	500	500
mg/m ³	3200	3400	2000

<u>Toxicology:</u> Only at very high vapour concentrations: will have narcotic effects and may cause dizziness.

<u>Application</u>: Solvents, thinning, cleaning and degreasing agents for lacquers and paints. Non-fluorescent dielectric material for non-destructive testing.

<u>Manufacturers:</u> Royal Dutch Shell plc Shellsol TD and T Carel van Bylandtlaan 30 NL – 2596 HR DEN HAAG www.shell.com

Valvoline Europe, Solvent FP68 Pesetastraat 5 NL – 2991 XT, Barendrecht www.valvolineeurope.com

16.0.2 Corrosion inhibitors for Wärtsilä 2-stroke diesel engines

For closed cooling water circuits

Approved and recommended for use in Wärtsilä 2-stroke diesel engines

	Product b	rand name	Suppl	ier	Main reagent		
	Liquidewt		Ashland	d Drew Marine	Nitrite/borate		
	Maxigard		Ashland	d Drew Marine	Nitrite/borate/o	orgar	nic
	CorrShield C	DR4411	GE Betz		Organic compounds		ls
	Q8 Corrosio	n Inhibitor Long-Life	Kuwait Petroleum		Organic compounds		ls
	D.C.W.T. No	on Chromate	Marichem Marigases		Nitrite/borate		
	Marisol CW		Maritech		Nitrite/borate		
	Nalfleet EW	T 9-108	Nalco / Nalfleet		Nitrite		
-							
	<i>O</i> WÄRTSILÄ	RTA / RT-flex	GUIDELINE FOR ENGINE AFTER SHOP TE			N	Group 0345
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RD 25 Complex	Rohm and Haas	Molybdate/phosphate
Havoline XLI	Texaco	Organic compounds
WT Supra	Total	Organic compounds
Colorcooling	Uniservice	Nitrite
Anticorr	Uniservice	Phosphonate
NCLT	Uniservice	Nitrite
Cooltreat AL	Unitor Chemicals	Organic compounds
Dieselguard NB	Unitor Chemicals	Nitrite/borate
Rocor NB Liquid	Unitor Chemicals	Nitrite/borate
		d be as follows:

The dosage of the corrosion inhibitor and the maintenance of its concentration in service should be carried out according to the supplier's instructions. The supplier company undertakes all responsibility for the performance of the water treatment in service to the exclusion of any liability of Wärtsilä Switzerland Ltd.

-]			
WÄRTSILÄ	RTA / RT-flex	GUIDE	ELINE FOR ENGINE PROTECTION AFTER SHOP TEST	N Group 0345
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16.0.4 <u>De</u>	ewatering Fluid WA									
Type of corro	sion-protective product		atering w /, dry pro			protection				
Name of product:	Dewatering Fluid WA				Article	e No:				
						fication No: itute for Spec.	No			
General and phys			Protection							
Oil-based corr	osion preventive		Humidity	, pers	piration, s	shower-proc	of			
Application Tem	perature: 15°C to 35°C		Applica meth		Thinner %	Viscosity	Spraying pressure	Nozzle mm	k/ Oh	
Hum			Brush	Yes						
Colour:	like Vaseline		Roller	Yes						
Degree of gloss:	mat		Dipping	Yes						
Covering power:			Spraying: low press.	Yes						
Density:	810 kg/m ³ at 15°C		high press.	Yes						
Content of solids:	15.5 %		Airless	Yes						
Viscosity:			Electro- static	Yes						
Danger class:	A-II		Drying: Air	dust- free	set to touch	n completely dry	Recoa spraying	atable after:		
Poison class:	free BAG T Nr. 611 500		20°	nee	1 h		no	r	10	
Flash point:	40°C in closed pot		Oven	Time r	10	Temperature	of component	t		
Identification duty	ADR/SDR Cl. 3 Pt. 31 c		Forced	Time f	סר	Temperature	of component	t:		
Shelf life:	12 months cool/dry		Technical da	ata:						
Mixing ratio: 1)	2)		Cross-cut te	st						
With hardener:			DIN 53151 Hardness ad	cc. to:						
Pot life:			Steel ball jet							
Coverage:	180 m ² /l		DIN 53154 Mandrel ber	d test:						
with dry film thick		3)	DIN 53152 Ericcson cu	oping inde	ex IE:					
•	le: - 20°C to + 60°C	0)	DIN 53156 Salt-spray te	est:		DIN 50'907 150 hrs				
Dry film melting-p			DIN 50021 Kesternich t							
1) Weight	2) Volume 3) On smooth	surface	DIN 50018 Condensed		nate:	DIN 51'359	150 bro			
, 0			ASTM-D-14	B, DIN 51	359		TOUTIS			
Surface preparat		-			ist surfac	æ.				
Features:	Highly water displa films on metal surfa				nd moist	ure out of pa	ocket holes			
Duration of prote	ection: Indoor storage 9 - 1	12 month	ns / shed	storag	e 4 - 8 m	onths				
Removal, cleanir	Removal with white	e spirit or	petroleu	m.			•			
Supplier:	Valvoline Oil Co. Lt Tel. +41 (0) 1/446 5		turmstr. 1	75, P.	O. Box, C	CH-8005 Zu	rich, Switze	erland		
The data given specification a	n are mean values based nd at user's risk with rega	on pract ard to clir	ical expe	rience I speci	. Applica fic condit	tion accordi ions.	ng to the su	ipplier's		
Ø	RTA / RT-flex	GUI	DELINE	-	R ENGI		ECTION		oup 45	
VARTSILA	Drawn: K.Luethi 27.10.09	н		1_1	07 /	26.585		59 /	70	
rtsilä Switzerland Ltd.	Verify: B.Schumacher 27.10.09									

Type of corro	osion-protective product	Waxy, dry preservat				long-term		
Name of product:	TECTYL 506				No: fication No: itute for Spec.	No:		
General and phys Oil-based cor	ical properties: rosion preventive	Atm		nfluences	incl. rain, s	now, etc., a uch as SO ₂		9
Application Terr	perature: 10°C to 35°C		plication-	Thinner	Viscosity	Spraying pressure	Nozzle	k,
Hun	idity:	Brush	nethod Yes	%		pressure	mm	Oł
Colour:	brown	Rolle	No					
Degree of gloss:	wax-like, consistent	Dippi	ng No					
Covering power:		Sprayi low pr						
Density:	870 kg/m ³ at 20°C	high p						
Content of solids:	54 %	Airles	s Yes		1			+
Viscosity:		Electro	- Yes					+
Danger class:	A-II	static Drying		set to touch			atable after:	
Poison class:	free BAG T Nr. 16889	Air 20°C	free 2 2hrs	3 hrs	dry 4 hrs	spraying	<u> </u>	
Flash point:	41°C in closed pot	Oven	Time		Temperature	e of componen	it:	
dentification duty	: ADR/SDR Cl. 3 Pt. 31 c	Force	d Time		Temperature	e of componen	it:	
Shelf life:	12 months cool/dry	Techn	ical data:					
Mixing ratio: 1)	2)		-cut test					
With hardener:		DIN 53 Hardn	ess acc. to:					
Pot life:			oall jet:					
Coverage:	16 m ² /l		el bend test:					
with dry film thick	ness of 35 microns		on cupping in	dex IE:				
Temperature ran	ge: - 40°C to + 120°C		oray test:		5 % 80 days			
Dry film melting-p	oint:		nich test:					
1) Weight	2) Volume 3) On smooth	surface Conde	DIN 50018 Condensed water climate: > 100 days			6		
Surface prepara	tion: Dry, dust-free, oil- a		-D-148, DIN 9	51359			ng Fluid W	A/
Features:	Non water displacir							
Duration of prot	ection: Indoor storage up to	o 4 years / ou	tdoor sto	rage up to	2 years			
Removal, cleani	ng: With petroleum, arc steam or hot-water							
Supplier:	Valvoline Oil Co. Lt Tel. +41 (0) 1/446 5		str. 175, F	P.O. Box, C	CH-8005 Zu	ırich, Switze	erland	
	n are mean values based and at user's risk with rega					ing to the su	upplier's	
	1							
<i>O</i>	RTA / RT-flex	GUIDEL	-	R ENGI	NE PROT TEST	ECTION		oup 45
VARTSILA								

	osion-protective product	Waxy, prese	, dry, gr rvation	ip-dry and ex	protectiv	ve film for rotection	long-term		
Name of product:	TECTYL 5006W	<u> </u>				No: ication No: tute for Spec.	No:		
General and phys Oil-based cor emulsifiable v	rosion preventive	 5		ate res	istant to a	atmospherio	c influences osphere ar		
Application Terr	perature: 10°C to 35°C		Applica methe		Thinner %	Viscosity	Spraying pressure	Nozzle mm	k/ Oh
Hun	nidity:	E	Brush	Yes					
Colour:	milky white	F	Roller	Yes					
Degree of gloss:	wax-like, consistent	[Dipping	Yes					
Covering power:			Spraying: ow press.	Yes					
Density:	1090 kg/m ³ at 20°C		high press.	Yes					
Content of solids	40 %	ļ	Airless	Yes					
Viscosity:	DIN 4 - 20°C - 30 sec.		Electro- static	Yes					
Danger class:	none	[Drying: Air	dust-	set to touch	completely dry	Reco spraying	atable after:	1
Poison class:	none		20°	free 1,5h	2 hrs	3 hrs	no	r	10
Flash point:	none (emulsion)	(Oven	Time 1	1∕₂ h	Temperature	of componen	t: max.	60°C
Identification duty	r: no	F	Forced	Time 1	1 ½ h	Temperature	of componen	t: max.	60°C
Shelf life:	cool/dry + 5°C to + 35°C	1	Fechnical da	ata:					
Mixing ratio: 1)	2)	0	Cross-cut te	st					
With hardener:			DIN 53151 Hardness ad	c. to:					
Pot life:			Steel ball jet	:					
Coverage:	10 m²/l	Ν	DIN 53154 Mandrel ben	d test:					
with dry film thick	ness of 40 microns	3) E	DIN 53152 Ericcson cupping index IE:			-			
,	ge: - 30°C to + 120 °C	· [DIN 53156 Salt-spray te	est:		5 % > 240 hrs			
Dry film melting-p	-	٢	DIN 50021 Kesternich t	est:					
1) Weight	2) Volume 3) On smooth s		DIN 50018 Condensed	water clir	nate:	> 240 hrs			
i) wought	, , ,	A	ASTM-D-14		359		surface		
, ,	Surface treated with						5011000.		
Surface prepara									
, ,	Storage: protect aga								
Surface prepara	Storage: protect aga Treated parts should	d only be	taken o	utside	when cor	npletely dr	/.		
Surface prepara Features: Duration of prot	Storage: protect aga Treated parts should ection: Indoor storage up to	<u>d only be</u> o 4 years	<u>taken o</u> / outdoo	or stora	age up to	2 years			
Surface prepara	Storage: protect aga Treated parts should ection: Indoor storage up to	d only be 0 4 years matic-fre	e taken o / outdoo e white s	or stora spirit, a	age up to a	2 years			
Surface prepara Features: Duration of prot	Storage: protect aga Treated parts should ection: Indoor storage up to ng: With petroleum, aro hot-water cleaner w Valvoline Oil Co. Lto	d only be o 4 years matic-fre ith corros d., Hardtu	e taken o / outdoo e white s sion prot	or stora spirit, a ection	age up to alkaline so additive	2 years baker, stea	m or	erland	
Surface prepara Features: Duration of prot Removal, cleani Supplier:	Storage: protect aga Treated parts should ection: Indoor storage up to ng: With petroleum, aro hot-water cleaner w Valvoline Oil Co. Lto Tel. +41 (0) 1/446 5	d only be 0 4 years matic-fre ith corros d., Hardtu 0 50	e taken o / outdoo e white s sion prot urmstr. 1	or stora spirit, a ection 75, P.	age up to alkaline so additive O. Box, C	2 years baker, stea H-8005 Zu	m or rich, Switze		
Surface prepara Features: Duration of prot Removal, cleani Supplier: The data give	Storage: protect aga Treated parts should ection: Indoor storage up to ng: With petroleum, aro hot-water cleaner w Valvoline Oil Co. Lto	d only be o 4 years matic-fre ith corros d., Hardtu 0 50 on practic	e taken o / outdoo e white sion prot urmstr. 1 cal expe	or stora spirit, a ection 75, P. rience	age up to alkaline so additive O. Box, C	2 years paker, stear H-8005 Zu ion accordi	m or rich, Switze		
Surface prepara Features: Duration of prot Removal, cleani Supplier: The data give	Storage: protect aga Treated parts should ection: Indoor storage up to ng: With petroleum, aro hot-water cleaner w Valvoline Oil Co. Lto Tel. +41 (0) 1/446 5 n are mean values based of	d only be o 4 years matic-fre ith corros d., Hardtu 0 50 on practic	e taken o / outdoo e white sion prot urmstr. 1 cal expe	or stora spirit, a ection 75, P. rience	age up to alkaline so additive O. Box, C	2 years paker, stear H-8005 Zu ion accordi	m or rich, Switze		
Surface prepara Features: Duration of prot Removal, cleani Supplier: The data give	Storage: protect aga Treated parts should ection: Indoor storage up to ng: With petroleum, aro hot-water cleaner w Valvoline Oil Co. Lto Tel. +41 (0) 1/446 5 n are mean values based of	d only be o 4 years matic-fre ith corros d., Hardtu 0 50 on practio rd to clim	e taken o / outdoo e white s sion prot urmstr. 1 cal expe	or stora spirit, a ection 75, P. rience I speci	age up to alkaline so additive O. Box, C . Applicati fic conditi	2 years baker, stear H-8005 Zu ion accordi ons. IE PROT	m or rich, Switze ng to the su	upplier's Gro	oup 45
Surface prepara Features: Duration of prot Removal, cleani Supplier: The data give	Storage: protect aga Treated parts should ection: Indoor storage up to ng: With petroleum, aro hot-water cleaner w Valvoline Oil Co. Lto Tel. +41 (0) 1/446 5 n are mean values based o and at user's risk with rega	d only be o 4 years matic-fre ith corros d., Hardtu 0 50 on practio rd to clim	taken o / outdoo e white sion prot urmstr. 1 cal expenatic and	spirit, a ection 75, P. rience speci	age up to alkaline so additive O. Box, C . Applicati fic conditi R ENGIN R SHOP	2 years baker, stear H-8005 Zu ion accordi ons. IE PROT	m or rich, Switze ng to the su	upplier's Gro	45

Type of corrosion-protective product Dry	protective	ecoat	for short	-term pres	ervation		
Name of product: TECTYL 5805 W				No: Tication No:	No:		
General and physical properties:	Protection	against:					
Oil-based corrosion preventive	Industria	al atmo	sphere in		door storage		
emulsifiable with water Application Temperature: 10°C to 35°C	Applica		st atmosp Thinner	Viscosity	Spraying	as rain, e Nozzle	tc.
	meth	od	%	Tieseenty	pressure	mm	Ö
Humidity:	Brush	No					
Colour: yellowish	Roller	No					
Degree of gloss: Oily	Dipping	Yes					
Covering power:	Spraying: low press.	Yes					
Density: 900 kg/m ³ at 20°C	high press.	Yes					
Content of solids: NONE	Airless	Yes					+
Viscosity: 17 mm ² /s at 40°C	Electro-	No					+
Danger class: NONE	static Drying:	dust-	set to touch	completely	Recoa	atable after:	
	Air	free		dry	spraying	<u> </u>	
Poison class: NONE	20°C		(2 hrs	<u> </u>	<u> </u>	
Flash point: 140°C	Oven	Time ¹	_	Temperature	of component	t: max.	60°
Identification duty: NONE	Forced	Time 1	∕₂ h	Temperature	of component	t: max.	60°
Shelf life: 12 months cool/dry	Technical d	ata:					
Mixing ratio: 1) 1:4 2) 1:10	Cross-cut te DIN 53151	est					
With hardener:	Hardness a	cc. to:					
Pot life:	Steel ball je	et:					
Coverage: 150 - 400 m ² /l	DIN 53154 Mandrel be	nd test:					
	DIN 53152 Ericcson cu	ippina inda	ex IE:				
•	DIN 53156 Salt-spray t						
Temperature range: - 10°C to + 50°C	DIN 50021						
Dry film melting-point:	Kesternich DIN 50018						
1) Weight 2) Volume 3) On smooth surface	e Condensed ASTM-D-14			Mixture 1:3	> 10 days		
Surface preparation: Dust-free, oil- and grease				ed to moist	surfaces.		
Features: Storage: protect against results in milky emulsion	frost. Mixab	le in ev	very ratio	with water,			
Duration of protection: Indoor storage up to 6 m	onths, depe	ending	on mixtur	e ratio			
Removal, cleaning: If required, with petroleur steam or hot-water clean	n, aromatic	-free w	hite spirit	, alkaline so additive	oaker,		
Supplier: Valvoline Oil Co. Ltd. Har Tel. +41 (0) 1/446 50 50		-			ich, Switze	rland	
The data given are mean values based on prospecification and at user's risk with regard to					ng to the su	upplier's	
						1	
RTA / RT-flex	UIDELINE	-	R ENGIN	-	ECTION		oup 45

Type of corrosion-protective product Rus	st-prevent	ing oil	for prese	ervation a	nd lubricat	ion	
Name of product: TECTYL 910 / TECTYL 930			Article				
				cation No: ute for Spec.	No:		
General and physical properties:	Protection				gressive air	, etc	
Oil-based corrosion preventive. Stays oil, does not become gummy.					nd rain, etc		
MIL-L-21260 B+C, API SF/CD							
Application Temperature: 0°C to 50°C	Applica meth		Thinner %	Viscosity	Spraying pressure	Nozzle mm	
Humidity:	Brush	Yes					
Colour: yellow-brown	Roller	Yes					
Degree of gloss: Wet gloss	Dipping	Yes					
Covering power:	Spraying: low press.	Yes					
Density: 880 - 890 kg/m ³ at 15°C	high press.	Yes		1			
Content of solids: NONE	Airless	Yes					
Viscosity: 910: VG46 930: VG100	Electro- static	Yes		1			
Danger class: NONE	Drying: Air	dust- free	set to touch	completely dry	Recoa spraying	atable after:	
Poison class: free BAG T No. 611 500		nee		u.y	opraying		
Flash point: 218-230°C in closed pot	Oven	Time	I	Temperature	of component	t	
dentification duty:	Forced	Time		Temperature	of component	t:	
Shelf life: 24 months cool/dry	Technical da	ata:					
Mixing ratio: 1) 2)	Cross-cut te DIN 53151	st					
With hardener:	Hardness ad	cc. to:					
Pot life:	Steel ball jet DIN 53154	t:					
Coverage: 910:140 930:110 m ² /I	Mandrel ber DIN 53152	nd test:					
with dry film thickness of 5 - 7 microns 3)	Ericcson cu DIN 53156	pping ind	ex IE:				
Temperature range: - 20°C to + 50°C	Salt-spray te DIN 50021	est:	F	passed 20 hrs			
Dry film melting-point:	Kesternich t DIN 50018	est:					
1) Weight 2) Volume 3) On smooth surface	Condensed		nate:	Jan-791 7	20 hrs with	out finding	
Surface preparation: Dry, dust- and grease-free	ASTM-D-14 surface	8, DIN 51	359			_	
Features:							
Duration of protection: Indoor storage 6 - 24 mont	ths. depen	dina o	n climatic	conditions			
Removal, cleaning: Normally not necessary. If		-					
Supplier: Valvoline Oil Co. Ltd. Hard	•			1-8005 Zur	ich. Switze	rland	
Tel. +41 (0) 1/446 50 50		,			, •		
The data given are mean values based on prac					ng to the su	ipplier's	
specification and at user's risk with regard to cl	limatic and	l speci	tic condition	ons.			
· · · · · · ·							
				E PROT	FCTION	-	
C RTA / RT-flex GU	IDELINE					Grou 034	

Type of corrosion term	n-protective product				s, dry, grip xternal pr		ective film	for long-
Name of product: TEC	CTYL 175GW; 185 G	W; 132				No: cation No: ute for Spec.	No:	
General and physical p Oil-based corrosic			atmosph	atmos nere ar	spheric infl	uences, ao uch as SO	gressive in $_2$ and acid	
Application Temperat	ure: 10°C to 35°C		Applica		Thinner	Viscosity	Spraying pressure	Nozzle k
Humidity:			meth Brush	yes	%		pressure	mm O
Colour: yel	low		Roller	no				
Degree of gloss: Wa	ху		Dipping	no				
Covering power:			Spraying:	no				
Density: 95	0 kg/m ³ at 20°C		low press. high press.	no				
Content of solids: 65	± 3 %		Airless	yes				
Viscosity:			Electro- static	yes				
Danger class: A-I	I		Drying: Air	dust-	set to touch	completely dry	Re-co spraying	patable after:
Poison class: fre	e BAGT No. 611 500		20°C	free 2 h	5 h	10 h	зргаунту	
Flash point: 43	°C in closed pot		Oven	Time	1	I Temperature	of componer	nt:
Identification duty: AD	R/SDR cl. 3 zif. 31c		Forced	Time		Temperature	of componer	nt:
Shelf life: 12	months cool/dry stora	age	Technical d	ata:				
Mixing ratio: 1)	2)		Cross-cut te DIN 53151	est				
With hardener:			Hardness a	cc. to:				
Pot life:			Steel ball je DIN 53154	t:				
Coverage: 5 n	n²/I		Mandrel ber DIN 53152	nd test:				
with dry film thickness	of 100 microns	3)	Ericcson cu DIN 53156	pping ind	ex IE:			
Temperature range: -	23°C to + 175°C		Salt-spray t DIN 50021	est:	Ę	5 % at 75 n	nicrons, 15	00 h
Dry film melting-point:			Kesternich test: DIN 50018					
1) Weight 2) Ve	olume 3) On smooth	surface	Condensed ASTM-D-14					
Surface preparation:	Dry, dust-free, oil- a and TECTYL 506 c		ase-free s			reated with	Dewaterir	ng Fluid WA
Features:	Non water displacir	ng.						
Duration of protectio	n: Indoor storage up t			or stor	age up to 3	3 years.		
Removal, cleaning:	Immersion-resistan With petroleum, arc hot-water cleaner w	omatic-fr	ree white			aker; stea	m or	
Supplier:	Valvoline Oil Co. Lt Tel. +41 (0) 1/446 5	50 50						
	e mean values based at user's risk with rega						ng to the s	upplier's
			BBBBBBBBBBBBB					T
<i>C</i> Värtsilä –	RTA / RT-flex	GUI		-	R ENGIN	E PROT TEST	ECTION	Group 0345
VANUISILA	wn: K.Luethi 27.10.09	T						

17.0.0 Overview of regular inspection lists during engine storage

Mainly four lists have to be used during engine storage:

- 17.0.1 Inspection List for general parts purpose
- 17.0.2 Inspection List for dehumidifier
- 17.0.3 Inspection List for time-dependant inspections or moving of parts
- 17.0.4 Inspection List for final delivery inspection
 - (carried out at engine maker / see chapter 9.0) Same list to be used for "Inspection upon arrival" (carried out at shipyard / see chapter 11.0)

17.0.1 Inspection List for general parts purpose

The below-mentioned inspection record list for the inspection of engine and/or parts is for reference only, as every person responsible for storage may create his/her own list, as long as the 7 items given in the list below are mentioned in a way or other and clearly identified respectively.

If possib Part inspected	Re- coated Yes/No	re and hur Temp. °C	nidity should b Humidity %	e recorded in th Signature	e same daytin Date	ne period Rema (e.g. ru visible	st
<i>O</i> Wärtsilä	RTA / RT-1	lex	GUIDELIN	E FOR ENGI AFTER SHOP		CTION	Group 0345
	Drawn: K.Luethi 2 Verify: B.Schumacher	27.10.09 27.10.09	Н	4-107.42	26.585		65 / 70

Date	Total hour	Temp (°C)	Humidity (%rh)	Humidity (%rh)	Humidity (%
			Crankcase	Piston underside	Camshaft hou

Once a week	Lubrication of Check oil lev Operation of Move the fue	d with main lube oil pump running f the cylinder liners el in the fuel system the cooling water pumps I regulating linkage	
Unce a week	Lubrication of Check oil lev Operation of Move the fue	f the cylinder liners el in the fuel system the cooling water pumps	
Once a week	Check oil lev Operation of Move the fue	el in the fuel system the cooling water pumps	
Unce a week	Operation of Move the fue	the cooling water pumps	
Once a we	Move the fue	• · ·	
Ouce			
5	remperature	and humidity recording	
	Inspection/re	-coating of blank metal parts	
	mapeeuonine		
	Inspection of	the crankcase	
		the piston underside	
	-	the exhaust manifold	
		nain starting shut-off valve	
Once a month		nidifying system (filter, hoses, etc.)	
9 0 0		r of the turbocharger(s) by 90°	
		liary blower(s) by hand	
	Inspection of	a cross head bearing pin	
uns	Inspection of	a main bearing journal pin	
ee montns	Replacemen	of the silica gel desiccant bags	
96	Analysis of th	e cooling water	
<u> </u>	Analysis of th	ie system oil	
а.			

17.0.4. Inspection List for final delivery inspection / inspection upon arrival

Final delivery inspection (carried out at engine maker / see chapter 9.0)
Inspection upon arrival (carried out at shipyard / see chapter 11.0)

This parts list can/should be used for: Final delivery inspection (at engine maker) & Inspection upon arrival (at shipyard)

No.	Part - Designation	Inspe Yes		Signature	Date	Remar k (e.g. rust visible)
1	Crankshaft					
2	Main bearing shell					
3	Main bearing cover					
4	Jacking bolt main bearing (For RTA52U ; RTA62U-E RTA72U-B ; RTA84T-D or	3;				
5	Crank web					
6	Crankpin : web journal & m journal	ain				
7	Gear wheels					
8	Thrust bearing					
9	Thrust bearing pads					
10	Bottom end bearing					
11	Connecting rod					
12	Crosshead bearing					
13	Crosshead guide shoes					
14	Piston rod					
15	Piston					
16	Exhaust valve					
17	Bedplate: machined surfac	æs				
18	Column: machined surfac	es				
19	Column (guide rails)					
20	Cylinder block					
21	Tie rods					
22	At cyl. block top					
23	At bedplate bottom					
24	Diaphragm					
25	Piston rod gland					
26	Cylinder liner					
27	Scavenge ports					
28	Anti-Polishing ring					
29	SAC cooler					
	RTA / RT-flex	GUIDEL	INE FOR ENGI		ON	Group 0345
WARTS Värtsilä Switzer	Drawn: K.Luethi 27.10.09		4-107.42	26 585		68 / 70

30	Cylinder cover				
31	Fuel injectors				
32	Combustion space				
33	Starting air valve				
34	Starting air shut-off valve				
35	Exhaust valve cage				
36	Exhaust manifold				
37	Scavenge air receiver				
38	Auxiliary scavenge air blower				
39	Flywheel				
40	Turning gear				
41	Electric motor				
42	RTA fuel pump block				
43	Starting air distributor				
44	Camshaft/reversing servomotor				
45	Linkage local manoeuvring stand				
46	RT-flex Supply Unit				
47	All flanged SU parts				
48	High-pressure fuel pumps				
49	Servo oil pumps				
50	Rail unit box				
51	Fuel oil rail				
52	Injection Control Unit (ICU)				
53	Servo oil rail				
54	Exhaust valve drive		1	1	
55	High-pressure pipes to fuel injectors				
56	Electronic cabinets				
57	All relief valves				
58	Turbocharger				

18.0 Engine tools

The engine tools should be stored in a clean, well ventilated and dry place; in addition they need to be protected against corrosion. It is advisable to check the condition and completeness of the engine tools to avoid any problems during commissioning and engine hand over.

-	1				
WÄRTSILÄ	RTA / RT-flex	GUIDE	ELINE FOR ENGINE PROTECTIO AFTER SHOP TEST	N	Group 0345
Wärtsilä Switzerland Ltd.	Drawn: K.Luethi 27.10.09 Verify: B.Schumacher 27.10.09	Н	4-107.426.585		69 / 70

Т

19.0 Spare parts

All spare parts must be firmly secured to prevent any movement. Metal-to-metal contact is to be avoided during storage of any components. All open ports, adapters, pipes, etc. are to be sealed in order to prevent ingress of foreign particles.

All spare parts have to be protected against corrosion. Large components should be treated with 'Valvoline' Tectyl 506 or a suitable equivalent. Smaller components, with the exception of electronic equipment, may be wrapped in a corrosion-protective VCI paper.

20.0 <u>Health protection and safety at work</u>

The official statutes and regulations for occupational hygiene and technical equipment measures are to be stringently observed, and the working conditions with cleaning agents and corrosion protective products have to be allowed for.

Samples of safety mask & safety goggle which are to be used:



20.2 Engine dismantling

Engines transported as part assemblies are to be systematically disassembled and cleaned using dry cloths. Each item is to be clearly identified with 'paint ball' pen, similar indelible marker ink or figure and letter stamps, and protected from damage by careful crating as well as corrosion protected by rust preventing oils or paper (see section 20.1). To ensure correct reassembly and eliminate the risk of parts from one cylinder unit being fitted to another by mistake, it is indispensable that bearings and running gear are clearly marked cylinder by cylinder. Use a paint brush to apply high-viscosity rust preventing oil to the piston and connecting rods, crosshead guides, gear wheels, camshaft and rollers. Air powered spray guns are to be used only if the air is absolutely free of water. Crankshaft and crosshead pins are to be protected with an anti-corrosive coating of Tectyl 506 or a similar product.

20.3 Removing rust preventing oils

Rust preventing oils applied to the internal parts of an assembled engine do not contain thickening agents of wax or bitumen. These oils have properties similar to the engine lubricating oils, will wash off easily and mix without causing harm to the engine or its systems.

Rust preventing oils of the wax-type applied to exposed surfaces of the engine components do contain thickening agents of wax or bitumen forming an anti-corrosion coating when applied, which has to be washed off using a proprietary 'cold cleaner'. It is not sufficient to use gas oil, kerosene or white spirit on their own as solvents; they are to be mixed with 2 to 3 parts of a 'cold cleaner', such as 'Magnusol', 'Agitol' or 'Emultan'.

20.4 Engine installation

The alignment and chocking of the engine should be carried out in accordance with our recommendations and is subject to test and inspection by the relevant classification society. Each stage of the engine mounting is to be checked by qualified personnel and measurements cross-checked with the design figures. The responsible parties (e.g. shipyard) are to advise the representative of the engine builder or Wärtsilä Switzerland Ltd. directly in the event of any discrepancies. Engines may be installed as complete units or assembled from sub-assemblies in the vessel, which may be afloat, in dry dock, or on the slipway. The engine alignment can be done with either jacking screws or wedges.

20.4.1 Installation and assembly of subassemblies

When the engine seating has been approved, the bedplate is lowered onto blocks placed between the chocking points. The thickness of the blocks depends on the final alignment of the engine. Engine bedplates comprise fabricated sections with drilled holes to allow the passing of the holding-down bolts and tapped holes for the jacking screws for engine alignment.

Proceed with the preliminary alignment of the bedplate using one of the methods mentioned in section 20.4 to position the engine coupling flange to the intermediate shaft coupling flange. Ensure that the gap between both flanges is close to the calculated figures and that both flanges are exactly parallel on the horizontal plane (max. deviation 0.05 mm). In the vertical plane, the engine coupling flange is to be set 0.4 to 0.6 mm higher than the calculated figures. Place bearing caps in position, install turning gear and check that crankshaft deflections are as recorded on the "Engine Assembly Records". To check the bedplate level in longitudinal and diagonal direction a taut-wire measuring device will be provided by the engine builder. Compare the readings with those recorded at works. Optical devices or lasers may also be used.

All final dimensions are to be witnessed by the representatives of the engine builder and the classification society and to be recorded on appropriate log sheets. Crankshaft deflections at this stage are to correspond with the values recorded at works. Secure the bedplate temporarily against unexpected movement.

Continue engine assembly by mounting the columns, cylinder blocks, running gear and scavenge air receiver, but ensure that the bearing caps are loose before tensioning the tie rods. Make periodic checks of the crankshaft deflections to observe and correct any possible engine distortions. Careful adjustments of the wedges or of the jacking screws are necessary to re-establish the preliminary alignment setting. Once the engine assembly is completed, the final alignment and chocking is carried out with the vessel afloat.

20.4.2 Installing a complete engine

In the event that the engine is shipped in part deliveries and assembled at the shipyard before installation in the vessel, the shipyard is to undertake the assembly work in accordance with the demands of a representative of the engine builder and the classification society. The engine mounting is to be carried out systematically and measurement readings taken, recorded on appropriate log sheets and compared for correctness with the data of the "Engine Assembly Records" completed after test run in the works of the manufacturer.

NOTICE

Strict attention is to be paid to the removal of anti-corrosion coatings and the subsequent application of rust preventing oil where required.

The engine is to be lowered onto blocks placed between the chocking points. The alignment tools are to be clean and ready for use. Set the blocks in such a manner that the engine is slightly higher than the final position, because less effort is required to lower the engine than to raise it for alignment.

For movements in the horizontal plane, both in lateral or longitudinal directions, the shipyard is to construct appropriate anchor points for the use of hydraulic jacks. Such movements have to be carried out with great care to avoid stresses and distortions to the bedplate. Regular crankshaft deflection readings have to be taken to observe the effects, and any noticed deviations have to be rectified immediately.

20.4.3 Installing an engine from assembled subassemblies

Subassemblies of the engine may be assembled ashore before installation in the ship. One such assembly may comprise bedplate, main and thrust bearings, crankshaft, turning gear, and flywheel. The placing on blocks and alignment to shafting is analogue to the description in section *20.4.1*.

20.4.4 Engine installation with ship on slipway

Installing complete or partially assembled engines in ships under construction on an inclined slipway is possible when careful attention is paid to the following:

- 1 Suspending large components to take account of the incline
- 2 Tie rods to be centred and exactly perpendicular to the bedplate before tightening
- 3 Fit temporary side, fore and aft arresters to prevent the engine from moving during launching
- 4 Attach additional temporary stays at the upper platform level to steady the engine during launching.

21. Engine and Shaft alignment

21.1 Procedure

21.1.1 Drawings

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Engine Alignment, Direct-Coupled Marine Propulsion, W5-8X40 2005

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0	Contents
1	Introduction
1.1	Preface
1.2	Validity of this instruction
1.3	Responsibilities
1.4	Wärtsilä alignment services
1.5	Aim of alignment
2	Alignment in brief
3	Shaft bearing arrangement / Optimum bearing distances
4	Alignment layout calculation
4.1	Whirling calculation
4.2	Calculation basics and definitions
4.3	Wärtsilä's alignment program EnDyn integrated engine models
4.4	Two-dimensional crankshaft model
4.5	Calculation for cold condition
4.5.1	Basic principle: main bearing load distribution
4.5.2	Recommended static main bearing loads, alignment layout calculation condition
4.6	Calculation for hot condition
4.7	Calculation for running condition
5	Alignment steps and alignment checks before chocking
5.1	Shaft and engine alignment by gap & sag method
5.2	Bedplate bending curves
5.2.1	Bedplate bending in relation to the engine temperature
5.2.2	Engine pre-sag
5.2.3	Bedplate bending measurement: piano-wire or laser measurement
5.3	Static shaft bearing loads, before chocking condition
5.4	Crankweb deflection limits for new alignment, before chocking condition
5.4.1	Validity of new alignment crankweb deflection limits
5.4.2	Description of new alignment crankweb deflection limits
5.4.3	Overview: limits for crankweb deflection before chocking
5.5	Recommended static main bearing loads, before chocking condition
5.5.1	Jack correction factors
5.5.2	Influence of crank angle on bearing load
5.6	Chocking and fixation
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6	Alignment checks for commissioning / ship delivery
6.1	Static shaft bearing loads, commissioning / ship delivery condition45
6.2	Crankweb deflections, commissioning / ship delivery condition45
6.2.1	Validity of crankweb deflection limits for commissioning / ship delivery 45
6.2.2	Description of crankweb deflection limits for commissioning / ship delivery45
6.2.3	Overview: crankweb deflection limits for commissioning / ship delivery 46
6.3	Recommended static main bearing loads, commissioning / ship delivery condition
7	Alignment checks during normal ship's service
7.1	Crankweb deflection limits for normal ship's service
7.1.1	Validity of crankweb deflection limits for normal ship's service
7.1.2	Description of crankweb deflection limits for normal ship's service50
7.1.3	Overview: crankweb deflection limits for normal ship's service51
7.2	Minimum main bearing load in ship's service condition under any draught condition

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1 Introduction

1.1 Preface

This instruction aims to facilitate the complete alignment process, from the initial shafting arrangement design stage to the final normal ship's service operation condition. The objective is an easy and trouble-free alignment by guiding through this process. The final goal is a safe and trouble-free propulsion system operation over the complete ship's lifetime.

The instruction contains different kinds of information:

- General information and background information to provide better technical understanding of alignment procedures
- Guidelines and guidance values, guiding through the alignment process
- Alignment limits which have to be kept in order to ensure safe propulsion system operation.

1.2 Validity of this instruction

This instruction is valid for direct-coupled Wärtsilä two-stroke engines under the conditions mentioned in the following.

A proper bearing arrangement is the prerequisite for proper engine and shaft alignment. Section 3, p.13 provides further information. If the bearing arrangement does not fulfil the mentioned requirements, the guidance values of this instruction are **not applicable**. All data mentioned in this instruction are only valid for *standard installations* of the mentioned Wärtsilä two-stroke engines on board of seagoing vessels. The term *standard installations* means:

- the bearing arrangement fulfils the requirements defined in section 3, p.13
- no additional heavy masses like shaft generators are installed on the shaft line.

In case of non-standard installations it is strongly recommended to contact Wärtsilä¹. However, even for standard installations it is not possible to cover all possible installation variants and their characteristics, as the ship design varies². Therefore the given guidance values can only provide strong indication whether the alignment is acceptable or needs to be improved. In some special cases the guidance values might be exceeded, while the alignment is acceptable, and vice versa. In case of

Case-specific guidance values will be defined according to the basic approach of this instruction.

² Ship design in general, frame arrangement and design, properties of applied steel, tank arrangements, applied components, etc.

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any doubts, Wärtsilä can provide case-specific support. Wärtsilä case-specific instructions supersede the general values provided in this document. All engine type-specific data provided in this instruction are valid for all crankshaft executions, e.g. FCV1, FCV2, FCV3.

Finally, after ship delivery it is essential that under all normal operating conditions all bearings are statically loaded and the crankweb deflections do not exceed the admissible limits (= aim of alignment, as explained in following section 1.5, p. 6). The referred crankweb deflection limits are provided in table 7.1, p. 52, and the main bearing³ load limits are provided in table 7.2, p. 53.

1.3 Responsibilities

It is the shipyard's responsibility to guarantee that the final ship service requirements will be kept under all operation conditions. The referred crankweb deflection limits are provided in table 7.1, p. 52, and the main bearing load limits are provided in table 7.2, p. 53. Guidelines on how these requirements can be fulfilled are given in this instruction. However, Wärtsilä does not take any responsibility for the correctness of these guidance values.

As long as Wärtsilä is not involved as direct contractual partner, Wärtsilä will just provide technical support and issue comments if requested, e.g. whether an alignment condition meets Wärtsilä's expectations or not. Therefore Wärtsilä only provides guidelines and proposals for the complete alignment process, but will not specify the exact way of working, as this remains within the shipyard's responsibility.

1.4 Wärtsilä alignment services

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Wärtsilä provides various services concerning the engine and shafting alignment of direct-coupled two-stroke marine diesel engines. Certain services, e.g. the review of the shafting arrangement during design stage, are free of charge, whereas other services, e.g. complete shafting alignment calculations, will be charged to the purchaser, except when otherwise stipulated. A special service exclusively provided by Wärtsilä is the offer of a special alignment calculation program which includes all portfolio engines as full three-dimensional models for quick and easy alignment calculations. This program is provided on order and free of charge to Wärtsilä's licensees and shipyards installing a Wärtsilä engine⁴. Further information concerning Wärtsilä services can be found in the document 'Engine / Shafting Alignment - Scope of Services'.

³ The abbreviation *mb* is used for *main bearing*.

⁴ Wärtsilä agrees to the use of this program in parallel also for other alignment projects, e.g. four-stroke installations, different engine brands, etc. The program is suitable for such tasks. In connection with Wärtsilä products the full advantage of the program can be utilised as more detailed information can be provided.

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For additional information, ordering alignment layout calculation, any kind of alignment review or requesting the EnDyn alignment program⁵, please contact Wärtsilä, e.g. by email to: <u>application.engineering.ch@wartsila.com</u>. Onsite support for alignment execution can be ordered from Wärtsilä field service: <u>fieldservice.ch@wartsila.com</u> or by contacting the local Wärtsilä office.

1.5 Aim of alignment

All bearings need to be statically loaded under all conditions! (The term 'all bearings' refers to all shaft line bearings as well as to all engine main bearings.) In addition, all crankweb deflections – engine stopped – need to be within the service limits under all ship service conditions.

In order to get this requirement fulfilled, the following three principles have to be considered, mentioned in sequence of decreasing priorities:

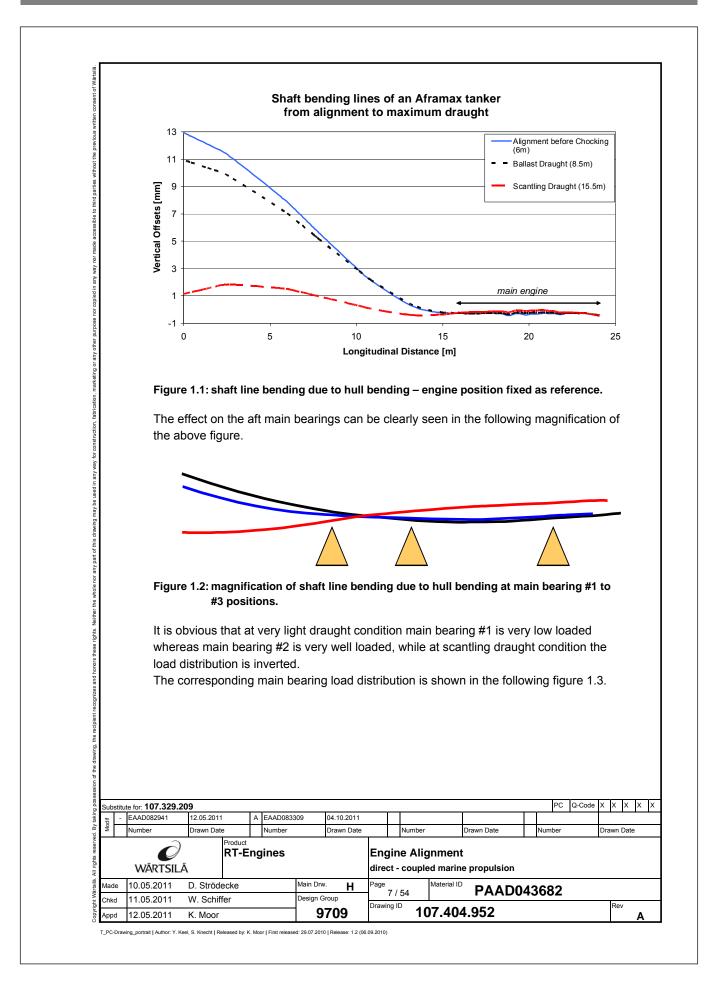
- 1. The influences on bearing load distribution need to be kept small⁶.
- 2. The various influences on the shaft line and the engine during the ship's lifetime need to be considered in the alignment process, i.e. the expected changes due to the different influences⁷ need to be pre-compensated.
- 3. Take care of the new crankweb deflection limits during engine installation⁸.

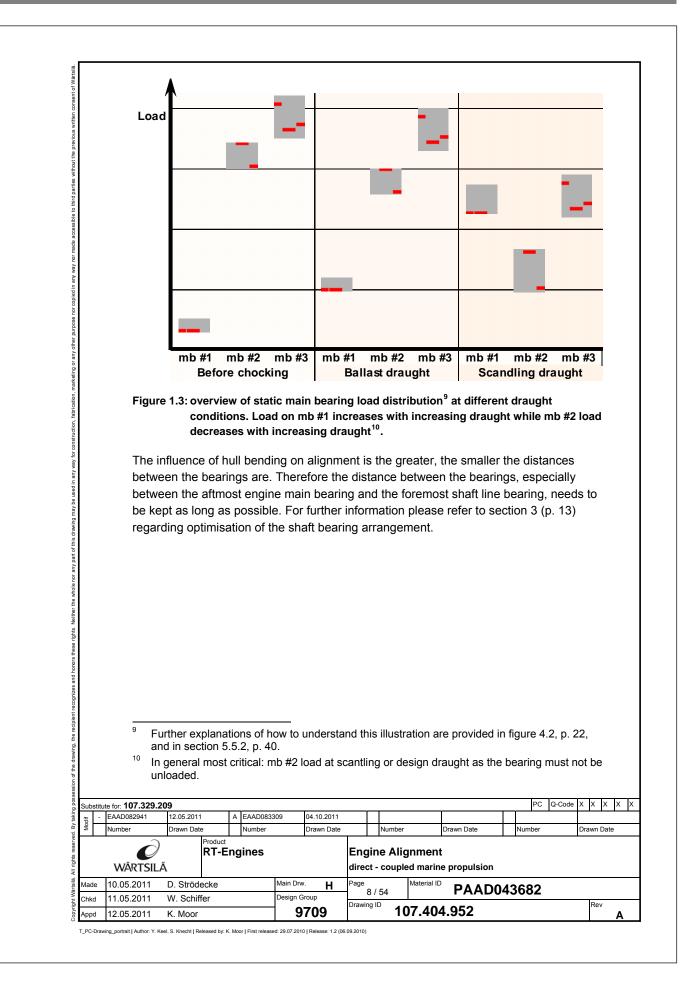
The main influence on the shafting system is the ship's hull bending. It is obvious that the aft hull section of the engine bends downwards with increasing draught. The engine alignment in new ship buildings is performed at very light draughts and therefore the hull bending due to increasing draughts needs to be pre-compensated. The following figure shows a typical shaft bending line of an Aframax tanker. It is obvious that the aft end bends downward with increasing draught.

⁵ Please ask regularly, e.g. when starting a new project or about every 6 months, for updates in order to have up-to-date documentation at hand.

- ⁶ See section 3, p. 13.
- ⁷ Mainly ship hull bending; see figure 1.1, p. 7.
 - Lowest priority: in some special cases Wärtsilä might introduce case-specific limits.

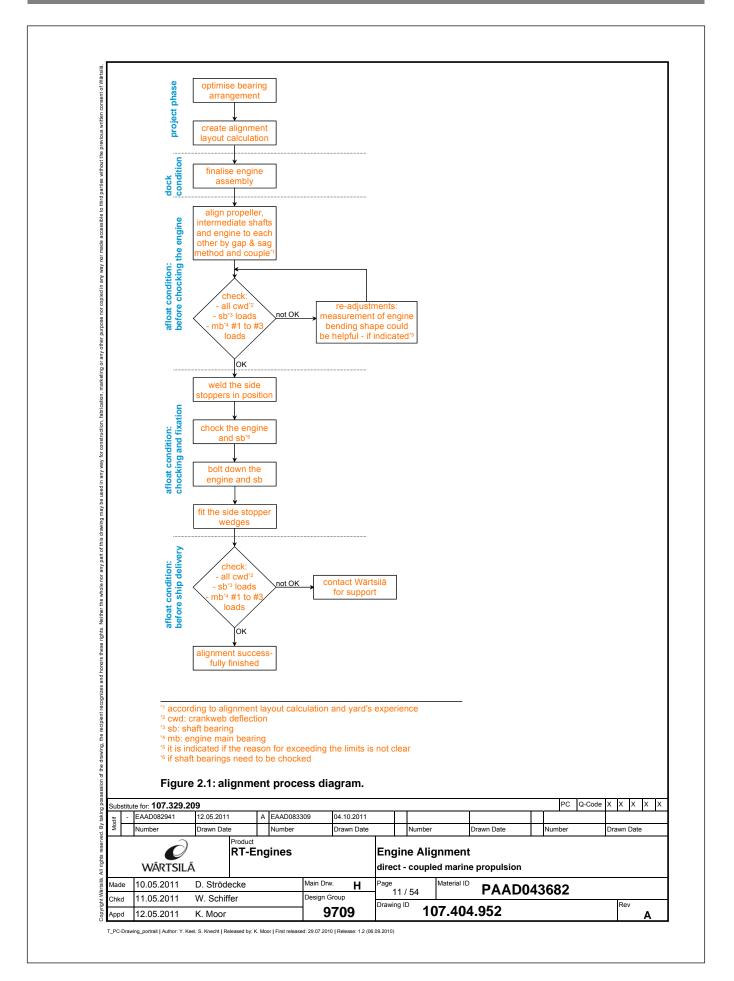
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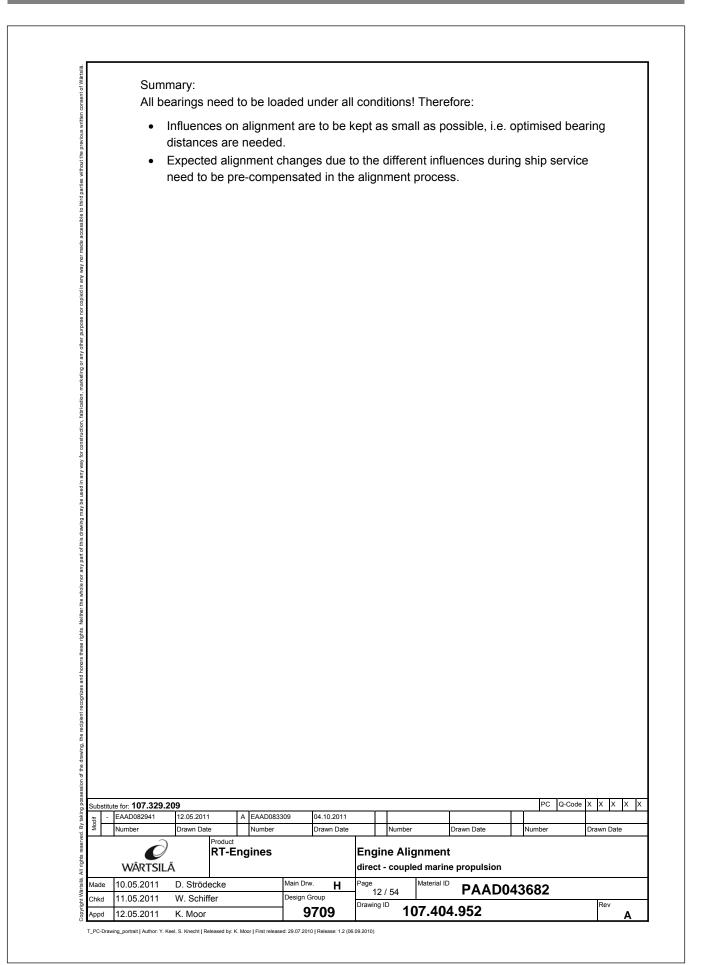




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3 Shaft bearing arrangement / Optimum bearing distances

The key to a successful propulsion system installation is an optimized bearing arrangement. It is essential to optimise the distances¹⁸ between the shaft line bearings as recommended by the following in order to avoid poor shaft and main bearing performances.

In case of too long bearing distances the risk of whirling vibration with its negative effects will be increased.

On the other hand, in case of too short bearing distances, the risk of excessive bearing load changes will be increased. In such cases the bearing design loads may easily exceed both the upper and the lower limits, even more down to totally unloaded bearings; this means the system will be out of its (approved!) design. The following problems may be expected in case of unloaded bearings:

- In case of totally unloaded shaft line bearings, the distance between the still loaded bearings may become too long, i.e. whirling vibration may become a problem.
- In case of a totally unloaded engine main bearing (usually main bearing #2), engine main bearing damage may occur, namely on the unloaded bearing itself or on another engine main bearing due to vibration effects, as the engine is then operated out of design.
- In addition, an unloaded bearing means that its load has to be carried by other bearings, which might then become overloaded.

Optimum shaft bearing distances are the most important prerequisite for proper alignment. On the one hand, too long bearing distances may, as mentioned, lead to whirling vibration, while on the other hand too short bearing distances cause excessive static bearing load changes due to ship hull bending. Furthermore, in case of too short bearing distances, the bearings are relatively low loaded and consequently the risk for unloading is quite significant. According to experience, designs with too long bearing distances are very seldom, but with too short distances oftentimes.

The usual maximum limit for bearing distances can be calculated according to the following guidance formula¹⁹ by putting the outer shaft diameter d_{shaft} in millimetres, resulting in the maximum bearing distance x_{max} in millimetres:

$$\mathbf{x}_{\max} = 450\sqrt{\mathbf{d}_{\text{shaff}}} \tag{3.1}$$

The following table gives an approximative overview on the recommended optimum bearing distances. However, for a detailed layout please apply formula 3.2.

¹⁸ Also required by class rules.

¹⁹ Formula of GL class. Confirmed by Wärtsilä experience.

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Shaft diameter	Recommended optimum intermediate bearing distances, including distance foremost intermediate bearing to main bearing #1
400 mm	6.5 m to 8 m
600 mm	8 m to 10 m
800 mm	9 m to 11.5 m

Table 3.1: guideline for recommended bearing distances.

As mentioned in section 1.2, p. 4, this instruction is only valid for standard installations in new ship buildings which consider the following rules of bearing distances:

• The distance x_{actual} between the aftmost engine main bearing #1 and the forward shaft line bearing is in a range of

$$67\% \mathbf{x}_{\text{max}} \le \mathbf{x}_{\text{actual}} \le 90\% \mathbf{x}_{\text{max}}$$
(3.2)

• Or at least within the exceed range of

$$60\% x_{\text{max}} \le x_{\text{actual}} \le 100\% x_{\text{max}}$$
(3.3)

If it is necessary to apply the extended range, Wärtsilä should be contacted. Installations with distances outside the limits given in above formula 3.3 are not at all recommended and not covered by this instruction.

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4 Alignment layout calculation

From the engine installation aspect, the binding alignment layout calculation is created for the real alignment condition as it can be found on board the vessel, i.e. for very light draught conditions with engine cold and stopped (as it is not yet installed). During the installation process this allows referring directly to the calculation and finally makes it possible to compare the alignment measurement results directly with the calculation. However, the later ship operation conditions need to be considered in the layout calculation as well. From the shaft line installation aspect, the so called 'running condition' is the most important calculation, as the influence of the propeller forces and moments on the shafting system can be checked. The aim is to achieve reliable static loads on all bearings in all ship service conditions.

In the calculation the following influences need to be considered:

- Ship hull bending
- Engine temperature
- Propeller service forces.

Detailed information about ship hull bending, which could be used as an input for the alignment layout calculation, is usually not available. In such cases the ship hull bending needs to be considered based on experience. An increase of ship draught generally leads to a more hogging shape of the engine and shaft line foundation. This causes a load shift from main bearing #2 – and to a very low extent also from main bearing #3 – to main bearing #1. This means, the more ship hull bending is expected, the less load on main bearing #1 and the more load on main bearing #2 has to be adjusted.

The following exemplary ship hull bending can be expected:

- VLCC and bulk carriers have most hull bending due to the huge difference between ballast and scantling draught. In the alignment layout calculation²⁰ and during the alignment process, loads just above zero should be adjusted for main bearing #1.
- Container vessels have less hull bending than VLCC and bulk carriers, but still significant.
- Gas tankers have quite limited hull bending.
- Car carriers have only very limited hull bending.

In those cases where the hull bending is known, the alignment calculation has also to be carried out for the alignment condition as mentioned before, but in addition it is possible to carry it out for any other service draught condition. At least the ballast

²⁰ Cold / stopped condition.

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4.1	Whirling calculation
	Whirling calculations are required from the engine's ²⁴ perspective if:
	 demanded by the classification society or other involved parties bearing distances exceed the normal maximum limit (see formula 3.1, p. 13) no forward stern tube bearing is installed shaft generator or shaft motor is installed in case of very low loaded shaft bearings (less than 15% of design load) For all other cases no whirling calculation is needed from the engine's perspective.
4.2	Calculation basics and definitions
	Independent of which alignment calculation program is used, the following basics need to be taken into account:
	 alignment is carried out in stopped condition, the static structure stiffness (without oil film) has to be taken. Bearing clearance, at least for the engine main bearings, as otherwise a low loaded main bearing might be calculated with negative load. The shaft line model used in the calculation program has to provide a realistic picture of the real installation. If the EnDyn alignment program is used, also the real bearing load measurement positions should be included, as this allows calculating the expected jack-load curves. A direct comparison between the jack-load curves calculated in the layout
	calculation and the really measured jack-load curves is possible. This is very helpful to evaluate the alignment.
	helpful to evaluate the alignment.
	 ²⁴ Two-stroke engine's perspective. In contrast, the whirling calculation is always needed for four-stroke installations. ²⁵ While non-observance of shaft bearing stiffness will just produce inaccurate calculation results, non-observance of main bearing stiffness may produce totally wrong results, i.e. even the load distribution trend might not be correct.
- EAA	 ²⁴ Two-stroke engine's perspective. In contrast, the whirling calculation is always needed for four-stroke installations. ²⁵ While non-observance of shaft bearing stiffness will just produce inaccurate calculation results, i.e. even the load distribution trend might not be correct. <u>25 IO7.329.209 PC Q-Code X X X X</u>
EAA	 ²⁴ Two-stroke engine's perspective. In contrast, the whirling calculation is always needed for four-stroke installations. ²⁵ While non-observance of shaft bearing stiffness will just produce inaccurate calculation results, i.e. even the load distribution trend might not be correct. <u>25 IO7.329.209 PC Q-Code X X X X</u>
V lade 10.	 ²⁴ Two-stroke engine's perspective. In contrast, the whirling calculation is always needed for four-stroke installations. ²⁵ While non-observance of shaft bearing stiffness will just produce inaccurate calculation results, i.e. even the load distribution trend might not be correct. 25 <u>IOC Que X X X X Description of the standard of the s</u>

The definitions used in the calculation need to be clear:

- Definition of gap & sag, e.g. sag referring to the centre line or to the top sides of flanges. This consideration is important if the coupling flange pair has different diameters.
- Definition of reference / datum line, e.g. defined by the forward and aft stern tube bearings, by the main engine position, etc.
- Definition of bearing offset, e.g. difference between datum line and centre of unloaded bearing²⁶.

4.3 Wärtsilä's alignment program EnDyn integrated engine models

It is strongly recommended to use the EnDyn calculation program for alignment layout calculations of Wärtsilä two-stroke diesel engines, as it provides accurate and detailed results. The program incorporates the full three-dimensional FE based models of all actual portfolio RT-flex and RTA engines. No further modelling by the user is required, only the correct crankshaft type needs to be selected.

Before starting a new project, it should be ensured that the latest release of the EnDyn program is available. The EnDyn calculation program can be ordered by licensees and shipyards free of charge (see also section 1.4, 'Wärtsilä alignment services' on page 5).

4.4 Two-dimensional crankshaft model

Two-dimensional²⁷ crankshaft models are provided for use, if other programs than EnDyn are used for preparing the alignment calculations. The relevant information is given in figure 4.1, p. 20, along with the data in table 4.1, p. 20. As common use, these models simulate the reduced stiffness of the crank by a cylinder of similar stiffness. The two-dimensional crankshaft model is also known under the name 'equivalent crankshaft model'. However, a two-dimensional crankshaft model provides only a very limited picture of reality, as the content of information is quite limited. Consequently the results deviate from reality and therefore the naming 'equivalent crankshaft model' might be misleading.

The two-dimensional crankshaft models provide similar results²⁸ for static main bearing loads as obtained from the EnDyn integrated three-dimensional FE crankshaft models at crank angle (CA) 0 degree position (aftmost crankpin in top dead centre). But this applies only to the three aftmost engine main bearings.

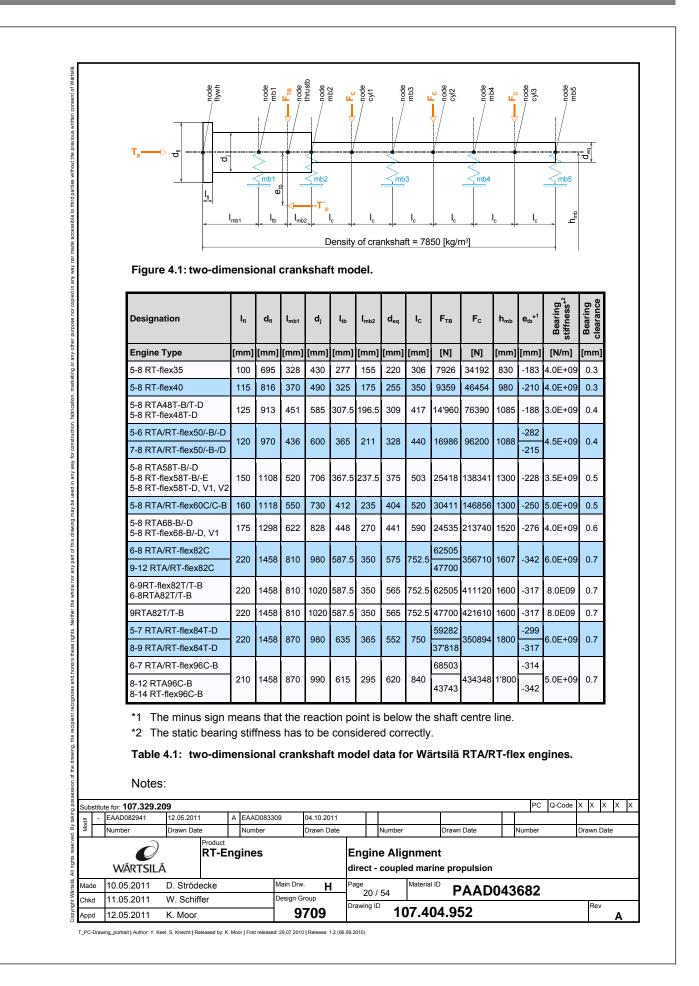
²⁶ This definition is used by Wärtsilä.

²⁷ Two-dimensional under the aspect that just the element lengths and diameters are considered.

²⁸ It is essential to apply the model exactly as described in this instruction (e.g. considering the bearing stiffness), otherwise the calculation results are not valid!

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The reason is that th bearing load is different for different crank angles, i.e. while turni the turning gear, the static bearing loads are continuously chang by the geometry of the cranks where the vertical bending stiffnees crank angle position due to the crank geometry; contrary to that stiffness of a simple shaft is independent of the turning angle due symmetrical rotary geometry. The loads calculated by applying the dimensional crankshaft model consists of the following elements of a simple shaft is independent of the cranks is for each support of 0°CA, i.e. dead centre position, as this is the reference condition 30. Please 5.5.2, p. 40. The two-dimensional crankshaft model consists of the following element (if arranged on thrust collar) • Main coupling flange and thrust shaft • Cylinders of similar stiffness in the range of the cranks • Forces to simulate the masses of cranks, running gears, thrust or wheel (if arranged on thrust collar) • Elastic main bearings with clearance. 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For such calculation a realistic calculation model considering the geometry of the cranks is required, e.g. as it is contained in the EnDyn program. Direct comparison between the calculated and measured static loads for main bearings #2 to #n (foremost main bearing). The reason is that the static main bearing load is different for different crank angles, i.e. while turning the engine with the turning gear, the static bearing loads are continuously changing. This is caus by the geometry of the cranks where the vertical bending stiffness depends on th crank angle position due to the crank geometry; contrary to that the vertical stiffness of a simple shaft is independent of the turning angle due to the symmetrical rotary geometry. The loads calculated by applying the two-dimensional crankshaft model refer to the condition of 0°CA, i.e. cylinder #1 in to dead centre position, as this is the reference condition ³⁰. Please refer to section 5.5.2, p. 40. The two-dimensional crankshaft model consists of the following elements: Main coupling flange and thrust shaft Cylinders of similar stiffness in the range of the cranks Forces to simulate the masses of cranks, running gears, thrust collar and gear wheel (if arranged on thrust collar) Elastic main bearings with clearance.



It is mandatory to use the full two-dimensional crankshaft model as described in figure 4.1, p. 20, and above table 4.1.

This includes the aftmost main bearing #1 up to main bearing #5 as well as their elastic supports. The elasticity of the main bearing supports refers to stopped conditions – that means no oil film is considered, corresponding to the actual condition during the alignment process and the jack-up tests. Alignment calculations which do not consider the correct elasticity of engine main bearing supports are wrong and consequently cannot be judged with the Wärtsilä limits and recommendations.

4.5 Calculation for cold condition

This is the calculation for the condition at which the real alignment will be carried out.

4.5.1 Basic principle: main bearing load distribution

As introduced in section 4, p. 15, the ship hull bending influence on the bearing loads needs to be pre-compensated by adjusting the appropriate bearing loads during the alignment process. It is expected that static load will be transferred from main bearing #2 – and to a limited degree also from main bearing #3 – to main bearing #1. The expected extent of total load shift depends on the shaft arrangement and the vessel type, i.e.:

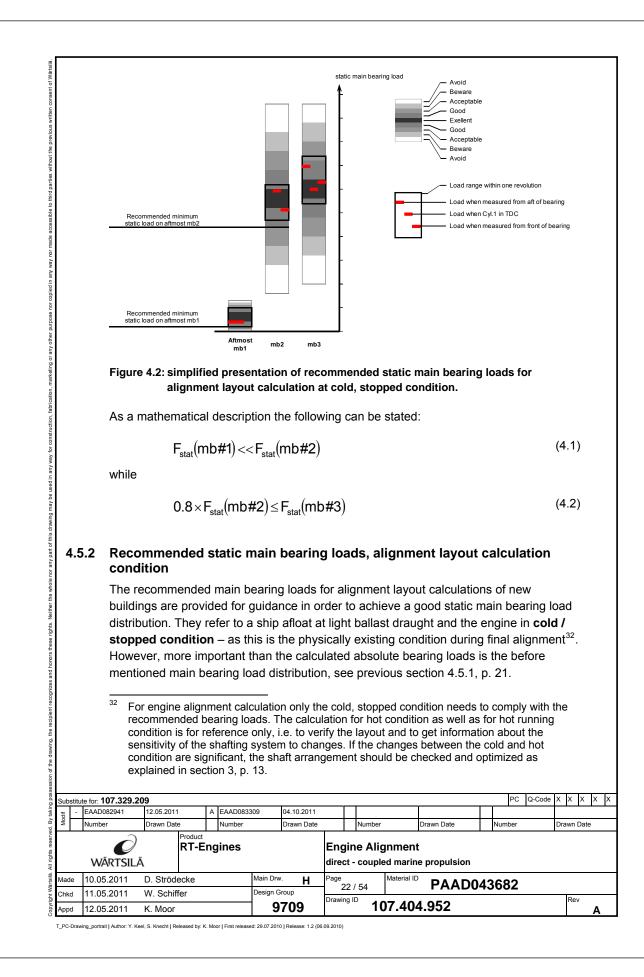
- the closer the distance between main bearing #1 and the foremost intermediate bearing, the more load shift is expected
- the bigger the difference between alignment and scantling draught, the more load shift is expected.

Consequently, in the alignment layout calculation low load has to be defined for main bearing #1; the less load, the more load change is expected.

Figure 4.2 below gives a simplified general overview on the recommended bearing load³¹ distribution between main bearings #1 to #3.

¹¹ Further information regarding the indicated load range box and the red lines therein is provided in section 5.5.2, p. 40.

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	mb #1* ³	ed cold condition mb #2	mb #3* ⁴	mb #4 to n ³³
RT-flex35	4-15	30-45	30-45	>15
RT-flex40	5-20	45-70	45-70	>20
RT-flex48T-D RTA48T-D	10-35	70-140	70-140	>35
RTA48T-B RT-flex50-D RT-flex50-B	10-40	80-150	80-150	>35
RT-flex50 RT-flex58T-E RT-flex58T-D, V1, V2 RTA58T-D RT-flex58T-B RTA58T-B	10-60	120-210	120-210	>35
RT-flex60C-B RT-flex60C	10-65	140-220	140-220	>35
RT-flex68-D, V1 RTA68-D RT-flex68-B RTA68-B	10-90	190-280	190-280	>50
RT-flex82C RTA82C	10-130	310-460	310-460	>90
RT-flex82T-B RT-flex82T RTA82T-B RTA82T	5-120	360-540	360-540	>90
RT-flex84T-D RTA84T-D	5-110	320-480	320-480	>90
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4.6 Calculation for hot condition

The alignment layout calculation for hot condition considers the following:

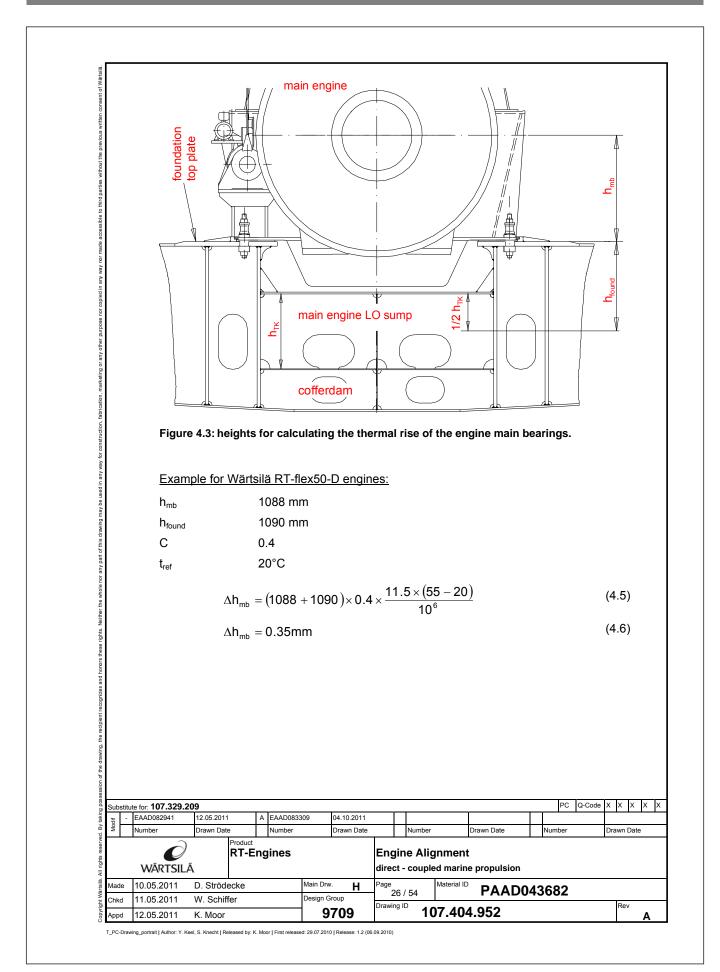
• the thermal rise of the engine main bearings

It is possible to consider in addition the thermal rise of the shaft bearings. However, as the distances between the shaft bearings are quite long, this influence can be usually neglected. Otherwise, the shaft bearing thermal rise has to be considered analogous as described in the following for the main bearings.

The recommended static loads provided in previous table 4.2 are valid for new buildings at very light ship draught in cold/stopped condition. The results of alignment layout calculations which refer to cold/stopped condition are used to align the shafts and the engine. Also the verification of alignment before chocking and fixation refers to cold / stopped condition at very light ship draught. Additional conditions contained in the alignment layout calculations are calculated for verifying the alignment result. The hot condition calculation provides information about the sensitivity of the shafting system regarding the thermal rise " Δh_{mb} " of the engine main bearings. If the changes between the cold and hot condition are significant, the shaft arrangement should be checked and optimized as explained in section 3, p. 13.

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				bearing offsets	s is calculate	ed with t	o the follo	win	g formula	
	(dime	nsions in	[mm]):							
		Δh_n	$_{nb} = (h_{mb}$	$+h_{found}) \times C \times -$	11.5×(t _{eng} - 10 ⁶	$-\mathbf{t}_{ref}$				(4.3)
		_{ւժ} is not av ing formul		the stage of al be used:	lignment lay	out calc	ulation pr	epa	ration, the	9
		∆h _n	$_{\rm nb} \approx {\rm h}_{\rm mb} \times$	$D \times \frac{11.5 \times (t_{enq})}{10^6}$	$g - t_{ref}$					(4.4)
	Δh_{mb}	[mm]	therma	al rise of all eng	gine main be	earings f	rom cold	to h	ot conditi	on
	h _{mb}	[mm]	height	between bedp	late bottom	and cra	nkshaft c	entr	e line	
	h _{found}	[mm]		from the middl ate of the engin			ink below	ma	in engine	to the
	С	[-]	accord	tion factor ³⁵ , us ling to shipyarc ence is availab	d's experien	ce with o	current sh			10
	D	[]	correc	tion factor for s	implified ca	Iculatior	of therm	al ri	se: 0.75	
	t _{eng}	[°C]	engine	e operating tem	perature (de	efault: 5	5°C)			
	\mathbf{t}_{ref}	[°C]		nce temperatur rts and engine	e during ali	gnment	for founda	atior	n, shaft be	earing
				applied as finally		ermal rise	of the eng	gine	in relation	to the
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	 service-related forces and momen The thermal rise of the engine The maximum axial propeller The maximum bending mome eccentricity 	e main bearings thrust
	 The maximum axial propeller The maximum bending mome eccentricity 	thrust
	The maximum bending mome eccentricity.	ent at the thrust bearing due to the thrust bearing
	-	ant calculation under the aspect of shaft bearing fied under consideration of the following influences:
	 propeller service forces, whic tube bearing to the next forwa the next intermediate bearing some minor changes on the r misalignment between propel tube bearing, will change. The bending moment produce 	ed by the propeller thrust eccentricity as well as the h will mainly shift static bearing load from the aft stern ard bearing, i.e. to the forward stern tube bearing or , if no forward stern tube bearing is installed. Also nore forward bearings can be seen. In addition the ler shaft and the aft, respectively the forward stern ed by the thrust bearing eccentricity, which will reduce iate bearing next to the engine.
	It has to be checked that under the allowable range.	s condition the bearing loads are still within the
	importance from the engine's point calculation is a static calculation; g into account. Therefore the calcula calculation provides only very limit with unloaded main bearing #1 is f bearing loads ³⁶ are not acceptable However, the full propeller thrust c	ondition will not act at alignment draught condition, equently the result can only provide a general
	³⁶ Considering the given bearing clea	arance.
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Alignment steps and alignment checks before chocking

Before starting the final alignment, the engine has to be finally assembled and the main ship components, especially the superstructure, need to be installed and finally welded. In addition all major welding operations in the vicinity of the engine have to be completed.

For all alignment measurements it is important to keep the external influences on the measurement as limited as possible. This means that:

- draught changes during the measurements have to be avoided as far as possible, i.e. no ballasting operation, no movement of heavy parts like hatch covers, etc.
- local heat sources have to be avoided, i.e. lubricating oil sump tank heater has to be shut off, no welding works in vicinity of the propulsion system, etc.

It is strongly recommended to carry out the final alignment in afloat condition³⁷! Please consider the validity of this instruction as well as its guiding characteristic as described in section 1, p. 4 at the beginning of this instruction. An overview of the alignment steps is given in section 2, p. 9 and by the alignment

5.1 Shaft and engine alignment by gap & sag method

process diagram in figure 2.1, p. 11.

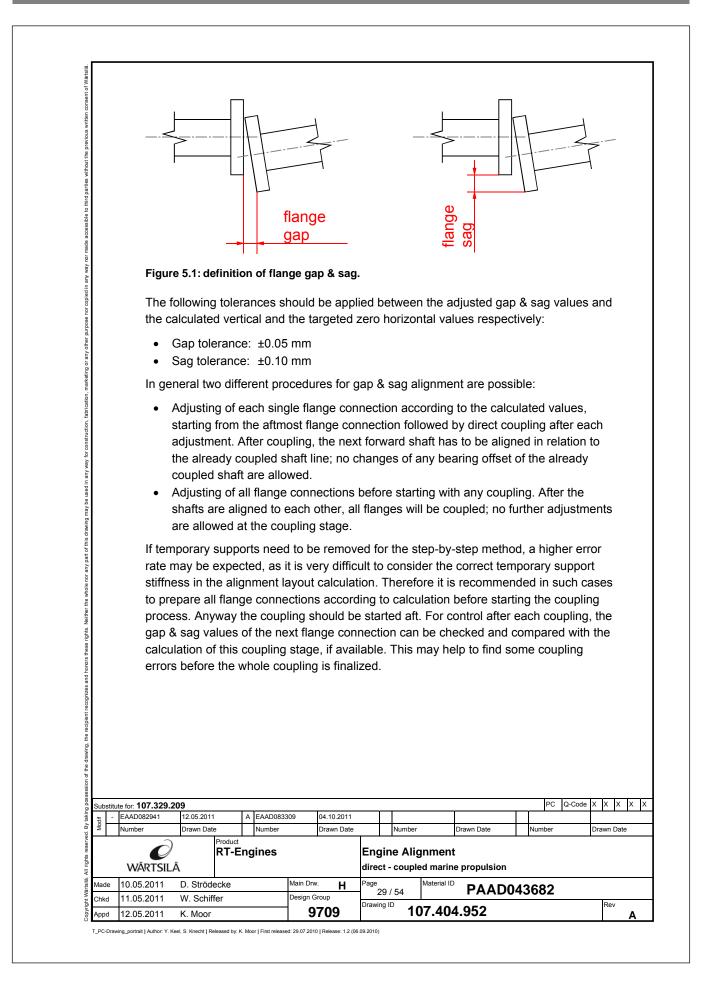
Propeller and intermediate shafts are aligned to each other by applying the gap & sag method, i.e. the uncoupled shaft flanges are aligned to each other in such a way that the vertical gap & sag between the flanges comply with those of the alignment layout calculation.

In the horizontal plane the shaft line has to be aligned straight, i.e. the horizontal gap & sag values have to be zero.

Before starting the gap & sag alignment, a reference crankweb deflection measurement might be taken according to shipyard's experience.

⁷ It is within the responsibility of the shipyard to carry out the final alignment including chocking of the engine according to their experience already gained at the dry dock. However, the risk of a possibly required re-chocking has to be born in mind.

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5.2 Bedplate bending curves

The bedplate of an engine installed in the ship is not always ideally straight. This is caused mainly by:

- the influence of engine temperature
- the installation tolerances

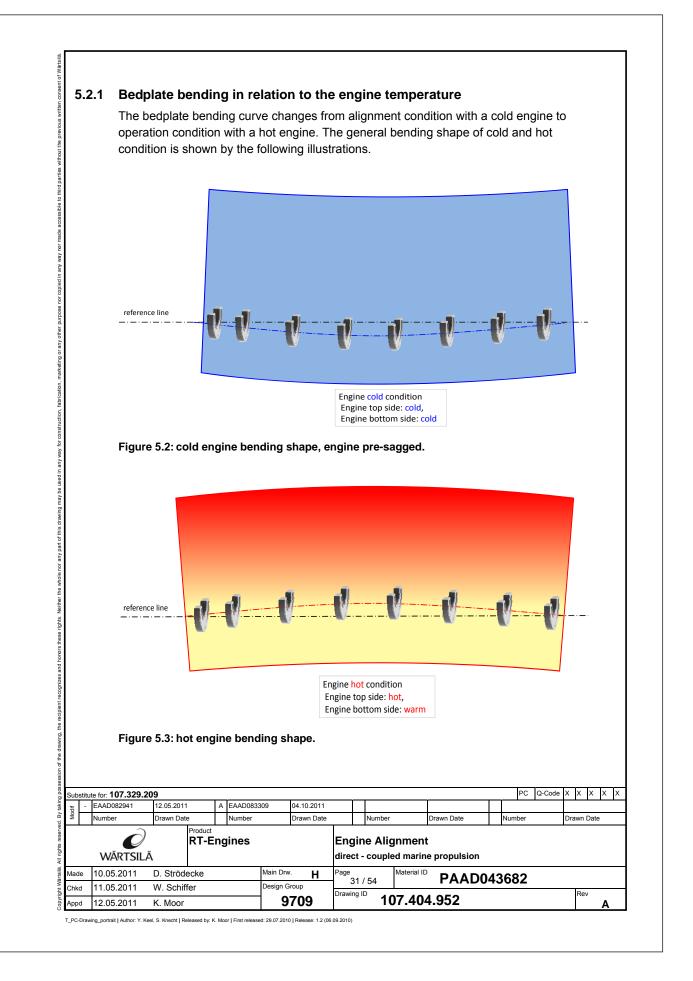
getting the alignment properly done.

• the ship hull bending.

In general an ideal straight bedplate can be considered as being the optimum for engine operation. However, more important than straightness is that the bedplate bending line is as smooth as possible, i.e. without kinks. From the alignment point of view the interesting thing is not the bedplate bending itself, but its influence on the main bearing offsets. However, measuring the main bearing offsets directly is not possible, but it is possible to measure the bedplate bending shape on both sides of the bedplate by a piano wire or laser measurement. However, direct information regarding the bearing offsets can be obtained by analysing the crankweb deflection measurement results together with the bearing load measurement results, as it is done by Wärtsilä, if a review of the alignment measurement results is ordered. Therefore the bedplate sag measurement has a negligible priority regarding the final alignment check criteria and consequently Wärtsilä does not ask any longer for the bedplate measurement as a criterion for alignment approval (please refer to figure 2.1, p. 11). The main function of the bedplate bending measurement is to find the possible reasons if horizontal or vertical crankweb deflections as well as bearing loads are not within the required range. This

means, the measurement of the engine bedplate shape can be considered as a tool for

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5.2.2 Engine pre-sag

As the bedplate bending shape will change to hogging for hot condition, the engines may be installed with some pre-sag for pre-compensating the expected change. However, as long as all crankweb deflections are within the limits, no special care for engine pre-sag is required. More positive crankweb deflections³⁸ of cylinders #2 to #n-1, measured before chocking, give an indication that the engine is pre-sagged. Experience has shown that more important than pre-sagging is that the bedplate bending is as smooth as possible, i.e. the variation from one main bearing measurement position to the next is as low as possible in relation to the actual sag curve. Consequently **the pre-sag measurement is not any longer a check criterion for alignment confirmation**.

It is not at all recommended to support the engine only in its four corner positions in order to adjust a pre-sag. This is of disadvantage in the aspect of smooth engine bending. It is much more preferable to have less or no pre-sag instead of distorting the bedplate. The engine has to be supported by all supporting points (wedges or jacking screws), as indicated on the engine installation drawings.

5.2.3 Bedplate bending measurement: piano-wire or laser measurement

The engine **bedplate bending measurement is no longer a check criterion for alignment confirmation**. However, this measurement should be considered as a perfect **tool for aligning the engine**. The bedplate bending measurement is recommended in case the alignment criteria 'bearing load distribution' and / or 'crankweb deflections' exceed the limits and the reason for that needs to be investigated further (see also the alignment process diagram in figure 2.1, p. 11). Exceeding vertical crankweb deflections as well as unexpected bearing load distributions might be reflected in a sharp upward respectively downward bending change. Correcting the engine bending shape can help solving the problem. Exceeding horizontal crankweb deflections which are not caused by an improper horizontal alignment between engine and shaft might be reflected in different bending shapes on both of the engine's longitudinal sides. Correcting the engine bending to similar shapes on both longitudinal sides can help solving the problem.

5.3 Static shaft bearing loads, before chocking condition

The static loads of all shaft bearings – except the aft stern tube bearing which is not accessible – need to be checked by jack-up test measurements. The loads must comply with the alignment layout calculation. Usually this is considered as being the case if the measured loads are within a tolerance range of $\pm 20\%$ of the loads determined by the alignment layout calculation.

¹⁸ Sign definition: _/+__\-/_

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It is essential to carry out these measurements directly before or after the engine alignment checks and under the same measurement conditions, i.e. same draught, same temperature conditions (engine, tanks in vicinity), etc. Taking such complete sets of measurements is needed as engine, shaft line and propeller make up one common propulsion system³⁹; consequently this also needs to be considered as one system during the evaluation. Hence Wärtsilä asks for information about the shafting system as well as the shaft bearing load measurement results, if Wärtsilä is required to review the engine alignment. However, the shaft alignment is not within the responsibility of Wärtsilä Switzerland.

5.4 Crankweb deflection limits for new alignment, before chocking condition

The absolute crankweb deflection limits are increasing from the most strict testbed reference measurement condition⁴⁰ to the final ship service condition⁴¹. Compared to the absolute crankweb deflection limits for final service, the 'before chocking' condition limits are still quite strict. This is to provide sufficient reserves for later changes produced by the influences of engine operation and ship hull bending. The absolute vertical and horizontal crankweb deflections indicate different aspects:

- The absolute vertical crankweb deflections are related to the main bearing offsets and by that to the static main bearing loads.
- The absolute horizontal crankweb deflections indicate the twisting of the engine housing, which has to be avoided. Therefore the limits for the absolute horizontal crankweb deflections are of utmost importance and as a consequence more stringent than those for the absolute vertical crankweb deflections.

The main purpose of the crankweb deflection limits is to ensure proper engine running behaviour.

These three parts are coupled rigidly, i.e. without any flexible coupling or gear.
 This measurement is taken from the uncoupled cold engine on the testbed as a basic

reference.

¹¹ This is the maximum which must not be exceeded. Exception: Wärtsilä provided casespecific values, based on detailed case-specific investigations.

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5.4.1 Validity of new alignment crankweb deflection limits

These limits are valid for the <u>completely assembled engine</u> on board the <u>afloat</u> <u>vessel</u>⁴² before chocking the engine. The <u>flywheel is installed</u> and the <u>tie rods are</u> <u>correctly tightened</u> according to latest engine assembly instruction. The engine is <u>cold</u> and <u>coupled</u> to the shaft line, i.e. all intermediate and propeller shafts are coupled and temporary supports are removed. No tank heating close or below the engine is active. **These limits are not valid** for any other measurements on board the vessel⁴³.

5.4.2 Description of new alignment crankweb deflection limits

Compared to the limits for the inner cylinders, the positive⁴⁴ vertical crankweb deflection limit for cylinder #1 is increased to more positive. This is due to the typical shaft bending line at alignment condition, see figure 1.1, p. 7. The described shaft line shape is a result of pre-compensating the expected ship hull bending at increased draught conditions; usually the ship hull bending at increasing draught conditions causes decreasing (less positive) cylinder #1 crankweb deflections.

The vertical crankweb deflection limit for the foremost engine free-end cylinder allows more negative values in case of an installed external mass like a T/V damper or a front disc, as the more negative crankweb deflection is caused by the bending moment created by the external mass. This is fully acceptable and – even more – required in order to keep all main bearings statically properly loaded.

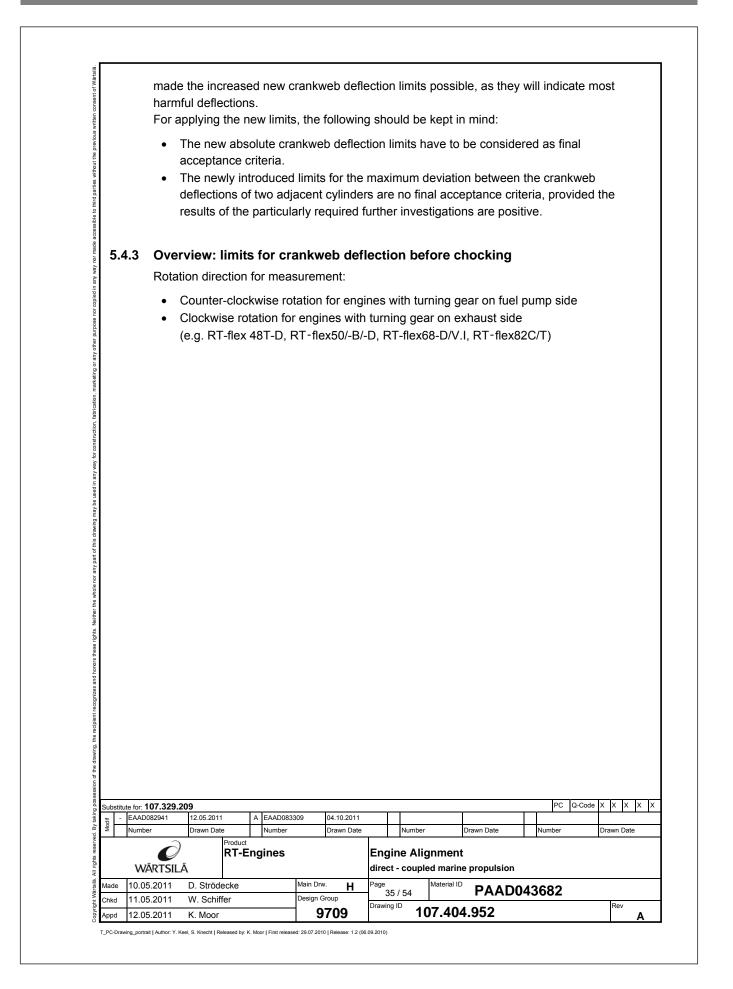
It has to be kept in mind that the crankweb deflection measurement results provide quite complex information. Therefore the limits provided in this document may not cover all possible installation cases and situations. Hence Wärtsilä may provide case-specific limits, if indicated⁴⁵.

For the vertical as well as for the horizontal crankweb deflections, the maximum deviations between two adjacent crankweb deflections have to be checked. The maximum values provided in the deflection limit tables have an indicator function⁴⁶, as huge deviations between two adjacent cylinders give the indication that there might be some deficiencies. In such cases further investigations are required; Wärtsilä should be contacted. Depending on the particular investigation results, the crankweb deflections might be accepted or countermeasures might be recommended. These additional limits

⁴² New ship building

- ⁴³ In case of an engine re-alignment on board vessels already in service, values between 'before chocking' and 'ship delivery' can be applied. Wärtsilä should be contacted for further assistance.
- ⁴⁴ Sign definition: _/+_ _\-/_
- ⁴⁵ Based on detailed case-specific investigation results.
- ⁴⁶ These values are no final acceptance limits.

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Reading convention: /+\ RT-flex35 RT-flex40 RT-flex48T-D RTA48T-D	cyl.1 +0.16 -0.10	cyl.2 to cyl.(n-1) cyl.(n)* ¹	cyl.(n)* ²	max. absolute		max.
RT-flex40 RT-flex48T-D				deviation between two adjacent cranks* ³	cyl.1 to cyl.(n)	absolute deviation between two adjacent cranks* ³
RT-flex48T-D		±0.10	+0.10 -0.17	0.10	±0.04	0.04
	+0.20	±0.13	+0.13	0.13	±0.06	0.06
	+0.36	±0.22	+0.22	0.22	±0.09	0.09
RTA48T-B RT-flex50-D	-0.22 +0.36	.0.00	-0.36 +0.22	0.00	.0.00	0.00
RT-flex50-B RT-flex50 RT-flex58T-E	-0.22	±0.22	-0.37	0.22	±0.09	0.09
RT-flex58T-D, V1, V2 RTA58T-D		±0.24	+0.24	0.24	±0.10	0.10
RT-flex58T-B RTA58T-B RT-flex60C-B	-0.24 +0.33	10.00	-0.52 +0.20	0.20	10.00	0.00
RT-flex60C RT-flex68-D, V1	-0.20 +0.53	±0.20	-0.40 +0.32	0.20	±0.08	0.08
RTA68-D RT-flex68-B RTA68-B	-0.32	±0.32	-0.55	0.32	±0.13	0.13
RT-flex82C RTA82C	+0.37 -0.23	±0.23	+0.23 -0.40	0.23	±0.09	0.09
RT-flex82T-B RT-flex82T RTA82T-B	+0.59	±0.36	+0.36	0.36	±0.14	0.14
RTA82T RT-flex84T-D	-0.36 +0.53	±0.32	-0.64 +0.32	0.32	±0.13	0.13
RTA84T-D RT-flex96C-B	-0.32 +0.44		-0.58 +0.27			
RTA96C-B	-0.27	±0.27	-0.46	0.27	±0.11	0.11
 *1 For engines with *2 For engines with *3 This value is not investigations and Table 5.1: crankwe engine c 	T/V damper a limit for fin e required.	or front dis al acceptan	c ⁴⁷ . ce, but it is 00mm] for	new alignmer		
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Recom	mended ^{*1} static ma	in bearing loads [I	kN] before chockii	ng
	mb #1* ²	mb #2	mb #3* ³	mb #4 to n ⁴
RT-flex35	4-20	25-50	20-55	>12
RT-flex40	5-25	40-75	35-80	>15
RT-flex48T-D				
RTA48T-D	10-40	60-155	50-160	>30
RTA48T-B RT-flex50-D				
RT-flex50-B	10-45	70-165	55-170	>30
RT-flex50				
RT-flex58T-E RT-flex58T-D, V1, V2				
RTA58T-D	10-65	100-230	85-240	>30
RT-flex58T-B				
RTA58T-B RT-flex60C-B	10-70	120-240	100-250	>30
RT-flex60C	10-70	120-240	100-250	>30
RT-flex68-D, V1 RTA68-D				
RT-flex68-B	10-100	170-310	140-320	>40
RTA68-B				
RT-flex82C RTA82C	10-140	280-510	230-530	>70
RT-flex82T-B				
RT-flex82T	5-130	330-600	270-630	>70
RTA82T-B RTA82T				
RT-flex84T-D	5-120	290-530	230-560	>70
RTA84T-D RT-flex96C-B				
RTA96C-B	10-150	320-610	260-640	>70
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5.5.1 Jack correction factors

The jack correction factors provided by the alignment layout calculation should be used for the evaluation of static bearing loads.

EnDyn provides jack correction factors for the shaft bearings according to the userdefined jack positions and for the engine main bearings as defined by its integrated crankshaft models of Wärtsilä RT-flex and RTA engines.

However, if the alignment layout calculation was created with any other programs, then the average jack correction factors provided by table 5.3, p. 38, should be applied.

Bearing	Jack and gauge position	Jack correction factor
aftmost mb1	below flywheel	1.5
mb2 (fwd)	aft crank of aft cylinder #1	0.8 or 1.2 ⁵⁰
mb3 (aft)	forward crank of aft cylinder #1	1

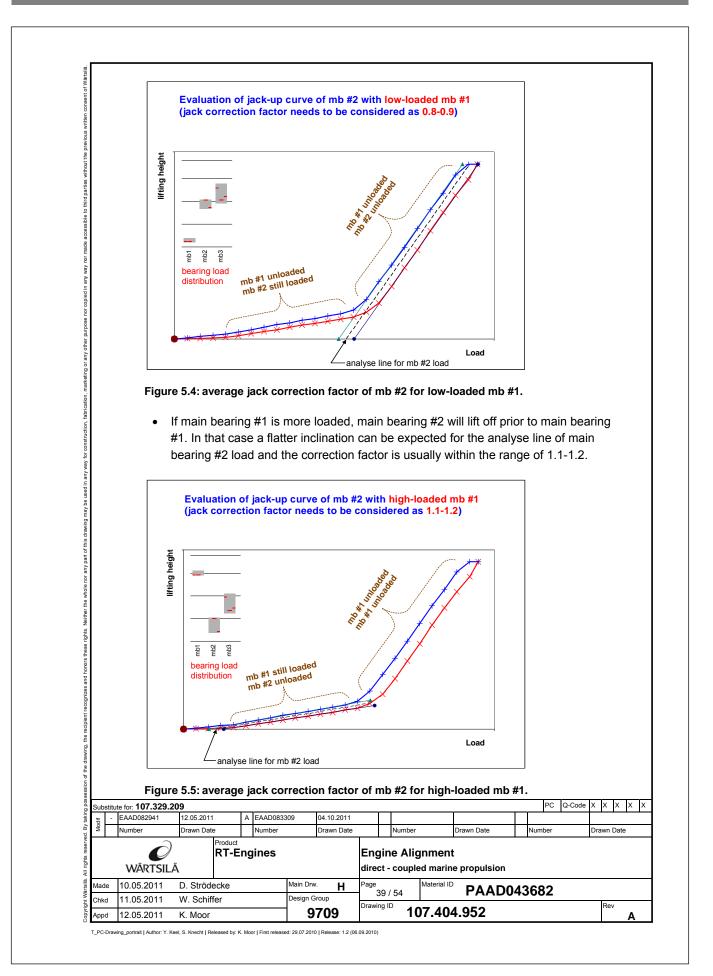
Table 5.3: average jack correction factors⁵¹.

The jack correction factor depends not only on the arrangement of jack and gauge positions in relation to the bearings, but also on the bearing load distribution. While for most bearings the jack correction factor changes only within the negligible range of ± 0.1 due to different load distributions, the jack correction factor of main bearing #2 may change significantly:

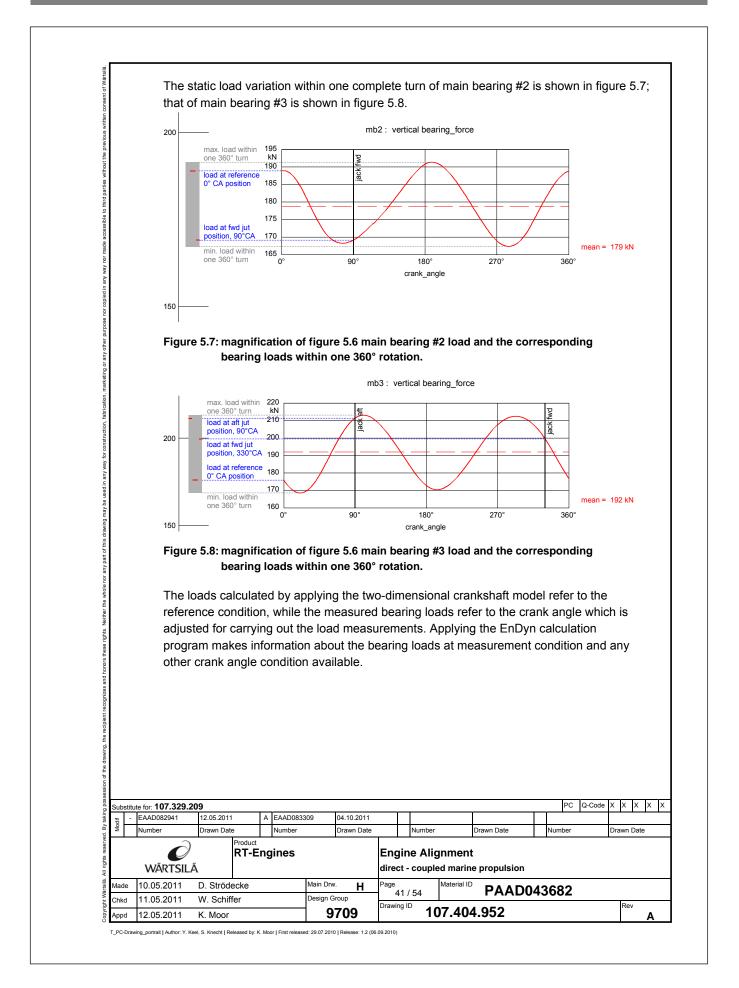
If main bearing #1 is very low loaded, it will lift off prior to main bearing #2. In this case a steep inclination can be expected for the analyse line of main bearing #2 load and the correction factor is usually within the range of 0.8-0.9. This is usually only the case in very light draught conditions as found before or shortly after chocking the engine.

See the following explanation. In short: if mb #1 is very low loaded: 0.8; otherwise: 1.2.
 Only to be applied if not provided by alignment calculation.

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Wärtsilä provides support for that analysis free of charge by performing a so called 'reverse calculation'. 5.5.2 Influence of crank angle on bearing load The main bearing loads vary depending on the crank angle (CA). The reason for this can be found in the geometry of the cranks which causes non-rotary symmetrical stiffness of the cranks, i.e. the crankshaft stiffness between the bearings is different for different crank angles and consequently the bearing load distribution is different. Therefore a reference condition is defined which refers to 0° CA, i.e. cylinder #1 in top dead centre position. The total extent of each bearing's load range within one 360° rotation is indicated on the EnDyn calculation output graphics by a grey load range field. The cylinder #1 top dead centre position (TDC) which refers to 0° CA is marked by the longer red centre line. The shorter red lines on the left and right sides in the grey box mark the main bearing loads at jack-up test condition, i.e. on the left side for jack-up test from the main bearing's aft side and on the right side for the jack-up test from the main bearing's forward side. As main bearing #1 can only be measured from aft side, the line on the right side is omitted, and the left line accordingly for main bearing #2, as this bearing can only be measured from forward side. The following figure 5.6 shows an example of the vertical bearing load graphic as provided by EnDyn, but reduced to just the aft main bearings #1 to #3. Vertical bearing load [kN] 300 load range load cyl1 TDC 200 load jack aft 100 load jack fwd 0 mb3 mb2 mb1 Figure 5.6: example of RT-flex58T-D main bearing #1 to #3 loads as plotted by the EnDyn alignment calculation program. PC Q-Code X X X X X Substitute for: 107.329.209 A EAAD083309 04.10.2011 EAAD082941 12.05.2011 Numbe Drawn Date Number Drawn Date Number Drawn Date Numbe Drawn Date **RT-Engines** Engine Alignment WÄRTSILÄ direct - coupled marine propulsion Made 10.05.2011 D. Strödecke Main Drw н age laterial ID PAAD043682 40 / 54 11.05.2011 W. Schiffer Design Group Chkd Drawing ID lev 107.404.952 9709 12.05.2011 Appd K. Moor

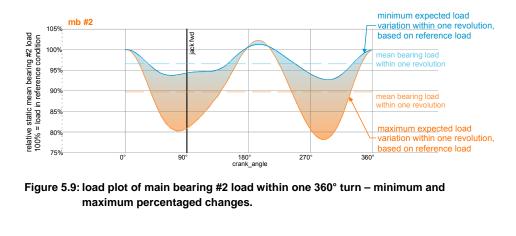


Main bearing #1 load is measured at 0° CA (reference condition) position and therefore the measured load refers directly to the calculated load. However, the jack-up tests for main bearings #2 and #3 are usually carried out with the aftmost crankpin on exhaust side, as indicated in the bearing load graphics. For these jack-up test conditions the bearing loads generally deviate compared to 0°CA as follows:

Mb #2: lower⁵² static bearing load⁵³, close to the minimum of the one-revolution load range.

Mb #3: higher⁵⁴ static bearing load⁵³, close to the maximum of the one-revolution load range.

The extent of the bearing load change depends on the engine type as well as the current situation (bending moments in the crankshaft). In general the range of expected load change within one 360° rotation is less for main bearing #2 than for main bearing #3. The following two figures provide the related relative maximum and minimum ranges.

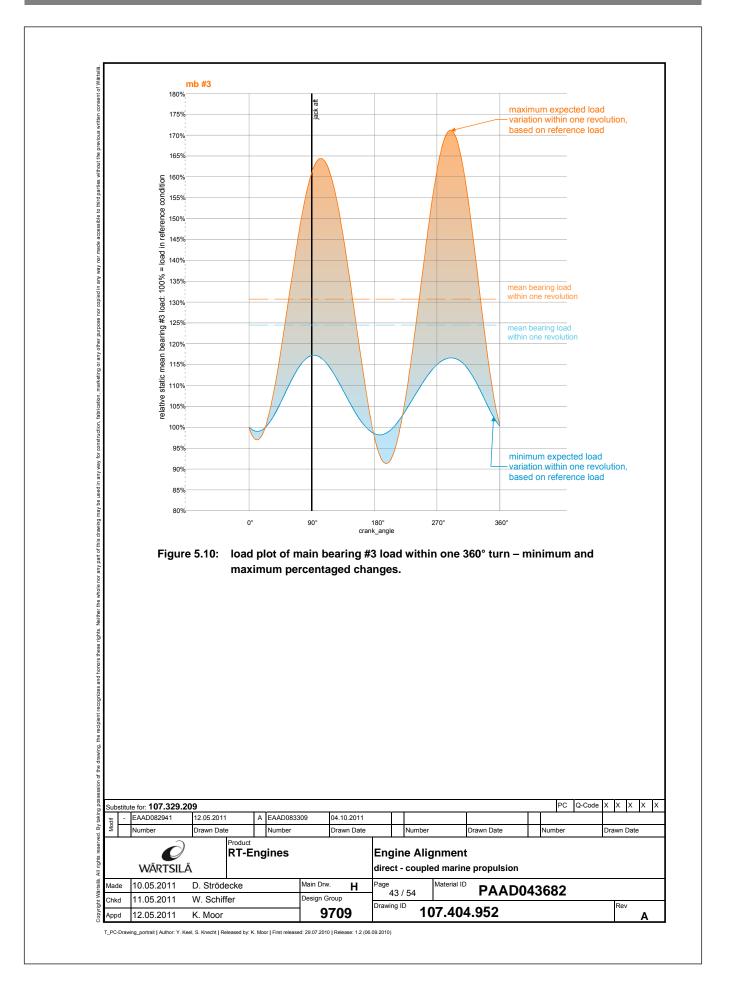


⁵³ Static bearing load = jack load multiplied by the jack correction factor.

⁵⁴ Depending on engine type and current situation (bending moments in the crankshaft), usually a variation within the range of 15% to 70% can be expected, as long as main bearing #3 is loaded as recommended. EnDyn alignment layout calculation helps at least to know the influence of the engine type. Advanced analyses support is provided on request by Wärtsilä.

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⁵² In most cases between 80% and 90% of reference load for high-loaded bearing #2 as requested for the layout condition. In case of low-loaded main bearing #2, the load might be reduced to 0%, i.e. unloaded.



5.6 Chocking and fixation

Before pouring the resin chock under the engine, the engine side stoppers have to be placed in their final positions. The correct heights and the minimum contact surfaces as given in the relevant side stopper drawings have to be ensured.

The chocking of the engine has to be prepared as described in the Marine Installation Manual (MIM). It is important that the epoxy resin material (chock) meets the defined properties. Then chock the engine, following the pouring procedure of the epoxy resin manufacturer's instructions.

Also the shaft bearings need to be chocked, either by pouring epoxy resin chocks or by installing metal chocks. It is possible to do that as a final installation step, after a preliminary alignment check after engine fixation has been carried out. The advantage of performing that step as last step is that some minor errors occurred during the engine chocking and fixation process can be corrected. However, the extent of such a correction has to be considered as very limited and should not counter-act any accurate working procedure. Therefore it is also suitable to do this along with engine chocking. After the time required for resin chock hardening has elapsed, the engine holding-down bolts have to be tightened. For tightening the holding-down studs, please follow the instruction on the relevant drawing.

Finally the side stopper wedges need to be fitted.

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6 Alignment checks for commissioning / ship delivery

The limits for crankweb deflections and static main bearing loads should be maintained at ship's commissioning, i.e. just before, during or after sea trial, when the ship is afloat and ready for operation.

The ship has a normal draught and trim within the limits for normal ship service. The measurements can be taken almost straight after stopping the engine⁵⁵ or with the engine already cooled down, but in all cases the engine temperature (crankshaft temperature, e.g. measured by a handheld infrared thermometer) needs to be recorded for reference. More important than the engine temperature itself is an equal longitudinal temperature of the engine and the engine foundation / sump tank in the aft half of the engine – as this is the case during normal engine operation. Therefore it is essential to stop the sump tank preheater early before starting the measurements – otherwise unequal temperature distribution will cause unequal thermal rise and by that unequal main bearing offsets, which may cause inacceptable main bearing load distribution.

6.1 Static shaft bearing loads, commissioning / ship delivery condition

The same requirements as mentioned in section 5.3, p. 32, have to be fulfilled.

6.2 Crankweb deflections, commissioning / ship delivery condition

6.2.1 Validity of crankweb deflection limits for commissioning / ship delivery

These limits are valid for the completely assembled engine on board the <u>afloat</u> vessel at commissioning / delivery of the ship to the owner, i.e. usually directly before, during and after the sea trial. The engine is <u>hot or cold</u>. The draught is within the normal ship operation limits. The lubricating oil sump tank heating has to be inactive in order to avoid any local heat spot below the engine, which does not exist under normal engine operation condition.

These limits can be applied for additional measurements after chocking the engine. However, if the ship has not yet been in operation, the limit should not be maxed out, as influences of settling effects cannot be predicted exactly.

These limits are not valid for the condition before chocking.

6.2.2 Description of crankweb deflection limits for commissioning / ship delivery

The limits are defined close to the normal ship service limits. However, some reserve for the unexpected is kept.

⁵⁵ Please consider the safety advices provided in the Maintenance Manual.

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The negative crankweb deflection limit of the foremost cylinder is increased in case of installed external masses like T/V damper or front disc, as the negative crankweb deflection is caused by the bending moment produced by an external mass. This is fully acceptable and - even more - required in order to keep all main bearings statically properly loaded, which has top priority.

6.2.3 Overview: crankweb deflection limits for commissioning / ship delivery

Rotation direction for measurement:

- Counter-clockwise rotation for engines with turning gear on fuel pump side
- Clockwise rotation for engines with turning gear on exhaust side (e.g. RT-flex48T-D, RT-flex50/-B/-D, RT-flex68-D/V.I, RT-flex82C/T)

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Reading		v	ertical		ho	rizontal
convention: $/+ \sqrt{-2}$	cyl.1	cyl.2 to cyl.(n-1) cyl.(n)* ¹	cyl.(n)* ²	max. absolute deviation between two adjacent cranks* ³	cyl.1 to cyl.(n)	max. absolute deviation between two adjacent cranks* ³
RT-flex35	±0.23	±0.15	+0.15	0.10	±0.06	0.04
RT-flex40	±0.29	±0.19	-0.17 +0.19	0.13	±0.07	0.05
RT-flex48T-D RTA48T-D	±0.52	±0.33	-0.22 +0.33	0.22	±0.13	0.09
RTA48T-B RT-flex50-D			-0.36			
RT-flex50-D RT-flex50-B RT-flex50	±0.52	±0.33	+0.33	0.22	±0.13	0.09
RT-flex58T-E RT-flex58T-D, V1, V2		10.20	+0.36	0.04	10.44	0.40
RTA58T-D RT-flex58T-B RTA58T-B	±0.58	±0.36	-0.52	0.24	±0.14	0.10
RT-flex60C-B RT-flex60C	±0.48	±0.30	+0.30	0.20	±0.12	0.08
RT-flex68-D, V1 RTA68-D RT-flex68-B	±0.77	±0.48	+0.48	0.32	±0.19	0.13
RTA68-B RT-flex82C			-0.55 +0.34			
RTA82C	±0.54	±0.34	-0.40	0.23	±0.14	0.09
RT-flex82T-B RT-flex82T RTA82T-B	±0.86	±0.54	+0.54	0.36	±0.22	0.14
RTA82T RT-flex84T-D RTA84T-D	±0.77	±0.48	+0.48	0.32	±0.19	0.13
RT-flex96C-B RTA96C-B	±0.64	±0.40	+0.40	0.27	±0.16	0.11
 *1 For engines with *2 For engines with *3 This value is not investigations are Table 6.1: crankwe ⁵⁶ In this case the n foremost crankwe bearings have to actions are require 	T/V dampe a limit for f e required. b deflection naximum a ebs might b be checke	on front dis inal acceptar on limits [mi _ bsolute devia be exceeded	sc ⁵⁶ . nce, but it is m] for com ation betwee . If so, the b	missioning / s en the deflectio earing loads o	hip deliver on values of f the two for	'y. the two ⁻emost mair
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6.3 Recommended static main bearing loads, commissioning / ship delivery condition

For jack correction factors and the crank angle influence on the bearing load, please refer to section 5.5.1, p. 38 and section 5.5.2, p. 40 respectively.

Table 6.2 gives the recommended main bearing loads at commissioning / ship delivery condition for measurements under ballast draught condition, table 6.3 for measurements under scantling / design draught condition.

Recommended*1		g loads [kN] for co draught condition	mmissioning / ship	o delivery,
	mb #1	mb #2	mb #3* ²	mb #4 to n ⁵⁷
RT-flex35	4-25	20-55	15-60	>10
RT-flex40	5-30	30-80	25-85	>15
RT-flex48T-D RTA48T-D RTA48T-B	10-50	50-170	35-180	>20
RT-flex50-D RT-flex50-B RT-flex50	10-55	60-180	40-190	>20
RT-flex58T-E RT-flex58T-D, V1, V2 RTA58T-D RT-flex58T-B RTA58T-B	10-85	90-250	60-260	>20
RT-flex60C-B RT-flex60C	10-90	110-265	70-280	>20
RT-flex68-D, V1 RTA68-D RT-flex68-B RTA68-B	10-130	150-340	90-360	>30
RT-flex82C RTA82C	10-180	230-550	150-580	>50
RT-flex82T-B RT-flex82T RTA82T-B RTA82T	5-170	270-650	180-680	>50
RT-flex84T-D RTA84T-D	5-160	240-580	160-610	>50
RT-flex96C-B RTA96C-B	10-200	260-660	180-690	>50

*1 The given values are for guidance only.

*2 mb #3 load should be \geq 50% of mb #2 load.

 Table 6.2: recommended main bearing loads [kN] for commissioning / ship delivery, valid at ballast draught condition.

⁵⁷ Usually just mb #1 to #3 are measured, except if Wärtsilä recommends further case-specific measurements.

These minimum values have to be kept for any crank angle position.

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<u>Recommended</u> s	tatic main bearing scantling or d	loads [KN] for con lesign draught con		delivery,
	mb #1	mb #2	mb #3	mb #4 to n ⁵⁸
RT-flex35	>5	>10	>10	>10
RT-flex40	>5	>15	>15	>15
RT-flex48T-D RTA48T-D RTA48T-B	>10	>20	>20	>20
RT-flex50-D RT-flex50-B RT-flex50	>10	>20	>20	>20
RT-flex58T-E RT-flex58T-D, V1, V2 RTA58T-D RT-flex58T-B RTA58T-B	>10	>20	>20	>20
RT-flex60C-B RT-flex60C	>10	>20	>20	>20
RT-flex68-D, V1 RTA68-D RT-flex68-B RTA68-B	>20	>30	>30	>30
RT-flex82C RTA82C	>20	>50	>30	>30
RT-flex82T-B RT-flex82T RTA82T-B RTA82T	>20	>50	>30	>30
RT-flex84T-D RTA84T-D	>20	>50	>30	>30
RT-flex96C-B RTA96C-B	>20	>50	>30	>30

 Table 6.3: recommended main bearing loads [kN] for commissioning / ship delivery, valid at scantling or design draught condition.

In general the design draught condition is the hull bending condition which in container vessels diverges the most from the alignment draught condition, whereas in bulk carriers and tankers it is the scantling draught condition.

⁵⁸ Usually just mb #1 to #3 are measured, except if Wärtsilä recommends further case-specific measurements.

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7 Alignment checks during normal ship's service

Usually no detailed alignment checks during normal ship's service are needed! Regular crankweb deflection measurements following the intervals defined by the class rules are sufficient. Only in case of abnormalities, like sudden change of crankweb deflection measurement results, bearing temperature alarms or bearing damages, detailed alignment measurements might become necessary. In any such cases it is recommended to contact Wärtsilä for further support.

7.1 Crankweb deflection limits for normal ship's service

7.1.1 Validity of crankweb deflection limits for normal ship's service

The limits for *normal ship's service* are valid for any condition of ship's service, i.e. after ship delivery, vessel afloat. The engine is <u>hot or cold</u>.

7.1.2 Description of crankweb deflection limits for normal ship's service

The main purpose of the vertical crankweb deflection limits is to ensure that all main bearings are statically properly loaded.

The main purpose of the horizontal crankweb deflection limits is to ensure that the engine housing is not twisted.

The crankweb deflections are affected by:

- the difference in temperature between the lubricating oil sump tank and the seawater
- the engine temperature
- the draught.

Therefore the measured crankweb deflections need to be considered along with the a.m. conditions. On any measurement protocol at least the engine temperature (in crankcase / at crankshaft) and the draught need to be mentioned.

As the draught change has its main influence on the aft cylinder #1, the permissible range of crankweb deflection for cylinder #1 is wider compared to the other cylinders.

Another aspect of the maximum allowed crankweb deflections is the limitation of the crankshaft stress. However, this aspect can be neglected as the limits are defined even more strictly for the above mentioned reasons.

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Reading				horizontal				
convention: /+ / -/	cyl.1	cyl.2 to cyl.(n-1) cyl.(n)* ¹	cyl	.(n)* ²	max. absolute deviatior between adjacent cranks* ³	n cyl.1 two cyl.(n		max. absolute deviation between tw adjacent cranks* ³
RT-flex35	±0.26	±0.16	+0.		0.10	±0.06		0.04
RT-flex40	±0.33	±0.20	+0.		0.13	±0.08		0.06
RT-flex48T-D RTA48T-D RTA48T-B	±0.58	±0.36	+0.		0.22	±0.14		0.09
RT-flex50-D RT-flex50-B RT-flex50	±0.58	±0.36	+0.		0.22	±0.14		0.09
RT-flex58T-E RT-flex58T-D, V1, V2 RTA58T-D RT-flex58T-B	±0.64	±0.40	+0.		0.24	±0.16		0.10
RTA58T-B RT-flex60C-B RT-flex60C	±0.53	±0.33	+0.		0.20	±0.13		0.08
RT-flex68-D, V1 RTA68-D RT-flex68-B RTA68-B	±0.85	±0.53	+0.	.53	0.32	±0.21		0.13
RT-flex82C RTA82C	±0.60	±0.37	+0.		0.23	±0.15		0.09
RT-flex82T-B RT-flex82T RTA82T-B RTA82T	±0.95	±0.59	+0.		0.36	±0.24		0.14
RT-flex84T-D RTA84T-D	±0.85	±0.53	+0.		0.32	±0.21		0.13
RT-flex96C-B RTA96C-B	±0.71	±0.44	+0.		0.27	±0.18		0.11
 *1 For engines withor *2 For engines with T *3 This value is not a investigations are Table 7.1: crankweb 	V dam limit for required	per or front d final accepta	isc ⁵⁹ . ance,	but it is			that fu	urther
⁵⁹ In this case the ma foremost crankwel bearings have to b actions are require 07.329.209	bs might be check	be exceede	d. If s	o, the b	earing loa	ds of the tw	wo fore imit, no	most main
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Drawing ID 107.404.952

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7.2 Minimum main bearing load in ship's service condition under any draught condition

As already stated in the introduction, section 1.5, p. 6, all main bearings need to be statically loaded under all normal ship's service operation conditions after ship delivery, i.e. at all draught conditions between ballast draught and scantling draught, engine <u>hot</u> <u>or cold</u>.

The minimum bearing loads which have to be reached are given in the following table. Reaching the **minimum bearing loads** is the **finally binding bearing load requirement for alignment**.

For jack correction factors and the crank angle influence on the bearing load, please refer to section 5.5.1, p. 38 and section 5.5.2, p. 40 respectively.

	oad <i>limits</i> for ship service co any draught, any crank ang	
	mb #1	mb #2 to n
RT-flex35	>5	>10
RT-flex40	>5	>15
RT-flex48T-D RTA48T-D RTA48T-B	>10	>20
RT-flex50-D RT-flex50-B RT-flex50	>10	>20
RT-flex58T-E RT-flex58T-D, V1, V2 RTA58T-D RT-flex58T-B RTA58T-B	>10	>20
RT-flex60C-B RT-flex60C	>10	>20
RT-flex68-D, V1 RTA68-D RT-flex68-B RTA68-B	>20	>30
RT-flex82C RTA82C	>20	>30
RT-flex82T-B RT-flex82T RTA82T-B RTA82T	>20	>30
RT-flex84T-D RTA84T-D	>20	>30
RT-flex96C-B RTA96C-B	>20	>30

Table 7.2: minimum main bearing load limits [kN] for ship service condition.

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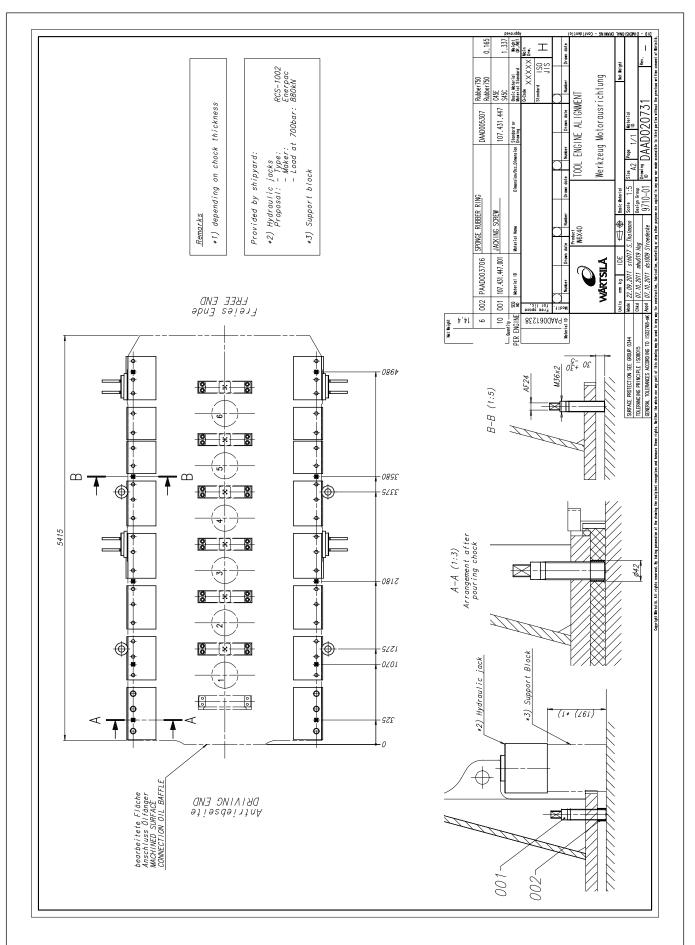
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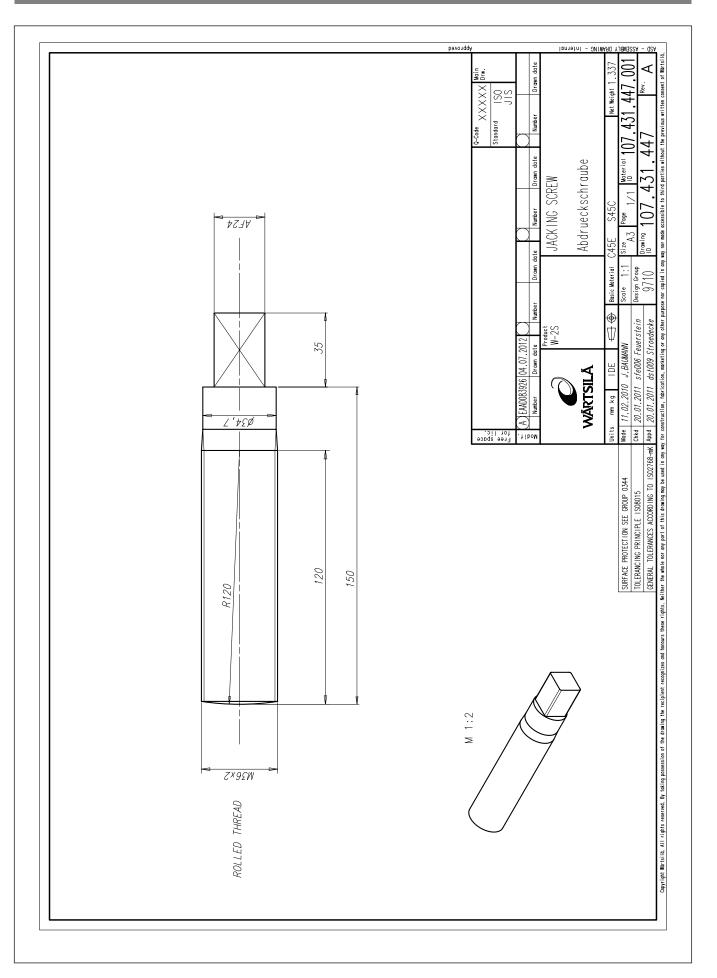
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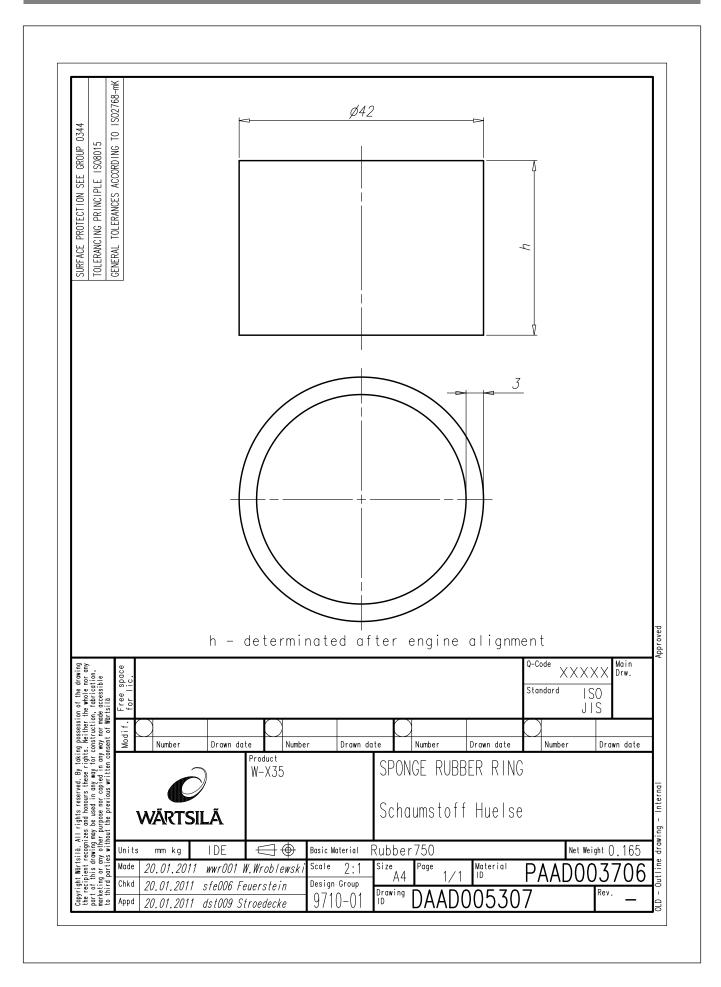
21.2 Tools

21.2.1 Drawings

DAAD020731 -	Tool Engine Alignment, W6X40	2005
107.431.447 a	Jacking Screw, W6X40	2002183
DAAD005307 -	Sponge Rubber Ring, W6X40	2001







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22. Appendix

22.1 Abbreviations

ABB	ASEA Brown Boveri	MAPEX	Monitoring and maintenance performance enhance- ment with expert knowledge		
ALM	Alarm	MCR	Maximum continuous rating (R1)		
AMS	Attended machinery space	MDO	Marine diesel oil		
BFO	Bunker fuel oil	mep	Mean effective pressure		
BN	Base Number	METxxMB	Turbocharger (Mitsubishi manufacture)		
BSEF	Brake specific exhaust gas flow	мні	Mitsubishi Heavy Industries		
BSFC	Brake specific fuel consumption	MIM	Marine installation manual		
CCAI	Calculated Carbon Aromaticity Index	MMI	Man-machine interface		
CCR	Conradson carbon	N, n	Rotational speed		
CCW	Cylinder cooling water	NAS	National Aerospace Standard		
CMCR	Contract maximum continuous rating (Rx)	NCR	Nominal continuous rating		
CPP	Controllable pitch propeller	NOR	Nominal operation rating		
CSR	Continuous service rating (also designated NOR and NCR)	ОМ	Operational margin		
cSt	centi-Stoke (kinematic viscosity)	OPI	Operator interface		
DAH	Differential pressure alarm, high	Р	Power		
DENIS- UNIC	Diesel engine control and optimizing specification	PAL	Pressure alarm, low		
EM	Engine margin	PI	Pressure indicator		
EMA	Engine Management & Automation	PLS	Pulse Lubricating System (cylinder liner)		
FCM	Flex control module	ppm	Parts per million		
FPP	Fixed pitch propeller	PRU	Power related unbalance		
FQS	Fuel quality setting	РТО	Power take-off		
FW	Freshwater	RCS	Remote control system		
GEA	Scavenge air cooler (GEA manufacture)	RW1	Redwood seconds No. 1 (kinematic viscosity)		
HFO	Heavy fuel oil	S/G	Shaft generator		
НТ	High temperature	SAC	Scavenge air cooler		
IMO	International Maritime Organisation	SAE	Society of Automotive Engineers		
IND	Indication	SHD	Shut down		
IPDLC	Integrated power-dependent liner cooling	SIB	Shipyard interface box		
ISO	International Standard Organisation	SLD	Slow down		
kW	Kilowatt	SM	Sea margin		

kWe	Kilowatt electrical	SSU	Saybolt second universal
kWh	Kilowatt hour	SW	Seawater
LAH	Level alarm, high	тво	Time between overhauls
LAL	Level alarm, low	TC	Turbocharger
LCV	Lower calorific value	tEaT	Temperature of exhaust gas after turbine
LI	Level indicator	ТІ	Temperature indicator
LLT	Low-Load Tuning	A1xx-Lxx	Turbocharger (ABB manufacture)
LR	Light running margin	UMS	Unattended machinery space
LSL	Level switch, low	VI	Viscosity index
LT	Low temperature	WCH	Wärtsilä Switzerland
М	Torque	UNIC	UNIfied Control
M1H	External moment 1 st order horizontal	winGTD	General Technical Data program
M1V	External moment 1 st order vertical	ΔΜ	Torque variation
M2V	External moment 2 nd order vertical		

Table 22.1: Abbreviations

22.2 SI dimensions for internal combustion engines

Symbol	Definition	SI-Units	Other units
I,L	Length	m, mm, mm	
A	Area	m², mm², cm²	
V	Volume	m ³ , dm ³ , l, cm ³	
m	Mass	kg, t, g	
ρ	Density	kg/m ³ , g/cm ³ , kg/dm ³	
Z, W	Section modulus	m ³	
I _a , I _p	Second moment of area	m ⁴	
I, J	Moment of inertia (radius)	kgm ²	
α, β, γ, δ, φ	Angle	rad, °	
t	Time	s, d, h, min	
f, v	Frequency	Hz, 1/s	
v, c, w, u	Velocity	m/s, km/h	Kn
N, n	Rotational frequency	1/s, 1/min	rpm
а	Acceleration	m/s²	
ω	Angular velocity	rad/s	
α	Angular acceleration	rad/s ²	
q _m	Mass flow rate	kg/s	
q _v	Volume flow rate	m ³ /s	
р	Momentum	Nm	
L	Angular momentum	Nsm	
F	Force	N, MN, kN	
р	Pressure	N/m², bar, mbar, kPa	1 bar = 100 kPa, 100 mmWG = 1 kPa
σ, τ	Stress	N/m², N/mm²	
E	Modulus of elasticity	N/m ² , N/mm ²	
W, E, A, Q	Energy, work, quantity of heat	J, MJ, kJ, kWh	
Р	Power	W, kW, MW	
М, Т	Torque moment of force	Nm	
η	Dynamic viscosity	Ns/m ²	
v	Kinematic viscosity	m²/s	cSt, RW1
γ, σ	Surface tension	N/m	
Τ, Θ, t, θ	Temperature	K, °C	
ΔΤ, ΔΘ,	Temperature interval	K, °C	
α	Linear expansion coefficient	1/K	
C, S	Heat capacity, entropy	J/K	
с	Specific heat capacity	J/(kgK)	
λ	Thermal conductivity	W/(mK)	
К	Coefficient of heat transfer	W/(m ² K)	
е	Net calorific value	J/kg, J/m ³	

Symbol	Definition	SI-Units	Other units
L _{(LIN)TOT}	Total LIN noise pressure level	dB	
L _{(A)TOT}	Total A noise pressure level	dB	
L _{OKT}	Average spatial noise level over octave band	dB	
U	Voltage	V	
I	Current	A	
BSFC	Brake specific fuel consumption	kg/J, kg/(kWh), g/(kWh)	

Table 22.2: SI dimensions for internal combustion engines

22.3 Approximate conversion factors

	1 in			=	25.4 mm
	1 ft	=	12 in		304.8 mm
Length	1 It 1 yd		3 feet	=	914.4 mm
Lengui	1 statute mile	=	1760 yds	=	1609.3 m
	1 nautical mile	=	6080 feet	=	1853 m
	1 nautical mile	_ =	JUDU IEEL	=	0.0283 kg
	1 lb	=	16 oz		0.0283 kg 0.4536 kg
Mass	1 long ton	_	10.02	=	1016.1 kg
IVId55	1 short ton			=	
				=	907.2 kg
	1 tonne			=	1000 kg
	1 Imp. pint			=	0.568
	1 U.S. pint	=	0.473		
	1 Imp. quart	=	1.136		
Volume (fluids)	1 U.S. quart	=	0.946		
	1 Imp. gal	=	4.546		
	1 U.S. gal			=	3.785
	1 Imp. barrel	=	36 Imp. gal	=	163.66
_	1 barrel petroleum	=	42 US. gal	=	158.98
Force	1 lbf (pound force)			=	4.45 N
Pressure	1 psi (lb/sq in)			=	6.899 kPa (0.0689 bar)
Velocity	1 mph		=	1.609 km/h	
	1 knot			=	1.853 km/h
Acceleration	1 mphps			=	0.447 m/s ²
Temperature	1 °C			=	0.55 · (°F -32)
Energy	1 BTU			=	1.06 kJ
	1 kcal			=	4.186 kJ
Power	1 kW			=	1.36 bhp
	1 kW			=	860 kcal/h
	1 in ³			=	16.4 cm ³
Volume	1 ft ³			=	0.0283 m ³
	1 yd ³			=	0.7645 m ³
	1 in ²			=	6.45 cm ²
	1 ft ²			=	929 cm ²
Area	1 yd ²			=	0.836 m ²
	1 acre			=	4047 m ²
	1 sq mile (of land) (6	=	2.59 km ²		

Table 22.3: Approximate conversion factors

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